

Interference Channel with Intermittent Feedback

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Abstract—We investigate how to exploit intermittent feedback for interference management. Focusing on the two-user linear deterministic interference channel, we completely characterize the capacity region. We find that the characterization only depends on the forward channel parameters and the marginal probability distribution of each feedback link. The scheme we propose makes use of block Markov encoding and quantize-map-and-forward at the transmitters, and backward decoding at the receivers. Matching outer bounds are derived based on novel genie-aided techniques. As a consequence, the perfect-feedback capacity can be achieved once the two feedback links are active with large enough probabilities.

I. INTRODUCTION

The simplest information theoretic model for studying interference is the two-user Gaussian *interference channel* (IC). It is shown that feedback can provide an unbounded gain in capacity for two-user Gaussian interference channels [1], in contrast to the bounded power gain provided by feedback in point-to-point, multiple access, and broadcast channels. This has been demonstrated when the feedback is unlimited, perfect, and free of cost in [1]. This motivates the natural question of whether feedback can provide similar gains under more practical feedback models.

In this work, we investigate how to exploit *intermittent* feedback for managing interference. Such intermittent feedback could occur in several situations. For example, one could use a side-channel such as WiFi for feedback; in this case since the WiFi channel is best effort, dropped packets might cause intermittent feedback. In other situations, control mechanisms in higher network layers could cause the feedback resource to be available intermittently. We study the effect of intermittent feedback using the linear deterministic model [2] of the two-user Gaussian IC. For the feedback links, Bernoulli processes $\{S_1[t]\}$ and $\{S_2[t]\}$ control the presence of feedback for user 1 and 2, respectively. Although the joint distribution $p(S_1[t], S_2[t])$ can be time-variant in general, for simplicity, we focus on the case where it is i.i.d. over time. Our results suggest that extension to the time-variant case is straightforward. We assume that the receivers are *passive*: they simply feedback their received signals back to the transmitters without coding. In other words, each transmitter receives from feedback a punctured version of the received sequence at its own receiver with unit delay. We focus on the passive feedback model as the intermittence of feedback is motivated by the availability of feedback resources (either through use of best-effort WiFi for feedback or through feedback resource

scheduling). Therefore, it might be that the time-variant statistics of the intermittent feedback are not *a priori* available at the receiver and therefore precluding active coding. Moreover, the availability of the feedback resource may not be known ahead of transmission, therefore motivating the causal state-information at the transmitter.

In the literature, other practical feedback models are also investigated. Rate-limited feedback for the two-user IC was considered in [3], where the feedback from the receivers to the transmitters is modeled by two finite-capacity noiseless links. [3] characterized the capacity region for the linear deterministic IC and the sum capacity to within a constant gap for the symmetric Gaussian IC. If indeed the feedback statistics is *a priori* known at the receiver, one can use active feedback to code for these erasures thereby creating noiseless finite capacity feedback links. In contrast to our model, the receivers in [3] can actively code the feedback signals. On the other hand, [4] considered feedback with additive white Gaussian noise but the receivers are passive, that is, they cannot encode the feedback signal. The capacity region is characterized for the symmetric linear deterministic IC [4]. When feedback shares the same resource (spectrum) with the forward channel and hence is not free of cost, it is shown in [5] through the study on two-way interference channels that feedback can provide net capacity gain even taking the feedback cost into account.

Our main contribution is the characterization of the capacity region of the linear deterministic IC with intermittent feedback, which only depends on the forward channel parameters and the marginal distribution of S_1 and S_2 , not on the joint distribution. Interestingly, the full benefit obtained via perfect feedback can be achieved once the “on” probabilities of the two feedback links are large enough. Our result in the linear deterministic model also suggests that in the Gaussian case, the capacity gain from intermittent feedback remains unbounded.

We propose a block Markov encoding scheme to exploit intermittent feedback at the transmitters along with backward decoding at the receivers. For linear deterministic IC, the high-level idea is to exploit the additional information provided by intermittent feedback to refine the interfered signals or to relay additional information. Due to the passive nature of the receivers, not all the information contained in the feedback is useful, in sharp contrast to the case of rate-limited feedback [3]. Therefore, at the transmitters instead of the (partial) decode-and-forward scheme employed in [1] and [3], we use *quantize-map-and-forward* [2] to extract useful information

from the intermittent feedback and send it to the receivers.

