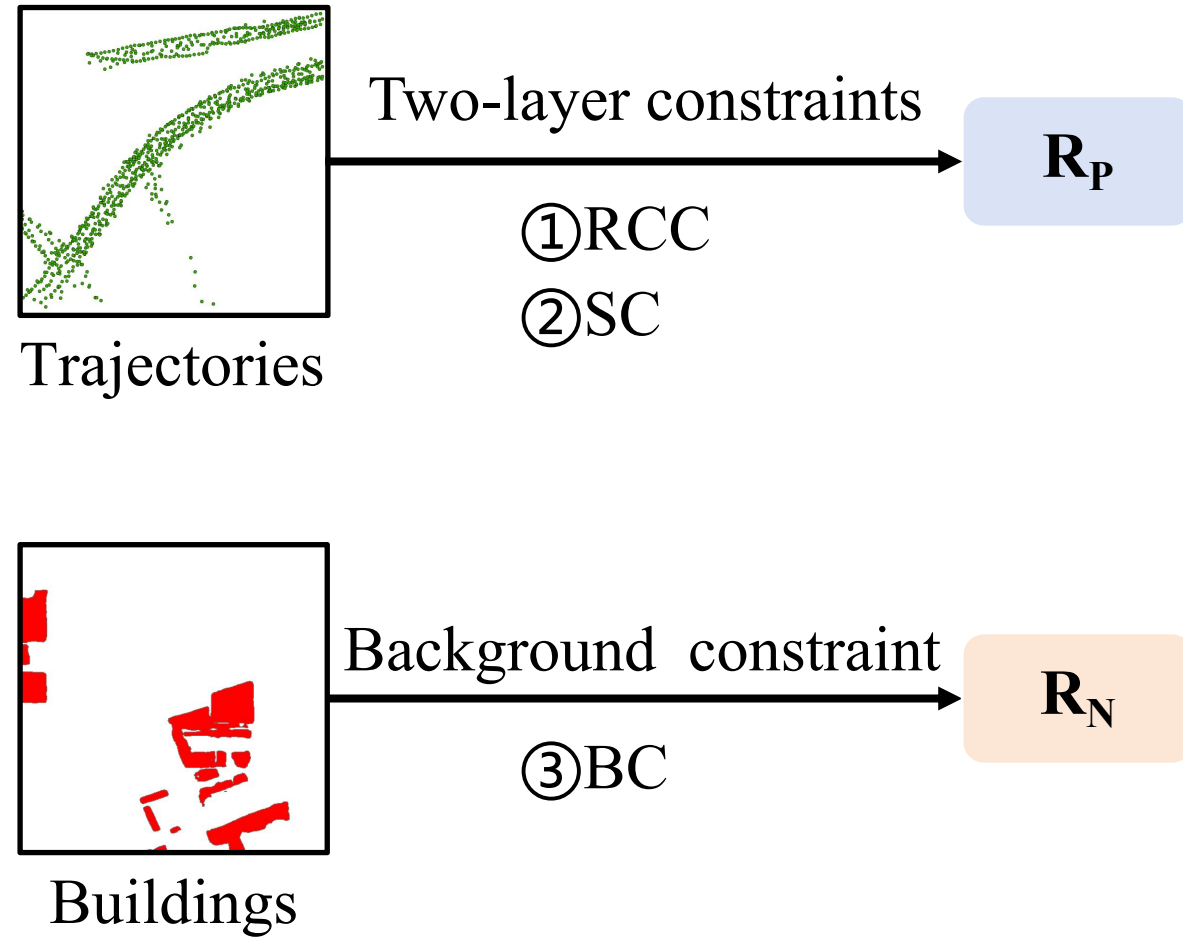
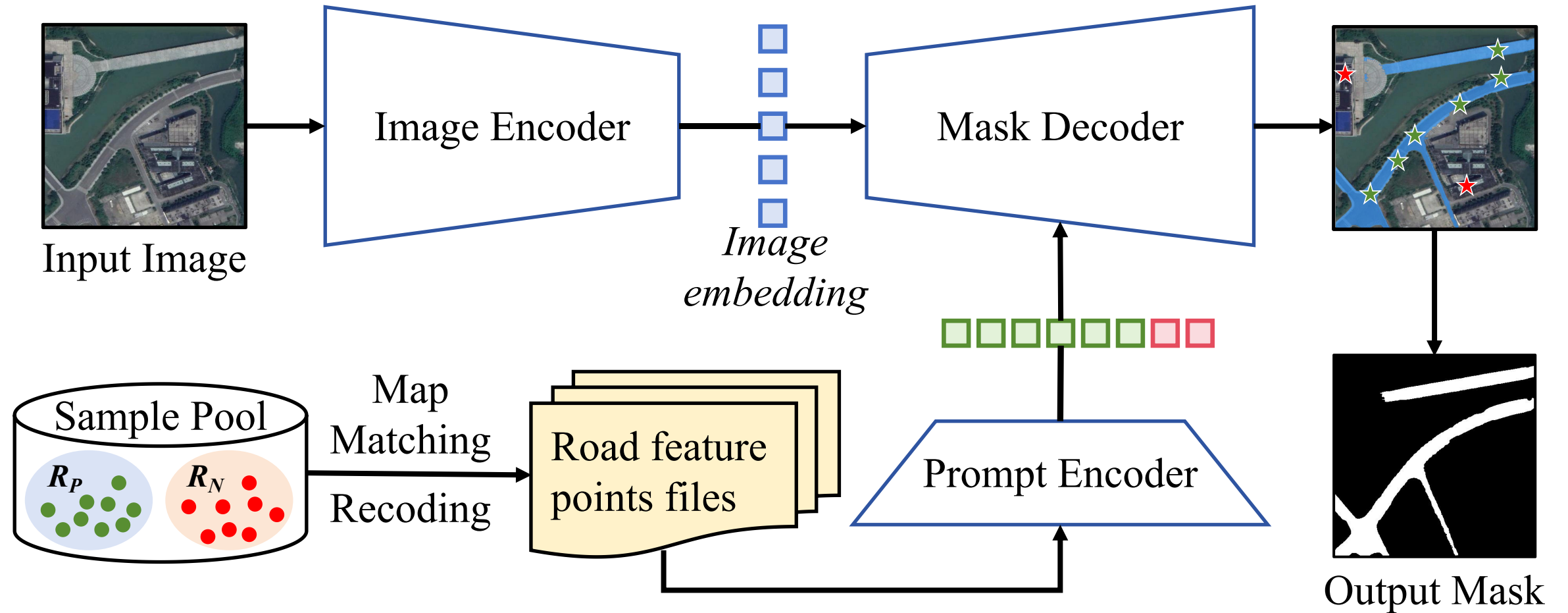


(a) Road feature points selection



(b) Road segmentation



$R_P$  Road positive feature points

$R_N$  Road negative feature points