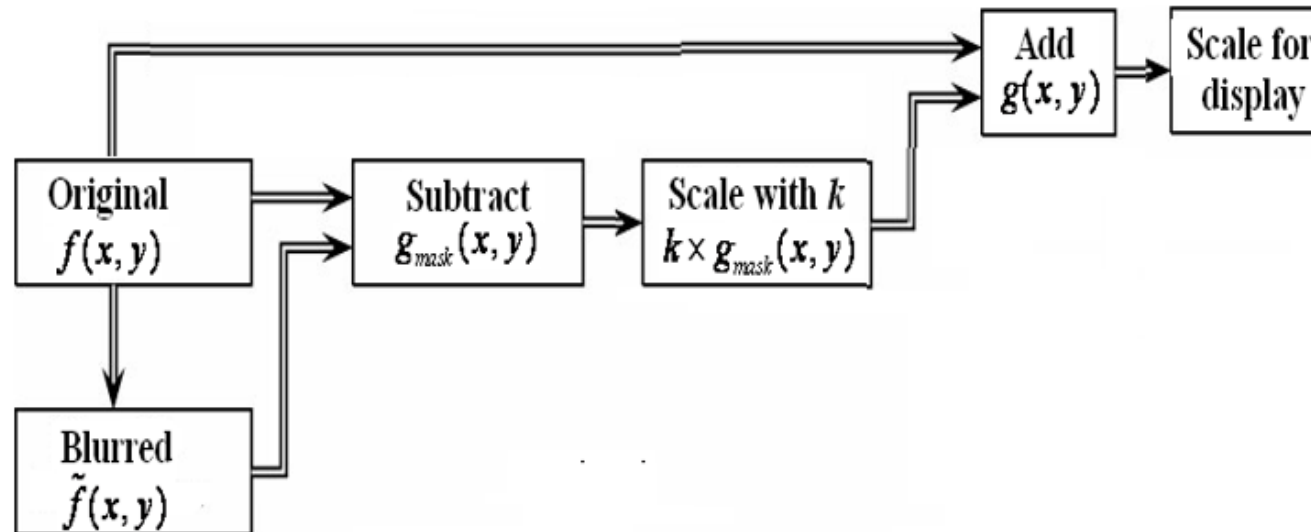
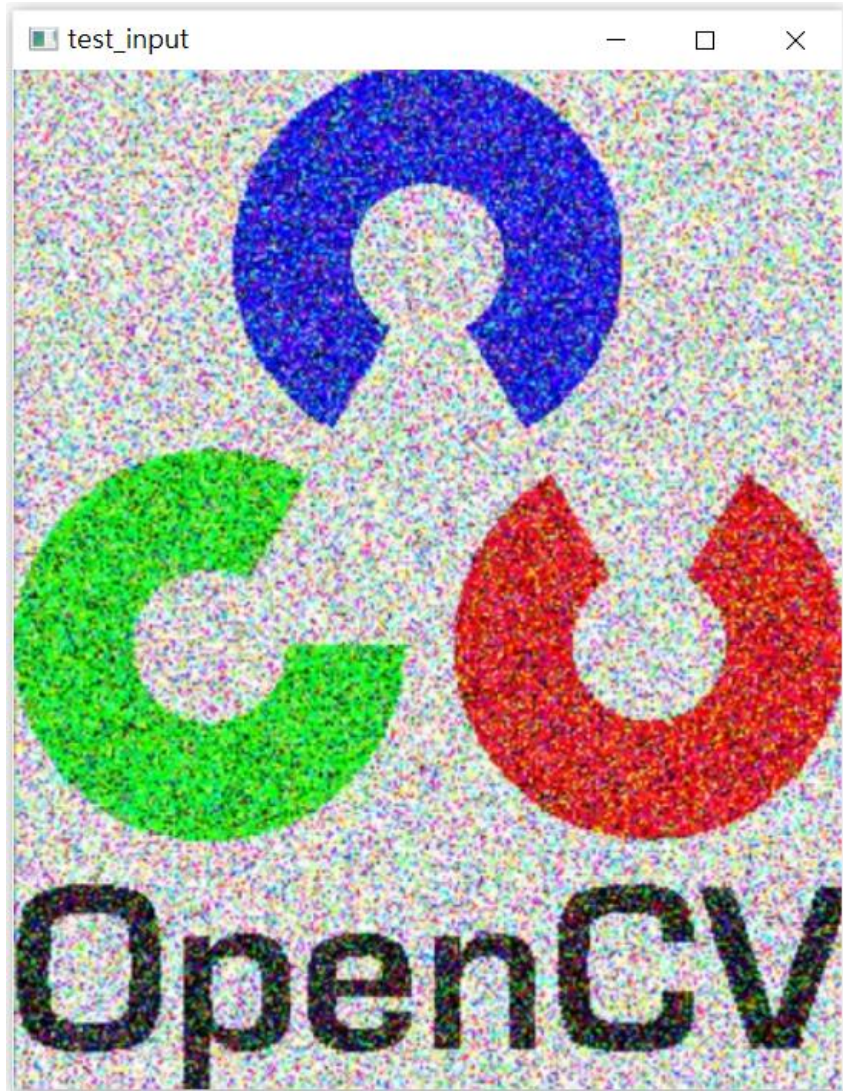