We also develop novel outer bounds that match the achievable rate region. Remarkably, in our proof we do not make use of the assumption that the states are known to the transmitters causally, which proves that even when the realization of (S_1^N, S_2^N) is known non-causally, the capacity region remains the same.

The rest of this paper is organized as follows. We formulate the problem in Section II and present our main result in Section III. Achievability and converse are proved in Section IV and Section V respectively. An extended version of this paper that includes the proof details can be found in [6].

II. PROBLEM FORMULATION

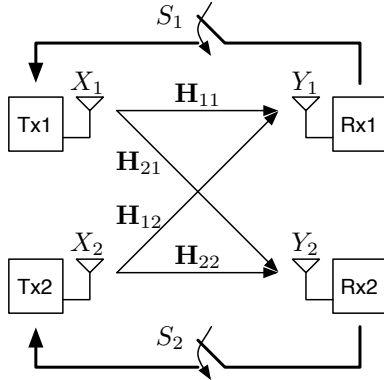


Fig. 1. Linear Deterministic IC with Intermittent Feedback

In this paper, we focus on the linear deterministic model [2] of the two-user Gaussian IC. An illustration is given in Fig. 1.

The transmitted signal at transmitter i ($\text{Tx}i$) is $X_i \in \mathbb{F}_2^q$, for $i = 1, 2$. Here \mathbb{F}_2 denotes the binary field $\{0, 1\}$. The received signals at receiver 1 ($\text{Rx}1$) and receiver 2 ($\text{Rx}2$) are

$$\begin{aligned} Y_1[t] &= \mathbf{H}_{11}X_1[t] + \mathbf{H}_{12}X_2[t], \\ Y_2[t] &= \mathbf{H}_{22}X_2[t] + \mathbf{H}_{21}X_1[t], \end{aligned}$$

where additions are modulo-two component-wise. Channel transfer matrices $\mathbf{H}_{ij} := \mathbf{S}^{q-n_{ij}}$ for $(i, j) \in \{1, 2\}^2$, where $q = \max\{n_{11}, n_{12}, n_{21}, n_{22}\}$, and $\mathbf{S} \in \mathbb{F}_2^{q \times q}$ is the shift matrix $\begin{bmatrix} \mathbf{0}^T & \mathbf{0} \\ \mathbf{I}_{q-1} & \mathbf{0} \end{bmatrix}$, where $\mathbf{0}$ is the zero vector in \mathbb{F}_2^{q-1} and \mathbf{I}_{q-1} is the identity matrix in $\mathbb{F}_2^{(q-1) \times (q-1)}$. The transmit signal from $\text{Tx}i$ at time t , $X_i[t]$, is determined by the message W_i , $\tilde{Y}_i[1 : t-1]$, and $(S_1[1 : t-1], S_2[1 : t-1])$, where $\tilde{Y}_i[t] := S_i[t]Y_i[t]$. Let us use the notation $A \stackrel{f}{=} B$ to denote that A is a function of B . Then, $X_i[t] \stackrel{f}{=} (W_i, \tilde{Y}_i[1 : t-1], S_1[1 : t-1], S_2[1 : t-1])$.

The feedback state sequences have the joint distribution

$$p(S_1^N, S_2^N) = \prod_{t=1}^N p(S_1[t], S_2[t]).$$

Let $q_{i_1 i_2} := p(S_1 = i_1, S_2 = i_2)$, $i_1, i_2 \in \{0, 1\}$. Marginally, $S_i[t] \sim \text{Ber}(p_i)$, i.i.d. over time. In other words, the feedback

signal is erased with probability $1 - p_i$, where

$$p_1 := q_{10} + q_{11}, \quad p_2 := q_{01} + q_{11}.$$

For notational convenience, denote $\underline{S} := (S_1, S_2)$ and

$$V_1 := \mathbf{H}_{21}X_1, \quad V_2 := \mathbf{H}_{12}X_2, \quad \tilde{V}_1 := S_2V_1, \quad \tilde{V}_2 := S_1V_2.$$

III. MAIN RESULT

The main result is summarized in the following theorem.

