



- We usually divide illumination techniques in two groups:
 - Direct illumination
 - Objects lit by rays coming directly from a light source (one "bounce")
 - •Indirect illumination
 - •Rays that have been reflected/refracted by other sources in the scene (more than one "bounce")
- •Global illumination includes both illumination types, while Local only focuses on direct illumination.



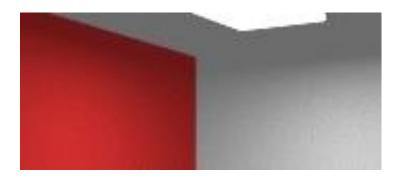
- •Any global illumination technique you have implemented?
 - Reflections
 - Refractions
 - Shadows?
 - •Light changes depending on other objects in scene other than light sources, so YES. But...
- In practice we mainly call GI only to diffuse inter-reflection



- •What is our approach to global illumination in Phong shading model?
 - -Ambient light
 - Not realistic
 - Flat and position independent
 - Cheap



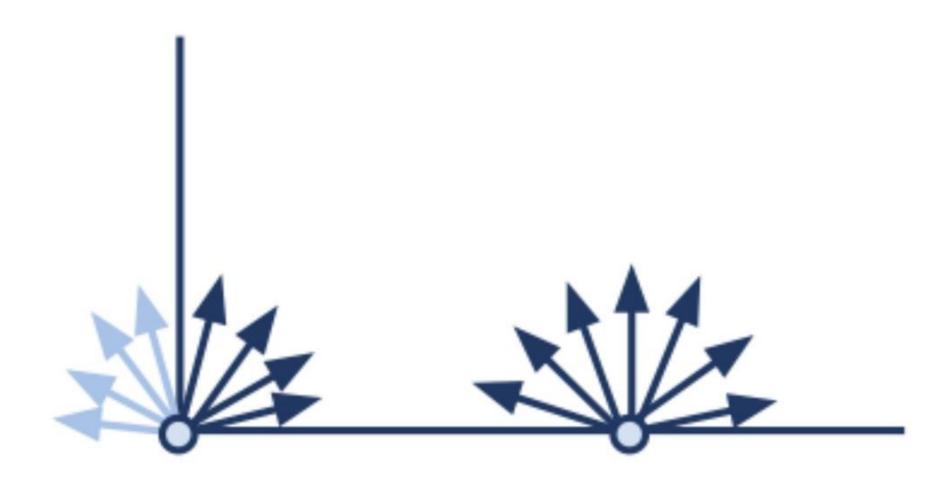
- In reality, the amount of light that reaches a point on the surface of an object depends on the environment
- Objects that can self-occlude or occlude nearby objects
- Think about following scenario:
 - Is the amount of light reaching a corner of the room the same as the center of the wall?
- •Why is this happening?





Wikipedia





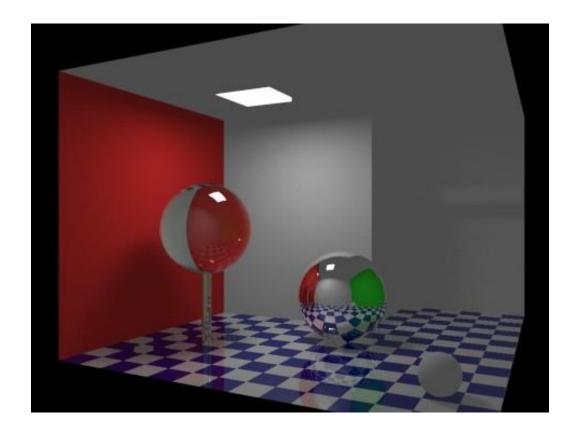


- •How can we implement global illumination?
 - •A bunch of different techniques:
 - Image-based lighting
 - Radiosity
 - Ray tracing
 - Light Probing
 - Cone tracing
 - Photon mapping
 - Signed Distance Fields
 - Ambient occlusion

•

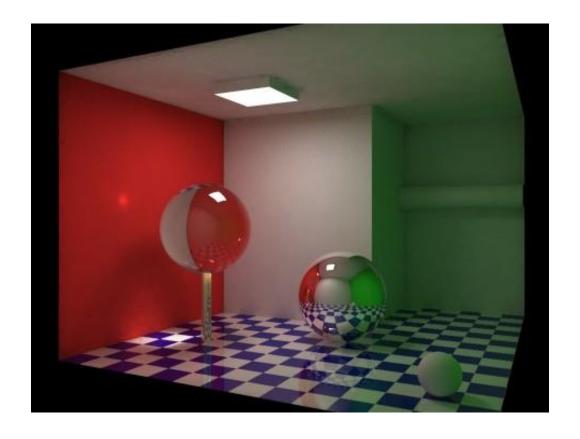


Local Illumination



Wikipedia





Wikipedia



- Shading rendering technique that calculates how exposed a surface is to incoming light
- •What light component does it affect?
 - -AMBIENT!
- Our ambient light lacks directional and spatial variation
- We want to add "shadows" to the ambient



