FAKE VIDEO CLASSIFICATION USING LSTM

MAJOR PROJECT STAGE-II REPORT

BACHELOR OF TECHNOLOGY

IN

INFORMATION TECHNOLOGY

BY

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Under the Guidance Of

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Assistant Professor & Head of IT



DEPARTMENT OF INFORMATION TECHNOLOGY

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY
HYDERABAD UNIVERSITY COLLEGE OF ENGINEERING JAGTIAL

Nachupally (Kondagattu), Jagtial Dist – 505501, T.S

(ACCREDITED BY NAAC A+ GRADE)

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DEPARTMENT OF INFORMATION TECHNOLOGY CERTIFICATE

DATE:

This is to certify that the major project stage-II entitled "FAKE VIDEO CLASSIFICATION USING LSTM" is a bonafide work carried out by AMENA TOUSIATH UNNISA – 20JJ1A1203, G.SOUMYA – 20JJ1A1215, U. NIHARIKA – 20JJ1A1253, L. PRASHANTHIKA –20JJ1A1224 respectively in partial fulfillment of the requirements for the degree of BACHELOR OF TECHNOLOGY in INFORMATION TECHNOLOGY at Jawaharlal Nehru Technological University Hyderabad University College of Engineering Jagtial during the academic year 2023-24.

Project Guide

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It is privilege to express our gratitude to **Prof. Dr. BITLA PRABHAKAR**, Principal JNTUHUCEJ for providing us an excellent environment to complete our project work successfully.

We also thank all the other staff of **IT Department** who assisted us when we need help.

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DECLARATION

I hereby declare that the major project stage-II titled "FAKE VIDEO CLASSIFICATION USING LSTM" has been undertaken by our team and this work has been submitted to JNTUH University College of Engineering Jagtial, Nachupally, Kondagattu, Jagtial(Dist)., in partial fulfillment of the requirement for the award of the degree Bachelor of Technology in Information Technology.

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ABSTRACT

The proliferation of fake videos, fueled by advancements in deepfake technology, presents a significant challenge to the integrity of digital media. In this project, we propose a deep learning framework utilizing Long Short-Term Memory (LSTM) networks for the classification of fake videos. Our approach leverages the temporal dynamics inherent in video data to discern subtle differences between authentic and manipulated content.

We construct a dataset comprising both real and synthetic videos across various contexts and employ pre-trained LSTM models for feature extraction. Subsequently, these features are fed into a classification layer for binary decision-making.

Extensive experiments demonstrate the effectiveness of our method in accurately detecting fake videos, even in the presence of sophisticated manipulations. Furthermore, we explore the generalization of our model to unseen datasets and discuss its potential applications in combating the spread of misinformation and ensuring the authenticity of multimedia content.

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CHAPTER-1

INTRODUCTION

The advent of deep learning and artificial intelligence has brought both remarkable advancements and new challenges. One such challenge is the proliferation of fake videos, often referred to as deepfakes, which leverage sophisticated techniques to manipulate visual content convincingly. These manipulated videos pose serious threats to various sectors, including journalism, politics, and security.

In response to this growing concern, researchers and developers have been exploring methodsto detect and mitigate the spread of deepfake videos. One promising approach is the use of Long Short-Term Memory (LSTM) neural networks, a type of recurrent neural network (RNN)known for its ability to model sequential data effectively.

In this document, we present a project focused on the classification of fake videos using LSTM neural networks. By training the model on a dataset of both real and synthetic videos, we aim to develop a robust system capable of identifying deepfake content with high accuracy. Our project not only contributes to the ongoing efforts in combating misinformation but also showcases the potential of deep learning in addressing complex societal challenges.

1.1 Problem Description:

In the digital age, the prevalence of manipulated video content significantly threatens the authenticity of information, potentially leading to widespread misinformation. This project addresses this critical challenge by developing a robust machine learning model designed to accurately classify videos as real or fake. Utilizing Long Short-Term Memory (LSTM)networks and sophisticated image processing techniques, the system aims to enhance digital trust and reduce the impact of fake videos across various media platforms.

1.2 Objective:

The objective of this project is to develop a deep learning model based on Long Short-Term Memory (LSTM) neural networks to accurately classify videos as either authentic or manipulated (fake). The goal is to create a robust system capable of detecting various forms of video manipulation, including deepfakes, video slicing, and other forms of digital tampering. By training the model on a diverse dataset of both authentic and fake videos, weaim to achieve high accuracy and generalization performance, enabling the model to effectively discern subtle cues and anomalies indicative of video manipulation. This classification system will serve as a crucial tool in combating the spread of misinformationand protecting the integrity of visual media in various domains, including journalism, socialmedia, and security.

1.3 Existing System:

The current paradigm of fake video classification primarily relies on Convolutional Neural Networks (CNNs), recognized for their proficiency in image-based tasks. Existing systems leverage the spatial feature extraction capabilities of CNNs, forming the backbone of fake video methodologies. While these systems exhibit commendable success in discerning manipulated content within images, they encounter challenges in the temporal analysis of videos. The frame-level analysis characteristic of CNNs may lead to difficulties in capturing subtle temporal dynamics, contributing to occasional false positives and false negatives. As the landscape of fake video technology continues to evolve with more sophisticated techniques, there exists discernible need for advanced detection systems that can adapt to the nuanced temporalintricacies inherent in synthetic media. The effectiveness of this model is not that advantageous in this project and has the following limitations:

Disadvantages:

- Limited Temporal Understanding
- Large Computational Requirements
- Vulnerability to Adversarial Attacks
- Training data Imbalances

1.4 Proposed System:

The Long Short-Term Memory (LSTM) network is a specialized form of Recurrent Neural Network (RNN) designed to address the shortcomings of traditional RNNs, particularly in handling long-term dependencies in sequence data. This is achieved through a sophisticated architecture that includes several gates and states, enabling the network to regulate the flowof information effectively. Here's a deeper look into the key components and operations within an LSTM unit:

Key Components of LSTM:

1.Cell State: The cell state acts as the "memory" of the LSTM unit and carries relevant information throughout the sequence processing. It ensures that information that is useful long-term can travel unchanged if needed.

2.Hidden State: The hidden state contains information derived from previous input features and is used for predictions. It is also passed to the next time step and can be used in the output sequence.

Gates in LSTM: Gates in LSTM control the flow of information using a sigmoid activation function, which outputs values between 0 (ignore this entirely) and 1 (let everything through).

- **.Forget Gate**: Decides what information to discard from the cell state. It looks at the previous hidden state (H_(t-1)) and the current input (x_t) and outputs a number between 0 and 1 for each number in the cell state C_(t-1).
- **2.Input Gate and Candidate Layer:** The input gate decides which values willbe updated, and the candidate layer creates a vector of new candidate values that could be added to the state.

• Output Gate: The output gate decides what the next hidden state should be. Thehidden state contains information on previous inputs. The contents of the cell state are passed through tanh (to push values to be between -1 and 1) and multiplied by the output of the output gate, so that only certain parts of the cell state are output.

3.Updating the Cell State: The old cell state, C_(t-1), is updated into the new cellstate C_t. The forget gate decides what is thrown away from the old cell state, and the input gate decides which new information is added from the candidate layer.

Implementation Details in the Proposed System:

In the proposed system, the LSTM processes the feature maps extracted from each frame of the video, leveraging the above mechanisms to analyze and remember essential temporal features necessary for detecting inconsistencies indicative of manipulated content. Each LSTM unit's operations, from gating to state updates, play a pivotal role in ensuring that both short-term detail.

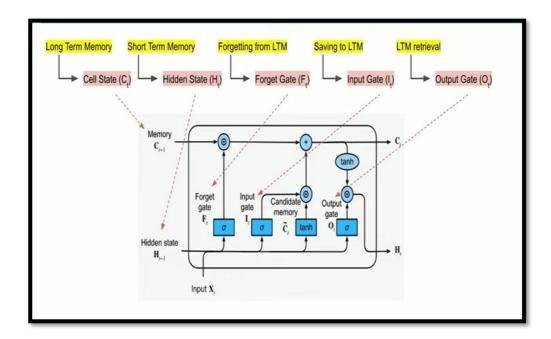


Fig no.1.4.1 LSTM Architecture Unit

CHAPTER-2 LITERATURE SURVEY

Face Warping Artifacts:

The approach to detect artifacts by comparing the generated face areas and their surrounding regions with a dedicated Convolutional Neural Network model. In this work there were two-fold of Face Artifacts. Their method is based on the observations that current deepfake algorithm can only generate images of limited resolutions, which are then needed to be further transformed to match thefaces to be replaced in the source video. Their method has not considered the temporal analysis of the frames.