Theorem 3.1 (Capacity Region): The capacity region \mathcal{C} for the linear deterministic IC with intermittent feedback is the collection of non-negative (R_1, R_2) satisfying (1) – (6).

Note that the rate region defined by (1) – (3) is the perfect-feedback IC capacity region [1]. Therefore, once p_1 and p_2 are so large that (4) – (6) become inactive, the perfect-feedback performance can be attained even under intermittent feedback. The thresholds on p_1, p_2 will depend on $\{n_{ij}, i, j \in \{1, 2\}\}$.

As an example, let us focus on the symmetric capacity C_{sym} under the symmetric setting $n_{11} = n_{22} = n, n_{12} = n_{21} = \alpha n, p_1 = p_2 = p$: ($C_{\text{sym}} := \max_{(R, R) \in \mathcal{C}} R$)

$$\frac{C_{\text{sym}}}{n} = \begin{cases} \min\{1 - \alpha/2, 1 - (1 - p)\alpha\}, & \alpha \leq 1/2 \\ \min\{1 - \alpha/2, p + (1 - p)\alpha\}, & 1/2 \leq \alpha \leq 1 \\ \min\{\alpha/2, (1 - p) + p\alpha\}, & \alpha \geq 1 \end{cases},$$

where the first term in each minimization is the perfect-feedback capacity. Hence, we find the threshold on p above which perfect-feedback capacity can be achieved, as follows:

$$p^* = \begin{cases} 1/2, & \alpha \leq 1/2 \\ (2 - 3\alpha)^+ / (2 - 2\alpha), & 1/2 \leq \alpha \leq 1 \\ (\alpha - 2)^+ / (2\alpha - 2), & \alpha \geq 1 \end{cases}.$$

Note that in the regime $2/3 \leq \alpha \leq 2$, feedback does not increase the symmetric capacity of IC [1] and hence $p^* = 0$, that is, we do not need feedback at all. Also note that $p^* \leq 1/2$ for all α . Therefore, once $p \geq 1/2$, perfect-feedback capacity can be achieved with intermittent feedback regardless of channel parameters α and n . Note that the larger p is, the larger the amount of additional information about the past reception can be obtained through intermittent feedback at the transmitters. If the amount of such information is larger than a threshold, then sending it to the receivers will limit the rate for delivering fresh information. The threshold p^* represents the maximum limit at which the help of feedback is not neutralized by this effect.

IV. ACHIEVABILITY PROOF

To prove the achievability part of Theorem 3.1, in this section we provide a coding scheme to exploit intermittent feedback in the interference channel. Since the feedback is passive, one cannot code against the erasures in the feedback links. This is the key difference with the active feedback case [3]. In the active feedback case, a block Markov coding scheme based on decode-and-forward at the transmitters is employed, which is a natural extension of that in the perfect feedback case [1]. Instead, we employ a block Markov coding scheme based on *quantize-map-and-forward*, which can be viewed as a non-trivial extension of the perfect feedback scheme. Below we describe the scheme in detail.

$$R_1 \leq \min \{ \max(n_{11}, n_{12}), n_{11} + p_2(n_{21} - n_{11})^+ \} \quad (1)$$

$$R_2 \leq \min \{ \max(n_{22}, n_{21}), n_{22} + p_1(n_{12} - n_{22})^+ \} \quad (2)$$

$$R_1 + R_2 \leq \min \{ \max(n_{11}, n_{12}) + (n_{22} - n_{12})^+, \max(n_{22}, n_{21}) + (n_{11} - n_{21})^+ \} \quad (3)$$

$$R_1 + R_2 \leq \max \{ n_{12}, (n_{11} - n_{21})^+ \} + \max \{ n_{21}, (n_{22} - n_{12})^+ \} + p_1 \min \{ n_{12}, (n_{11} - n_{21})^+ \} + p_2 \min \{ n_{21}, (n_{22} - n_{12})^+ \} \quad (4)$$

$$2R_1 + R_2 \leq \max(n_{11}, n_{12}) + \max \{ n_{21}, (n_{22} - n_{12})^+ \} + (n_{11} - n_{21})^+ + p_2 \min \{ n_{21}, (n_{22} - n_{12})^+ \} \quad (5)$$

$$R_1 + 2R_2 \leq \max(n_{22}, n_{21}) + \max \{ n_{12}, (n_{11} - n_{21})^+ \} + (n_{22} - n_{12})^+ + p_1 \min \{ n_{12}, (n_{11} - n_{21})^+ \} \quad (6)$$

