* Confirm that the joystick is fully charged.
* Check *homing* of motors on ’Motors page’ by clicking on “Devices Check” button. Home any motor if necessary.
* Confirm that all motors are enabled.
* Confirm CS and WI units are out of UC7 space. If not, use joystick to position CS and WI units out of the way.
* Remove any CS from the CS arm.
* Select ‘Ready CS’ sequence on ’Sequences page’
  + Check the ‘Execute process by process’ checkbox
  + Click ‘Start’ button.
  + If necessary, adjust **motor end positions** for the process by using the joystick.
    - Click the ‘Update final process positions’ button to update positions, or update manually by entering new numbers.
  + Confirm that microscope is out of the way for a lift.
  + Press ‘Continue’ button.
  + Position WI in approximate ribbon docking position by using the joystick.
* Select the ‘Lift Ribbon’ sequence.
  + Press the ‘Start’ button.
  + Confirm process end positions validity
* Select the ‘Stow CS’ sequence
  + Click ‘Start’ button
  + Click ‘Continue’ button

When *confident* about above sequences positions, run sequences using shortcut buttons

* Attach a DUMMY CS to test a Ribbon Collection Cycle
  + Run ‘Ready CS’ sequence using shortcut button.
  + Move WI to pick up position by using the joystick.
  + Run ‘Lift Ribbon’ sequence using shortcut button.
  + Run ‘Stow CS’ sequence using shortcut button