Detection by Eye Blinking:

Describes a new method for detecting the deepfakes by the eye blinking as a crucial parameter leading to classification of the videos as deepfake or pristine. The Long-term Recurrent Convolution Network (LRCN) was used for temporal analysis of the cropped frames of eye blinking. As today the deepfake generation algorithms have become so powerful that lack of eye blinking cannot be the onlyclue for detection of the deepfakes. There must be certain other parameters must be considered for the detection of deepfakes like teeth enchantment, wrinkles on faces, wrong placement of eyebrowsetc.

Capsule networks to detect forged images and videos:

Uses a method that uses a capsule network to detect forged, manipulated images and videos in different scenarios, like replay attack detection and computer-generated video detection. In their method, they have used random noise in the training phase which is not a good option. Still the model performed beneficial in their dataset but may fail on real time data due to noise in training. Ourmethod is proposed to be trained on noiseless and real time datasets.

Recurrent Neural Network (RNN):

For deepfake detection used the approach of using RNN for sequential processing of the frames along with ImageNet pre-trained model. Their process used the HOHO dataset consisting of just 600videos. Their dataset consists small number of videos and same type of videos, which may not perform very well on the real time data. We will be training out model on large number of Realtimedata.

Synthetic Portrait Videos using Biological Signals:

Approach extract biological signals from facial regions on pristine and deepfake portrait video pairs.

CHAPTER-3

SYSTEM DESIGN

3.1 Hardware Requirements:

- Intel Xeon E5 2637- 3.5 GHz
- RAM-8 GB
- Hard Disk-100 GB
- Graphic card NVIDIA GeForce GTX Titan (6 GB)
- Operating System: Windows 7+

3.2 Software Requirements:

- Programming Language: Python
- IDE: Google Colab, Visual Studio Code
- Development Platforms: Anaconda Navigator
- Machine Learning Libraries: PyTorch, torchvision, OpenCV (cv2), NumPy, face_recognition, Keras
- Data Visualization Libraries: Matplotlib, Seaborn
- Algorithm: Long Short-Term Memory
- Web Framework: Flask (for building the website)

CHAPTER-4

PROPOSED ARCHITECTURE

4.1 Dataset Collection

To make the model efficient for real-time prediction, we gathered data from the Deepfake Detection Challenge (DFDC) dataset. We focused exclusively on this dataset to streamline the data collection process and ensure a balanced dataset for training.

We collected a total of 600 videos from the DFDC dataset, comprising 300 real and 300 fake videos. This balanced approach, with an equal number of real and fake videos, helps to avoid training bias and ensures accurate and real-time detection on various types of videos.

4.2 Data Preprocessing

In this step, the videos are preprocessed and all the unrequired and noise is removed from videos. Only the required portion of the video face is detected and cropped. The first steps in the preprocessing of the video is to split the video into frames. After splitting the video into frames the face is detected in each of the frame and the frame is cropped along the face. Later the cropped frame is again converted to a new video by combining each frame of the video. The process is followed for each video which leads to creation of processed dataset containing face only videos. The frame that does not contain the face is ignored while preprocessing. To maintain the uniformity of number of frames, we have selected a threshold value based on the mean of total frames count of each video. Another reason for selecting a threshold value is limited computation power. As a video of 10 second at 30 frames per second(fps) will have total 300 frames and it is computationally very difficult to process the 300 frames at a single time in the experimental environment. So, based on our Graphic Processing Unit (GPU) computational power in experimental environment we have selected 150 frames as the threshold value. While saving the frames to the new dataset we have only saved the first 150 frames of the video to the new video. To demonstrate the proper use of Long Short-Term Memory (LSTM) we have considered the frames in the sequential manner i.e. first 150 frames and not randomly. The newly created video is saved at frame rate of 30 fps and resolution of 112 x 112.

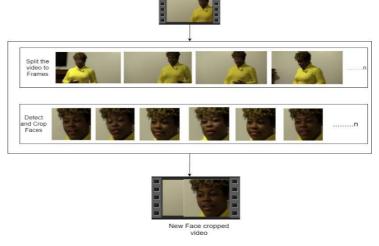


Fig no.4.2.1. Preprocessed video

4.3 Training the Model

We have used the Pre-trained ResNext CNN model to extract the features at frame level and based on the extracted features a LSTM network is trained to classify the video as fake or pristine. Using the Data Loader on training split of videos the labels of the videos are loaded and fitted into the model for training.

ResNext: Instead of writing the code from scratch, we used the pre-trained model of ResNext for feature extraction. ResNext is Residual CNN network optimized for high performance on deeper neural networks. For the experimental purpose we have used resnext50_32x4d model. We have used a ResNext of 50 layers and 32 x 4 dimensions. Following, we will be fine-tuning the network by adding extra required layers and selecting a proper learning rate to properly converge the gradient descent of the model. The 2048-dimensional feature vectors after the last pooling layers of ResNext is used as the sequential LSTM input.

LSTM for Sequence Processing: 2048-dimensional feature vectors is fitted as the input to the LSTM. We are using 1 LSTM layer with 2048 latent dimensions and 2048 hidden layers along with 0.4 chance of dropout, which is capable to do achieve our objective. LSTM is used to process the frames in a sequential manner so that the temporal analysis of the video can be made, by comparing the frame at 't' second with the frame of 't-n' seconds. Where n can be any number of frames before t. The model also consists of Leaky Relu activation function. A linear layer of 2048 input features and 2 output features are used to make the model capable of learning the average rate of correlation between eh input and output. An adaptive average polling layer with the output parameter 1 is used in the model. Which gives the the target output size of the image of the form H x W. For sequential processing of the frames a Sequential Layer is used. The batch size of 4 is used to perform the batch training. A SoftMax layer is used to get the confidence of the model during predication.

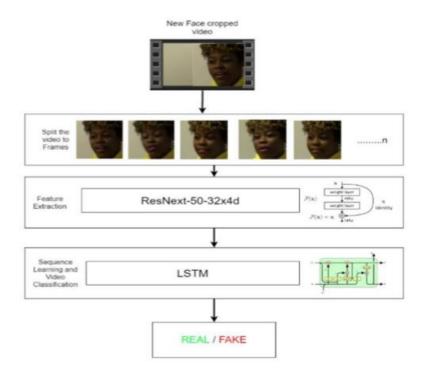


Fig no.4.3.1 Overview of the model

4.4 Hyper-parameter tuning

It is the process of choosing the perfect hyper-parameters for achieving the maximum accuracy. After reiterating many times on the model. The best hyper-parameters for our dataset are chosen. To enable the adaptive learning rate Adam[21] optimizer with the model parameters is used. The learning rate is tuned to 1e-5 (0.00001) to achieve a better global minimum of gradient descent. The weight decay used is 1e-3. As this is a classification problem so to calculate the loss cross entropy approach is used. To use the available computation power properly the batch training is used. The batch size is taken of 4. Batch size of 4 is tested to be ideal size for training in our development environment.

4.5Development of Web Interface using Flask

Developing a user interface using Flask that enables users to interact with the fake video classification system. This interface allows users to upload videos and classifies them as real or fake, displaying the confidence percentage of the classification. Additionally, it provides a platform for users to give feedback, contributing to the ongoing refinement of the model.

4.6 Creating and Installation of dependencies in Anaconda Navigator

The below dependencies should be installed in Anaconda Navigator for this project by creating an Anaconda environment.

```
pip install tensorflow

conda install -c conda-forge keras

conda install -c anaconda scikit-learn

conda install -c conda-forge opencv

conda install -c anaconda scikit-image

conda install -c anaconda flask

pip install pandas

pip install werkzeug==2.3.7

conda install pytorch torchvision torchaudio cudatoolkit=10.2 -c pytorch

conda install matplotlib

pip install face_recognition
```

CHAPTER-5

CODE IMPLEMENTATION

- 1. At first we should be developing and training the LSTM-based machine learning model which is essential for classifying videos as real or fake. This portion of the implementation involves preparing the dataset, selecting appropriate features through meticulous preprocessing, and then employing these features to train the LSTM model. The training process is carefully designed to optimize the model's accuracy by fine-tuning various hyperparameters and employing techniques such as dropout to prevent overfitting. This code ultimately produces a robust trained model capable of detecting subtle manipulations in video content, which is critical for maintaining the integrity and trustworthiness of digital media.
- 2. Next part focuses on the implementation of a user-friendly web interface using Flask. This interface serves as the point of interaction for users, enabling them to upload videos and receive real-time classifications. The Flask framework was chosen for its simplicity and efficiency, allowing rapid deployment and easy scalability of the web application.

