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Bayesian Model of Multisensory Comfort and Adaptation in Intelligent Building

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Abstract

Understanding a building's ambiance and user's preferences and then providing corresponding comfort is substantial in a smart home environment. In this work, we aim to design a model for an intelligent system (building) controller whose intelligence is adaptation, in changing situations, according to the preferences of occupants without their intervention. Adaptation, according to Humphreys is: "If a change occurs such as to produce discomfort, people react in ways which tend to restore their comfort". Therefore, our adaptive system restores comfort to the occupants based on their preferences, it has the ability to self-regulate and adapt to the climate conditions in buildings. In order to use adaptive control a model of the building is necessary and predictive control is very important because it includes a model for future disturbances. The starting point of this work was the modeling of multisensory comfort, and, the dynamic and adaptive behavior of an occupant with his environment. A key element was to find a way to model these adaptive actions. To achieve our goal, we used Bayesian networks that are powerful tools for decision and reasoning under uncertainty.

Keywords: *Intelligent building, multisensory comfort, adaptation, Bayesian network*

1. Introduction

Nowadays, comfort is highly required in the field of buildings because of its impact on the quality of indoor environment atmosphere, health and productivity of people who live and spend almost the $\frac{3}{4}$ of their time indoor. But with the current needs of energy-saving and controlling environmental impacts of building, one may ask what definition could be given to comfort, how to produce it and keep its environmental conditions. Comfort is revealed to be difficult to define, since most of the people have an impetuous illustration of this concept but they can neither express it in a suitable way nor give and define criteria about what is comfortable. The notion of comfort is very labile and depends on the context. [1] defines comfort as an unidentified scientific object "U.S.O". In fact, to identify comfort means to know its properties but this can be only obtained by a person with a subjective estimation towards "something" in a given context.

In building standards, approaches were set to define the notion of comfort and they deal with most of the work, the thermal surroundings of building. Thus it leads to two current definitions. The first being stated by [2] and it expresses a state of neutrality that is to say "the state of mind expresses satisfaction with its thermal environment". A second definition was proposed by [3], as part of his researches on thermal comfort, denotes that conditions for which the self-regulatory mechanisms of the body are at a minimum level of activity.

However, this notion of comfort is complicated by the several parameters that it combines both human (perception) and physical (measurement).

Measure comfort is to determine and compare, for every type of comfort such thermal, acoustic, visual comfort and indoor air quality, the physical environment variables with a person judgment to the same environment. Current standards move toward comfort with an analytic and reductive approach of the reality within its complexity. Studies in situ revealed an overestimation of uneasiness level in reality. These studies were applied to set the basis of the adaptive approach which differentiates comfort through the adaptive interaction between the resident and his environment.

In the literature, several researches have been done with the aim of automating daily activities by designing adaptive smart home system. In [4] CASAS utilizes machine learning techniques in order to dynamically adapt to user advice or changes in daily routine activities. The adaptation capability of CASAS is achieved by utilizing data mining methods as well as learning strategies that adapt to the resident's explicit and implicit preference feedback. In [5], adaptation is to retrain the preference model, in other words, the proposed system observes each interaction from users and then tries to provide its best-estimated service automatically. Given the service, the users will feedback acceptance/rejection of the service to the system. In turn, the system, after analyzing the feedback, then infers the most probable labels for updating the original models involved.

The first part of our study aims and consists to define the intelligent building and the multisensory comfort, and then present the analytic and adaptive approaches and the different model of sensorial comfort. The second part is allocated to the same context of intelligent building (DOMUS) and using adaptive approach, we manage to design, with machine learning, a probabilistic (Bayesian) model reproducing the specific comfort (thermal, acoustic, indoor air quality and visual comfort), their involvement in multisensory comfort and the dynamic behavior of the occupants towards environment changes in the building. Finally to check the presentation of our model, we will use the N.fold cross validation which is a statistical method of evaluating and comparing learning algorithms by dividing data into two segments: one used to learn or train a model and the other used to validate this model.