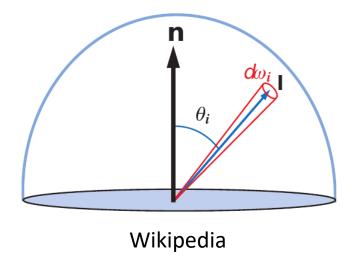




- Ambient Occlusion is a technique for approximating the effect of selfocclusion
- Gives perceptual clues of depth, curvature and spatial proximity
- We will compute the accessibility of every point on the surface of an object
- •How can we compute accessibility?
 - Ray tracing offline (might be real-time nowadays) and baking results to a texture (light maps)
 - Approximated using Screen Space techniques



- •What is irradiance?
 - Randiant flux received per unit area
 - •Energy received on a surface from all incoming directions of the hemisphere





 Ambient light defined as a constant incoming radiance for all incoming directions (without ambient occlusion)

$$E(p,n) = \int_{\Omega} L_A(n \cdot l) d\omega_i = \pi L_A$$

Where:

E(p, n) is the surface irradiance

 L_A is incoming ambient radiance



$$E(p,n) = L_A \int_{\Omega} (n \cdot l) d\omega_i$$

We will add a visibility factor to this equation

$$k_A(p) = \frac{1}{\pi} \int_{\Omega} \boldsymbol{v}(\boldsymbol{p}, \boldsymbol{l}) (n \cdot l) d\omega_i$$

- So that the irradiance varies with surface location
- • $k_A(p)$ between 0 (occluded) and 1 (visible)

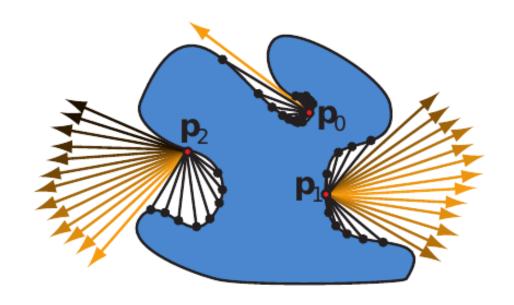


Visibility Function

- Various ways to approach this integral
 - •Precomputation
 - Ray casting
 - Bent normal
 - Lightmaps
 - Real time
 - Unsharp Masking
 - ·SSAO
 - HBAO