A. High-level Description

For the two-user linear deterministic IC, Han-Kobayashi coding scheme is a natural choice where we split the message into common and private: $W_i := (W_{ic}, W_{ip})$ for $i = 1, 2$. The total number of blocks to be transmitted is B , and the length of each block is N . For block $b \in [1 : B]$, the messages $\{W_1(b), W_2(b)\}$ are independent from the messages of other blocks. In the following we describe the encoding and decoding for a particular block b for user 1. Operations of user 2 are similar.

In the beginning of block b , from the punctured feedback $\tilde{Y}_1^N(b-1)$ and the state sequence $\underline{S}^N(b-1)$, Tx1 generates

$$\tilde{V}_1^N(b-1) = S_2^N(b-1)V_1^N(b-1),$$

$$\tilde{V}_2^N(b-1) = \tilde{Y}_1^N(b-1) - S_1^N(b-1)\mathbf{H}_{11}X_1^N(b-1).$$

Note that Tx2 can also generate $(\tilde{V}_1^N(b-1), \tilde{V}_2^N(b-1))$. The high-level idea is to use this common information to cooperatively refine the previously received signals at the receivers and/or relay additional information, as in the perfect feedback case [1]. The only difference is that here we do not decode at the transmitters. The reason is that the imperfect feedback may lay additional constraints on the achievable rate if we insist to decode. Decoding partially is not optimal since the realization of erasures in the feedback links is not known beforehand, and if we insist to decode at the transmitters some pre-assigned sub-messages, this could harm the achievable rate of other sub-messages.

Hence, we shall quantize $\tilde{V}_1^N(b-1)$ and $\tilde{V}_2^N(b-1)$, and map the quantized outputs to a codeword $X_{1e}^N(b)$ which contains the helping information for interference refinement or message relaying regarding block $b-1$. On top of it, we further superpose fresh information of block b , the messages $W_{1c}(b)$ and $W_{1p}(b)$, to generate the transmit codeword $X_1^N(b)$.

For decoding, we employ backward decoding. At the end of block b , assuming that quantized version of $\tilde{V}_1^N(b)$ and $\tilde{V}_2^N(b)$ have been successfully decoded from the future block $b+1$, Rx1 decodes $W_{1c}(b)$, $W_{2c}(b)$, and $W_{1p}(b)$ jointly with the quantized version of $\tilde{V}_1^N(b-1)$ and $\tilde{V}_2^N(b-1)$.

In the above scheme, we can see that $\tilde{V}_1^N(b-1)$ and $\tilde{V}_2^N(b-1)$ will contain some information of block $b-2$, which contains information about block $b-3$, and so on. This dependency across blocks hampers a single-letter characterization of the

achievable rates, since the mutual information terms obtained will depend on all the signals sent in previous blocks. In order to remove the dependency across more than two blocks, we carry out the following operation before quantizing $\tilde{V}_1^N(b-1)$ and $\tilde{V}_2^N(b-1)$: generate

$$\bar{V}_i^N(b-1) := \tilde{V}_i^N(b-1) - \tilde{V}_{ie}^N(b-1)$$

where $\tilde{V}_{ie}^N(b-1) := S_j^N(b-1)\mathbf{H}_{ji}X_{ie}^N(b-1)$ for $(i, j) = (1, 2), (2, 1)$. The operation is feasible since both $X_{1e}^N(b-1)$ and $X_{2e}^N(b-1)$ are generated from shared information $\bar{V}_1^N(b-2)$ and $\bar{V}_2^N(b-2)$, and hence (by induction) available at both transmitters. In our proposed encoding architecture, the quantization is performed on $\bar{V}_1^N(b-1)$ and $\bar{V}_2^N(b-1)$. An illustration of the encoding architecture is given in Fig. 2.

