CPE301 - SPRING 2018

Design Assignment X

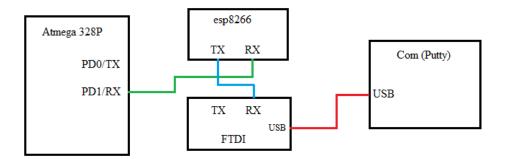
DO NOT REMOVE THIS PAGE DURING SUBMISSION:

The student understands that all required components should be submitted in complete for grading of this assignment.

NO	SUBMISSION ITEM	COMPLETED (Y/N)	MARKS (/MAX)
1	COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS		
2.	INITIAL CODE OF TASK 1/A		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 2/B		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 3/C		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 4/D		
3.	INCREMENTAL / DIFFERENTIAL CODE OF TASK 5/E		
4.	SCHEMATICS		
5.	SCREENSHOTS OF EACH TASK OUTPUT		
5.	SCREENSHOT OF EACH DEMO		
6.	VIDEO LINKS OF EACH DEMO		
7.	GOOGLECODE LINK OF THE DA		

1. COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS

The components used in this project were the Atmega xplained mini, a FTDI chip, the esp8266 wifi chip, and the lm34 temperature sensor/



I have the Atmega xplained mini writing to the esp8266(For some reason It would only work when I connected the RX port of the mini to the RX port of the esp8266) and the esp8266 writing to the FTDI chip which would display what the esp8266 was writing back on putty.

2. INITIAL/DEVELOPED CODE OF TASK 1/A

```
* DAMidterm.c
 * Created: 3/26/2018 9:04:20 PM
 * Author : trace
#include <avr/io.h>
#include <avr/interrupt.h>
#define F_CPU 1600000L
#include <util/delay.h>
#include <stdlib.h>
#define BAUD 9600
volatile int ovrflw; // global variable for keeping track of # of times Timer0 overflows
volatile uint8 t ADCvalue; // Global variable, set to volatile if used with ISR
// functions
void initUART();
void writeChar(unsigned char c);
void writestring(char *c);
void writefloat(float c);
int main(void){
      initUART();
                           // Initialize UART
      // initialize ADC
                                  // Set PORTC as input for adc
      DDRC = 0;
      DIDR0 = 0x1;
                           // Disable digital input on ADC0 pin
```

```
ADMUX = 0; // ADC0 (PC.0) used as analog input
ADMUX |= (1 << REFS0); // use AVcc as the reference
ADMUX |= (1 << ADLAR); // Right adjust for 8 bit resolution
       ADCSRA = 0x87; // Enable ADC,
ADCSRB = 0x0; // Free running mode
                                     // Enable ADC, system clock, 10000111
       // initialize timer0 with starting value of 0, normal mode with no prescaler
       TCNT0 = 0;
       TCCR0A = 0;
       TCCR0B |= 2;
       // enable interrupts
       TIMSK0 |= (1 << TOIE0); // enable overflow interrupt
                                                   // enable global interrupts
       sei();
       while (1);
       return 0;
}
void initUART() {
       unsigned int baudrate;
       // Set baud rate: UBRR = [F CPU/(16*BAUD)] -1
       baudrate = ((F CPU/16)/BAUD) - 1;
       UBRROH = (unsigned char) (baudrate >> 8);
       UBRROL = (unsigned char) baudrate;
                                                    // Enable receiver and transmitter
       UCSR0B |= (1 << RXEN0) | (1 << TXEN0);
       UCSR0C |= (1 << UCSZ01) | (1 << UCSZ00); // Set data frame: 8 data bits, 1 stop
bit, no parity
}
void writeChar(unsigned char c) {
       UDR0 = c;
                                     // Display character on serial (i.e., PuTTY) terminal
       _delay_ms(10);
                                     // delay for 200 ms
}
void writestring(char *c){
       unsigned int i = 0;
       while(c[i] != 0)
       writeChar(c[i++]);
}
// this interrupt service routine (ISR) runs whenever an overflow on Timer0 occurs
ISR (TIMER0_OVF_vect) {
       // Variable Declarations
       char output[6];
                                                                   // Output string based on
ADC
       float temperature;
                                                                   // Voltage received by ADC
then edited for Temperature
```

```
char *AT = "AT \r\n";
       char *CIPMUX = "AT+CIPMUX=0 \r\n";
       char *ATCW = "AT+CWJAP=\"SSID\",\"Password\" \r\n";
char *CIPSTART = "AT+CIPSTART=\"TCP\",\"api.thingspeak.com\",80 \r\n";
       char *CIPSEND = "AT+CIPSEND=44";
       char *SEND DATA = "GET /update?key=M52FZABUR6UTS03B&field2=";
       char *ENTER = "\r\n";
       if (ovrflw == 7500) {
              ADCSRA = (1 << ADSC);
                                                        // Start conversion
              while((ADCSRA&(1<<ADIF))==0); // Wait for conversion to finish
              ADCvalue = ADCH;
                                                  // Only need to read the high value for 8
bit then equation for Fahrenheit
              temperature = (ADCvalue * 5.0 / 256) * 100;
                                                              // Temperature
              dtostrf(temperature, 0, 0, output); // Float to char* conversion
              ovrflw = 0;
                                                 // reinitialize ovrflw
       delay ms(200);
       initUART(); // initialize usart
       _delay_ms(500);
       writestring(AT);
      _delay_ms(2000);
       writestring(CIPMUX); // Mux at command
       _delay_ms(5000);
       writestring(ATCW); // Connect to wifi
       _delay_ms(5000);
       writestring(CIPSTART); // Connect to website
       _delay_ms(5000);
       writestring(CIPSEND); // Send characters of get command
       writeChar('\r');
       writeChar('\n');
       _delay_ms(5000);
       writestring(SEND_DATA); // Send get command
       _delay_ms(1000);
      writestring(output); // Send Temperature value
       delay ms(500);
       writestring(ENTER); // enter line
       _delay_ms(1000);
       for(int i=0; i < 1000; i++)</pre>
       _delay_ms(1000); // 16 minute loop
       else
       ovrflw++; // increment ovrflw
```

