

Yuxuan Fang

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Education

Huazhong University of Science and Technology

Wuhan, China

B.Eng. in Electrical Engineering

Sept 2018 - Jun 2022

- Major in Electrical Engineering and its Automation - Power Electronics and Electric Drive.
- Graduated with GPA 3.81/4.0.

University of Michigan - Ann Arbor

Ann Arbor, USA

MSE in Electrical Engineering

Sept 2022 - Present

- Major in Control Systems Track
- **Courses:** EECS 460: Control Systems Analysis and Design, EECS 560: Linear Systems Theory, EECS 566: Discrete Event Systems (FA 2022); EECS 562: Nonlinear Systems and Control, EECS 565: Linear Feedback Control Systems (WN 2023); AEROSP 590: Directed Study (Advisor: Prof. Max Z. Li, SP-SM 2023); EECS 562: Hybrid Control, EECS 501: Probability and Random Process. (FA 2023)
- Current GPA 4.0/4.0.

Publications

Brief Talk about Application of Matrix Control in Industrial Automation

Published

Techniques of Automation and Applications

Mar 2021

- Designed a PLC-SCADA system design regarding bag precipitators cleaning with STEP-7 and WinCC.
- Reduced the complexity by cutting the number of the timer from $m \times n$ to 2. Thus increased the reusability and extensibility of the system.
- Please review [bit.ly/CNKI-FYX](#) for English abstract.

The Optimization of Control Logic Based on Abrasion-Averaging Model

Published

Techniques of Automation and Applications

Nov 2021

- Designed a pump station based on PLC-SCADA architecture with STEP-7 and WinCC.
- Managed the operations of the pumps as equally intensively as possible according to the water level. Avoided idle or long-run damage.
- Please review [bit.ly/CNKI_2-FYX](#) for English abstract.

Stealthy and Private Trajectories through Plausible Deniability

In Review

IEEE Transactions on Intelligent Transportation Systems

Oct 2023

- Introduced the plausible deniability concept for UAV transport systems. Formally estimated plausibly reachable zone and ranked privacy score.
- **Second** author. Majorly responsible for the plausible deniability analysis in the partially unobservable scenario.
- The pre-print version is available on [arXiv.org](#).

Projects

Communication of a Magnetic Bearing Control System and its Upper System Design

Bachelor's Thesis

Huazhong University of Science and Technology

Dec 2021 - May 2022

- Upon a DSP-based magnetic bearing system, designed a customized communication protocol including package data paradigm, necessary data processing operations, details to utilize UDP protocols, etc.
- Composed a GUI and its APIs with Python, which smoothly controls the system and visualizes the communications information.

Plausible Deniability and Privacy Analysis in the Drone Package Delivery Systems

Master's Directed Study

University of Michigan - Ann Arbor

May 2023 - Aug 2023

- Continuity of the previous plausible deniability analysis. The trajectory is only partially observable.
- A spline-based Bézier curve approximation and a privacy scoring method were designed for plausible deniability quantification.
- A corresponding journal paper on IEEE T-ITS is now in review.

Work Experience

Nanjing Electrical Engineering & Technology Co., Ltd HTC

Nanjing, China

Intern at Department of Engineering

Jul 2020 - Aug 2020

- Designed a PLC-SCADA system for the pump station with STEP-7 and WinCC, which organizes the system well.
- Published a paper based on the design in Nov. 2021.

Miscellaneous

Computer Skills Python, MATLAB, C/C++, SQL, Mathematica, Mark Down, \LaTeX , Microsoft Office.

Honor Society Electee of Tau Beta Pi and Eta Kappa Nu. Anticipated to be an active member since Dec 2023.