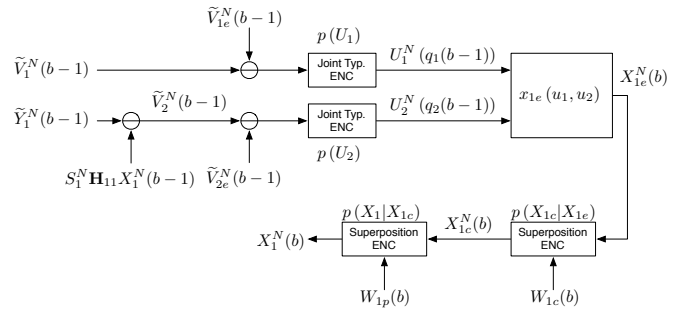


Fig. 2. Block Diagram of Encoder at Tx1

B. Codebook Generation and Detailed Coding Process

We describe the scheme for block b in detail below.

Codebook Generation and Encoding:

Based on $p(U_i)$, generate 2^{Nr_i} quantization codewords U_i^N i.i.d. over time, for $i = 1, 2$, to quantize $\bar{V}_i^N(b-1)$. Let $q_1(b-1)$ and $q_2(b-1)$ denote the quantization indices. The quantization is carried out by a joint typicality encoder as in standard source coding. We then choose a symbol-by-symbol map $x_{1e}(u_1, u_2)$ for mapping $(U_1^N(q_1(b-1)), U_2^N(q_2(b-1)))$ into $X_{1e}^N(b)$. This completes the joint-source-channel coding part of the encoder. Note that we shall use the same pair of quantization codebooks at both transmitters.

Superposition encoding is done in a standard way. We base on $p(X_{1c}|X_{1e})$ to generate $2^{NR_{1c}}$ common codewords $X_{1c}^N(W_{1c}(b), X_{1e}^N(b))$ i.i.d. over time. Then based on $p(X_1|X_{1c})$, we generate $2^{NR_{1p}}$ transmit codewords $X_1^N(W_{1p}(b), X_{1c}^N(b))$ i.i.d. over time.

Decoding:

At the end of block b , we assume that quantization indices $\{q_1(b), q_2(b)\}$ have been decoded from block $b + 1$. The additional information carried by $\{U_1^N(q_1(b)), U_2^N(q_2(b))\}$ can be used in conjunction with $Y_1^N(b)$ to decode $(W_{1c}(b), W_{1p}(b), q_1(b-1), q_2(b-1)) = (i_1, j, q_1, q_2)$. We find such a unique (i_1, j, q_1, q_2) and some $W_{2c}(b) = i_2$ such that

$$\left(\begin{array}{l} Y_1^N(b), U_1^N(q_1(b)), U_2^N(q_2(b)), U_1^N(q_1), U_2^N(q_2), \\ X_{1c}^N(i_1, q_1, q_2), X_1^N(j, i_1, q_1, q_2), X_{2c}^N(i_2, q_1, q_2) \end{array} \right) \quad (7)$$

is jointly ϵ -typical.

C. Analysis

The key to a single-letter rate characterization of the above scheme is that, the actual quantization codewords are independent across different blocks, that is, $(U_1^N(q_1(b)), U_2^N(q_2(b)))$ and $(U_1^N(q_1(b-1)), U_2^N(q_2(b-1)))$ are independent. This is due to the removal of $\tilde{V}_{1e}^N(b-1)$ and $\tilde{V}_{2e}^N(b-1)$ described above. The error probability analysis is standard so we omit the details here. Below we sketch the analysis of the error event where j is decoded incorrectly but (i_1, i_2, q_1, q_2) is correct. Note that the joint distribution of the random vectors in (7) is

$$p(y_1^N, u_1^N, u_2^N | u_1'^N, u_2'^N, x_1^N, x_{2c}^N) p(u_1'^N, u_2'^N) \cdot p(x_1^N | x_{1c}^N) p(x_{1c}^N | u_1'^N, u_2'^N) p(x_{2c}^N | u_1'^N, u_2'^N)$$

