

# Quantum Mechanics Study Group Math Primer

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## 1. Sets

- (a) equivalence, subsets
- (b) functions
- (c) open and closed sets
- (d) metric spaces
- (e) balls and spheres
- (f) external measure
- (g) continuity and sequential characterization of the limit
- (h) measurable functions

## 2. Complex Numbers

- (a) the imaginary unit
  - i. the complex plane
  - ii. powers of  $i$
  - iii. roots of unity
- (b) modulus and argument
  - i. complex conjugate
  - ii. De Moivre's Theorem
  - iii. polar representation
  - iv. trigonometric identities
- (c) Complex functions of a single real variable
- (d) Complex functions of a single complex variable
  - i. analytic functions
  - ii. homogenous polynomials,  $p(\alpha z) = \alpha^n p(z)$
- (e) Exponential Functions of a complex argument
- (f) Consider the complex-valued function  $f(z) = \frac{az + b}{cz + d}$ . For some  $a, b, c, d \in \mathbb{C}$  find the fixed points  $\{z_o | f(z_o) = z_o\}$ .

## 3. Linear Algebra

- (a) Matrix Definition
  - i. arithmetic
  - ii. norm
- (b) Examples and exercises with commutative and non-commutative groups of matrices.
- (c) Matrix representation of complex numbers
  - i. isomorphism of the two

- ii. determinant of a matrix representation of a complex number
- iii. exponential of a matrix representation of a complex number
- (d) Action of  $M_{n \times n}$  on  $M_{n \times m}$  for any  $M$ .

example with eigenvector, confirm result is parallel

- (e) Vectors are  $M_{n \times 1}$ .

action of gamma matrices on  $\mathbb{C}_{2 \times 1}$

prove that every linear transformation is a composition of a scaling and a rotation, which commute.

- (f) eigenvectors  
Diagonal matrix

- (g) vector spaces

basis

orthonormal basis

- (h) inner product and dual space

inner product

linear independence and orthogonality

angle

example of matrix multiplication of vector, find angle between

example of an inner product on a vector space

dual space is a vector space

Dual space of  $M_{n \times 1}$  is matrix product with some  $\mathbf{v} \in M_{1 \times n}$ .

prove the Pauli vector identity  $(\boldsymbol{\sigma} \cdot \mathbf{a})(\boldsymbol{\sigma} \cdot \mathbf{b}) = \mathbf{a} \cdot \mathbf{b} + i\boldsymbol{\sigma} \cdot (\mathbf{a} \times \mathbf{b})$  where  $\boldsymbol{\sigma} = (\sigma_1, \sigma_2, \sigma_3)$

- (i) Linearity
- (j) Functions of a Complex Variable
- (k) Exponential Functions
- (l) Eigenvectors and Eigenvalues
- (m) Hermitian Matrices

definition

spectral theorem

eigenvectors form an orthonormal basis

Example of a Hermitian matrix

Show it's Hermitian

Express a vector in that basis

Two Hermitian matrices, find a matrix  $T$  that changes the basis from one to the other.

Pauli Matrices a basis for  $2 \times 2$  Hermitian Matrices

Prove that the span of the Pauli Matrices is a vector space (subspace of  $SL(2)$ ?)

Prove that a linear combination of the Pauli Matrices is Hermitian

Hermitian operators on a Hilbert space

quaternions isomorphic to  $\text{span}(i\sigma_1, i\sigma_2, i\sigma_3)$  as (vector space?).

(n) Unitary Matrices

- i. The Hermitian conjugate is the inverse
- ii. Eigenvectors of different eigenvalues are orthogonal
- iii. Eigenvectors span the space
- iv.  $T$

4. Differential Calculus

- (a) the derivative
- (b) chain and product rules
- (c) Taylor's Theorem
- (d) Convergence in the complex plane
- (e) The complex derivative
- (f) curl and divergence of scalar fields

5. Integral Calculus

- (a) Definition and Riemann sums
- (b) The mean value theorem
- (c) Integration by Substitution
- (d) Integration by Parts
- (e) Integration in series form
- (f) distributions, the dirac delta function

6. Algebraic objects

- (a) groups
  - i. roots of unity

- ii. rotations and
- iii. translations of the plane
- (b) commutativity and associativity
- (c) rings and fields

#### 7. Abstract vector spaces

- (a) complex numbers
- (b) square integrable functions
- (c) solutions of LDE
- (d) separable vector spaces

#### 8. Integral Calculus of Probability Theory

- (a) discrete and continuous random variables
- (b) PDFs and CDFs
- (c) Expected values and variance
- (d) independence
- (e) For each of the following functions
  - i. normalize.
  - ii. find the expected value and the standard deviation
  - iii. prove that  $f$  is a PDF (positive, sums to 1, subadditive)

#### 9. Differential Equations

- (a) definition
- (b) solutions
- (c) linear differential equations
- (d) separation of variables
- (e) solution of a system of linear differential equations
- (f) series solutions of LDEs

#### 10. Partial Derivatives and Partial Differential Equations

- (a) definition
- (b) solutions
- (c) gradient
- (d) linearity
- (e) example solution of the wave equation
- (f) potential functions
- (g) harmonic polynomials  $\Delta p = \sum_{i=1}^3 \frac{\partial^2 f(x)}{\partial x_i^2} = 0$