3. SCHEMATICS

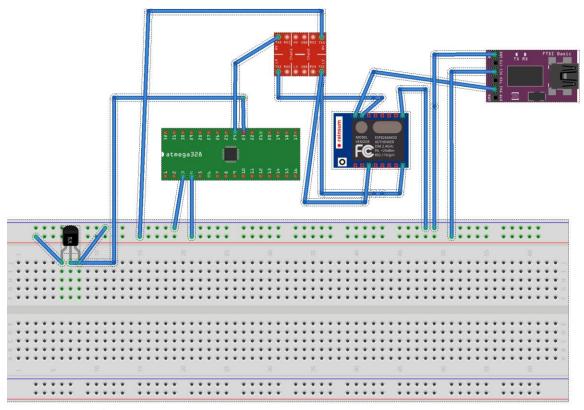


Figure 1: Fritzing Schematic

4. SCREENSHOTS OF EACH TASK OUTPUT (ATMEL STUDIO OUTPUT)

```
GET /update/key=M52F @ COM6 - PuTTY
char "ENTER = "\r\n";
if (ovrflw == 7500) {
                                               Unlink
     ADCSRA |= (1 << ADSC);
     while((ADCSRA&(1<<ADIF))==0); // AI
     Aucvalue = ADCH; // OnlyAT+CIPMUX=0

dtostrfftamore...

### CADCValue * 5.0 / 256
     dtostrf(temperature, 0, 0, output);
                                               AT+CWJAP="
                                // reinitia
  delay_ms(200);
                                               AT+CIPSTART="TCP", "api.thingspeak.com", 80
 initUART(); // initialize usart
 _delay_ms(500);
writestring(AT);
                                               AT+CIPSEND=44
> GET /update?key=M52FZABUR6UTS03B&field2=72
 _delay_ms(2000);
 writestring(CIPMUX);
  _delay_ms(5000);
 writestring(ATCW);
 _delay_ms(5000);
writestring(CIPSTART);
                                                IPD, 2:59
  _delay_ms(5000);
  writestring(CIPSEND);
  writeChar('\r');
writeChar('\n');
  _delay_ms(5000);
writestring(SEND_DATA);
  _delay_ms(1000);
writestring(output);
   _delay_ms(500);
   writestring(ENTER);
   _delay_ms(1000);
```