## Homework 4 (Due: 3/30)

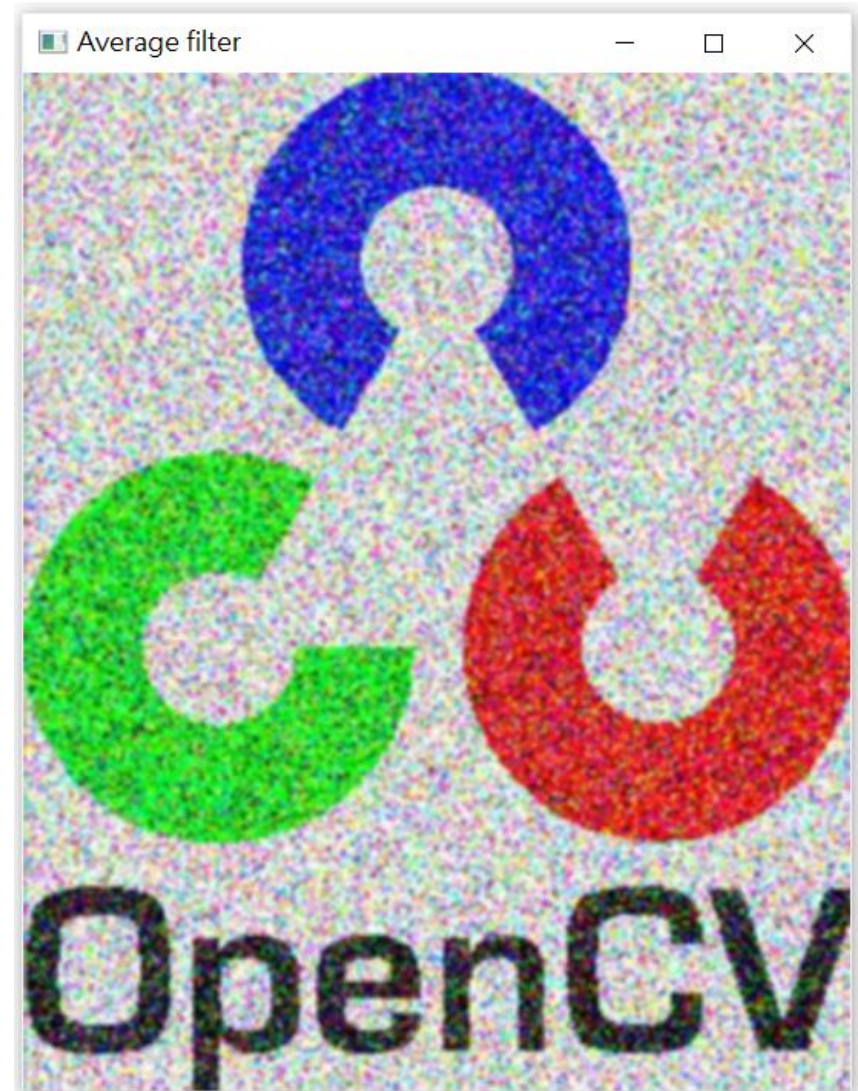
1. Select an experimental image
2. Apply a 3 by 3 (a) average filter and (b) median filter to the image
3. Unsharp masking



