

# Weekly Meeting (20.02.2026)

**Workers attendees:** Pierre-Yves, Alexandre, Jeremy, Cédric, Marco, Nathan, Kevin, Louis  
**Direction attendees:** Louis Lettru, Cédric Travelletti

**Time:** 10h00

**Scribes :** Jeremy & Louis

## Critics received :

### General

#### Presentation

- Transform the flowchart diagramm to a more transversal one
- When defining milestones, always have precise validation criterias
- Link work presented directly with milestones list
- Have local conclusions for each team part
- Continue to always display findings with tests results
- Add bullet points to slides, to help coming back in the future
- When presenting milestones, always with visual DONE/TODO
  - if still in TODO then also add the blockers
- Always present existing sources of a displayed information

#### Organisation

- a locally flat duck will help for the coloring part (in prototype)
- when testing something - push up to 5-10 cases to be able to quantify complexity
- arguing about « what we will produce/not produce » is only a client's privilege
- being an expert able to manipulate the client
- Be careful that tasks don't overlap each others (e.g. research conducted by GenAI and Tracing teams)
- Pen type must be ASAP steps
- Define the interfaces
- Define the robot solution (e.g. know which move type command will suffice )

#### Research tips

- use a promise paper's reference in Google scholar to find recent development in the field

### Team focused

#### GenAI

- the client prompt could be internally updated before being sent to generative model
- Try more realistic model in generation tests
- Synthesise state of research results

#### Tracing

- limiting the color panel and/or patterns
- **discretisation :** attention to contiguous zone **size** : not smaller than the pen tip

#### robot

- Add a visual about the simulation's environment and robot environment
- Add a visual (disc into disc) about the robot range