with a change of notations for the sake of simplicity:

$$\begin{aligned} Y_1^N(b) &\rightarrow y_1^N, U_1^N(q_1(b)) \rightarrow u_1^N, U_2^N(q_2(b)) \rightarrow u_2^N, \\ U_1^N(q_1) &\rightarrow u_1'^N, U_2^N(q_2) \rightarrow u_2'^N, X_{1c}^N(i_1, q_1, q_2) \rightarrow x_{1c}^N, \\ X_1^N(j, i_1, q_1, q_2) &\rightarrow x_1^N, X_{2c}^N(i_2, q_1, q_2) \rightarrow x_{2c}^N. \end{aligned}$$

By packing lemma [7], the probability of this error event vanishes as $N \rightarrow \infty$ if

$$R_{1p} \leq I(X_1; Y_1, U_1, U_2 | X_{1c}, X_{2c}, U_1', U_2').$$

Analysis of the other error events follows similarly. For the joint-typicality encoding to be successful with high probability, we need $r_i \geq I(U_i; \bar{V}_i)$ for $i = 1, 2$, due to covering lemma [7]. Hence, decoding is guaranteed to be successful with high probability if the following holds: for $(i, j) = (1, 2)$ and $(2, 1)$,

$$\begin{aligned} R_{ip} &\leq I(X_i; Y_i, U_i, U_j | X_{ic}, X_{jc}, U_i', U_j') \\ R_{jc} + R_{ip} &\leq I(X_{jc}, X_i; Y_i, U_i, U_j | X_{ic}, U_i', U_j') \\ R_i &\leq I(X_i; Y_i, U_i, U_j | X_{jc}, U_i', U_j') \\ R_{jc} + R_i &\leq I(X_{jc}, X_i; Y_i, U_i, U_j | U_i', U_j') \\ r_i + r_j + R_{jc} + R_i &\leq I(U_i', U_j', X_{jc}, X_i; Y_i, U_i, U_j) \\ r_i &\geq I(U_i; \bar{V}_i). \end{aligned}$$

for some mapping functions $\{x_{1e}(u_1, u_2), x_{2e}(u_1, u_2)\}$ and input distribution

$$p(U_1, U_2) p(U_1', U_2') p(X_{1c} | U_1', U_2') p(X_1 | X_{1c}) \cdot p(X_{2c} | U_1', U_2') p(X_2 | X_{2c}).$$

Here $R_i = R_{ip} + R_{ic}$ is the achievable rate for user i , $i = 1, 2$. $\bar{V}_i := \tilde{V}_i - \tilde{V}_{ie}$ as defined previously. (U_1', U_2') corresponds to the $(U_1^N(b-1), U_2^N(b-1))$ while (U_1, U_2) corresponds to the $(U_1^N(b), U_2^N(b))$. Hence, $p(U_1', U_2')$ and $p(U_1, U_2)$ should be the same, since we use the same distribution to generate the quantization codebooks in all the blocks.

D. Rate Region Evaluation

To achieve the capacity region, we choose the input distribution and the mapping function as follows. For the input distribution, we pick

$$\begin{aligned} U_i &= \bar{V}_i := \tilde{V}_i - \tilde{V}_{ie}, \quad U_i', U_i : \text{i.i.d.} \\ X_{ic} &= X_{ie} + \text{Ber}_{1/2}[\text{supp} V_i] \\ X_i &= X_{ic} + \text{Ber}_{1/2}[\text{supp} X_i \setminus \text{supp} V_i] \end{aligned}$$

and $x_{ie}(u_1, u_2)$ is a linear map such that the random linear combinations of all levels of u_1 and u_2 is put uniformly at random on all the levels of $\text{supp} X_i$. The support $\text{supp} X_i$ and $\text{supp} V_i$ denote the levels of X_i and V_i respectively, and $\text{Ber}_{1/2}(A)$ denotes a random vector with i.i.d. $\text{Ber}(1/2)$ random variables on all the levels of A .

