

SVL

SIMULATOR

Khan

Store

Maps

Vehicles

Plugins

Library

Maps

Vehicles

Plugins

Clusters

Simulations

Test Results

Test Results > EOVS_S_65_60

Sharing

Delete

Simulation Details

Iterations

101

Status: Success

Start time: 7/22/2021, 11:49:30 PM

Real time duration: 00 : 00 : 35.000

Simulation time duration: 00 : 00 : 18.000

Lincoln2017MKZ

Bridge type: CyberRT

Connection: N/A

AnalysisVisualization

IMU

(Simulator Sensor ImuSensor)

Signal Sensor

(Simulator Sensor SignalSensor)

-40.718 km

15.473 km

-0.004 °

0.005 °

-1.035 km

15.065 km

-0.003 °

0.005 °

-1.624 km

0 km

0 °

0.993 °

CAN Bus

Wheel Car Control

1

0 (user input)

7.796 m/s

0 (user input)

0 (user input)

0 (user input)

0 °

0 (user input)

GPS

GPS INS Status

37.417 °

3 misc

-122.016 °

56 misc

0.352 m

4,141,577 m East

587,068.651 m North

open Google Maps

37.417 °

-122.016 °

-1.529 m

4,141,592.065 m East

587,029.282 m North

open Google Maps

Clock Sensor

Keyboard Car Control

18 seconds

0 (user input)

18.336 seconds

0 (user input)

0 (user input)

0 (user input)

3D Ground Truth

Apollo Car Control

0 counts

0.126 (user input)

0.986 (user input)

0 (user input)

IsControlReceived : true misc

GPS Odometry [Simulator.Sensors.GpsOdometrySensor]

Start Latitude: 37.417 °
Start Longitude: -122.016 °
Start Altitude: 0.352 m
Start Northing: 4,141,577 m East
Start Easting: 587,068.651 m North
Start Map Url: [open Google Maps](#)
Latitude: 37.417 °
Longitude: -122.016 °
Altitude: -1.529 m
Northing: 4,141,592.065 m East
Easting: 587,029.282 m North
Map Url: [open Google Maps](#)

Callbacks