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Simulations

Test Results

Test Results › EOVS\_65\_60

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## Simulation Details ▾

## Iterations

1 0 1

1

Status: Success

Start time: 7/22/2021, 11:42:39 PM

Real time duration: 00 : 01 : 35.000

Simulation time duration: 00 : 00 : 17.500

## Lincoln2017MKZ

Bridge type: CyberRT

Connection: N/A

Analysis

Visualization

## Sensors

## IMU

[Simulator.Sensors.ImuSensor]

minX: -38.965 km  
maxX: 15.473 km  
minGyroX: -0.005 °  
maxGyroX: 0.004 °  
minY: -1.035 km  
maxY: 13.82 km  
minGyroY: -0.003 °  
maxGyroY: 0.003 °  
minZ: -1.628 km  
maxZ: 0 km  
minGyroZ: 0 °  
maxGyroZ: 0.995 °

## Signal Sensor

[Simulator.Sensors.SignalSensor]

SignalsDetected: 0 counts  
DetectedStates: green misc

## CAN Bus

[Simulator.Sensors.CanBusSensor]

GearUsed: 1  
MaxSpeed: 8.291 m/s  
MaxThrottle: 0 (user input)  
MaxBrake: 0 (user input)  
MaxSteering: 0 °

## Wheel Car Control

[Simulator.Sensors.WheelControlSensor]

MaxSteer: 0 (user input)  
MaxAccel: 0 (user input)  
MaxBrake: 0 (user input)

## GPS

[Simulator.Sensors.GpsSensor]

Start Latitude: 37.417 °  
Start Longitude: -122.016 °  
Start Altitude: 0.352 m  
Start Northing: 4,141,577 m East  
Start Easting: 587,068.651 m North  
Start Map Url: [open Google Maps](#)  
Latitude: 37.417 °  
Longitude: -122.016 °  
Altitude: -1.527 m  
Northing: 4,141,590.82 m East  
Easting: 587,031.035 m North  
Map Url: [open Google Maps](#)

## GPS INS Status

[Simulator.Sensors.GpsInsSensor]

Status: 3 misc  
Position Type: 56 misc

## Clock Sensor

[Simulator.Sensors.ClockSensor]

SimulationDuration: 17.5 seconds  
RealtimeDuration: 17.891 seconds

## Keyboard Car Control

[Simulator.Sensors.KeyboardControlSensor]

MaxSteer: 0 (user input)  
MaxAccel: 0 (user input)  
MaxBrake: 0 (user input)

## 3D Ground Truth

[Simulator.Sensors.PerceptionSensor3D]

MaxTracked: 1 counts

## Apollo Car Control

[Simulator.Sensors.ApolloControlSensor]

MaxSteer: 0.103 (user input)  
MaxAccel: 0.983 (user input)  
MaxBrake: 0 (user input)

```
IsControlReceived      true misc
```