

SENSOR-LAB-1

Sensor-lab EE3901

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Design and Analysis of an Instrumentation Amplifier (INA)

Introduction:

Instrumentation amplifiers (INAs) are designed to amplify small differential signals while rejecting common-mode signal/noise. They are commonly employed in sensor signal conditioning, biomedical instrumentation, and industrial measurement systems where accurate, high common-mode rejection ratio (CMRR), and low-noise signal amplification are essential. The most popular INA configuration utilizes three operational amplifiers, providing high input impedance, precise gain control, and excellent common-mode rejection ratio (CMRR).

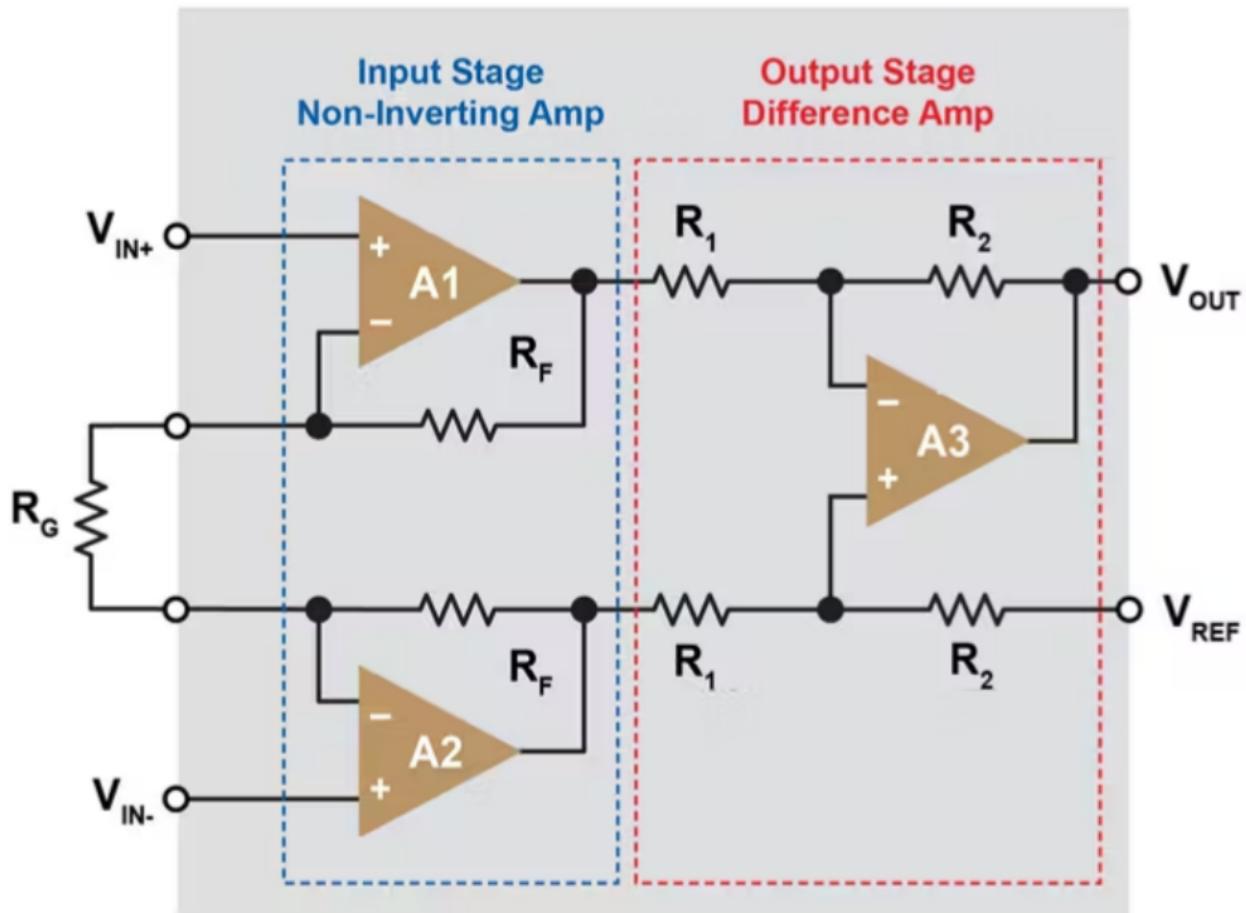


Fig. 1. Instrumentation amplifier circuit [ref](#). Set $R_F = R_1 = R_2 = R$. A1 to A3 are opamps.

Components used:

- MCP6004 IC - 1
- ADA LM1000 Kit - 1
- 10 k Ω resistors - 7
- Potentiometer - 2
- Digital multimeter - 1
- Wires - [Red, Black, Yellow]

Circuit design and Calculations

★ Difference input (V_d) = $V_1 - V_2$

★ $CMRR(V_o) = G_1(V_1 - V_2)$ → difference mode gain
 where, $CMRR, \rho = \frac{A_d}{A_c}$ → common mode gain

CMRR is the ability of the amplifier to reject common mode signals.