Together, these two codes encompass the complete system functionality from model training to user interaction, ensuring a seamless operation and user experience.

5.1 Code-1: Deep Learning Model Development

Mount the Drive in Google Colab and Import All Libraries

from google.colab import drive

drive.mount('/content/drive')

!pip3 install face_recognition

import glob import numpy as np import cv2

import torch

import torchvision

from torchvision import transforms

from torch.utils.data import DataLoader

from torch.utils.data import Dataset

import os

import matplotlib.pyplot as plt

 $import\ face_recognition$

import pandas as pd

import seaborn as sn

from torch import nn

from torchvision import models

from sklearn.metrics import confusion_matrix

from sklearn.model_selection import train_test_split

from torch.optim import Adam

from torch.autograd import Variable

import sys

import time

import random

from tqdm.autonotebook import tqdm

Uploading the dataset:

Directory containing the videos directory = '/content/drive/MyDrive/raw_videos/' files = glob.glob(directory + '*.mp4') video_count = len(files) print("Total number of videos:", video_count)

We collected a total of 646 videos from the DFDC dataset, comprising 323 real and 323 fake videos. This balanced approach, with an equal number of real and fake videos, helps to avoid training bias and ensures accurate and real-time detection on various types of videos.

1. Data Preprocessing:

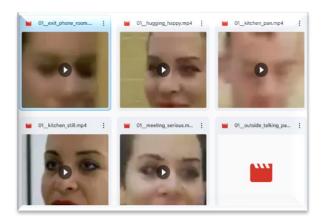
A)Splitting the frames

video_files = glob.glob('/content/drive/MyDrive/raw_videos/*.mp4')
frame_count = []
valid_video_files = []
for video_file in video_files:

```
cap = cv2.VideoCapture(video file)
  if int(cap.get(cv2.CAP_PROP_FRAME_COUNT)) >= 150:
     frame_count.append(int(cap.get(cv2.CAP_PROP_FRAME_COUNT)))
     valid video files.append(video file)
  else:
     print(f"Skipping video: {video_file}, frame count less than 150")
print("Total number of videos:", len(valid video files))
print("Frames:", frame_count)
print("Total number of videos_frames:", len(frame_count))
print('Average frame per video:', np.mean(frame_count))
#to extract frames
def frame extract(path):
 vidObj = cv2.VideoCapture(path)
 success = 1
 while success:
   success, image = vidObj.read()
   if success:
      yield image
#process the frames
!mkdir '/content/drive/MyDrive/preprocessed_before'
def create_face_videos(path_list,out_dir):
 already_present_count = glob.glob(out_dir+'*.mp4')
 print("No of videos already present ", len(already present count))
 for path in tqdm(path_list):
  out_path = os.path.join(out_dir,path.split('/')[-1])
  file_exists = glob.glob(out_path)
  if(len(file_exists) != 0):
   print("File Already exists: " , out_path)
   continue
  frames = []
  flag = 0
  face all = []
  frames 1 = []
  out = cv2.VideoWriter(out_path,cv2.VideoWriter_fourcc('M','J','P','G'), 30, (112,112))
  for idx,frame in enumerate(frame_extract(path)):
   if(idx <= 150):
     frames.append(frame)
     if(len(frames) == 4):
      faces = face_recognition.batch_face_locations(frames)
      for i,face in enumerate(faces):
       if(len(face) != 0):
        top,right,bottom,left = face[0]
        out.write(cv2.resize(frames[i][top:bottom,left:right,:],(112,112)))
       except:
        pass
      frames = []
  try:
 del top,right,bottom,left
  except:
   pass
  out.release()
```

B) Crop and Save Extracted Video Frames to a New Directory

create_face_videos(video_files,'/content/drive/MyDrive/preprocessed_before/')



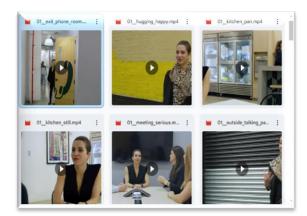


Fig no.5.1.1 Preprocessed outputs

- Using glob we imported all the videos in the directory in a python list.
- cv2.VideoCapture is used to read the videos and get the mean number of frames in each video.
- To maintain uniformity, based on mean a value 150 is selected as idea value for creating the new dataset.
- The video is split into frames and the frames are cropped on face location.
- The face cropped frames are again written to new video using VideoWriter.
- The new video is written at 30 frames per second and with the resolution of 112 x 112 pixels in the mp4 format.
- Instead of selecting the random videos, to make the proper use of LSTM for temporal sequence analysis the first 150 frames are written to the new video.

2.Training the data:

#THis code is to check if the video is corrupted or not, if the video is corrupted delete the video.

```
def validate_video(vid_path,train_transforms):
    transform = train_transforms
    count = 20
    video_path = vid_path
    frames = []
    a = int(100/count)
    first_frame = np.random.randint(0,a)
    temp_video = video_path.split('/')[-1]
    for i,frame in enumerate(frame_extract(video_path)):
        frames.append(transform(frame))
        if(len(frames) == count):
        break
```

```
frames = torch.stack(frames)
   frames = frames[:count]
   return frames
#extract a frame from video
def frame extract(path):
 vidObj = cv2.VideoCapture(path)
 success = 1
 while success:
   success, image = vidObj.read()
   if success:
      yield image
im size = 112
mean = [0.485, 0.456, 0.406]
std = [0.229, 0.224, 0.225]
train transforms = transforms.Compose([
                   transforms.ToPILImage(),
                   transforms.Resize((im size,im size)),
                   transforms.ToTensor(),
                   transforms.Normalize(mean,std)])
video_fil = glob.glob('/content/drive/MyDrive/preprocessed_after/*.mp4')
print("Total no of videos :" , len(video_fil))
print(video_fil)
count = 0:
for i in video_fil:
 try:
  count+=1
  validate_video(i,train_transforms)
  print("Number of video processed: " , count ," Remaining : " , (len(video_fil) - count))
  print("Corrupted video is: ", i)
  continue
print((len(video fil) - count))
#to load preprocessod video to memory
video_files = glob.glob('/content/drive/My Drive/preprocessed_after/*.mp4')
random.shuffle(video_files)
random.shuffle(video files)
frame count = []
for video file in video files:
 cap = cv2.VideoCapture(video_file)
 if(int(cap.get(cv2.CAP PROP FRAME COUNT))<100):
  video_files.remove(video_file)
  continue
 frame_count.append(int(cap.get(cv2.CAP_PROP_FRAME_COUNT)))
print("frames are " , frame_count)
print("Total no of video: " , len(frame_count))
print('Average frame per video:',np.mean(frame count))
# load the video name and labels from csv
class video_dataset(Dataset):
  def __init__(self,video_names,labels,sequence_length = 60,transform = None):
    self.video names = video names
    self.labels = labels
    self.transform = transform
    self.count = sequence_length
  def len (self):
    return len(self.video names)
```

```
def __getitem__(self,idx):
    video_path = self.video_names[idx]
    frames = []
    a = int(100/self.count)
    first frame = np.random.randint(0,a)
    temp_video = video_path.split('/')[-1]
    label = self.labels.iloc[(labels.loc[labels["file"] == temp_video].index.values[0]),1]
    if(label == 'FAKE'):
     label = 0
    if(label == 'REAL'):
      label = 1
    for i,frame in enumerate(self.frame extract(video path)):
      frames.append(self.transform(frame))
     if(len(frames) == self.count):
       break
    frames = torch.stack(frames)
frames = frames[:self.count]
    return frames, label
  def frame_extract(self,path):
   vidObj = cv2.VideoCapture(path)
   success = 1
   while success:
      success, image = vidObj.read()
      if success:
        yield image
#plot the image
def im_plot(tensor):
  image = tensor.cpu().numpy().transpose(1,2,0)
  b,g,r = cv2.split(image)
  image = cv2.merge((r,g,b))
  image = image*[0.22803, 0.22145, 0.216989] + [0.43216, 0.394666, 0.37645]
  image = image*255.0
  plt.imshow(image.astype(int))
  plt.show()
#count the number of fake and real videos
def number of real and fake videos(data list):
 header_list = ["file","label"]
 lab = pd.read csv('/content/drive/MyDrive/data1.csv',names=header list)
 fake = 0
 real = 0
 for i in data_list:
  temp video = i.split('/')[-1]
  label = lab.iloc[(labels.loc[labels["file"] == temp_video].index.values[0]),1]
  if(label == 'FAKE'):
   fake+=1
  if(label == 'REAL'):
   real += 1
 return real, fake
```