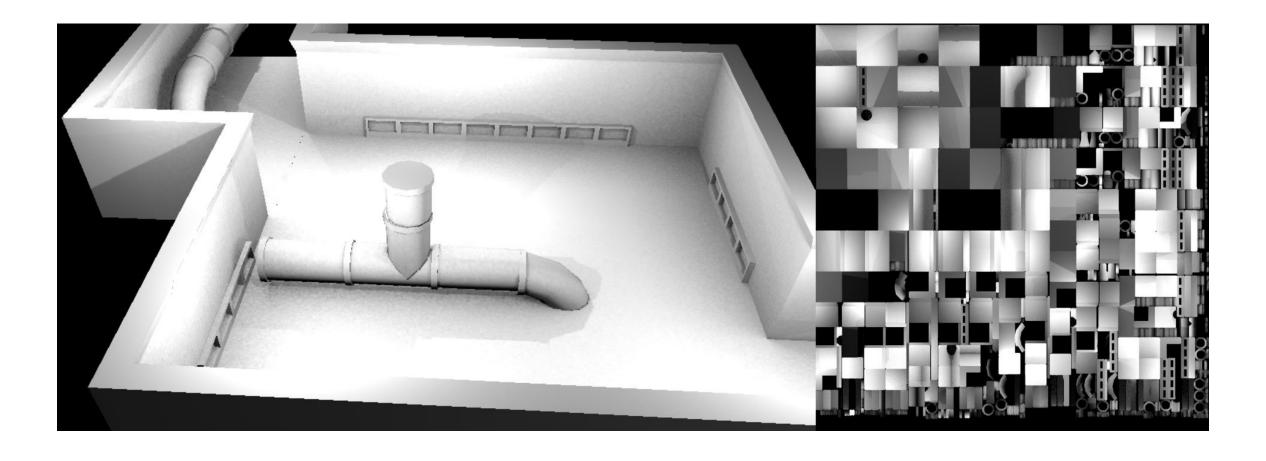


Bent Normal





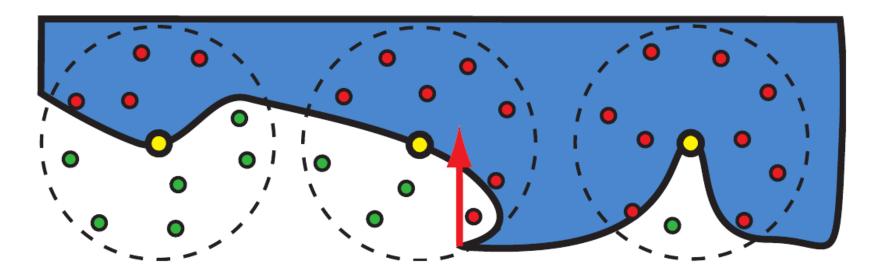
Lightmaps





Screen-Space Ambient Occlusion (SSAO)

- Consists on a post-process algorithm where visibility will be computed based on depth
- Developed by Crytek

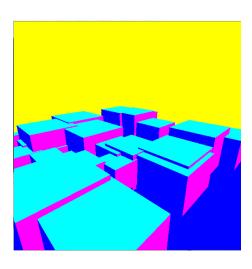


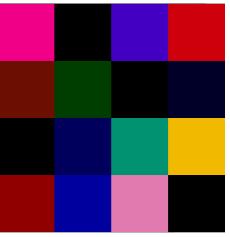


- Check different random position values in a region
 - ^oIf more than 50% of the values are LESS than the current fragment depth value
 - More than 50% of the neighboring fragments are closer to the camera than the current fragment
 - Current fragment is probably blocked so compute occlusion factor



- Needed inputs
 - Cam position
 - "View space position
 - Random values
 - Noise texture
 - Random buffer





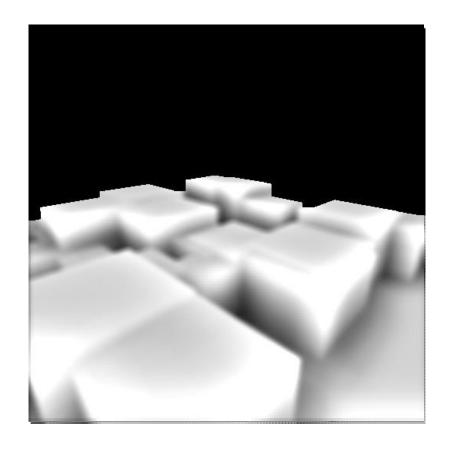


```
// Calculate occlusion value
float occlusion = 0.0f;
// remove banding
const float bias = 0.25f;
for(int i = 0; i < SSAO KERNEL SIZE; i++)</pre>
    vec3 samplePos = TBN * uboSSAOKernel.samples[i].xyz;
    samplePos = fragPos + samplePos * SSAO RADIUS;
    // project
    vec4 offset = vec4(samplePos, 1.0f);
    offset = ubo.projection * offset;
    offset.xyz /= offset.w;
    offset.xyz = offset.xyz * 0.5f + 0.5f;
    float sampleDepth = -texture(samplerPositionDepth, offset.xy).w;
    occlusion += (sampleDepth >= samplePos.z + bias ? 1.0f : 0.0f);
occlusion = 1.0 - (occlusion / float(SSAO KERNEL SIZE));
```

https://github.com/SaschaWillems/Vulkan/tree/master/data/shaders/glsl/ssao



- Aliasing and banding artifacts
- •Solution?
 - BLUR!
 - Gaussian blur... for now
- Use this texture to multiply to ambient



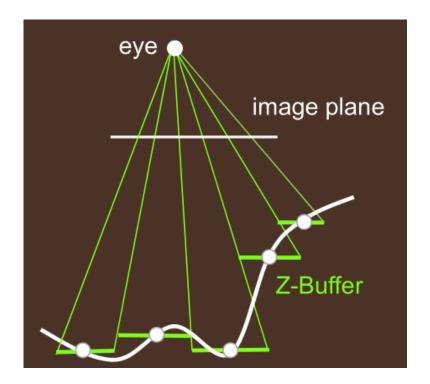


Horizon-Based Ambient Occlusion (HBAO)