2. Background

2.1. Smart Home

Before defining a smart home, we must begin with the definition of home automation and of ambient intelligence, these two sets of techniques converge, subsequently, to the smart home. The current definition of home automation is: "Set of techniques to integrate, in buildings, automation for security, energy management, communication...". In time, the different actors (academic, industrial, institutional) associated with home automation offered their ad hoc definitions. Ambient intelligence involves the concept of environment. In fact, it is to provide a given environment (urban space, office, commercial spaces ...) digital capabilities: perceptual abilities (with different sensors), processing capabilities and reaction capabilities (with different effectors). Ambient intelligence involves many fields, especially the field of sensor networks (and implicitly networks actuators), the field of human-computer interaction and the field of artificial intelligence. For the definition of intelligent building, we choose one of [6] that the IB is one that creates an environment that maximizes the efficiency of the occupants of the building while at the same time allowing effective management of resources with minimum life-time costs.

Intelligent buildings make good business sense. As the Information Age takes us to new heights, the Intelligent Building System (IBS) has the flexibility and modularity to accommodate every change. An intelligent premise distribution system will allow the owner, administrators, and occupants to take advantage of new technology as it becomes available, at a minimum cost and without a major disruption of the productivity of the office work space. Today's competitive society demands efficiency. In a typical building the power supplies, air conditioning systems (Heating, Ventilation and Air Conditioning HVAC), lighting, external fabric, security systems, and computers all operate independently; consequently, building management struggles to satisfy conflicting demands. But if one adds a comprehensive and integrated IBS and interrelates the various subsystems through a single control framework, then the building, factory, hotel, or other type structure can respond to its environment in a timely and cost-effective manner.

2.2. Components of the Intelligent Building

An IBS is the integration of a wide range of services and systems into a unified whole. In general terms the components are as follows [6]:

- Energy Management Systems (EMSs)
- Temperature Monitoring Systems (TMSs)
- Lighting Control and Reduction (LCRs)

Access and area locate systems

- Security systems
- Fire Life Safety (FLS)
- Telecommunications, including Integrated Services Digital
- Network (ISDN)
- Office Automation (OA)
- Computer systems
- Local Area Networks (LANs)
- Management Information Systems (MISS)
- Cabling schemes and records
- Maintenance systems
- Intelligent systems

2.3. Multisensory Comfort:

The quality of life in buildings (comfort conditions) is determined by several factors like: Thermal comfort, visual comfort, and Indoor Air Quality (olfactory comfort) [7]. Thermal comfort and visual comfort are often confronted, especially, with assumed relationships between luminosity and thermal perception.

In their study, Candas and Dufour [8] they maintained, in a climate chamber in which a thermal ambiance “slightly warm” was applied, 48 subjects under two different lighting: one “hot” (2700 ° K), the other “cold” (5000° K). The results show that the thermal comfort perceived by participants in cold light was better than the thermal comfort perceived in hot lighting. The difference is small, but according to the authors, significant. If the relationship between thermal comfort and visual comfort have a major place in literature, other links have also been revealed by some studies. For example, experiments where Clausen and Fanger intervened [9], they highlight a link between the operative temperature, thermal comfort criterion, and the perception of the air quality. In 2002, Ernst and Banks [10] they realized an experiment to understand the links between visual modalities and haptic. Their results

indicate that the sensation produced by these two modalities can be predicted in by probabilistic way, by sensors fusion technique. Similar works say these results, such as [11].

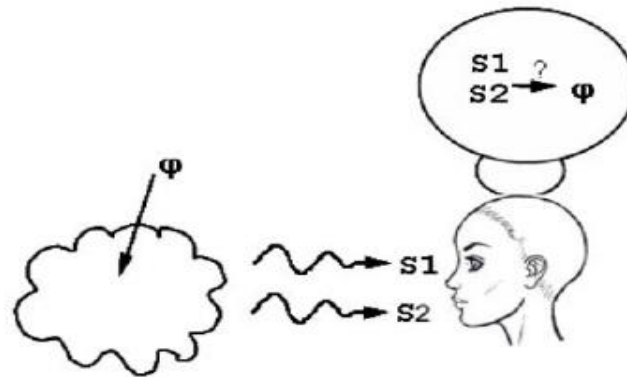


Figure 1. Human Perception and Integration of Sensations (S1 and S2) to Perceive a Phenomenon Ψ

2.4. Models of Comfort

2.4.1. Analytical Models

a) Thermal comfort model: Many analytical models (PMV, PMV*, ET, SET*) have been developed to predict the thermal and physiological responses of the human body depending on environmental conditions, in stationary or transient conditions. In the simplest models, the body is treated as a single unit. More complex models divide the body into several segments and simulate the dynamics of physiological responses. We describe below PMV as the main model.