This code is designed to preprocess video data by validating and filtering corrupted videos, extracting frames, and preparing datasets for training a deep learning model. It includes functions to check if a video is corrupted and remove it, extract frames from videos, and apply transformations to prepare the data. The script also calculates the number of frames

per video, counts the real and fake videos, and organizes the data for model training. The **video_dataset** class helps in loading videos and their corresponding labels from a CSV file, ensuring the dataset is balanced and ready for training.

Splitting the data into TRAINING and TESTING

```
from sklearn.model selection import train test split
header list = ["file", "label"]
labels = pd.read_csv('/content/drive/My Drive/data1.csv',names=header_list)
train_videos = video_files[:int(0.8*len(video_files))]
valid_videos = video_files[int(0.8*len(video_files)):]
print("train : " , len(train videos))
print("test:", len(valid videos))
print("TRAIN: ", "Real:",number_of_real_and_fake_videos(train_videos)[0],"
Fake:",number_of_real_and_fake_videos(train_videos)[1])
print("TEST: ", "Real:", number of real and fake videos(valid videos)[0],"
Fake:",number_of_real_and_fake_videos(valid_videos)[1])
im size = 112
mean = [0.485, 0.456, 0.406]
std = [0.229, 0.224, 0.225]
train_transforms = transforms.Compose([
                   transforms.ToPILImage(),
                   transforms.Resize((im_size,im_size)),
                   transforms.ToTensor(),
                   transforms.Normalize(mean,std)])
test_transforms = transforms.Compose([
                   transforms.ToPILImage(),
                   transforms.Resize((im_size,im_size)),
                   transforms.ToTensor(),
                   transforms.Normalize(mean,std)])
train_data = video_dataset(train_videos,labels,sequence_length = 10,transform =
train transforms)
val_data = video_dataset(valid_videos,labels,sequence_length = 10,transform =
train_transforms)
train loader = DataLoader(train data,batch size = 4,shuffle = True,num workers = 4)
valid loader = DataLoader(val data,batch size = 4,shuffle = True,num workers = 4)
image.label = train data[0]
im_plot(image[0,:,:,:])
```

Training the Model using LSTM Algorithm

```
from torch import nn
from torchvision import models
class Model(nn.Module):
    def __init__(self, num_classes,latent_dim= 2048, lstm_layers=1 , hidden_dim = 2048,
bidirectional = False):
        super(Model, self).__init__()
        model = models.resnext50_32x4d(pretrained = True)
        self.model = nn.Sequential(*list(model.children())[:-2])
        self.lstm = nn.LSTM(latent_dim,hidden_dim, lstm_layers, bidirectional)
        self.relu = nn.LeakyReLU()
        self.dp = nn.Dropout(0.4)
```

```
self.linear1 = nn.Linear(2048,num_classes)
self.avgpool = nn.AdaptiveAvgPool2d(1)
def forward(self, x):
batch_size,seq_length, c, h, w = x.shape
x = x.view(batch_size * seq_length, c, h, w)
fmap = self.model(x)
x = self.avgpool(fmap)
x = x.view(batch_size,seq_length,2048)
x_lstm,_ = self.lstm(x,None)
return fmap,self.dp(self.linear1(torch.mean(x_lstm,dim = 1)))
```

<u>Plotting Training and Validation Loss, Training and Validation Accuracy</u>

```
model = Model(2).cuda()
a,b =
model(torch.from_numpy(np.empty((1,20,3,112,112))).type(torch.cuda.FloatTensor))
import torch
from torch.autograd import Variable
def train_epoch(epoch, num_epochs, data_loader, model, criterion, optimizer):
  model.train()
  losses = AverageMeter()
  accuracies = AverageMeter()
  t = \prod
  for i, (inputs, targets) in enumerate(data loader):
    if torch.cuda.is_available():
       targets = targets.type(torch.cuda.LongTensor)
       inputs = inputs.cuda()
     _,outputs = model(inputs)
     loss = criterion(outputs,targets.type(torch.cuda.LongTensor))
     acc = calculate_accuracy(outputs, targets.type(torch.cuda.LongTensor))
     losses.update(loss.item(), inputs.size(0))
     accuracies.update(acc, inputs.size(0))
     optimizer.zero_grad()
     loss.backward()
     optimizer.step()
     svs.stdout.write(
        "\r[Epoch %d/%d] [Batch %d / %d] [Loss: %f, Acc: %.2f%%]"
         % (
            epoch,
            num_epochs,
            len(data loader),
            losses.avg,
            accuracies.avg))
  torch.save(model.state_dict(),'/content/drive/MyDrive/trained_model6.pt')
  return losses.avg,accuracies.avg
def test(epoch,model, data_loader ,criterion):
  print('Testing')
  model.eval()
  losses = AverageMeter()
  accuracies = AverageMeter()
  pred = []
  true = []
```

```
count = 0
  with torch.no_grad():
    for i, (inputs, targets) in enumerate(data_loader):
       if torch.cuda.is available():
         targets = targets.cuda().type(torch.cuda.FloatTensor)
inputs = inputs.cuda()
       _,outputs = model(inputs)
       loss = torch.mean(criterion(outputs, targets.type(torch.cuda.LongTensor))) \\
       acc = calculate_accuracy(outputs,targets.type(torch.cuda.LongTensor))
       _{,p} = torch.max(outputs, 1)
       true +=
(targets.type(torch.cuda.LongTensor)).detach().cpu().numpy().reshape(len(targets)).tolist(
       pred += p.detach().cpu().numpy().reshape(len(p)).tolist()
       losses.update(loss.item(), inputs.size(0))
       accuracies.update(acc, inputs.size(0))
       sys.stdout.write(
            "\r[Batch %d / %d] [Loss: %f, Acc: %.2f%%]"
            % (
              i,
              len(data_loader),
              losses.avg,
              accuracies.avg
    print('\nAccuracy { }'.format(accuracies.avg))
  return true,pred,losses.avg,accuracies.avg
class AverageMeter(object):
  """Computes and stores the average and current value"""
  def init__(self):
    self.reset()
  def reset(self):
    self.val = 0
    self.avg = 0
    self.sum = 0
    self.count = 0
  def update(self, val, n=1):
    self.val = val
    self.sum += val * n
    self.count += n
    self.avg = self.sum / self.count
def calculate accuracy(outputs, targets):
  batch_size = targets.size(0)
  _, pred = outputs.topk(1, 1, True)
  pred = pred.t()
  correct = pred.eq(targets.view(1, -1))
  n_correct_elems = correct.float().sum().item()
  return 100* n_correct_elems / batch_size
import seaborn as sn
#Output confusion matrix
def print_confusion_matrix(y_true, y_pred):
  cm = confusion_matrix(y_true, y_pred)
  print('True positive = ', cm[0][0])
 print('False positive = ', cm[0][1])
  print('False negative = ', cm[1][0])
```

```
print('True negative = ', cm[1][1])
  print(' \mid \mathbf{n}')
  df_cm = pd.DataFrame(cm, range(2), range(2))
  sn.set(font scale=1.4)
  sn.heatmap(df cm, annot=True, annot kws={"size": 16})
  plt.ylabel('Actual label', size = 20)
  plt.xlabel('Predicted label', size = 20)
  plt.xticks(np.arange(2), ['Fake', 'Real'], size = 16)
  plt.yticks(np.arange(2), ['Fake', 'Real'], size = 16)
  plt.ylim([2, 0])
  plt.show()
  calculated acc = (cm[0][0]+cm[1][1])/(cm[0][0]+cm[0][1]+cm[1][0]+cm[1][1])
  print("Calculated Accuracy",calculated_acc*100)
def plot_loss(train_loss_avg,test_loss_avg,num_epochs):
 loss train = train loss avg
 loss val = test loss avg
 print(num epochs)
 epochs = range(1,num_epochs+1)
 plt.plot(epochs, loss_train, 'g', label='Training loss')
 plt.plot(epochs, loss_val, 'b', label='validation loss')
 plt.title('Training and Validation loss')
 plt.xlabel('Epochs')
 plt.ylabel('Loss')
 plt.legend()
 plt.show()
def plot_accuracy(train_accuracy,test_accuracy,num_epochs):
 loss train = train_accuracy
 loss_val = test_accuracy
 epochs = range(1,num epochs+1)
 plt.plot(epochs, loss train, 'g', label='Training accuracy')
 plt.plot(epochs, loss val, 'b', label='validation accuracy')
 plt.title('Training and Validation accuracy')
 plt.xlabel('Epochs')
 plt.ylabel('Accuracy')
 plt.legend()
 plt.show()
from sklearn.metrics import confusion matrix
#learning rate
lr = 1e-5 \#0.00001
num epochs = 20
optimizer = torch.optim.Adam(model.parameters(), lr= lr,weight_decay = 1e-5)
criterion = nn.CrossEntropyLoss().cuda()
train_loss_avg =[]
train accuracy = []
test_loss_avg = []
test accuracy = []
for epoch in range(1,num_epochs+1):
  1, acc = train_epoch(epoch,num_epochs,train_loader,model,criterion,optimizer)
  train_loss_avg.append(1)
  train accuracy.append(acc)
  true,pred,tl,t_acc = test(epoch,model,valid_loader,criterion)
  test_loss_avg.append(tl)
  test_accuracy.append(t_acc)
plot_loss(train_loss_avg,test_loss_avg,len(train_loss_avg))
plot_accuracy(train_accuracy,test_accuracy,len(train_accuracy))
```