★ Common Mode Input (V_c) = $\frac{V_1 + V_2}{2}$

Also, • $\rho_{ideal} = \infty$

$$\bullet P_{dB} = 20 \log_{10} \left(\frac{A_d}{A_c} \right)$$

$$\bullet V_o = A_d V_d + A_c V_c$$

Difference Amplifier

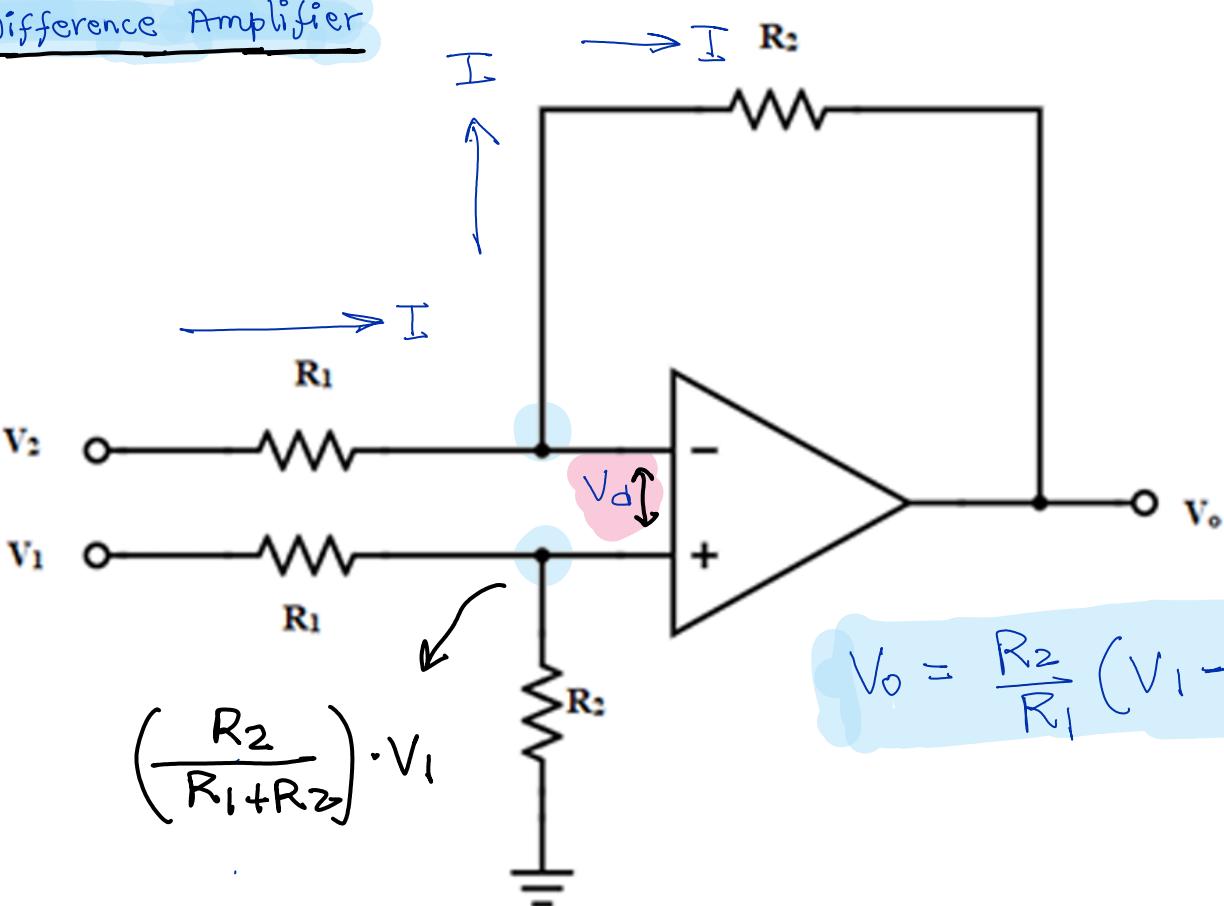


Fig-2

In general, with different R values

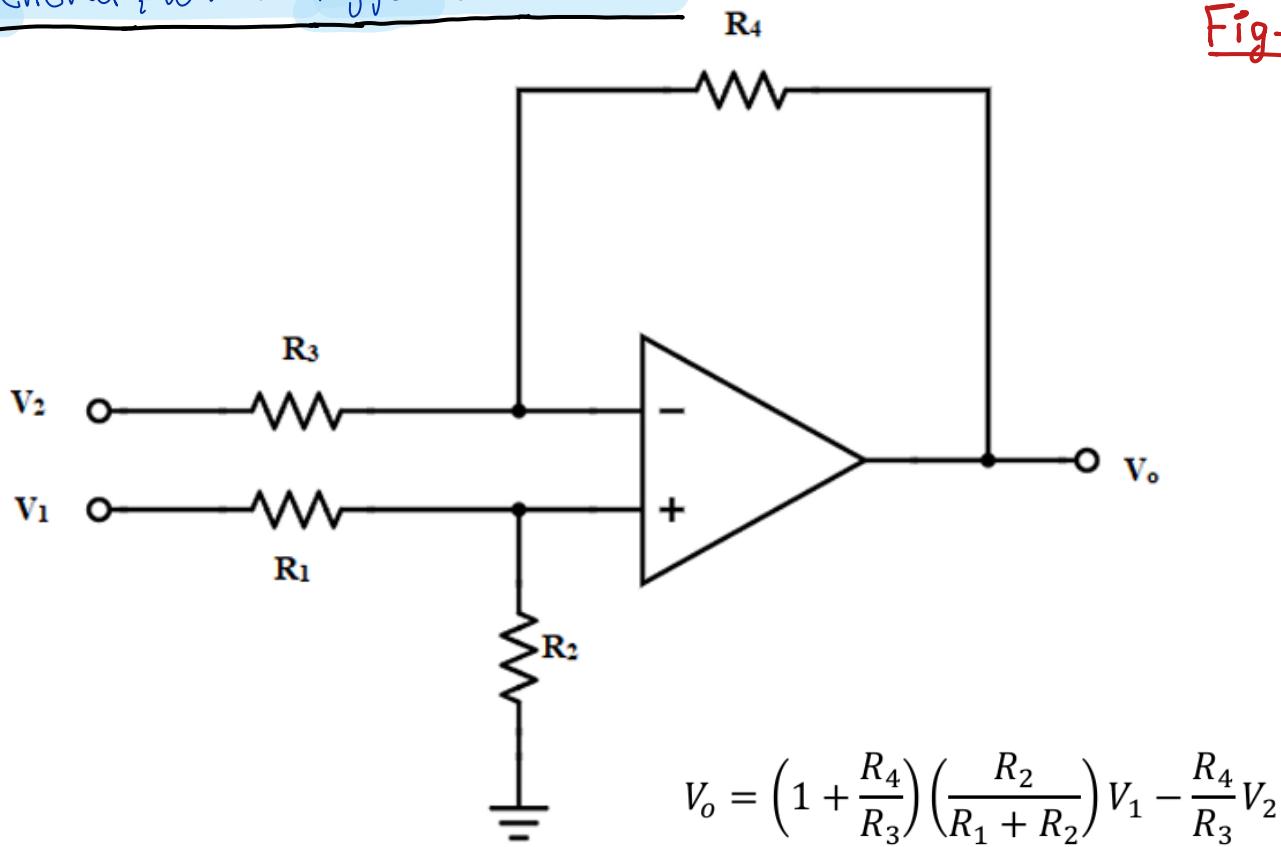
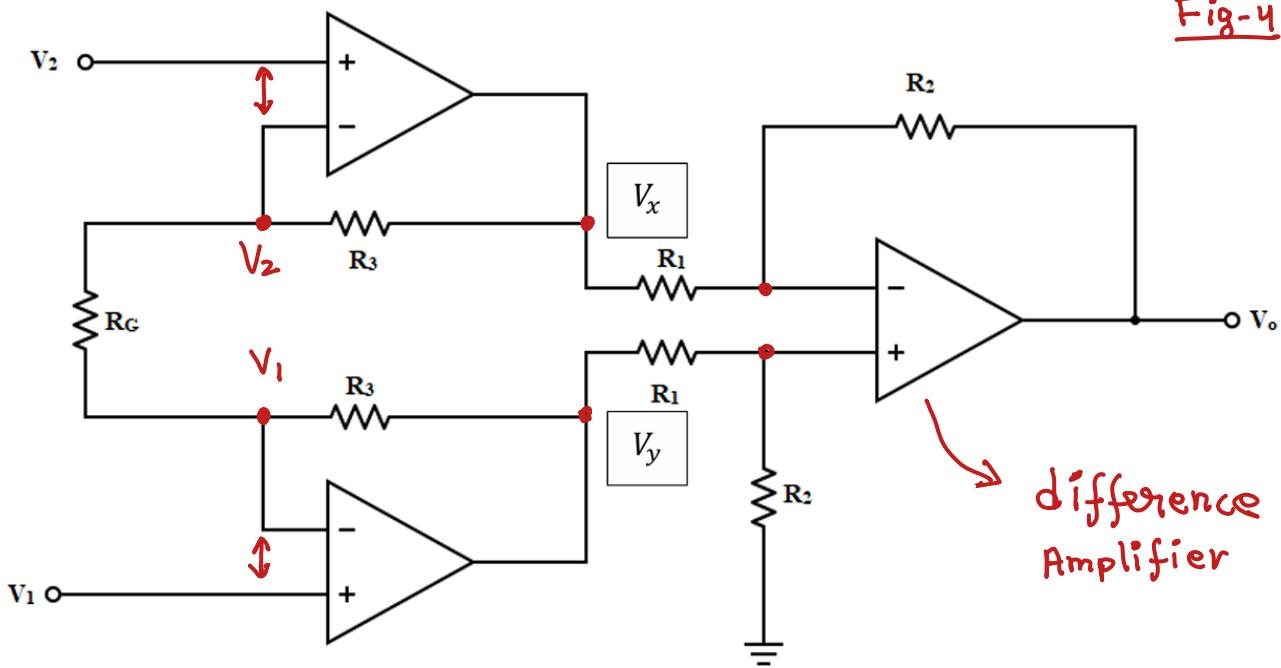


Fig-3

Instrumentation Amplifier (INA)



$$V_x = \left(1 + \frac{R_3}{R_{G1}}\right)V_2 - \frac{R_3}{R_{G1}}V_1 \quad ; \quad V_y = \left(1 + \frac{R_3}{R_{G1}}\right)V_1 - \frac{R_3}{R_{G1}}V_2 \quad ; \quad V_o = \frac{R_2}{R_1} (V_y - V_x)$$

$$V_o = \frac{R_2}{R_1} \left[\left(1 + \frac{R_3}{R_{G1}}\right)V_1 - \frac{R_3}{R_{G1}}V_2 - \left(1 + \frac{R_3}{R_{G1}}\right)V_2 + \frac{R_3}{R_{G1}}V_1 \right]$$

$$V_o = \frac{R_2}{R_1} \left[\left(1 + \frac{2R_3}{R_{G1}}\right)V_1 - \left(1 + \frac{2R_3}{R_{G1}}\right)V_2 \right] \Rightarrow V_o = \frac{R_2}{R_1} \left(1 + \frac{2R_3}{R_{G1}}\right) [V_1 - V_2]$$

