



Store

- Maps
- Vehicles
- Plugins



Library

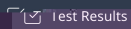
- Maps
- Vehicles
- Plugins



Clusters



Simulations



Test Results

Test Results › EOVS\_65\_60



Sharing



Delete



## Simulation Details

## Iterations

1

1

0

1

Status:

Success

Start time:

7/22/2021, 1:44:34 PM

Realtime...

duration:

00 : 01 : 59.000

Simulation time

duration:

00 : 00 : 33.000

## Lincoln2017MKZ

Bridge type:

CyberRT

Connection:

N/A

Analysis

Visualization

## Sensors

## IMU

[Simulator.Sensors.ImuSensor]

minX: -133.123 km  
maxX: 0 km  
minGyroX: -0.017 °  
maxGyroX: 0 °  
minY: -350.319 km  
maxY: 0 km  
minGyroY: -0.001 °  
maxGyroY: 0.013 °  
minZ: -7.324 km  
maxZ: 0 km  
minGyroZ: 0 °  
maxGyroZ: 0.739 °

## Signal Sensor

[Simulator.Sensors.SignalSensor]

SignalsDetected: 0 counts  
DetectedStates: misc

## CAN Bus

[Simulator.Sensors.CanBusSensor]

GearUsed: 1  
MaxSpeed: 2.694 m/s  
MaxThrottle: 0 (user input)  
MaxBrake: 0 (user input)  
MaxSteering: 0 °

## Wheel Car Control

[Simulator.Sensors.WheelControlSensor]

MaxSteer: 0 (user input)  
MaxAccel: 0 (user input)  
MaxBrake: 0 (user input)

## GPS

[Simulator.Sensors.GpsSensor]

Start Latitude: 37.417 °  
Start Longitude: -122.016 °  
Start Altitude: 0.352 m  
Start Northing: 4,141,577 m East  
Start Easting: 587,068.651 m North  
Start Map Url: [open Google Maps](#)  
Latitude: 37.414 °  
Longitude: -122.017 °  
Altitude: -7.214 m  
Northing: 4,141,226.681 m East  
Easting: 586,956.672 m North  
Map Url: [open Google Maps](#)

## GPS INS Status

[Simulator.Sensors.GpsInsSensor]

Status: 3 misc  
Position Type: 56 misc

## Clock Sensor

[Simulator.Sensors.ClockSensor]

SimulationDuration: 33 seconds  
RealtimeDuration: 33.755 seconds

## Keyboard Car Control

[Simulator.Sensors.KeyboardControlSensor]

MaxSteer: 0 (user input)  
MaxAccel: 0 (user input)  
MaxBrake: 0 (user input)

## Apollo Control Sensor

[Simulator.Sensors.ApolloControlSensor]

MaxTracked: 1 counts

## Apollo Car Control

[Simulator.Sensors.ApolloControlSensor]

MaxSteer: 0.424 (user input)  
MaxAccel: 0.986 (user input)  
MaxBrake: 0 (user input)

IsControlReceived  
: true misc

GPS Odometry (Simulator.Sensors.GPSOdometrySensor)

Start Latitude: 37.417 °  
Start Longitude: -122.016 °  
Start Altitude: 0.352 m  
Start Northing: 4,141,577 m East  
Start Easting: 587,068.651 m North  
Start Map Url: [open Google Maps](#)  
Latitude: 37.414 °  
Longitude: -122.017 °  
Altitude: -7.214 m  
Northing: 4,141,226.681 m East  
Easting: 586,956.672 m North  
Map Url: [open Google Maps](#)

Callbacks