Developed by NVIDIA

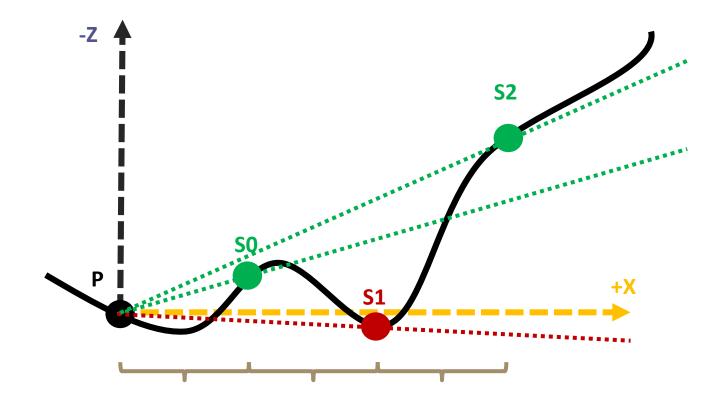
Uses depth buffer as a heightfield to evaluate visibility

Can use positions Z also



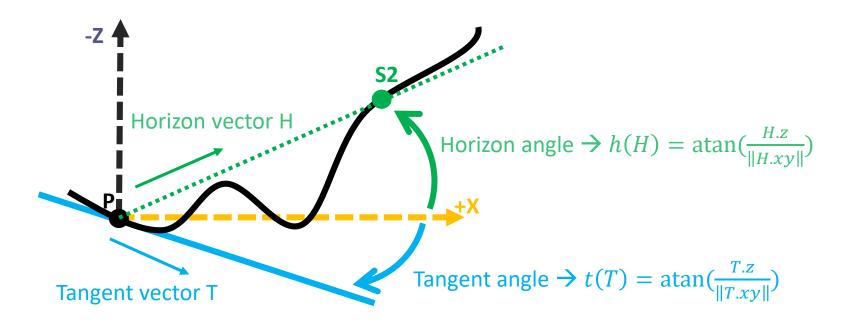


March along multiple directions on the heightfield





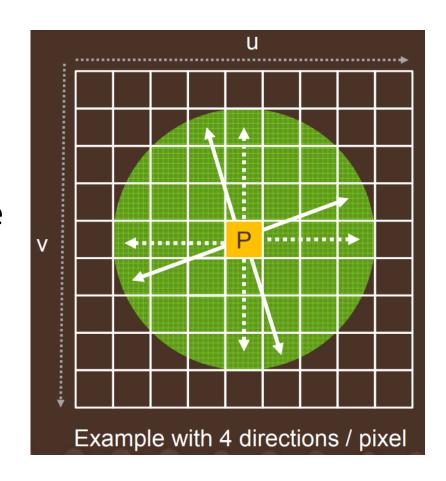
Tangent vector will be relevant for the final occlusion



$$AO = \sin h - \sin t$$

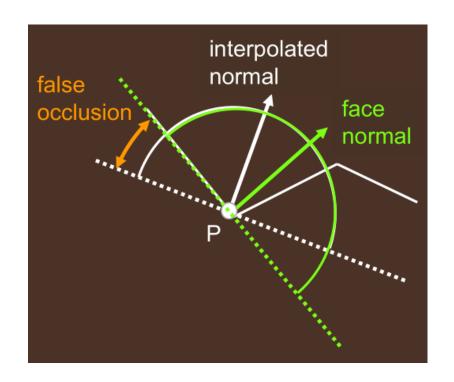


- A maximum radius of the disk needs to be defined
 - Usually in eye space
- Marching (sampling) will happen along multiple directions
- Each direction will have a uniform sampling
- Use per pixel randomization for sampling
 - Rotate the directions of sampling by a random factor
 - •Jitter sample by a random offset



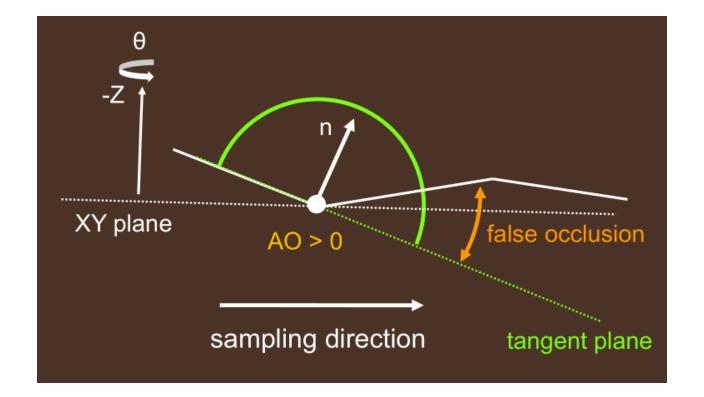


- Using face normal is recommended
 - Can use dFdx/dFdy to get those
 - Interpolated normal may generate false occlusion
- Normal maps may also create a good effect (might be noisy)