It is given that, $R_1 = R_2 = R_3 = R = 10k\Omega$, So,

$$V_o = \left(1 + \frac{2R}{R_{G1}}\right) [V_1 - V_2] \Rightarrow \frac{V_o}{V_1 - V_2} = 1 + \frac{2 \times 10k}{R_{G1}} \Rightarrow R_{G1} = \frac{20k}{2} = 10k$$

\downarrow
 $A_d = 3$

Expression when $V_1 = V_2 = 0V$ and $V_{ref} = 2.5V$

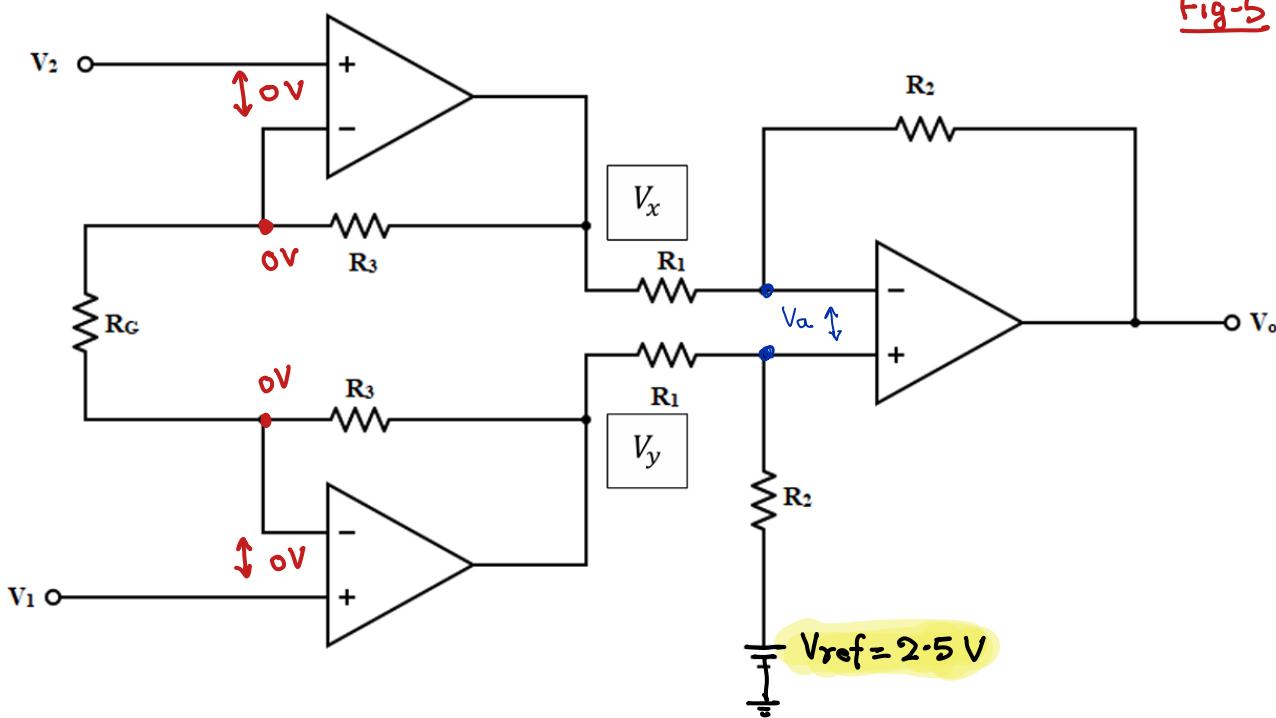


Fig-5

Since $V_o = \frac{R_2}{R_1} (V_y - V_x)$, and by symmetry $V_x = V_y$

Also, adding the effect of V_{ref} , by eqns forming -

$$\Rightarrow \frac{V_y - V_a}{R} = \frac{V_a - 2.5}{R}$$

$$\Rightarrow V_y = 2V_a - 2.5$$

$$\Rightarrow \frac{V_x - V_a}{R} = \frac{V_a - V_o}{R}$$

$$\Rightarrow V_x = 2V_a - V_o$$

Comparing, both above equations,

$$V_o = 2.5V$$

If $V_{REF} \neq 0V$ and $R_1 = R_2 = R_F = R$

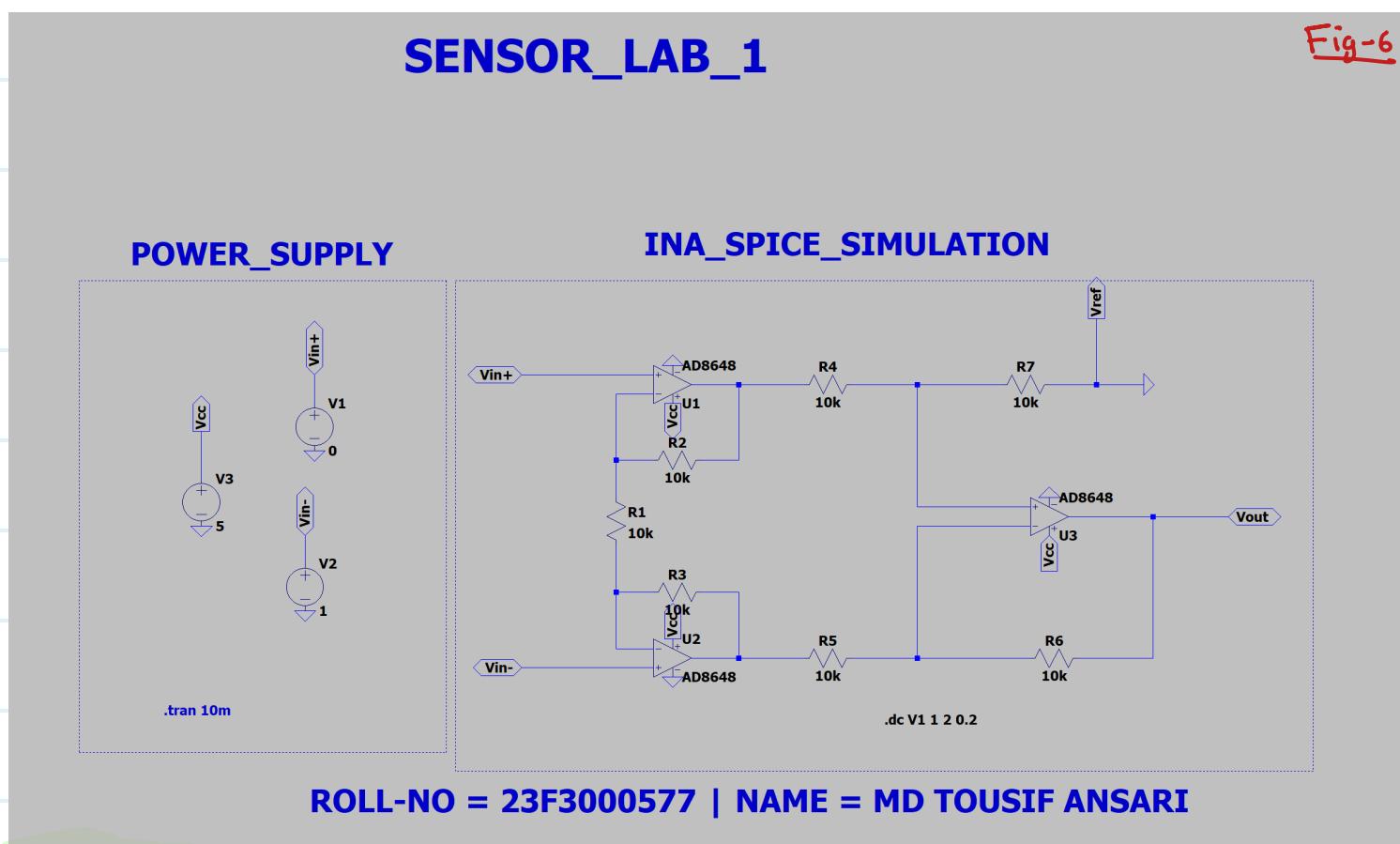
$$V_o = \left(1 + \frac{2R}{R_G}\right) V_d + \left(1 + \frac{R}{R}\right) \frac{1}{2} V_{ref}$$