PMV (that has been adopted by the ISO 7730 standard) is calculated by Fanger's equation [12], with maintaining the stability of the heat balance of the human body (necessary but not sufficient condition for thermal comfort), Fanger's method is to determine analytically the heat exchange between the subject and the environment. Then, depending on the difference between the produced and the dissipated heat (heat balance) by the dressed human body, it establishes an index "PMV" that predicts the mean thermal sensation vote on a standard scale for a large group of persons. The American Society of Heating Refrigerating and Air Conditioning Engineers (ASHRAE) developed the thermal comfort index by using coding -3 for cold, -2 for cool, -1 for slightly cool, 0 for natural, +1 for slightly warm, +2 for warm, and +3 for hot

$$PMV = \frac{0,303 \cdot \exp(-0,036 M) + 0,028}{L} \cdot L$$

$$L = M - (W + E_{dif} + E_{rsw, req} + E_{res} + C_{res} + R + C)$$

With:

L: The difference between produced and dissipated heat (thermal balance)

M: Internal heat generation (rate of metabolism), W/m²

W: Power needed by the external work, W/m²

E: Latent heat flux exchanged by evaporation (dif: diffusion through the skin, rsw, req: required for comfort, res: respiratory evaporation), W/m²

C: Heat flux exchanged by convection (res : respiratory convection), W/m²

R: Heat flux exchanged by radiation, W/m²

To determine the acceptability of the thermal environment, Fanger linked the PMV to another index, the “PPD” (Predicted Percentage Dissatisfied), that establishes a quantitative prediction of the thermally dissatisfied people assuming establishes a quantitative prediction of the thermally dissatisfied people assuming that who votes -2, -3, +2 or +3 on the thermal sensation scale is dissatisfied.

$$PPD = 100 - 95 \times e^{-(0.03353 \times PMV^4 + 0.2179 \times PMV^2)}$$

b) Visual comfort model: According Bodart [13], visual comfort is a sensation that is related to a clear and without fatigue perception of colorful and pleasant ambiance. Unlike thermal comfort, there isn't a general index expressing global form of visual comfort. The most common form to define the visual comfort is based on specific criteria like:

b.1. Characterization of light: Brightness is the main variable of visual comfort. Two main characteristics of a light are used as a criterion for comfort:

- **Light intensity:** The light intensity can be expressed in various physical quantities (it is expressed in lux). The other variables characterizing the light intensity correspond to sources, and they are used to estimate the contribution of these sources to the light intensity.

- **Spectral composition:** The light can be characterized by its spectrum, corresponding to different colors (wavelengths) that constitute it. In the field of interior lighting, this constitution (spectral light) is expressed by color temperature (in degrees Kelvin). This correspondence is established from the radiation of a black body at different temperatures, and it is formalized by Planck's law. Warm lighting is, paradoxically, a light whose temperature is low (10000K), compared with a cold light when the temperature is higher (higher than 30000K). Lighting neutral temperature corresponds to a temperature of 27000K. The Kruithof diagram below can be used to make an optimum choice. Zone (B) represents a comfortable environment.

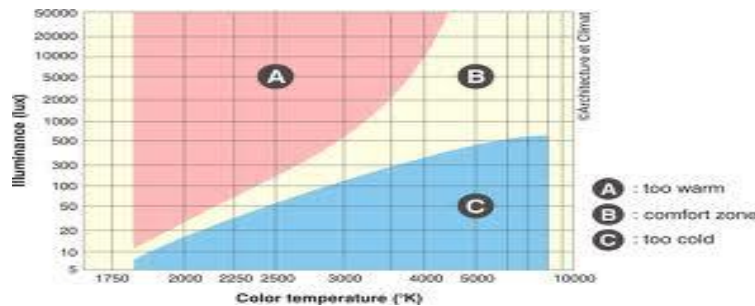


Figure 2. Kruithof Diagram

b.2. Unified Glare Rating (UGR): In recent years, the Unified Glare Rating (UGR) as recommended by the CIE (International Commission on Illumination) has become widely accepted as a general formula for assessing glare. The formula is given below:

$$UGR = 8 \log \frac{0,25}{L_b} \sum_{i=1}^n \frac{L_i^2 \omega}{p^2}$$

With:

L_b : background luminance (candela/m²).
 p : Guth factor, given in specific tables, representing the position of a light with compared with the vertical axis.
 L_i : Luminance of the glare source (candela/m²).
 ω : solid angle.