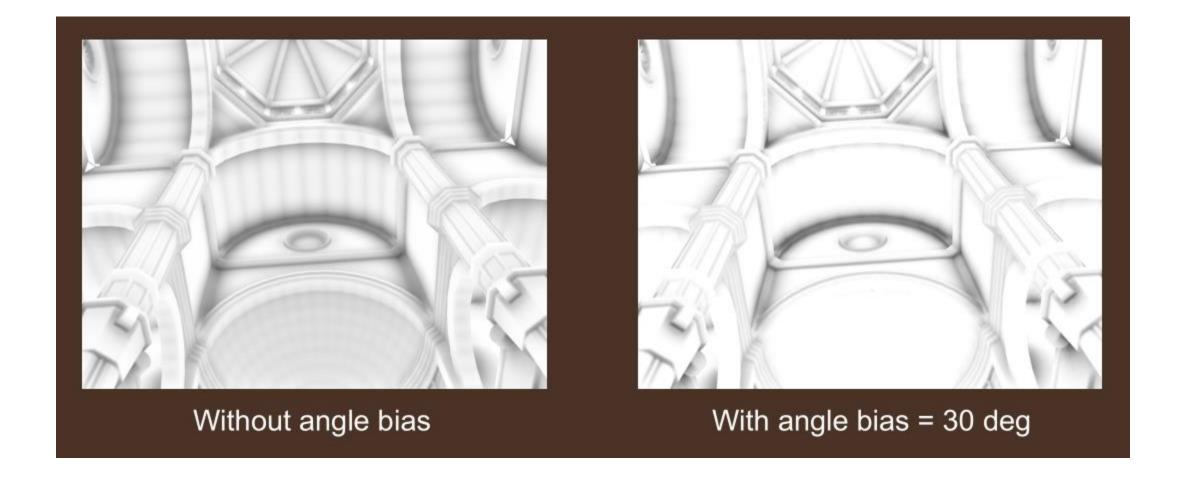


•Add a adjustable bias to ignore "false" or small occlusions





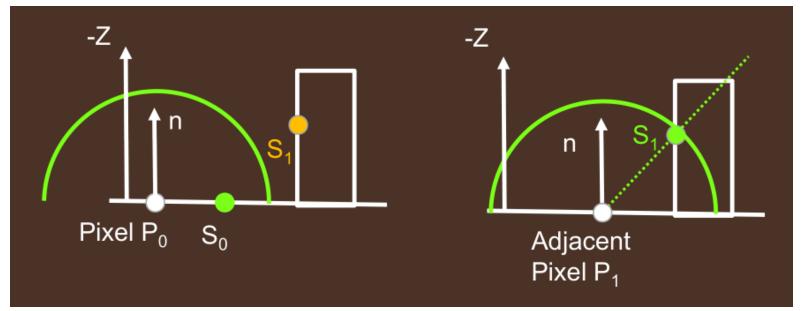
HBAO Bias





- Discontinuity problems may also arise
- Attenuate AO contribution with the function

$$W(r) = 1 - r^2$$
 where $r = \frac{|S_1 - P_0|}{Radius}$





HBAO Attenuation





With Attenuation $W(r) = 1 - r^2$

Without Attenuation W(r) = 1



Input parameters:

- Radius scale:
 - This is a scale factor for the radius R. The radius is the distance outside which occluders are ignored.
- Angle bias:
 - For low-tessellated geometry, occlusion variations tend to appear at creases and ridges, which betray the underlying tessellation. To remove these artifacts, we use an angle bias parameter which restricts the hemisphere.
- Number of directions:
 - This is the number of randomly-rotated 2D directions in image space distributed around the current pixel. The higher this parameter, the lower is the noise in the ambient occlusion.
- Number of steps:
 - This is the maximum number samples per direction. The actual number depends on the projected size of the sphere of radius R around the current surface point.
- Attenuation:
 - This scale factor W0 is applied to the per-sample attenuation function. The occlusion contribution of a given sample is attenuated by W0 * W(r/R) where W(x) = 1 x2.
- Contrast:
 - This value allows to scales up the ambient occlusion values.



- Like with SSAO randomly sampling will produce noise
 - BLUR!
- Regular Gaussian blur will produce halos because edges information is completely ignored
- •Bilateral Filter!



References

- Screen Space Ambient Occlusion by Martin Mittring
- Image-Space Horizon-Based Ambient Occlusion by Louis Bavoil & Miguel Sainz
- Image Enhancement by Unsharp Masking the Depth Buffer by Thomas Luft, Carsten Colditz and Oliver Deussen