$$V_o = \left(1 + \frac{2R}{R_G}\right) V_d + V_{ref}$$

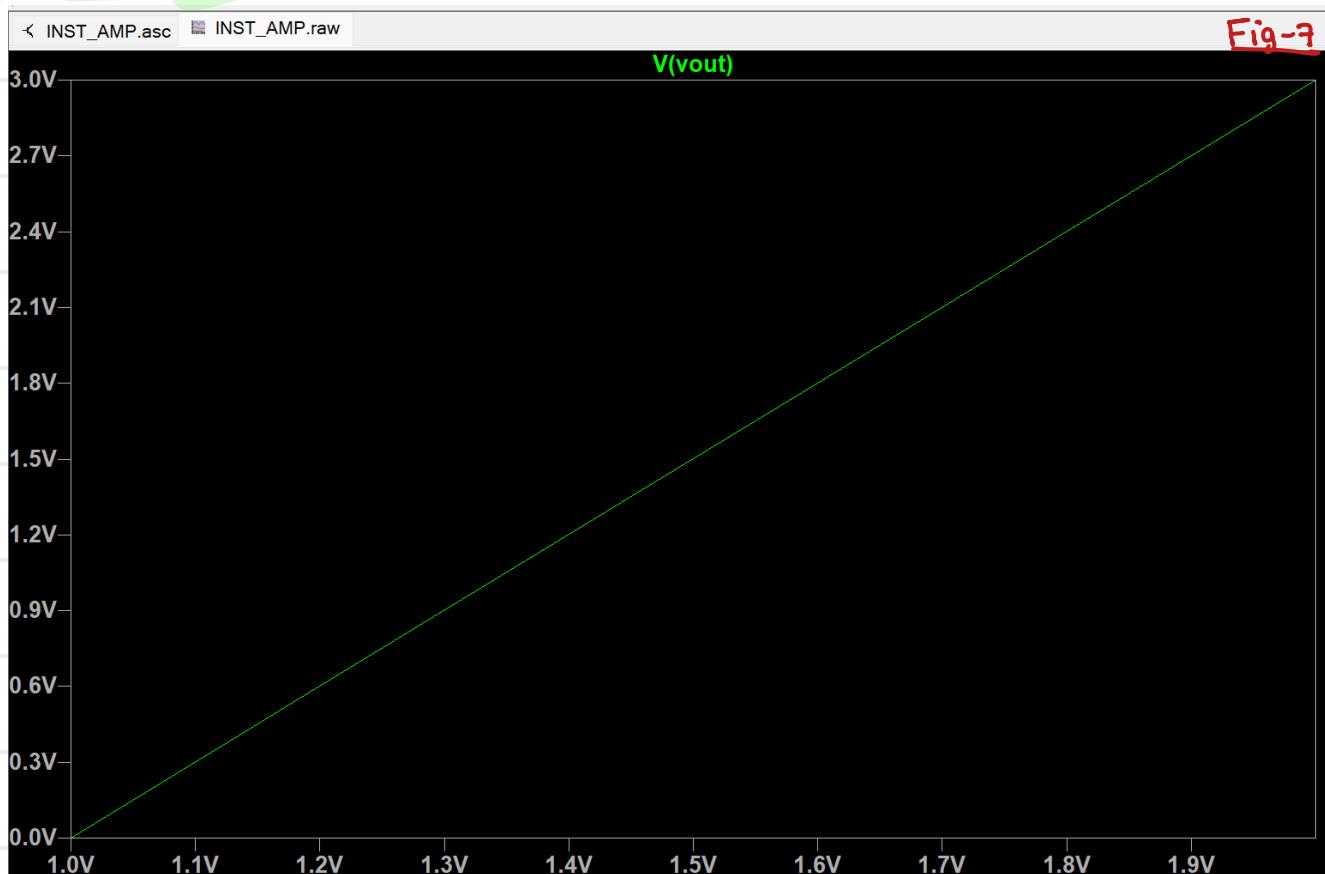
→ Also using these equation when $V_{ref} \neq 0$

$$V_1 = V_2 = 0 \Rightarrow V_d = (V_1 - V_2), \text{ so, } V_o = V_{ref}$$

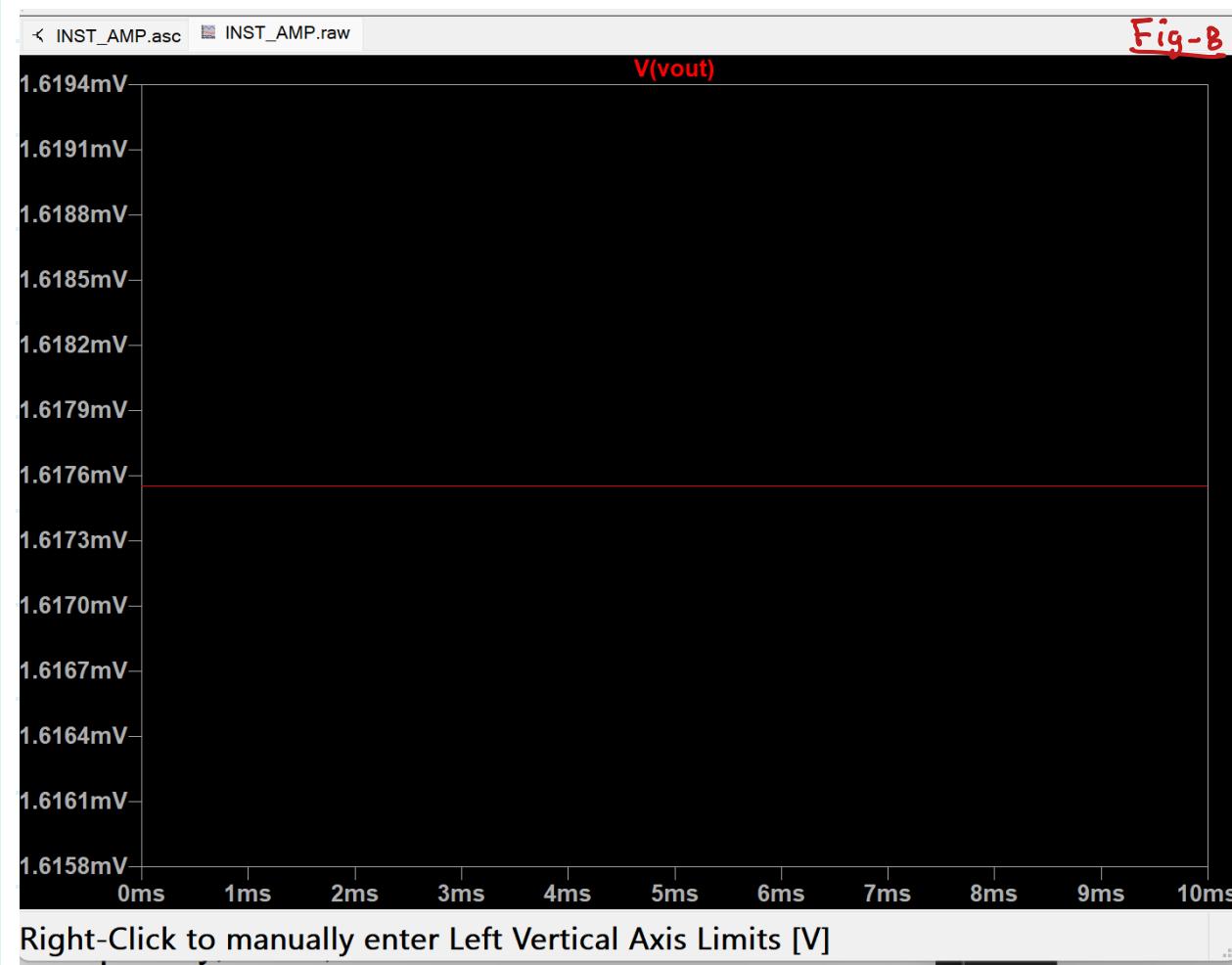
Simulation screenshots and associated voltage waveforms