This formula is requires the prior knowledge of the position and brightness of each potential glare source. It is quite accurate but relatively difficult to work with. It is best used from within some computer software. For artificial light sources, such packages exist from most major producers of light fittings. They all require the modeling of the scene under investigation and produce a glare index for a defined position within the room.

Table 1. Scale of Discomfort Associated with the UGR [14]

UGR	Sensation
10	Perceptible
16	Acceptable
22	Uncomfortable
28	Intolerable

c) Indoor air quality (*IAQ*): Indoor air quality can be indicated by the carbon dioxide (CO_2) concentration in a building [15]. The CO_2 concentration comes from the presence of the inhabitants in the building and from various other sources of pollution. Ventilation is an important means for controlling indoor-air quality (*IAQ*) in buildings. Supplying fresh outdoor-air and removing air pollutants and odors from interior spaces is necessary for maintaining acceptable *IAQ* levels. However, ventilation rates inside buildings must be seriously reduced in order to control the cooling or thermal load in an improved manner [16]. In many cases though, this contributes to a degradation of the indoor-air quality and to what is generally known as “sick building syndrome” (*SBS*).

The association between carbon dioxide concentrations and occupant perceptions of the indoor environment in terms of comfort and irritation is complex because it mixes several different issues, including the comfort impacts of the carbon dioxide itself, associations between carbon dioxide levels and the concentrations of other occupant-generated contaminants, and the relationship between carbon dioxide and ventilation. Some indoor air quality investigators associate indoor carbon dioxide concentrations from 1100 mg/m³ (600 ppm(v)) to 1800 mg/m³ (1000 ppm(v)) or higher with perceptions of stuffiness and other indicators of discomfort. However, these associations are often based on anecdotal observations of the investigator or on informal occupant surveys [15].

Then, a high rate of CO_2 shows an important number of persons in space, probably reflecting a high concentration of pollutants in the air. Studies like [17] were then used to determine a formula from the inside and outside CO_2 concentration:

$$P_{ins} = 395 * e^{-15.15 (CO_2^{int} - CO_2^{ext})^{-0.25}}$$

With

P_{ins} : Percentage of dissatisfied due to odors from the air inside. (%)
 CO_2^{int} , CO_2^{ext} : CO_2 concentration in indoor, outside air. (ppm)

d) Acoustic comfort: According Boulet [18], a suitable acoustic ambiance depends on three criteria, corresponding to the source of noise pollution (acoustic discomfort):

- Acoustic discomfort from equipment, moving or activity.
- Neighbor acoustic discomfort from adjoining dwellings.
- The outside noise from transportation, neighboring buildings, nearby work, *etc.*.

We characterize the noise by intensity criteria (noise level) and frequency. These two criteria are frequently united in the context of acoustic comfort, through dB (A) unit. For example, standard EN 15251 indicates a weighted acoustic pressure level between 25 dB (A) and 40 dB (A) for residential rooms.

Unlike thermal comfort, acoustic comfort has also the disadvantage of not having a dynamic way to regulate the indoor environment. We can rarely control the noise, we can only limit or endure it [14].

2.4.2. Adaptive Comfort Model: To overcome the difficulties in measuring of different criteria sensory comfort in analytical methods, Humphreys has proposed an approach called adaptive approach [19], which states the following principle: *«If a change occurs such as to produce discomfort, people react in ways which tend to restore their comfort»*. He then sought to integrate physiological and behavioral adaptation in the measurements of thermal comfort.

In thermal comfort, the model can be set up in a form that estimates the comfort temperatures T_c that is a complex adaptive function of the various circumstances C_1, C_2, C_3, \dots , which operates on the indefinitely large set of conceivable adaptive actions that are potentially present within the adaptive model [19]. So we may write in functional notation:

$$T_c = f(C_1, C_2, C_3, \dots)$$

The adaptive model is based on the concept that there is a strong relationship between indoor comfort and outdoor climate, taking into account that humans can adapt to, and tolerate different temperatures during different times of the year. The adaptive hypothesis predicts that contextual factors and past thermal history modify building occupants' thermal expectations and preferences [20].