print(confusion_matrix(true,pred)) print_confusion_matrix(true,pred)

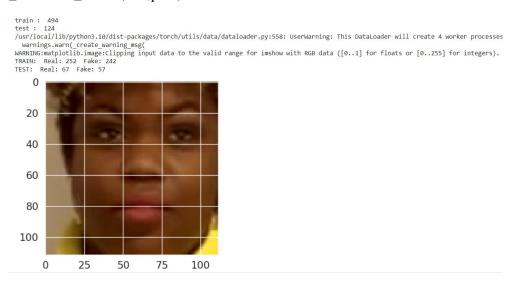


Fig no.5.1.2 Train test split output

Model Details

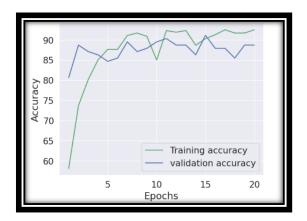
The model consists of following layers:

- **ResNext CNN:** The pre-trained model of Residual Convolution Neural Net work is used. The model name is resnext50_32x4d()[22]. This model consists of 50 layers and 32 x 4 dimensions.
- **Sequential Layer:** Sequential is a container of Modules that can be stacked together and run at the same time. Sequential layer is used to store feature vector returned by the ResNext model in a ordered way. So that it can be passed to the LSTM sequentially.
- LSTM Layer: LSTM is used for sequence processing and spot the temporal change between the frames.2048-dimensional feature vectors is fitted as the input to the LSTM. We are using 1 LSTM layer with 2048 latent dimensions and 2048 hidden layers along with 0.4 chance of dropout, which is capable to do achieve our objective. LSTM is used to process the frames in a sequential manner so that the temporal analysis of the video can be made, by comparing the frame at 't' second with the frame of 't-n' seconds. Where n can be any number of frames before t.
- ReLU: A Rectified Linear Unit is activation function that has output 0 if the input is less than 0, and raw output otherwise. That is, if the input is greater than 0, the output is equal to the input. The operation of ReLU is closer to the way our biological neurons work. ReLU is non-linear and has the advantage of not having any backpropagation errors unlike the sigmoid function, also for larger Neural Networks, the speed of building models based off on ReLU is very fast.
- **Dropout Layer:** Dropout layer with the value of 0.4 is used to avoid over f itting in the model and it can help a model generalize by randomly setting the output for a given neuron to 0. In setting the output to 0, the cost function becomes more

- sensitive to neighbouring neurons changing the way the weights will be updated during the process of backpropagation.
- Adaptive Average Pooling Layer: It is used To reduce variance, reduce computation complexity and extract low level features from neighbourhood.2 dimensional Adaptive Average Pooling Layer is used in the model.

Model Training Details

- Train Test Split: The dataset is split into train and test dataset with a ratio of 70% train videos and 30% test videos. The train and test split is a balanced split i.e 50% of the real and 50% of fake videos in each split.
- Data Loader: It is used to load the videos and their labels with a batch size of 4.
- **Training:** The training is done for 20 epochs with a learning rate of 1e-5(0.00001), weight decay of 1e-3 (0.001) using the Adam optimizer.
- Adam optimizer[21]: To enable the adaptive learning rate Adam optimizer with the model parameters is used.
- Cross Entropy: To calculate the loss function Cross Entropy approach is used because we are training a classification problem.
- Softmax Layer: A Softmax function is a type of squashing function. Squashing functions limit the output of the function into the range 0 to 1. This allows the output to be interpreted directly as a probability. Similarly, softmax functions are multiclass sigmoids, meaning they are used in determining probability of multiple classes at once. Since the outputs of a softmax function can be interpreted as a probability (i.e.they must sum to 1), a softmax layer is typically the final layer used in neural network functions. It is important to note that a softmax layer must have the same number of nodes as the output later. In our case softmax layer has two output nodes i.e REAL or FAKE, also Softmax layer provide us the confidence(probability) of prediction.
- Confusion Matrix: A confusion matrix is a summary of prediction results on a classification problem. The number of correct and incorrect predictions are summarized with count values and broken down by each class. This is the key to the confusion matrix. The confusion matrix shows the ways in which your classification model is confused when it makes predictions. It gives us insight not only into the errors being made by a classifier but more importantly the types of errors that are being made. Confusion matrix is used to evaluate our model and calculate the accuracy.
- **Export Model:** After the model is trained, we have exported the model. So that it can be used for prediction on real time data.