Output



Output when $V_{in+} = V_{in-} = 1.5 \text{ V}$ {Simulation}



★ Common mode Gain:

$$A_{cm} = V_{out} / V_{cm}$$

$$A_{cm} = 1.6 \text{ mV} / 1.5 \text{ V}$$

$$A_{cm} = 0.0010667$$

★ CMRR

$$CMRR = R_d / A_{cm}$$

$$CMRR = 3 / 0.0010667$$

$$CMRR = 2812.5$$

Circuit Simulation { $V_{in+} = V_{in-} = 0$, $V_{ref} = 2.5V$ }

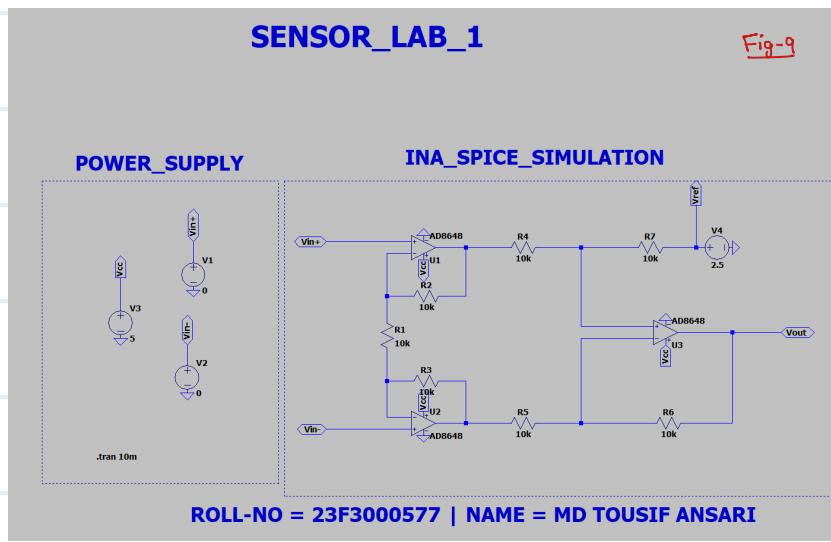


Fig-9



Fig-10

$$V_{out} = 2.5 \text{ V}$$

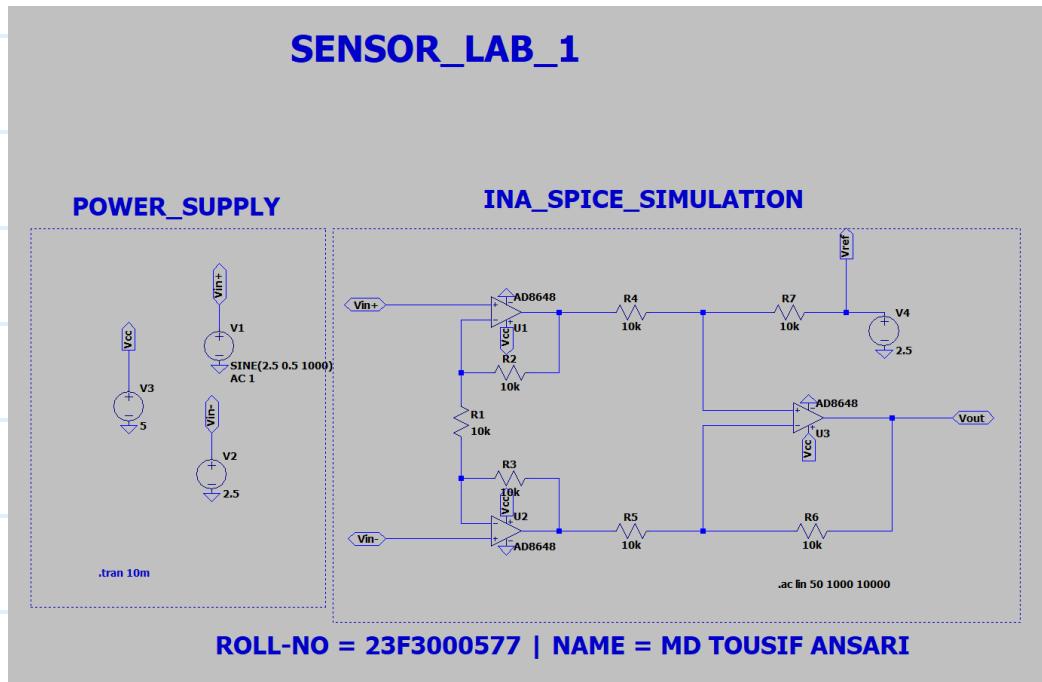
Frequency Analysis

→ To do so, we set, $V_d = 0.5 \sin(2\pi ft)$ and varying frequency. [1 kHz - 10 kHz]