3. Computational Intelligence in Smart Home

Application of intelligent methods to the control systems of buildings essentially started in the decade of the 1990s. Artificial Intelligence (AI) techniques were applied to the control of both conventional and bioclimatic buildings. Intelligent controllers, optimized by the use of evolutionary algorithms were developed for the control of the subsystems of an intelligent building. The synergy of the neural networks technology, with fuzzy logic, and evolutionary algorithms resulted in the so-called Computational Intelligence (CI), which now has started to be applied in buildings.

The need to guarantee comfort conditions, taking into consideration the users' preferences, drove researchers to develop intelligent systems for energy and comfort management in buildings, mainly for large buildings like office buildings, hotels, public and commercial buildings, etc. A large number of publications regarding the application of fuzzy techniques found in the references. In [21], we presented the modeling and simulation of user preferences. We developed an original multi-sensory model able to ensure the satisfaction of occupants. Also, we combined the DEVS formalism and the theory of fuzzy logic to cope with the complexity of the system.

Using Multi-agent systems, [22] proposed intelligent coordinator who receives as inputs PMV, IAQ, illumination level, energy consumption, occupants' preferences, and activation signals from the controllers–agents. It then performs two specific tasks using a master-slave coordination mechanism. Each task requires a separate intelligent agent. The dependency between the two tasks is that the lower level agent (slave) operates only when it receives an activation signal r from the upper level agent (master).

4. Proposed Adaptive System Overview

The proposed adaptive system (See Figure 3) comprises several main components: Sensors, data preprocessing unit, actuators and adaptive controller that not only has the ability to assess a discomfort but also provides services to an inhabitant interacting on the actuators to restore a comfort. The adaptive controller is designed to work fully (multisensory comfort) in the background, and requires minimal effort of the occupants.

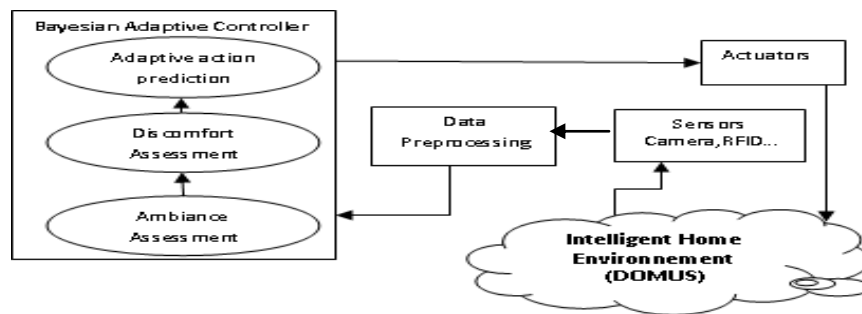


Figure 3. Adaptive System Overview

4.1. Experimental Data Set

Experimental data set is the most significant part of a research. The scenarios were played in the lab team Multicom which is the building CTL (center technology and software) at the University Joseph Fourier of Grenoble under the direction of Mr Jean Caelen. This lab contains an intelligent building called DOMUS Figure 4, which is an apartment type F2 and fully equipped space, consisting of a kitchen, bedroom containing bed, TV and window shutters, shower, toilet, office that contains desk, computer and stereo, hallway, two fixed cameras in each room and two fixed cameras in the kitchen. The entire apartment is controlled by a home automation system that allows interaction with tangible objects and the collection of activity traces.

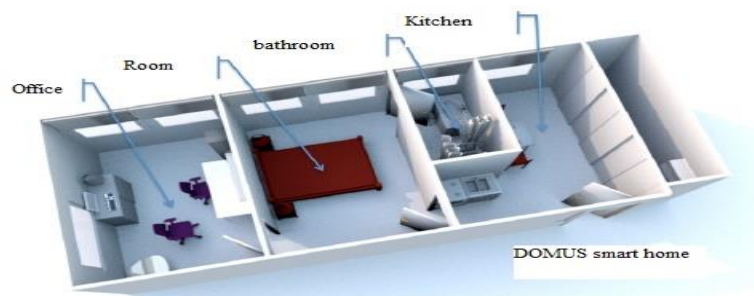


Figure 4. The DOMUS Smart Home

A total of 20 people (8 males, 12 females) were asked to participate in the research work. They were asked to spend about 1 hour and a half in the intelligent flat. The experiment was divided in 3 slots of 20 to 30 minutes, each one of them in a specific room with a specific activity. Also, inhabitants were asked to fill a form every five minutes in order to understand their perception of comfort with a sensorial semantic (see Table 2). Each of these variables was presented in the form of a *Likert* scale to the inhabitant. Answers were transposed into quantitative data for analysis, ranging from 0 for « very unpleasant » to 10 for « very pleasant », after receiving the sensory data we define the change from a state of an object to another as an “interaction”.

