

# Lecture 3

- **Gradient**  $\Phi(x, y, z)$  is a continuously differentiable function at the point  $\vec{r} = (x, y, z)$

$$\vec{r} = x\vec{e}_x + y\vec{e}_y + z\vec{e}_z$$

Moving an infinitesimal distance results in:

$$\vec{r}' = (x + \Delta x)\vec{e}_x + (y + \Delta y)\vec{e}_y + (z + \Delta z)\vec{e}_z$$

The difference in the function value is:

$$\Delta\Phi = \Phi' - \Phi = \Delta x\vec{e}_x + \Delta y\vec{e}_y + \Delta z\vec{e}_z$$

As  $\Delta x, \Delta y, \Delta z$  are infinitesimal, we can rewrite:

$$\Delta\Phi = \Phi' - \Phi = dx\vec{e}_x + dy\vec{e}_y + dz\vec{e}_z$$

The change in the function value is:

$$\Delta\Phi = \Phi(x + \Delta x, y + \Delta y, z + \Delta z) - \Phi(x, y, z) \xrightarrow[\Delta y \rightarrow 0]{\Delta x \rightarrow 0} d\Phi(x, y, z)$$

Which is the same as:

$$d\Phi = \frac{\partial\Phi}{\partial x}dx + \frac{\partial\Phi}{\partial y}dy + \frac{\partial\Phi}{\partial z}dz$$

Which can be written with a dot product as:

$$d\Phi = \left( \frac{\partial\Phi}{\partial x}\vec{e}_x + \frac{\partial\Phi}{\partial y}\vec{e}_y + \frac{\partial\Phi}{\partial z}\vec{e}_z \right) \cdot (dx\vec{e}_x + dy\vec{e}_y + dz\vec{e}_z) = \nabla\Phi \cdot d\vec{r} = \text{grad } \Phi \cdot d\vec{r}$$

- **Directional Derivative** Write  $d\vec{r}$  as:

$$d\vec{r} = ds\vec{e}$$

Where  $\vec{e}$  is a unit vector in the direction of  $d\vec{r}$ , i.e.

$$\vec{e}_s = \frac{d\vec{r}}{|d\vec{r}|}$$

The directional derivative is:

$$\frac{d\Phi}{ds} = \nabla\Phi \cdot \vec{e}$$

This tells us how much the function  $\Phi$  changes in the direction of  $\vec{e}$ .

## Theorem:

- The vector  $\nabla\Phi$  is the gradient of  $\Phi$  and is the direction of maximum rate of change of  $\Phi$ .

## Proof

Let  $\vec{e}$  be a unit vector in the direction of most rapid change of  $\Phi$ .

$$\frac{d\Phi}{ds} = \nabla\Phi \cdot \vec{e} = |\nabla\Phi| \cos \theta$$

Where  $\theta$  is the angle between  $\nabla\Phi$  and  $\vec{e}$ . The derivative is maximum when  $\cos \theta = 1$ , since  $|\cos \theta| \leq 1$  when  $0 \leq \theta \leq \pi$ . Therefore,  $\nabla\Phi$  is the direction of maximum rate of change of  $\Phi$ .



## Level Surfaces:

A Level surface is a surface on which a scalar field  $\Phi$  is constant.

$$\Phi(\vec{r}_c) = C$$

For all points  $\vec{r}_c$  on the surface. One surface for each value of C in the scalar field.

### Theorem:

If  $\Phi$  is a scalar field and has a max,min or saddle point at  $\vec{r}$ , then the gradient of  $\Phi$  is 0 at  $\vec{r}$ .

$$\nabla\Phi(\vec{r}) = \vec{0}$$

### Theorem:

If  $\Phi$  is a scalar field, then the gradient of  $\Phi$  is perpendicular to the level surfaces of  $\Phi$ .

### Proof:

Choosing two infinitesimal vectors  $d\vec{r}$  and  $d\vec{r}'$  such that then:

$$\Phi(\vec{r}_p + d\vec{r}) = \Phi(\vec{r}_p) \iff \Phi(\vec{r}_p + d\vec{r}') - \Phi(\vec{r}_p) = 0$$

But as showed earlier:

$$\Phi(\vec{r}_p + d\vec{r}') - \Phi(\vec{r}_p) = d\Phi$$

$$d\Phi = \nabla\Phi \cdot d\vec{r}' = 0$$



### Theorem:

The distance  $\Delta s$  between two iso-surfaces:

$$\Phi(\vec{p}) = C, \Phi(\vec{p}) = C + h$$

Can be approximated by:

$$\Delta s \approx \frac{h}{|\nabla\Phi(\vec{p})|}$$

### Proof:

Let

$$\Phi = C, \Phi = C + h$$

Be the two iso-surfaces. Choose a vector  $d\vec{r}$  such that  $d\vec{r} \perp$  to the level surfaces. Then:

$$h = \Delta\Phi \approx d\Phi = \nabla\Phi \cdot d\vec{r} = |\nabla\Phi|\Delta s \implies \Delta s \approx \frac{h}{|\nabla\Phi|}$$

Since  $d\vec{r}$  is perpendicular to the level surfaces,  $|\nabla\Phi|$  is the distance between the two level surfaces.