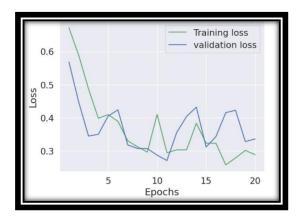


Fig no.5.1.3 Training and Validation Accuracy

Fig no.5.1.4 Training and Validation loss

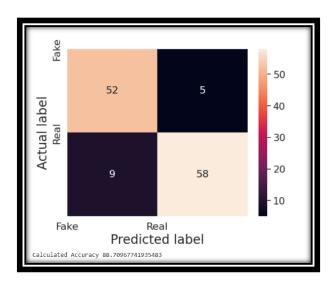


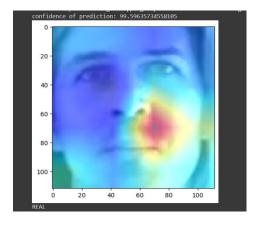
Fig no.5.1.5 Confusion Matrix

3. Prediction and Evaluation:

```
im_size = 112
mean=[0.485, 0.456, 0.406]
std=[0.229, 0.224, 0.225]
sm = nn.Softmax()
inv_normalize = transforms.Normalize(mean=
1*np.divide(mean,std),std=np.divide([1,1,1],std))
def im_convert(tensor):
    """ Display a tensor as an image. """
    image = tensor.to("cpu").clone().detach()
    image = image.squeeze()
    image = inv_normalize(image)
    image = image.numpy()
    image = image.transpose(1,2,0)
    image = image.clip(0, 1)
```

```
cv2.imwrite('./2.png',image*255)
  return image
def predict(model,img,path = './'):
 fmap,logits = model(img.to('cuda'))
 params = list(model.parameters())
 weight softmax = model.linear1.weight.detach().cpu().numpy()
 logits = sm(logits)
 prediction = torch.max(logits, 1)
 confidence = logits[:,int(prediction.item())].item()*100
 print('confidence of prediction:',logits[:,int(prediction.item())].item()*100)
 idx = np.argmax(logits.detach().cpu().numpy())
 bz, nc, h, w = fmap.shape
 out = np.dot(fmap[-1].detach().cpu().numpy().reshape((nc,
h*w)).T,weight_softmax[idx,:].T)
 predict = out.reshape(h, w)
 predict = predict - np.min(predict)
 predict_img = predict / np.max(predict)
 predict_img = np.uint8(255*predict_img)
 out = cv2.resize(predict_img, (im_size,im_size))
 heatmap = cv2.applyColorMap(out, cv2.COLORMAP_JET)
img = im\_convert(img[:,-1,:,:])
 result = heatmap * 0.5 + img*0.8*255
 cv2.imwrite('/content/1.png',result)
 result1 = heatmap * 0.5/255 + img*0.8
 r,g,b = cv2.split(result1)
 result1 = cv2.merge((r,g,b))
 plt.imshow(result1)
 plt.show()
class validation dataset(Dataset):
  def init (self, video names, sequence length = 60, transform = None):
    self.video names = video names
    self.transform = transform
    self.count = sequence_length
  def __len__(self):
    return len(self.video_names)
  def getitem (self,idx):
    video path = self.video names[idx]
    frames = []
    a = int(100/self.count)
    first frame = np.random.randint(0,a)
    for i,frame in enumerate(self.frame_extract(video_path)):
       faces = face recognition.face locations(frame)
       try:
        top,right,bottom,left = faces[0]
        frame = frame[top:bottom,left:right,:]
       except:
        pass
       frames.append(self.transform(frame))
       if(len(frames) == self.count):
        break
    frames = frames[:self.count]
    return frames.unsqueeze(0)
  def frame_extract(self,path):
   vidObj = cv2.VideoCapture(path)
   success = 1
```

```
while success:
      success, image = vidObj.read()
      if success:
        vield image
def im plot(tensor):
  image = tensor.cpu().numpy().transpose(1,2,0)
  b,g,r = cv2.split(image)
  image = cv2.merge((r,g,b))
  image = image*[0.22803, 0.22145, 0.216989] + [0.43216, 0.394666, 0.37645]
  image = image*255.0
  plt.imshow(image.astype(int))
  plt.show()
#Code for making prediction
im size = 112
mean=[0.485, 0.456, 0.406]
std=[0.229, 0.224, 0.225]
train transforms = transforms.Compose([
                   transforms.ToPILImage(),
                   transforms.Resize((im_size,im_size)),
                   transforms.ToTensor(),
                   transforms.Normalize(mean,std)])
path_to_videos= ["/content/drive/MyDrive/train_sample_videos/aelfnikyqj.mp4",
          "/content/drive/MvDrive/train sample videos/bndvbcqhfr.mp4".
          "/content/drive/MyDrive/train_sample_videos/bilnggbxgu.mp4",
          "/content/drive/MyDrive/train_sample_videos/bkmdzhfzfh.mp4"]
video_dataset = validation_dataset(path_to_videos,sequence_length = 10,transform =
train_transforms)
model = Model(2).cuda()
path to model = '/content/drive/MyDrive/trained model6.pt'
model.load state dict(torch.load(path to model))
model.eval()
for i in range(0,len(path to videos)):
 print(path_to_videos[i])
 prediction = predict(model, video_dataset[i],'./')
 if prediction[0] == 1:
  print("REAL")
 else:
  print("FAKE")
```



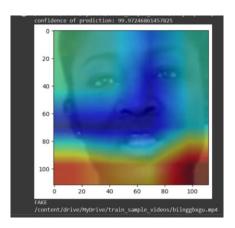


Fig No.5.1.6 Predicted outputs

Model Prediction Details

- The model is loaded in the application
- The new video for prediction is preprocessed and passed to the loaded model for prediction
- The trained model performs the prediction and return if the video is a real or fake along with the confidence of the prediction