The questionnaire was implemented in an electronic and mobile way in order to facilitate the user's annotations.

Table 2. User's Perceptions Questionnaire

Name	(Likert) Scale legend
Global comfort	Very unpleasant to very pleasant
Thermal comfort	Very unpleasant to very pleasant
Lighting comfort	Very unpleasant to very pleasant
Air quality	Very unpleasant to very pleasant
Acoustic comfort	Very unpleasant to very pleasant

4.2. Proposed Bayesian Model Construction

For design our controller model, several issues need to be addressed. The first issue is how to preprocess sensor data such that the preprocessed sensory data can be utilized to extract informative features. The second issue is how to choose among these informative features to represent a controller model effectively. The last issue is how to train the parameters of controller model from the selected informative features so that interactions with actuators can be successfully inferred.

To take into account comfort information and relationship between an interaction and its corresponding informative features, we use Bayesian Network (DBN), which models ambience information and predicts probability of an interaction. Figure 5 shows the graphical structure of our proposed Bayesian model.

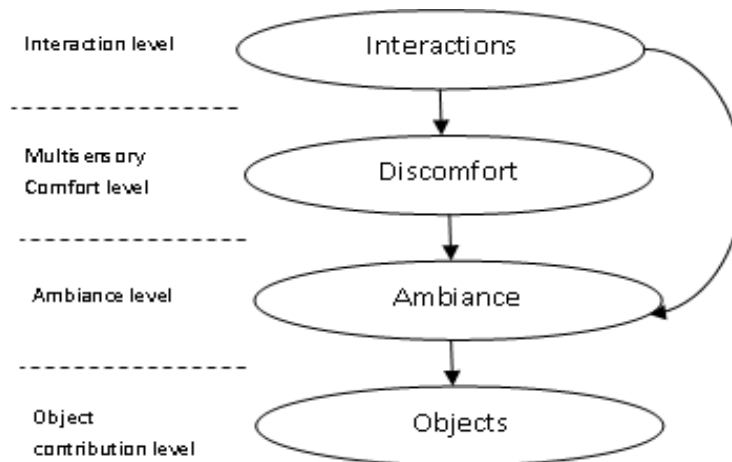


Figure 5. Proposed Network Bayesian Model

This proposed Bayesian network models the temporal information for objects (sensors), ambience and multisensory discomfort, and then we use this probabilistic network to predict appropriate action which restores a comfort. Each level is formally represented by a vector, the ambience vector is expressed by $A = (A_T, A_V, A_I, A_A)$, (thermal, visual, indoor air quality and acoustic ambience), which are measured in the Likert scale (Very unpleasant to very pleasant). The interaction vector is denoted by $I = (I_1, I_2, I_3, \dots, I_N)$ which represents all the interactions on actuators, for example I_1 is the interaction with lamp and its values are: turn on, turn off or don't change. The object vector is denoted by $O = (O_1, O_2, O_3, \dots, O_K)$ when $O_n = o_i$ represents state o_i of an object O_n .

The corpus data (observations) allow us to estimate the conditional probability distributions that can be made by a simple calculation of frequencies (Maximum Likelihood). However, when a value of an attribute A does not occur with a given value of its parent node B, the estimate of $P(A/B)$ produces a null value, and makes the prediction step difficult. To overcome this problem, we use the *Laplace* estimator.

4.3. Interactions Prediction

Our goal is to show how infer (predict) interactions with the actuators of the building given the current context (ambience and discomfort) recently observed. This prediction of interactions can be expressed by the **probability $P(\text{Interaction} / \text{Ambience}, \text{Discomfort})$ such as:**

$P(I = j | A, D) > P(I = k | A, D) \forall k \neq j$, which $I=j$ is the selected (inferred) interaction, D is the discomfort and A is the multisensory ambience.