input

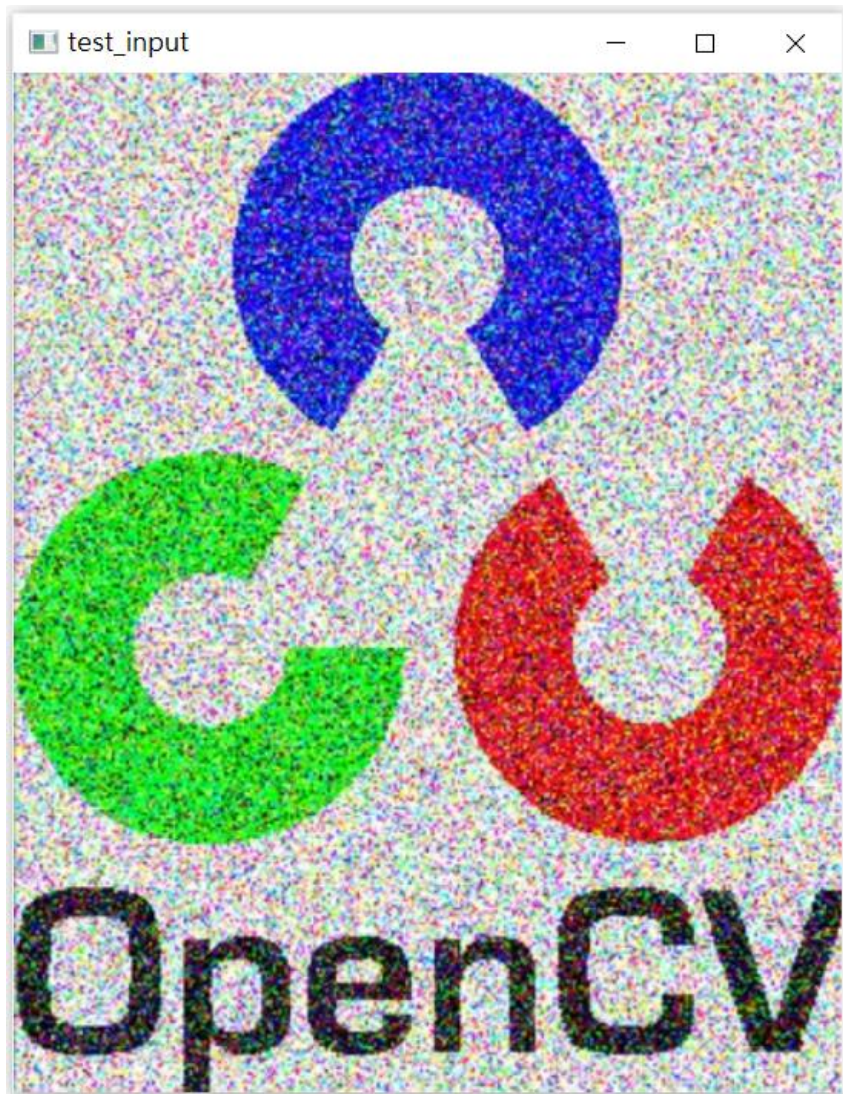


output\_average

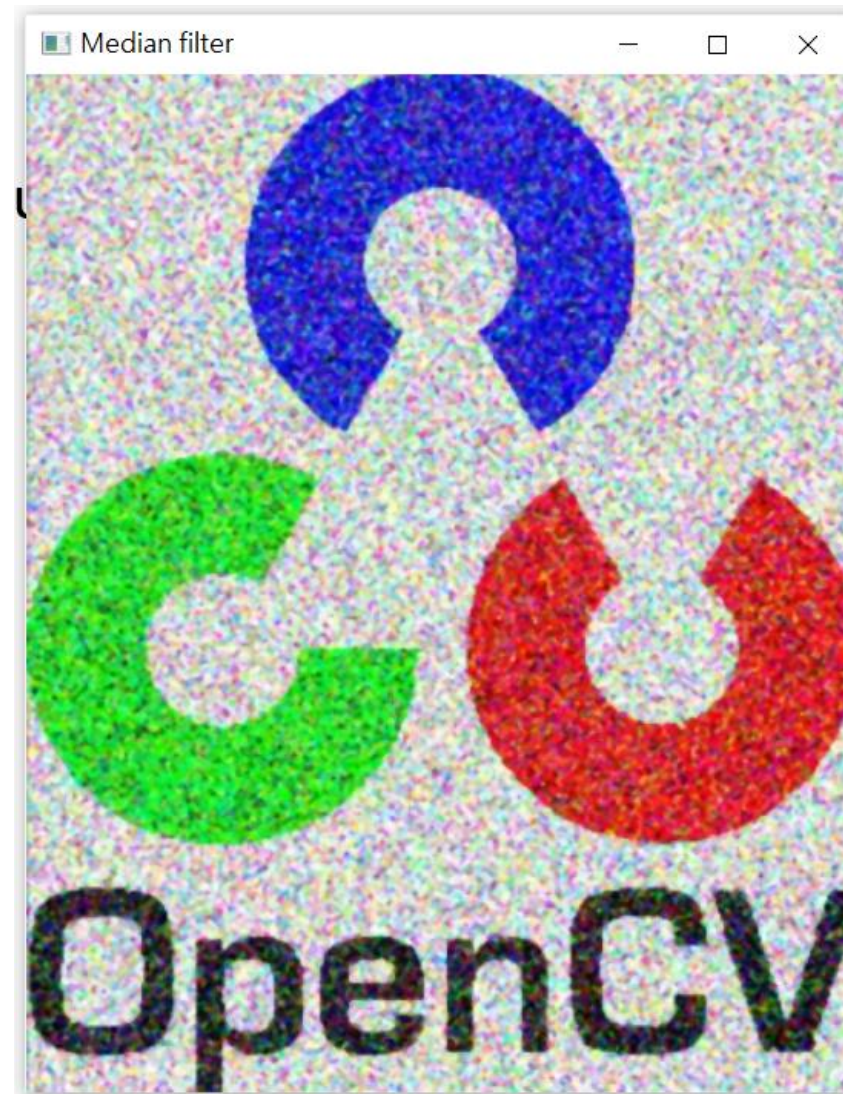




input

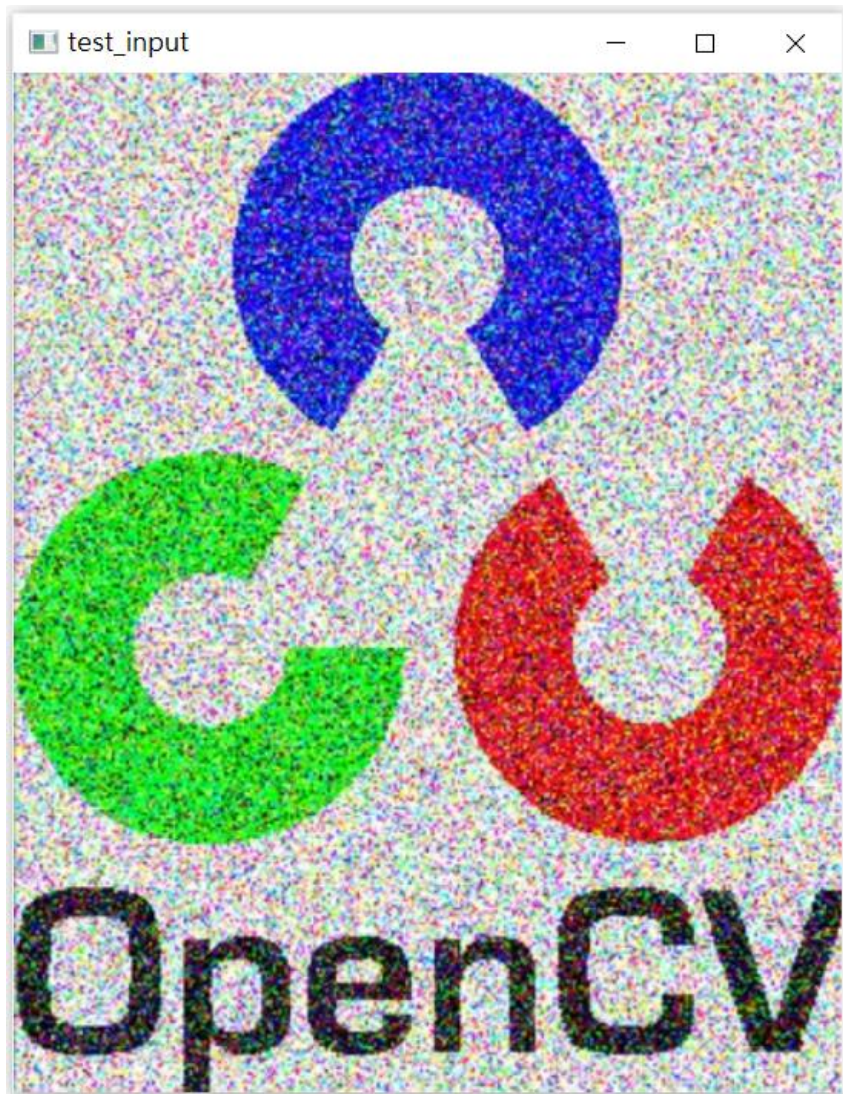


output\_median

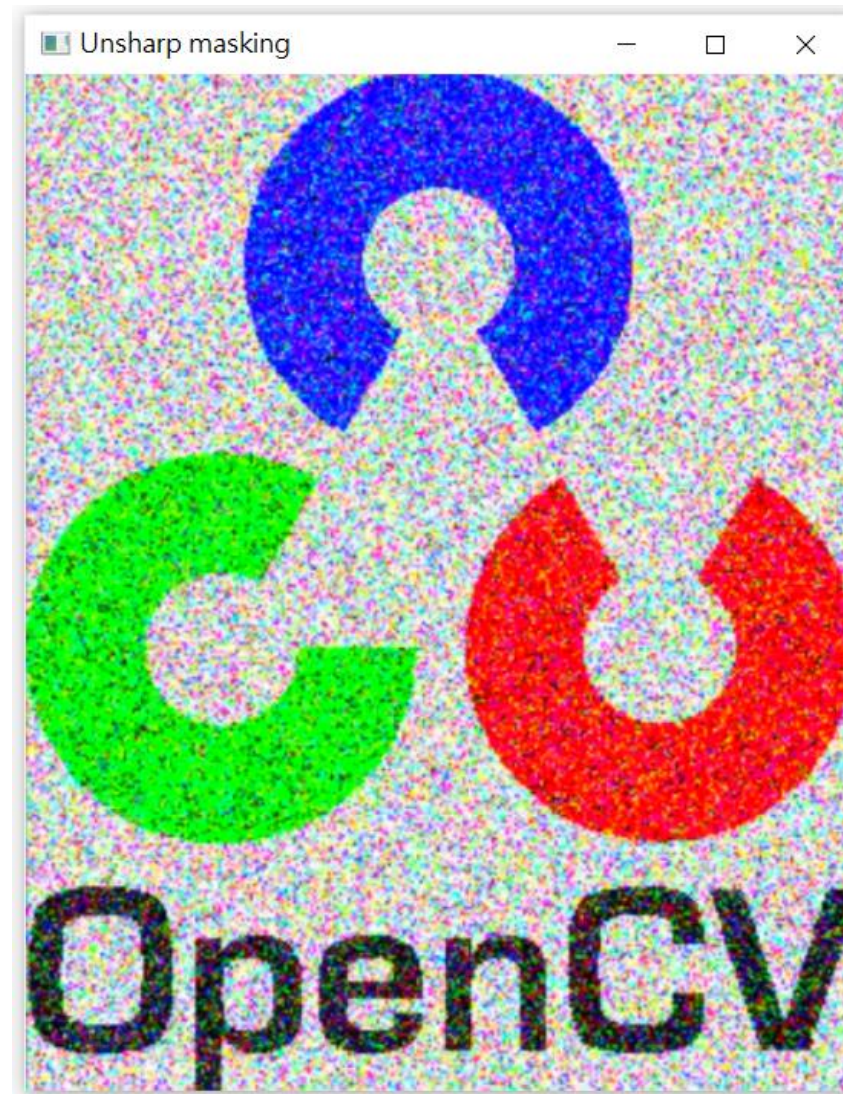




input



output\_unsharpMasking



# Source code

```
import cv2
import numpy as np

#讀入並顯示影像
img = cv2.imread('test_input.jpg')
cv2.imshow('test_input', img)
cv2.waitKey(0)
cv2.destroyAllWindows()
height, width, n = img.shape
print("影像大小為 :",img.shape)

# 【Average filter】
img_ave = cv2.blur(img, (3, 3))
#圖片存檔