→ Differential Gain Can be calculated using,

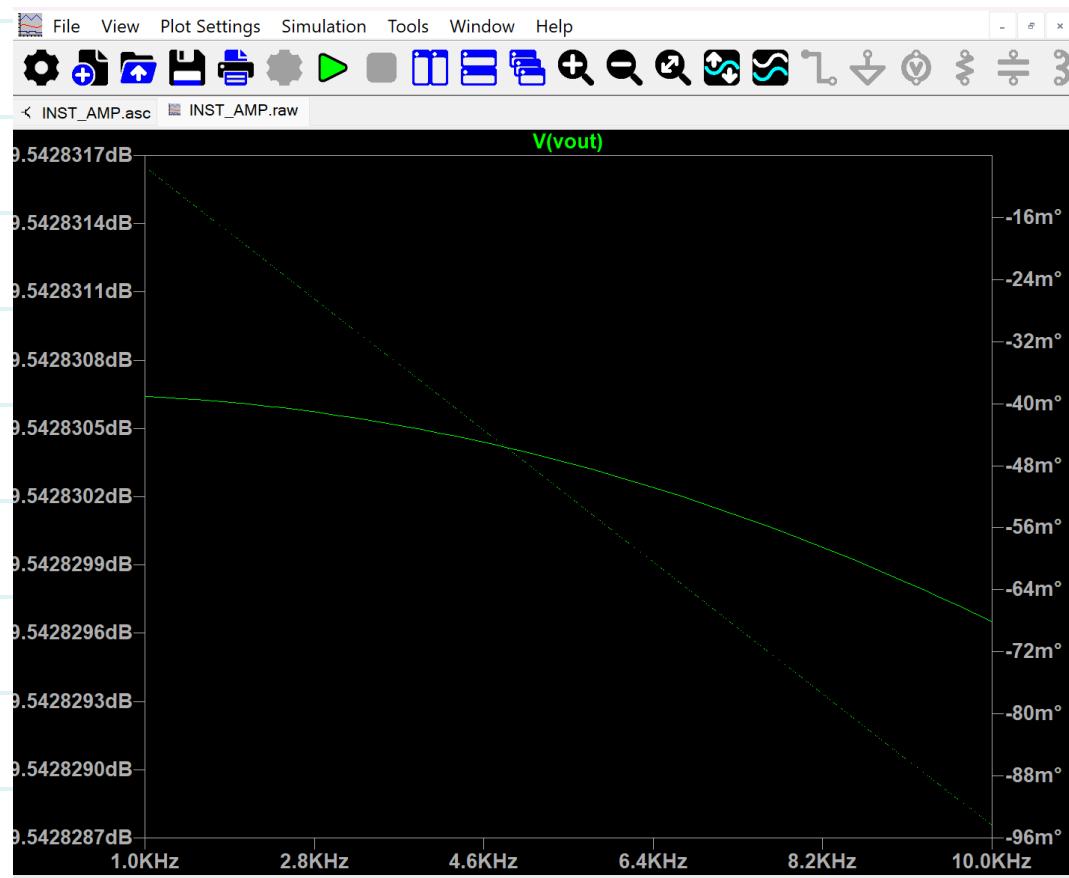
$$A_d = \frac{V_{out}}{V_d}$$

Simulation



Frequency response

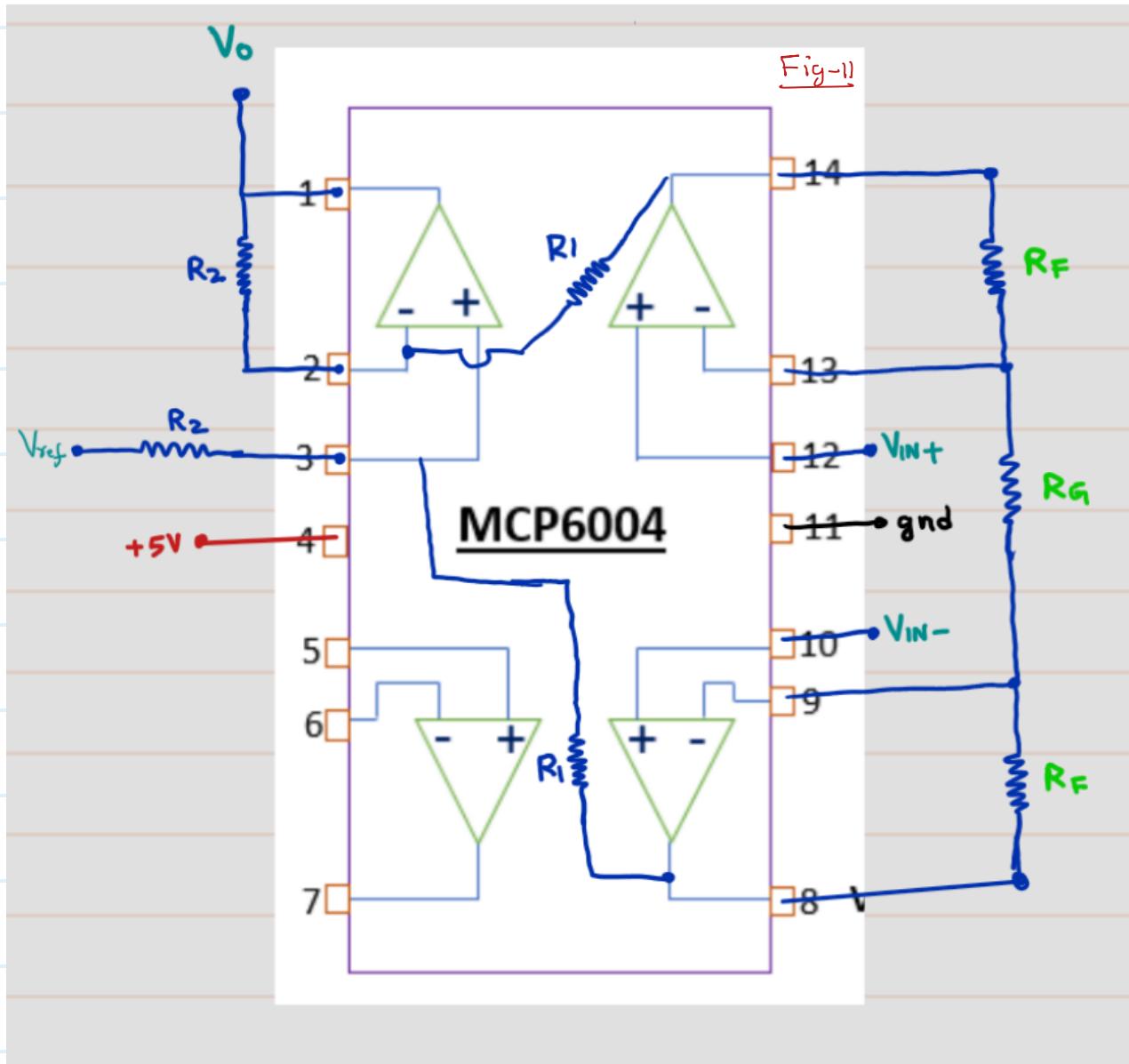
Simulation



Gain Remains Constant as we change frequency.

Photographs of the experimental setup, including the breadboard with the assembled circuit.

• Pin Diagram



INA Pin Diagram

All R are $10\text{ k}\Omega$ [$V_{in+} = 1\text{ V}$; $V_{in-} = \{1-2\}\text{ V} \{0.2\}$ varying ; $V_{ref} = 0\text{ V}$]

Breadboard View

All $10\text{k}\Omega$ Resistors are used.