To calculate the probability $P(I/A, D)$, the local joint probability is used, we have:

$P(I, A, D) = P(I) * P(D | I) * P(A | I, D)$ and $P(I, A, D) = P(D) * P(A | D) * P(I | A, D)$,
so

$$P(I | A, D) = P(I) * P(D | I) * P(A | I, D) / P(D) * P(A | D) = 1/\alpha * (P(I) * P(D | I) * P(A | I, D))$$

Note that for the probability $P(I = i | A, D)$ and $P(I = j | A, D)$, α is constant, so to compare these two probabilities it is done by calculating the $P(I) * P(D | I) * P(A | I, D)$ numerator for $I = j$, and $I = k$, with $P(I)$, $P(D | I)$ and $P(A | I, D)$ are parameters of our Bayesian network.

4.4. The Correlation between the Multi-Sensorial Comfort and Specific Ambiances

The goal now is to predict the discomfort knowing the current specific ambiances. For this, we focused on a Bayesian approach (Figure 6), which is inspired from the work **of Rohles [23], where the multisensory comfort is provided by a linear weighting according to the following formulation:**

$$\text{Confort}_{\text{Global}} = a * \text{Confort}_{\text{Thermal}} + b * \text{Confort}_{\text{Visual}} + c * \text{Confort}_{\text{Olfactory}} + d * \text{Confort}_{\text{Acoustic}}$$

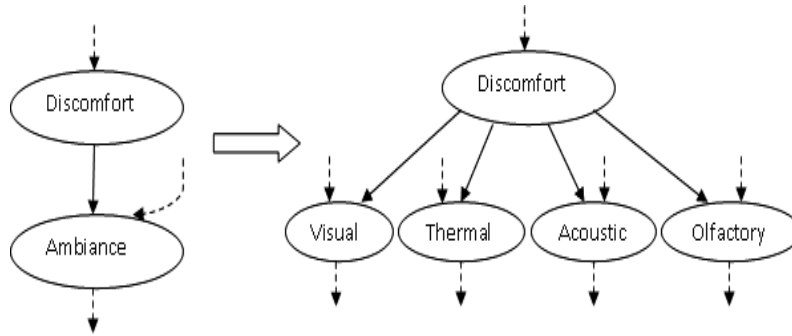


Figure 6. The Bayesian Network used for the Analysis of Multisensory Comfort

Formally, the objective is to estimate the probability $P(D|A)$, for this we will use Bayes' rule and the local joint probability $P(D, A, I)$.

$$P(D|A) = \frac{P(D, A)}{P(A)} = \frac{\sum_i P(D, A, I)}{P(A)} = \frac{\sum_i P(I) * P(D|I) * P(A|D, I)}{P(A)}$$

Note that for all values d_i of D , $1/P(A)$ is constant, so to compare the probabilities $P(D = d_i|A)$ and $P(D = d_k|A)$ it suffices to calculate:

$$\sum_i (P(I = i) * P(D = d_i|I = i) * P(A|D = d_i, I = i)) \text{ for } D = d_i \text{ and } D = d_k.$$

Where $P(I)$, $P(D|I)$ and $P(A|I, D)$ are parameters (already calculated) of our Bayesian network.

4.5. The Correlation between Specific Ambiances and Objects

To characterize the ambiance to be confronted with the judgment of the occupants, we propose a Bayesian model that presents different contributions of smart objects in each sensory domain. At this level the goal is to predict the values of the specific ambiance (elementary) vis-à-vis the state of all objects (sensors) of our environment. Formally we calculate the probability $P(\text{Ambiance} | \text{Objects})$.

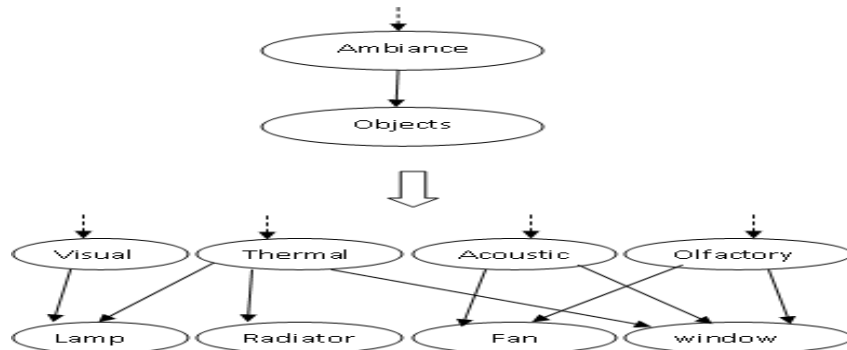


Figure 7. The Bayesian Structure Modeling Domain of Object Contribution in Comfort