Figure 2: Screenshot of putty terminal



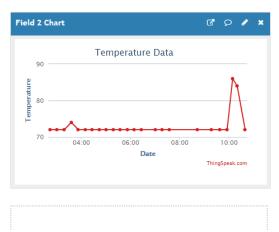


Figure 3: Temperature data graph on Thinkspeak

The temperature was very consistent so for the last couple of temperature reading I held onto the sensor to get some variance in the temperature as you can see with the spike at the end.

	Clippoard	-	ont	191		Alignme	nı
A:	1 * i ×	√ f _x	created	_at			
4	А	В	С	D	Е	F	G
1	created_at	entry_id	field2				
2	2018-04-08 09:44:17 UTC	39	72				
3	2018-04-08 10:01:22 UTC	40	72				
4	2018-04-08 10:18:27 UTC	41	72				
5	2018-04-08 10:35:32 UTC	42	74				
6	2018-04-08 10:52:36 UTC	43	72				
7	2018-04-08 11:09:41 UTC	44	72				
8	2018-04-08 11:26:46 UTC	45	72				
9	2018-04-08 11:43:51 UTC	46	72				
10	2018-04-08 12:00:56 UTC	47	72				
11	2018-04-08 12:18:01 UTC	48	72				
12	2018-04-08 12:35:05 UTC	49	72				
13	2018-04-08 12:52:10 UTC	50	72				
14	2018-04-08 13:09:15 UTC	51	72				
15	2018-04-08 13:26:20 UTC	52	72				
16	2018-04-08 14:00:29 UTC	53	72				
17	2018-04-08 14:17:34 UTC	54	72				
18	2018-04-08 14:34:39 UTC	55	72				
19	2018-04-08 15:42:51 UTC	56	72				
20	2018-04-08 16:17:00 UTC	57	72				
21	2018-04-08 16:38:31 UTC	58	72				
22	2018-04-08 16:55:36 UTC	59	72				
23	2018-04-08 17:09:04 UTC	60	86				
24	2018-04-08 17:20:09 UTC	61	84				
25	2018-04-08 17:39:34 UTC	62	72				
26							
27							
28							
29							
30							
31							

Figure 4: Data exported from thinkspeak channel

5. SCREENSHOT OF EACH DEMO (BOARD SETUP)

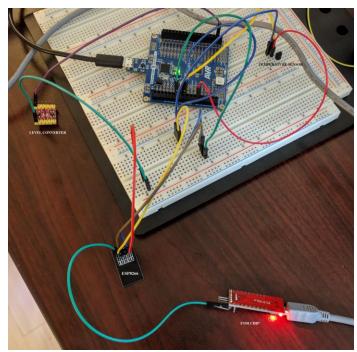


Figure 5: Board Setup

6. VIDEO LINKS OF EACH DEMO

None.

7. GITHUB LINK OF THIS DA

https://github.com/TraceStewart/epc103gnirps8102vlnu/tree/master/Midterm

ThinkSpeak Channel: https://thingspeak.com/channels/454833

Student Academic Misconduct Policy

http://studentconduct.unlv.edu/misconduct/policy.html

"This assignment submission is my own, original work".

Trace Stewart