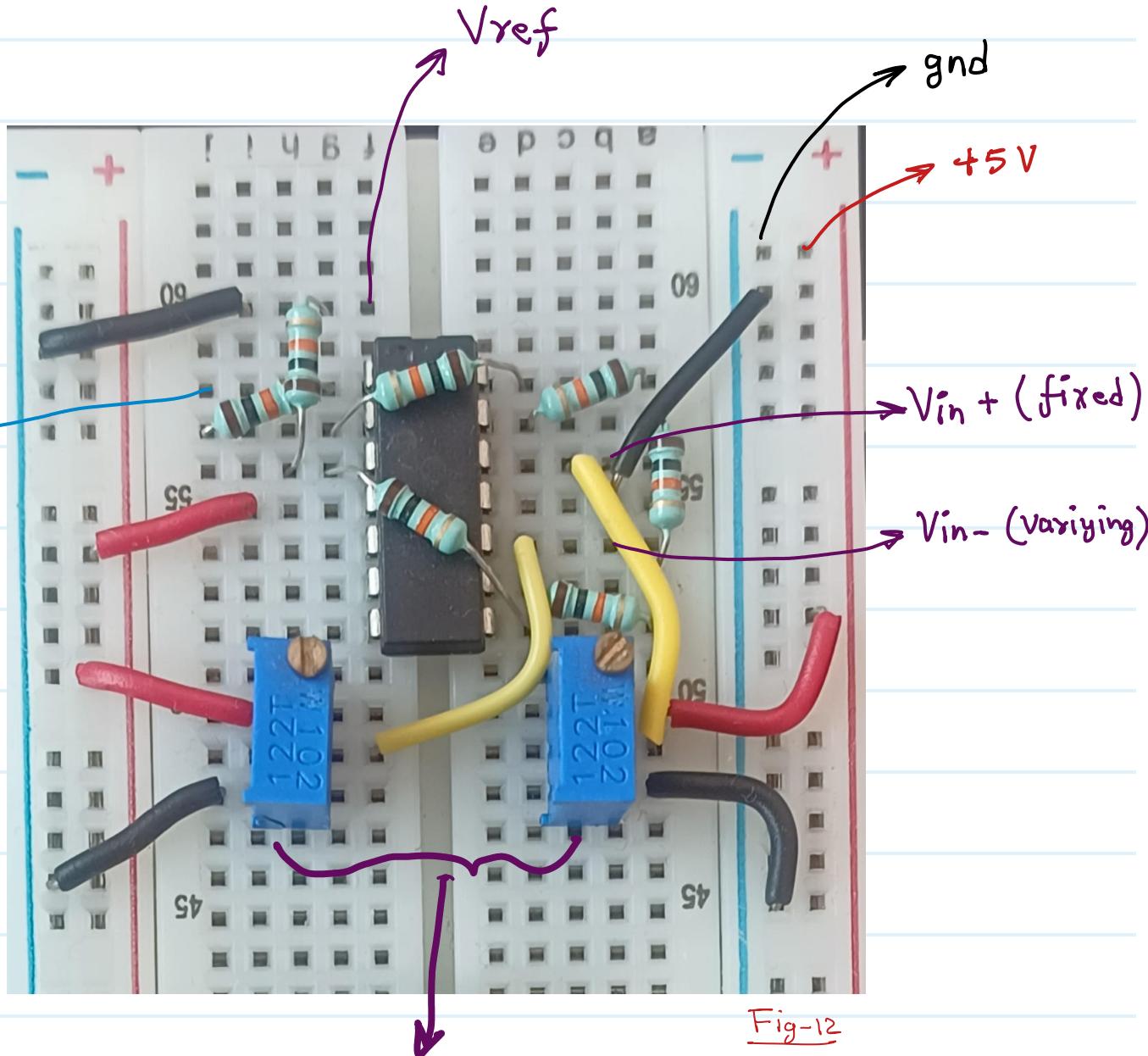


Fig-12

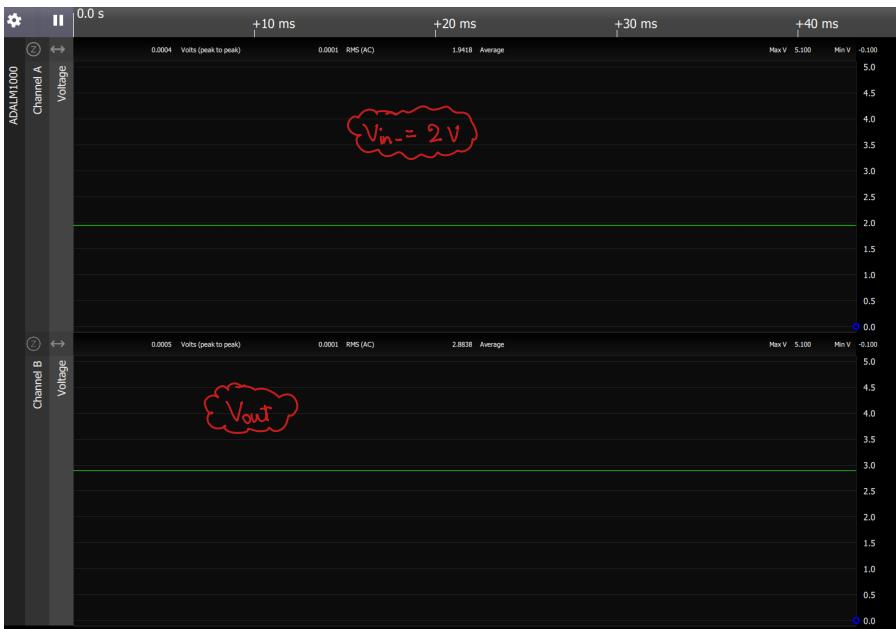
Potentiometer (10k)



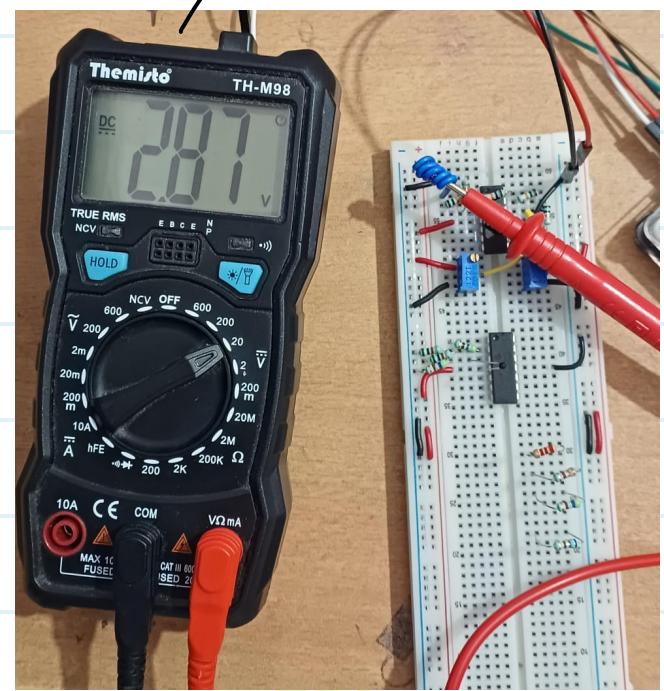
For varying voltage from
 $[1 \rightarrow 2 \text{ V}]$

