# LAB REPORT:

## LAB 4: 1D BLOCKED COLUMN ALGORITHM OF PARALLEL DGEMM

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### FA21-CS-490/CS525: INTRO TO PARALLEL COMPUTING USING GPUS

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### I. Introductio

The Goal of this Lab is to use MPI (Message Passing Interface) to implement the previous lecture "1DBlocked column Algorithm" to compute double-precision Matrix Multiplication with 1xP processes. 1D algorithms divide matrices like a one-dimension colon or row, p processors are logically arranged into a 1D topology like a ring. Using NxN square matrices, we will compute our operations on BigRed3 from 1 to 64 processes or higher if time permitting. Local matrix multiplication will call the CBLAS library for correctness

#### II. ALGORITHM

This program creates a number of parallel processes and calculates the product of matrices by splitting up the work between the threads. The root process is the process with an index of 0. The worker processes are all of the other processes. Each process calculates a portion of C by multiplying its portion of A with all of B to find the corresponding rows in C.

parallel\_dgemm(number\_of\_processes, N): calculate the number of rows in A that each thread should work on. each worker process should take N / number of processes. worker\_rows = N / number\_of\_threads, divide matrix A into submatrices with that number of rows. If the number of rows does not divide equally, the leftover rows are the remainder. share the B and C matrices between all processes for each process except the root: send a submatrix of A for the process to compute against B and C. on the root process, compute the multiplication of the first submatrix of A and the remainder. wait for all of the workers to send their portion of the calculation of C.

# A. Pseudocode

All matrices are row-major

p = number of processes $sub\_size = N/p$ 

if  $(my_rank == 0)$ 

 $A_{column} = A[0:sub\_size, 0:N]$ 

B column =  $B[0:sub\ size,\ 0:N]$ 

 $C_{\text{column}} = C[0:\text{sub\_size}, 0:N]$ 

for (k=0; k<p; k++)
for (j=0; j<p; j++)
block\_start = k\*sub\_size
A\_block = A\_column[:,
block\_start:block\_start+sub\_size]
B\_block = B\_column[:,
block\_start:block\_start+sub\_size]
C\_block = C\_column[:
block\_start:block\_start+sub\_size]
C\_block = A\_block \* B\_block
send A\_column to process 3
receive A\_column from process 2

if  $(my_rank == 1)$ A\_column = A[sub\_size:sub\_size+sub\_size, 0:N] B column = B[sub size:sub size+sub size, 0:N] C\_column = C[sub\_size:sub\_size+sub\_size, 0:N] for (k=0; k< p; k++)for (i=0; i< p; i++) $block\_start = k*sub\_size$ A\_block = A\_column[:, block\_start:block\_start+sub\_size] B block = B column[:, block\_start:block\_start+sub\_size] C block = C column[:, block start:block start+sub size] C block = A block \* B blocksend A\_column to process 0 receive A column from process 2

if (my\_rank == 2)
A\_column = A[2\*sub\_size:2\*sub\_size+sub\_size, 0:N]
B\_column = B[2\*sub\_size:2\*sub\_size+sub\_size, 0:N]
C\_column = C[2\*sub\_size:2\*sub\_size+sub\_size, 0:N]
for (k=0; k<p; k++)
for (j=0; j<p; j++)
block\_start = k\*sub\_size
A\_block = A\_column[:,
block\_start:block\_start+sub\_size]
B\_block = B\_column[:,
block\_start:block\_start+sub\_size]
C\_block = C\_column[:,
block\_start:block\_start+sub\_size]
C\_block = A\_block \* B\_block
send A\_column to process 1

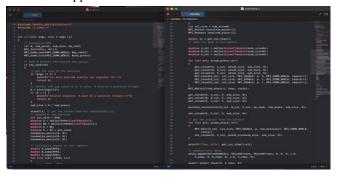
## receive A\_column from process 3

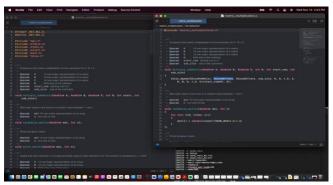
if  $(my_rank == 3)$ A\_column = A[3\*sub\_size:3\*sub\_size+sub\_size, 0:N] B\_column = B[3\*sub\_size:3\*sub\_size+sub\_size, 0:N]  $C_{column} = C[3*sub\_size:3*sub\_size+sub\_size, 0:N]$ for (k=0; k<p; k++) for (j=0; j< p; j++)block\_start = k\*sub\_size A\_block = A\_column[:, block\_start:block\_start+sub\_size] B\_block = B\_column[:, block\_start:block\_start+sub\_size] C\_block = C\_column[:, block\_start:block\_start+sub\_size]  $C_block = A_block * B_block$ send A\_column to process 2 receive A\_column from process 0

## B. Software Design and implementation

The software design that has been adopted for this project is the iterator because it provides a way to access the element of an aggregate object sequentially without exposing its underlying representation. This design is also known as the cursor, it's very useful in a message passing in high-performance parallel applications. A MPI program is one or more processes that can communicate either via sending and receiving individual messages point-to-point communication or by coordinating a group (collective communication). The iterator pattern lets you do all this. The key idea in this pattern is to take the responsibility for access and traversal out.

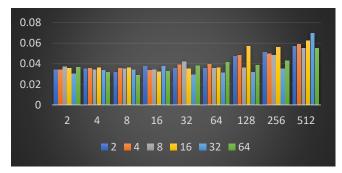
# C. Code Snippet





### III. EXPERIMENTAL RESULTS





68	64	32	16	8	4	2	N
	0.031578	0.033776	0.036175	0.034425	0.035606	0.035378	4
	0.028727	0.034356	0.035959	0.035019	0.035678	0.031582	8
	0.032521	0.037719	0.032069	0.034088	0.033834	0.037692	16
	0.038144	0.029501	0.035205	0.042049	0.03908	0.035425	32
	0.041446	0.031098	0.036261	0.035503	0.03957	0.035832	64
	0.038541	0.031552	0.057058	0.036055	0.048051	0.04722	128
	0.043133	0.034949	0.056226	0.048516	0.04973	0.051002	256
0.066205	0.055213	0.069445	0.062128	0.055024	0.059007	0.057138	512
							1024



# IV. CONCLUSION

There are some observations we can make about this lab results. First of all, the graphs show that MPI performance on parallel DGEEM and 1D blocked has a measurable run time that it has bandwidth limits.

The parallel efficiency of this program is  $W = O(p^2)$ . My values are correct because I have called CBLAS library, and I have try multiple runs and made changes to my algorithm to make it work better. It's cost optimal