5.2 Code-2: Web Interface Using Flask

i)app.py

```
from flask import Flask, render_template, request, session
import torch
import torchvision
from torchvision import transforms
from torch.utils.data import DataLoader
from torch.utils.data.dataset import Dataset
from torchvision import models
from torch.autograd import Variable
import os
import numpy as np
import cv2
import matplotlib.pyplot as plt
import face recognition
import time
import sys
from torch import nn
app = Flask(\underline{\quad name}\underline{\quad})
@app.route('/')
@app.route('/index')
def second():
  scrollValueText = 10
  return render_template('uploader.html', scrollValueText = scrollValueText)
app.secret_key = 'my_key'
class Model(nn.Module):
  def __init__(self, num_classes, latent_dim= 2048, lstm_layers=1, hidden_dim = 2048,
bidirectional = False):
     super(Model, self).__init__()
     model = models.resnext50_32x4d(pretrained = True)
     self.model = nn.Sequential(*list(model.children())[:-2])
     self.lstm = nn.LSTM(latent_dim,hidden_dim, lstm_layers, bidirectional)
     self.relu = nn.LeakyReLU()
     self.dp = nn.Dropout(0.4)
     self.linear1 = nn.Linear(2048,num classes)
     self.avgpool = nn.AdaptiveAvgPool2d(1)
  def forward(self, x):
     batch\_size,seq\_length, c, h, w = x.shape
     x = x.view(batch\_size * seq\_length, c, h, w)
     fmap = self.model(x)
     x = self.avgpool(fmap)
     x = x.view(batch\_size,seq\_length,2048)
     x_lstm_ = self.lstm(x,None)
```

```
return fmap,self.dp(self.linear1(x_lstm[:,-1,:]))
im_size = 112
mean=[0.485, 0.456, 0.406]
std=[0.229, 0.224, 0.225]
sm = nn.Softmax()
inv normalize = transforms.Normalize(mean=-1*np.divide(mean,std),std=np.divide([1,1,1],std))
def im convert(tensor):
  """ Display a tensor as an image. """
  image = tensor.to("cpu").clone().detach()
  image = image.squeeze()
  image = inv_normalize(image)
  image = image.numpy()
  image = image.transpose(1,2,0)
  image = image.clip(0, 1)
  return image
def predict(model,img,path = './'):
 fmap,logits = model(img.to('cpu'))
 params = list(model.parameters())
 weight_softmax = model.linear1.weight.detach().cpu().numpy()
 logits = sm(logits)
 _,prediction = torch.max(logits,1)
 confidence = logits[:,int(prediction.item())].item()*100
 print('confidence of prediction:',logits[:,int(prediction.item())].item()*100)
 idx = np.argmax(logits.detach().cpu().numpy())
 bz, nc, h, w = fmap.shape
 out = np.dot(fmap[-1].detach().cpu().numpy().reshape((nc, h*w)).T,weight_softmax[idx,:].T)
 predict = out.reshape(h,w)
 predict = predict - np.min(predict)
 predict img = predict / np.max(predict)
 predict img = np.uint8(255*predict img)
 out = cv2.resize(predict img, (im size,im size))
 heatmap = cv2.applyColorMap(out, cv2.COLORMAP_JET)
 img = im\_convert(img[:,-1,:,:])
 result = heatmap * 0.5 + img*0.8*255
 cv2.imwrite('/content/1.png',result)
 result1 = heatmap * 0.5/255 + img*0.8
 r,g,b = cv2.split(result1)
 result1 = cv2.merge((r,g,b))
 return [int(prediction.item()),confidence]
class validation_dataset(Dataset):
  def init (self, video names, sequence length, transform = None):
     self.video names = video names
     self.transform = transform
     self.count = sequence_length
  def len (self):
     return len(self.video_names)
  def __getitem__(self,idx):
     video_path = self.video_names[idx]
     frames = []
     a = int(100/self.count)
     first frame = np.random.randint(0,a)
     for i,frame in enumerate(self.frame_extract(video_path)):
       faces = face_recognition.face_locations(frame)
       try:
```

```
top,right,bottom,left = faces[0]
        frame = frame[top:bottom,left:right,:]
       except:
        pass
       frames.append(self.transform(frame))
       if(len(frames) == self.count):
    frames = torch.stack(frames)
    frames = frames[:self.count]
    return frames.unsqueeze(0)
  def frame extract(self,path):
   vidObj = cv2.VideoCapture(path)
   success = 1
   while success:
      success, image = vidObj.read()
     if success:
        vield image
@app.route('/upload', methods=['POST'])
def upload():
  fileReader = request.files['file']
  scroll_value = int(request.form['scrollValue'])
  fileReader.save('./static/video/' + fileReader.filename)
  path_to_videos= ["./static/video/" + fileReader.filename]
  session['video_filename'] = fileReader.filename
  train_transforms = transforms.Compose([
                        transforms.ToPILImage(),
                        transforms.Resize((im_size,im_size)),
                        transforms.ToTensor(),
                        transforms.Normalize(mean,std)])
  pathProvider = path_to_videos[0]
  video dataset = validation dataset(path to videos, sequence length = scroll value, transform =
train transforms)
  device = torch.device('cpu')
  model = Model(2).to(device)
  path to model = './models/trained model6.pt'
  model.load state dict(torch.load(path to model, device))
  model.eval()
  predictions = ""
  for i in range(0,len(path to videos)):
    print(path_to_videos[i])
    prediction = predict(model, video dataset[i],'.')
    accuracy = prediction[1]
    if prediction[0] == 1:
       prediction = "REAL"
    else:
       prediction = "FAKE"
  cap = cv2.VideoCapture(path_to_videos[0])
  total frames = int(cap.get(cv2.CAP PROP FRAME COUNT))
  frame_interval = total_frames // int(scroll_value)
  frame\_count = 0
  frame index = \mathbf{0}
  frame path = []
```

```
face_index = 0
   face_path = []
   while cap.isOpened():
      ret, frame = cap.read()
      if not ret:
        break
      if frame count % frame interval == 0:
        frame path.append('./static/images/'+f'frame {frame index}.jpg')
        output_path = os.path.join('./static/images/', f'frame_{frame_index}.jpg')
        frame rgb = cv2.cvtColor(frame, cv2.COLOR BGR2RGB)
        face locations = face recognition.face locations(frame rgb)
        for (top, right, bottom, left) in face locations:
           face image = frame[top:bottom, left:right]
           face_path.append('./static/images/'+f'face_{face_index}.jpg')
           face_output_path = os.path.join('./static/images/', f'face_{face_index}.jpg')
           cv2.imwrite(face output path, face image)
           face index += 1
           if prediction == 'REAL':
             cv2.rectangle(frame, (left, top), (right, bottom), (0, 255, 0), 2)
           else:
             cv2.rectangle(frame, (left, top), (right, bottom), (0, 0, 255), 2)
           label = f'{prediction}'
           font = cv2.FONT HERSHEY SIMPLEX
           font scale = 1.5
           text_size = cv2.getTextSize(label, font, font_scale, 1)[0]
           text_left = left + 5
           text_top = top - text_size[1] - 5
           if prediction == 'REAL':
             cv2.rectangle(frame, (text left - 5, text top - 5), (text left + text size [0] + 5, text top
 + text size[1] + 5), (0, 255, 0), cv2.FILLED)
           else:
             cv2.rectangle(frame, (text left - 5, text top - 5), (text left + text size [0] + 5, text top
 + \text{ text\_size}[1] + 5), (0, 0, 255), cv2.FILLED)
           cv2.putText(frame, label, (text_left, text_top + text_size[1]), font, font_scale, (0, 0, 0), 1,
 cv2.LINE_AA)
        cv2.imwrite(output path, frame)
        frame index += 1
      frame_count += 1
   cap.release()
   return render_template('results.html',prediction=prediction, accuracy=accuracy,
 frame path=frame path, video path= ".+pathProvider, face path=face path)
 if __name__ == "__main__":
   app.run(debug=True)
ii.results.html
 <!DOCTYPE html>
 <html>
 <head>
  <title>Uploaded Video</title>
  k rel="stylesheet" href="../static/css/uploadPage.css">
```

```
<script>
 window.onload = function () {
  const videoUrl = localStorage.getItem('uploadedVideo');
  if (videoUrl) {
   const videoElement = document.createElement('video');
   videoElement.src = videoUrl;
   videoElement.controls = true;
   const videoContainer = document.getElementById('video-container');
   videoContainer.appendChild(videoElement);
  } else {
   console.error('No uploaded video found.');
 };
</script>
<style>
body {
   overflow-y: scroll !important;
.container {
background-repeat: repeat !important;
background-size: contain;
header {
    padding: 20px;
    color: #fff;
    display: flex;
    align-items: center;
   header:hover{
     color: aquamarine;
   header h1 {
    margin: 0;
    flex-grow: 1;
    text-align: center;
   header a {
    color: white;
    text-decoration: none;
    font-size: 35px;
    font-weight: bold;
    margin-left: 20px;
    text-size-adjust: 20px;
   header a:hover {
    color: #00ffea;
   .first{
     position: absolute;
     top: 5%;
```

```
.second{
      position: absolute;
      top: 45%;
    .third{
      position: absolute;
      top: 80%;
      left: 28%;
    .first h1, .second h1, .third h1{
       color: white;
       position: relative;
      left: 50%;
    }
    .third p{
       position: relative;
      left: 10%;
  #video-container {
   margin-left: 33%;
   max-width: 35%;
   max-height: 35%;
   border: 2px solid #000;
   display: flex;
   justify-content: center;
   align-items: center;
  #video-container video {
   max-width: 100%;
   max-height: 100%;
  .image-container,.face-container {
   width: 1250px;
   overflow-x: scroll;
   white-space: nowrap;
  .image-container img {
   display: inline-block;
   height: auto;
   width: 300px;
   margin-right: 10px;
   margin-top: 30px;
  .face-container img{
   display: inline-block;
   height: 150px;
   width: 150px;
   margin-right: 10px;
   margin-top: 30px;
 </style>
</head>
<body>
```

```
<header>
 <a href="/upload">FAKE VIDEO DETECTION</a>
<div class="container" style="justify-content: center;">
 <div class="first">
   <h1>Extracted Frames</h1>
   <div class="image-container" style="margin-left: 10%">
   {% for frame in frame_path %}
   <img src= {{ frame }}>
   {% endfor %}
   </div>
 </div>
 <div class="second">
   <div class="face-container" style="margin-left: 10%">
     {% for frame in face_path %}
     <img src={{ frame }}>
     {% endfor %}
   </div>
 </div>
 <div class="third">
 <h1 style="margin-top:60px">Results</h1>
 <div style="margin-top: 20px;text-align: center;">
  <div style="text-align: center;">
   {% if prediction == 'REAL' %}
     PREDICTION =
REAL
   {% else %}
     PREDICTION = FAKE
   { % endif % }
 </div>
 <div style="margin-top: 20px; text-align: center;">
   % \red{\sigma endif \sigma\}; font-weight: bold;" > Confidence Percentage = {{ accuracy }} 
 </div>
</div>
 </div>
</body>
</html>
```