Output $[V_{in+} = 1V, V_{in-} = \{1 \rightarrow 2\}V, V_{ref} = 0V]$

★ $V_{int} = 1V ; V_{in-} = 2V$

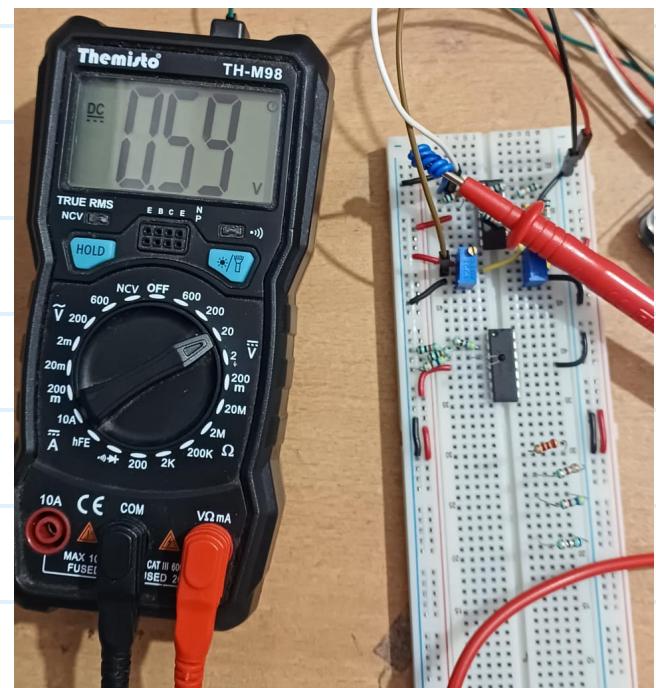


Adalm1000 output



Multimeter

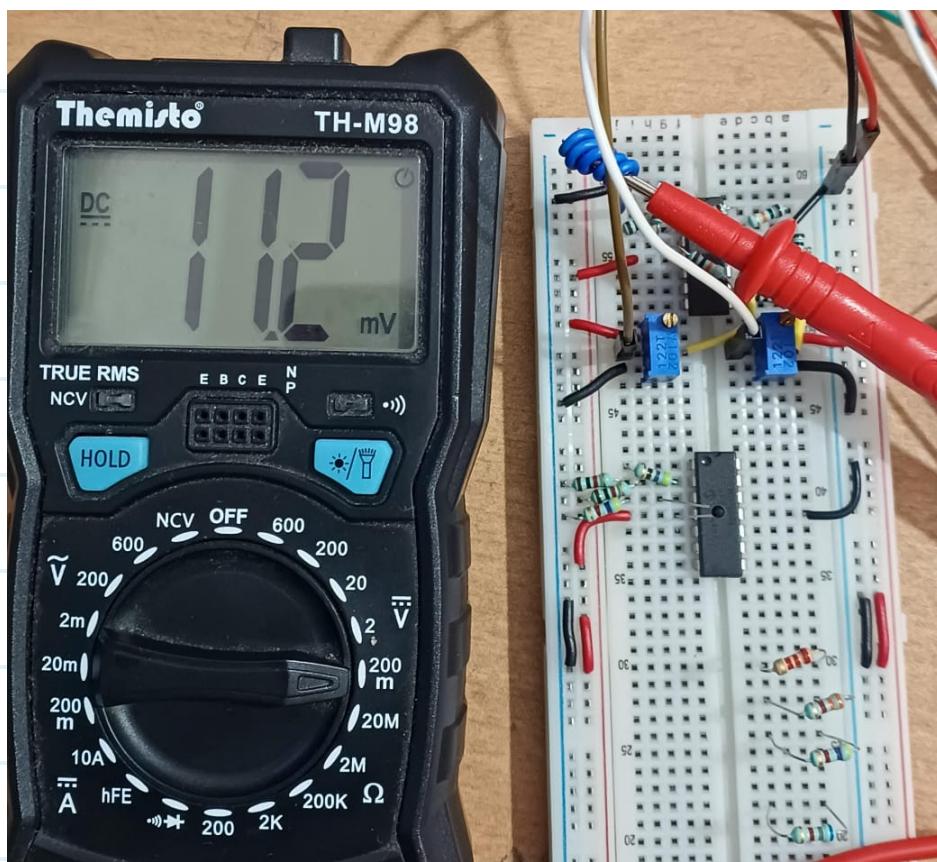
★ $V_{int} = 1V ; V_{in-} = 1.2V$



Output $V_{in+} = V_{in-} = 1.5 \text{ V}$, $V_{ref} = 0 \text{ V}$



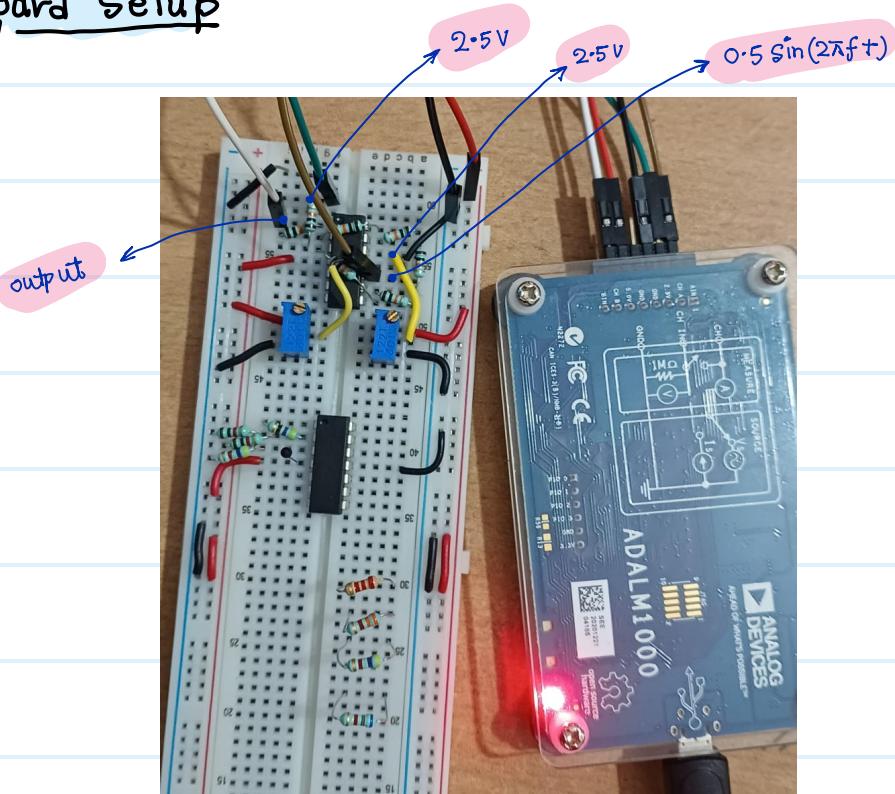
We notice it is a little bit above zero



* In multimeter we get V_{out} as 11.2 mV whereas in simulation we got 1.6 mV

Frequency Response Output

BreadBoard Setup



Adalm1000[Output]

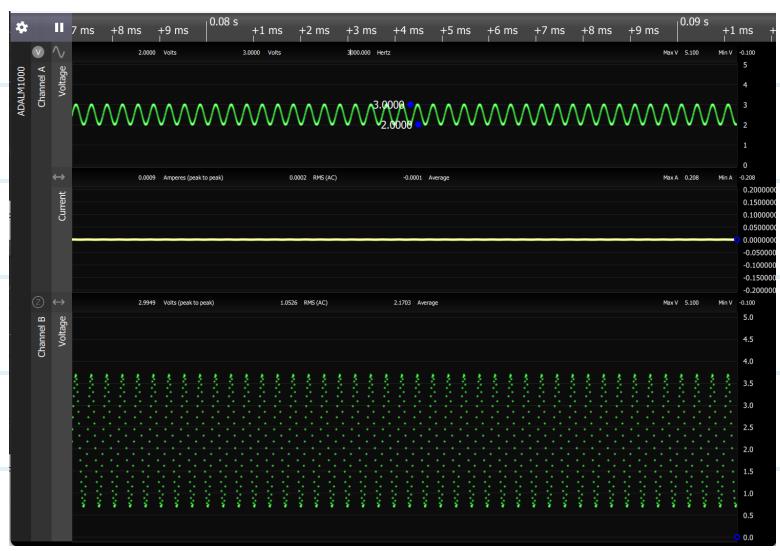
★ Frequency = 1000 Hz



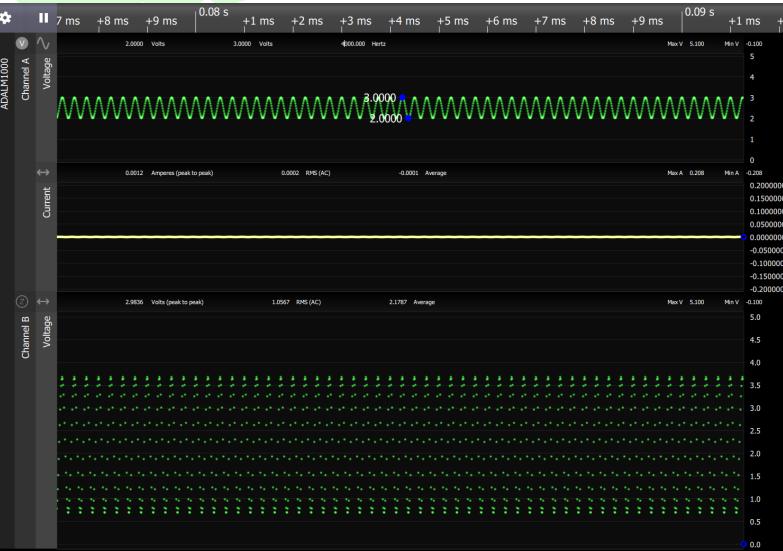
★ Frequency = 2000 Hz



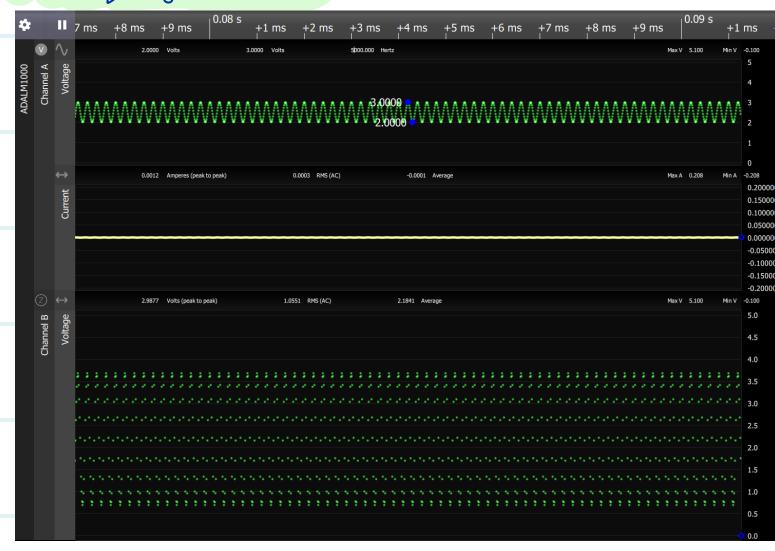
★ Frequency = 3000 Hz



★ Frequency = 4000 Hz

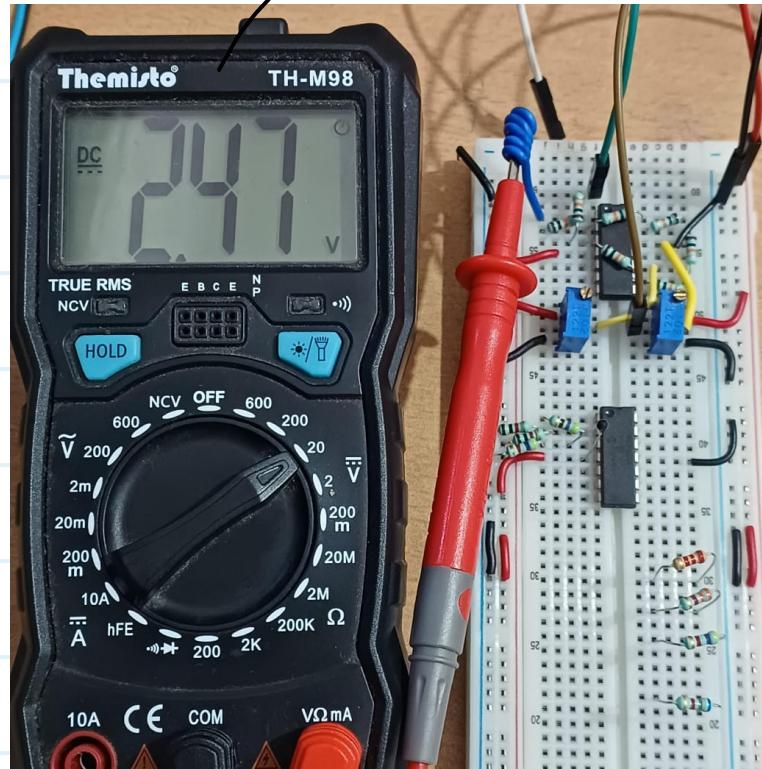


★ Frequency = 5000 Hz



Output $V_{in+} = V_{in-} = 0V$; $V_{ref} = 2.5V$

Multimeter output
 $V_o = 2.47V$



Deviation between Calculated values i.e $V_o = 2.5V$ and Actual value

$V_o = 2.47V$