### Example:

Find the normal to the surface  $z = x^2 + y^2$  at the point  $(1, 2, 5)$ . This surface can be seen as a level surface  $\Phi = 0$  for the scalar field  $\Phi = x^2 + y^2 - z$ . Then:

$$\nabla\Phi = \left( \frac{\partial\Phi}{\partial x}\vec{e}_x + \frac{\partial\Phi}{\partial y}\vec{e}_y + \frac{\partial\Phi}{\partial z}\vec{e}_z \right) = (2x\vec{e}_x + 2y\vec{e}_y - 1\vec{e}_z)$$

Evaluating at  $(1, 2, 5)$ :

$$\vec{n} = (2\vec{e}_x + 4\vec{e}_y - 1\vec{e}_z)$$

Normalizing:

$$\vec{n} = \frac{1}{\sqrt{21}} (2\vec{e}_x + 4\vec{e}_y - 1\vec{e}_z)$$



## Scalar Potential:

- If for a given vector field  $\vec{A}$  there is a scalar field  $\Phi$  such that:

$$\vec{A} = \nabla\Phi$$

Then  $\Phi$  is called the scalar potential of  $\vec{A}$ .

- If  $\vec{A}$  has a potential  $\Phi$ , then  $\Phi + C$  is also a potential for  $\vec{A}$ .
- The potential is often defined with a minus sign e.g. the electrostatic potential:

$$\vec{E} = -\nabla V$$

## Conditions for existence of a scalar potential:

- A continuously differentiable vector field  $\vec{A}$  has a scalar potential if and only if  $\vec{A}$  satisfies:

$$\frac{\partial A_x}{\partial y} = \frac{\partial A_y}{\partial x} \quad (1)$$

$$\frac{\partial A_y}{\partial z} = \frac{\partial A_z}{\partial y} \quad (2)$$

$$\frac{\partial A_z}{\partial x} = \frac{\partial A_x}{\partial z} \quad (3)$$

### Proof:

Assume that  $\vec{A} = \nabla\Phi$ . Then:

$$A_x = \frac{\partial\Phi}{\partial x}$$

$$A_y = \frac{\partial\Phi}{\partial y}$$

Using this we know that since  $\vec{A}$  is continuously differentiable:

$$\frac{\partial A_x}{\partial y} = \frac{\partial}{\partial y} \frac{\partial\Phi}{\partial x} = \frac{\partial}{\partial x} \frac{\partial\Phi}{\partial y} = \frac{\partial A_y}{\partial x}$$

The mixed partial derivatives of  $\Phi$  are the same as the mixed partial derivatives of  $\vec{A}$ .



## Example: Check if there exists a scalar potential

Check if the vector field  $\vec{A} = y\vec{e}_x - x\vec{e}_y$  has a scalar potential.

$$\frac{\partial A_x}{\partial y} = \frac{\partial}{\partial y} y = 1 \neq \frac{\partial A_y}{\partial x} = \frac{\partial}{\partial x} (-x) = -1$$

The vector field does not have a scalar potential since it does not satisfy equation 1.



## Example: Find the scalar potential

Find the scalar potential of the vector field  $\vec{A} = 2y^2\vec{e}_x + (4xy + y^2z^2)\vec{e}_y + (\frac{2}{3}y^3z + z)\vec{e}_z$ .

- Known that  $\vec{A} = \nabla\Phi$ . We know that each term of  $\vec{A}$  corresponds to the partial derivative of  $\Phi$  with respect to  $x$ ,  $y$  or  $z$ .

$$A_x = \frac{\partial\Phi}{\partial x} = 2y^2 \xrightarrow{\int dx} \Phi = 2y^2x + F(y, z)$$

Using this we can find the other terms successively:

$$A_y = \frac{\partial \Phi}{\partial y} = 4xy + \frac{\partial}{\partial y} F(y, z) = 4xy + y^2 z^2 \implies$$

Canceling  $4xy$  and integrating with respect to  $y$  yields:

$$F(y, z) = \frac{1}{3} y^3 z^2 + G(z)$$

Replacing  $F(y, z)$  in the equation for  $\Phi$ :

$$\Phi = 2y^2 x + \frac{1}{3} y^3 z^2 + G(z)$$

Deriving with respect to  $z$ :

$$A_z = \frac{\partial \Phi}{\partial z} = \frac{2}{3} y^3 z + \frac{\partial}{\partial z} G(z) = \frac{2}{3} y^3 z + z \implies G(z) = \frac{1}{2} z^2 + C$$

Replacing  $G(z)$  in the equation for  $\Phi$  concludes the calculation.

$$\Phi = 2y^2 x + \frac{1}{3} y^3 z^2 + \frac{1}{2} z^2 + C$$

