**Workflow**

1. First, Genesis AI is installed, and a robot arm is tested to check if the Genesis installation is correct.

2. The XML file of Unitree Go2 is integrated into Genesis.

3. The RL env for the Go2 robot is created.

4. Open-loop action is applied, and the observations are checked: The joint position of standing is applied to the robot to check the response visually.

Figure how to read the joint infos.

How to apply action to the joints.

5. Start from a random state and apply some action

6. Start training