cv2.imwrite('test_output_ave.jpg', img_ave)

#顯示結果
cv2.imshow('Average filter', img_ave)
cv2.waitKey(0)
cv2.destroyAllWindows()
```

```
# 【Median filter】
img_med = cv2.medianBlur(img,3)
#圖片存檔
cv2.imwrite('test_output_med.jpg', img_med)

#顯示結果
cv2.imshow('Median filter', img_med)
cv2.waitKey(0)
cv2.destroyAllWindows()
```

# Source code

```
# 【Unsharp masking】
# Convert the image to grayscale
gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# Apply Gaussian blur
blur = cv2.GaussianBlur(gray, (5, 5), 0)

# Calculate the unsharp mask
mask = cv2.addWeighted(gray, 1.5, blur, -0.5, 0)

# Add the mask to the original image
result = cv2.cvtColor(mask, cv2.COLOR_GRAY2BGR)
img_unsharp = cv2.addWeighted(img, 1.5, result, -0.5, 0)

#圖片存檔
cv2.imwrite('test_output_unsharp.jpg', img_unsharp)

cv2.imshow('Unsharp masking', img_unsharp)
cv2.waitKey(0)
cv2.destroyAllWindows()
```

## Comments

I found that if the original picture don't have a lot of noise, the change of the input and output of Median Filter is hard to distinguish.

After Unsharp Masking the output picture became brighter than the original one.