Using Bayes' rule, we have:

$$P(A|O) = \frac{P(A) * P(O|A)}{P(O)}$$

Note that for different values a_i in $P(A_s = a_i|O)$, $1/P(O)$ is constant, so to compare the probabilities of the different values a_i of a specific ambience A_s , where s designates type of specific ambience (thermal, visual, i-A-Q or acoustic ambience), knowing the same state of objects (sensors), it suffices to compare the numerators of this probabilities :

$P(A_s = a_i) * P(O|A_s = a_i)$ which $P(O|A_s = a_i)$ is a parameter of our Bayesian network. So to calculate $P(A_s = a_i)$ we will use the marginalization of local joint probability $P(A, I, D)$, so we have :

$$P(A_s = a_i) = \sum_I \sum_D P(A_s = a_i, I, D) = \sum_I \sum_D P(I) * P(D|I) * P(A_s = a_i|I, D)$$

Which $P(I)$, $P(D|I)$ and $P(A|I, D)$ are parameters (already calculated) of our Bayesian network.

4.6. Results and Validation

At this stage, we want to know the validity and performance of the model. The goal is to show that the result of the inference on the proposed model is closer to reality. For this, we used the method of cross-validation "N-fold cross-validation", that is a statistical method of evaluating and comparing learning algorithms by dividing data into two segments: one used to learn or train a model and the other used to validate the model. Therefore, learning from the corpus, excluding annotations of S_i for testing, and start learning n times by changing the subject S_i . The empirical error rate \hat{R}_{real}^i on the sample i (annotations of S_i) becomes the number (percentage) of poorly inferred interactions compared to those annotated by the subject S_i , and the final estimated error \hat{R}_{real} is given by the average of the measured errors \hat{R}_{real}^i . The result of this performance analysis is illustrated in Figure 8.

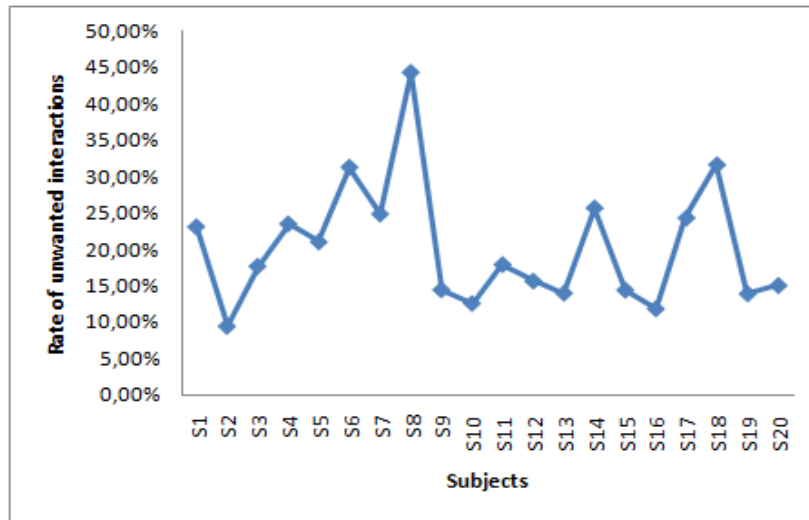


Figure 8. Rate of Inferred Undesirable Interactions per Subject

The results of this analysis indicate that 80% of inferred interactions (predicted) on the model satisfy all subjects, while 20% of inferred interactions are undesirable, which indicates the subjectivity of comfort.

5. Conclusion

In this work, we are interested to the concept of multisensory comfort in intelligent building. For this, we had to define the concept of this intelligent building. Then, we are interested, in particular, to the ambiance comfort, considering four areas: thermal comfort, visual comfort, olfactory comfort and acoustic comfort. Modeling the ambiance comfort can be done independently of each of these areas, or globally, multi-sensory, as we propose.

We proposed, in line with the possibilities offered by the smart home, a layered Bayesian model: first layer to characterize the contribution of objects in each specific ambiance, the other modeling multi-sensory comfort, the last allowing, after evaluating discomfort, a prediction of interactions to restore the comfort. All of this work was based on the intelligent Domus apartment, which served as a place of integration for the first part, and place of experimentation for the second.

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