iii.uploader.html

```
const scrollThumb = document.getElementById('scroll-bar-thumb');
 const scrollValue = document.getElementById('scroll-value');
 scrollBar.addEventListener('click', function(event) {
 const clickX = event.clientX - scrollBar.getBoundingClientRect().left;
 const scrollPercentage = clickX / scrollBar.offsetWidth;
 let scrollValueText;
 if (scrollPercentage < 0.15) {
  scrollValueText = 10;
 } else if (scrollPercentage < 0.35) {
  scrollValueText = 20;
 } else if (scrollPercentage < 0.55) {
  scrollValueText = 40;
 } else if (scrollPercentage < 0.75) {
  scrollValueText = 60;
 } else if (scrollPercentage < 0.95) {
  scrollValueText = 80;
 } else {
  scrollValueText = 100;
 scrollThumb.style.width = scrollPercentage * 100 + '%';
 scrollValue.textContent = scrollValueText;
 const scrollValueInput = document.getElementById('scrollValueInput');
 scrollValueInput.value = scrollValueText;
});
};
 function handleFileSelect(event) {
  const file = event.target.files[0];
  const reader = new FileReader();
  console.log(" I am here ")
  reader.onload = function (e) {
   const videoUrl = e.target.result;
   localStorage.setItem('uploadedVideo', videoUrl);
   window.location.href = '/upload';
  reader.readAsDataURL(file);
</script>
<style>
 header {
  padding: 20px;
  color: #fff;
  display: flex;
  align-items: center;
 header:hover{
   color: aquamarine;
 header h1 {
  margin: 0;
  flex-grow: 1;
  text-align: center;
 header a {
  color: white;
  text-decoration: none;
```

```
font-size: 35px;
     font-weight: bold;
     margin-left: 20px;
     text-size-adjust: 20px;
    header a:hover {
     color: #00ffea;
    #upload-form {
      position: absolute;
      top: 15%;
      left: 35%;
     width: 300px;
     margin: 0 auto;
     margin-top: 50px;
     border: 2px solid #a9a7a7;
     padding: 50px;
     border-radius: 5px;
     box-shadow: 0 0 10px rgba(0, 0, 0, 0.1);
    .no-background-image {
     background-color: transparent;
    #upload-form input[type="file"] {
     margin-bottom: 10px;
     background-color: white;
    #scroll-bar-container {
     width: 300px;
     margin: 50px auto;
     position: absolute;
     top: 50%;
     left: 38%;
    #scroll-bar {
     width: 100%;
     height: 20px;
     background-color: #f1f1f1;
     position: relative;
     cursor: pointer;
    #scroll-bar-thumb {
     width: 0;
     height: 100%;
     background-color: #007bff;
     position: absolute;
    #scroll-value {
     margin-top: 10px;
     text-align: center;
     font-size: 18px;
     color: white;
   </style>
</head>
```

```
<body>
 <header>
  <a href="/upload">
   <span style="color: white; font-weight: bold; font-family: 'Times New Roman', Times, serif;</pre>
font-size: 50px;">
       <span id="content"></span>
    </span>
  </a>
</header>
<script>
  const text = "Fake video Classification using LSTM";
  const contentElement = document.getElementById("content");
  let index = \mathbf{0}:
  function displayText() {
    if (index < text.length) {
       contentElement.textContent += text.charAt(index);
       setTimeout(displayText, 130);
  displayText();
</script>
  <div class="container" style="justify-content: center;">
  <div id="upload-form" class="no-background-image">
    <h2 style="text-align: center;color: white;font-size: 30px;">Upload Video</h2>
    <form method="post" enctype="multipart/form-data" action="/upload">
      <input type="file" name="file">
      <input type="text" name="scrollValue" value="{{ scrollValueText }}" style="display:</pre>
none;" id="scrollValueInput">
      <input type="submit" value="Upload" class="getStarted">
   </form>
   </div>
   <div id="scroll-bar-container">
    <div id="scroll-bar">
      <div id="scroll-bar-track"></div>
      <div id="scroll-bar-thumb"></div>
      <div id="drag-handle"></div>
    </div>
    <div id="scroll-value">0</div>
   </div>
</body>
</html>
```

- The User Interface for the application is developed using Flask framework.
- The first page of the User interface uploader.html contains a tab to browse and upload the video. The uploaded video is then passed to the model and prediction is made by the model. The model returns the output whether the video is real or fake along with the confidence of the model. The output is rendered in the results.html of the face of the playing video.

CHATPER-6 OUTPUT SCREENS

6.1 OUTPUT SCREENS

Fig no.6.1.1 Output Screen

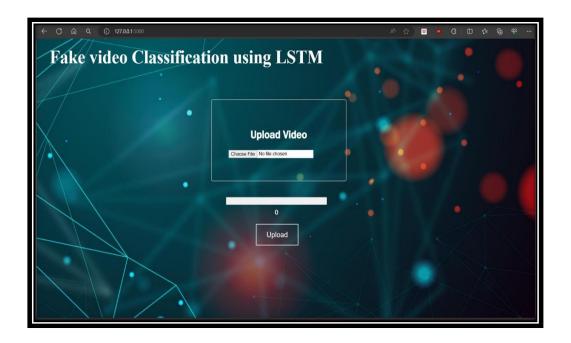


Fig no.6.1.2 Web Interface

1. When uploading the Fake video it gives the following output



Fig.no 6.1.3 Fake video output

2. When uploading the Real video it gives the following output



Fig.no 6.1.4 Real video output

CHAPTER-7

RESULTS AND DISCUSSIONS

Model Performance

In this section, we present the performance metrics of the fake video classification model, including the training and validation loss, training and validation accuracy, and the confusion matrix.

1. Training and Validation Loss:

Training and validation loss are calculated to evaluate how well the model is learning and generalizing. The loss is typically calculated using a loss function such as cross-entropy loss for classification problems.

• Cross-Entropy Loss: This loss measures the performance of a classification model whose output is a probability value between 0 and 1.

Loss=
$$-N1\sum_{i=1}^{N} [yi \log(pi)+(1-yi) \log(1-pi)]$$

where yi is the true label, pi is the predicted probability, and N is the number of samples.

2. Training and Validation Accuracy:

• Accuracy is a measure of the number of correct predictions made by the model divided by the total number of predictions. It is calculated as follows:

Accuracy=Total Number of Predictions/Number of Correct Predictions

3. Confusion Matrix:

- The confusion matrix is a table used to describe the performance of a classification model on a set of test data for which the true values are known. It includes four components:
- 1. True Positives (TP): The number of correct positive predictions.
- 2. True Negatives (TN): The number of correct negative predictions.
- 3. False Positives (FP): The number of incorrect positive predictions.
- 4. False Negatives (FN): The number of incorrect negative predictions.

Using these components, several metrics can be derived:

From the fig 5.1.3, fig 5.1.4, fig 5.1.5 the values are:

True Positives (TP): 52

True Negatives (TN): 58

False Positives (FP): 5

False Negatives (FN): 9

Precision:

Precision=TP/TP+FPPrecision= $52/52+5=52/57\approx0.9123$

Recall (Sensitivity):

Recall=TP/TP+FN

Recall= $52/52+9=52/61\approx0.8525$

F1 Score: The harmonic mean of precision and recall.

F1 Score=2×(Precision×Recall / Precision+Recall)

F1 Score=2×(0.9123x0.8525 / 0.9123+0.8525) ≈ 0.8817

Overall Accuracy:

Accuracy=TP+TN / TP+TN+FP+FN

Accuracy=52+58 / 52+58+5+9=110/124≈0.8871

This results in an overall accuracy of approximately 88.71%.

So, the calculated values are:

• Precision: ≈0.9123

Recall: ≈0.8525
F1 Score: ≈0.8817

• Overall Accuracy: ≈0.8871

4. Confidence Percentage:

For each video classified as real or fake, the model also provides a confidence percentage indicating the certainty of the prediction. This confidence score helps in assessing the reliability of each prediction.

By presenting these results, we can see that the model performs well with an overall accuracy of approximately 88.71%. The training and validation metrics indicate that the model has learned effectively and generalizes well to new data. The confusion matrix provides a detailed view of the classification performance, highlighting the balance between correctly identified real and fake videos. Other performance metrics such as precision, recall, and F1 score further validate the effectiveness of the model.

CHAPTER 8

CONCLUSION

The culmination of the fake video classification project employing LSTM models offers a compelling narrative of progress in the ongoing battle against visual misinformation. Through meticulous experimentation and analysis, the project has unveiled the potential of LSTM architectures to discern between authentic and manipulated video content with notable accuracy. By harnessing the temporal dependencies ingrained within video sequences, the LSTM model exhibits a remarkable ability to detect nuanced alterations and fabrications, thereby enhancing its utility in combating the proliferation of fake videos across digital platforms. Despite encountering challenges such as dataset imbalance and varying degrees of manipulation complexity, the project adeptly navigated these obstacles through rigorous data preprocessing and model optimization, ultimately reinforcing the credibility of its findings. Methodologically, the decision to employ LSTM proves astute, leveraging its innate capacity to capture long-term dependencies within sequential data, a crucial asset in decoding the nuanced patterns present in fake videos. The project's methodology underscores the significance of meticulous feature engineering, model architecture optimization, and robust evaluation protocols in achieving reliable and interpretable results. Looking ahead, the project not only opens avenues for further refinement and enhancement of LSTM-based approaches but also underscores the interdisciplinary significance of collaboration between machine learning experts, multimedia analysts, and information verification specialists in combating visual misinformation. In essence, the project represents a milestone in the quest to safeguard the integrity and credibility of visual content in an era characterized by the rapid dissemination of digital misinformation.

CHAPTER-9

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