With the above choice, we have

$$\begin{aligned} r_1 &\geq I(U_1; \bar{V}_1) = H(\bar{V}_1) = p_2 n_{21} \\ r_2 &\geq I(U_2; \bar{V}_2) = H(\bar{V}_2) = p_1 n_{12} \end{aligned}$$

We choose $r_1 = p_2 n_{21}$ and $r_2 = p_1 n_{12}$, and obtain the following rate region after eliminating r_1 , r_2 and redundant terms (see [6] for details):

$$\begin{aligned} R_{ip} &\leq p_i := (n_{ii} - n_{ji})^+ \\ R_{jc} + R_{ip} &\leq s_i := \max \{ (n_{ii} - n_{ji})^+, n_{ij} \} \\ &\quad + p_i \min \{ (n_{ii} - n_{ji})^+, n_{ij} \} \\ R_i &\leq t_i := n_{ii} + p_j (n_{ji} - n_{ii})^+ \\ R_{jc} + R_i &\leq n_i := \max(n_{ii}, n_{ij}) \end{aligned}$$

for $(i, j) = (1, 2), (2, 1)$.

After Fourier Motzkin elimination, (R_1, R_2) satisfying

$$\begin{aligned} R_1 &\leq \min \{ t_1, n_1, p_1 + s_2 \} \\ R_2 &\leq \min \{ t_2, n_2, p_2 + s_1 \} \\ R_1 + R_2 &\leq \min \{ p_1 + n_2, p_2 + n_1 \} \\ R_1 + R_2 &\leq s_1 + s_2 \\ 2R_1 + R_2 &\leq p_1 + n_1 + s_2 \\ R_1 + 2R_2 &\leq p_2 + n_2 + s_1 \end{aligned}$$

is achievable, which coincides with the capacity region (1) – (6) except the terms $p_1 + s_2$ and $p_2 + s_1$ in the individual rate constraints. We complete the achievability proof by the following fact.

Fact 4.1: $t_1 \leq p_1 + s_2$, $t_2 \leq p_2 + s_1$.

Proof: See [6]. ■

V. CONVERSE PROOF

Outer bounds (1) and (2) on individual rates are essentially cut-set bounds and we omit the details here. Sum rate outer bound (3) is the bound when feedback is perfect, and the proof can be found in [1]. The proof of the rest is a novel modification of those in the perfect feedback case [1] and the rate-limited feedback case [3]. Due to space constraints, below we outline the main proof of (4) and (5) and leave the proof details of following four useful facts to [6].

Fact 5.1: For $(i, j) = (1, 2), (2, 1)$,

$$X_i[t] \stackrel{f}{=} (W_i, \tilde{V}_j^{t-1}, \underline{S}^{t-1}) \stackrel{f}{=} (W_i, V_j^{t-1}, \underline{S}^{t-1}).$$

Fact 5.2: For $(i, j) = (1, 2), (2, 1)$,

$$H(Y_i^N | W_i, \underline{S}^N) = H(V_j^N, \tilde{V}_i^N | W_i, \underline{S}^N).$$

Fact 5.3: For $(i, j) = (1, 2), (2, 1)$,

$$I(W_i; V_j^N, \tilde{V}_i^N | \underline{S}^N) \leq N p_j n_{ji}.$$

Fact 5.4: For $(i, j) = (1, 2), (2, 1)$,

$$\begin{aligned} N^{-1} H(Y_i^N | V_i^N, \tilde{V}_j^N, \underline{S}^N) \\ \leq p_i (n_{ii} - n_{ji})^+ + (1 - p_i) \max\{n_{ij}, (n_{ii} - n_{ji})^+\}, \\ N^{-1} H(Y_i^N | V_j^N, \tilde{V}_i^N, \underline{S}^N) \\ \leq p_j (n_{ii} - n_{ji})^+ + (1 - p_j) n_{ii}, \end{aligned}$$

A. Proof of Outer Bound (4)

If (R_1, R_2) is achievable,

$$\begin{aligned} N(R_1 + R_2 - \epsilon_N) &\leq I(W_1; Y_1^N | \underline{S}^N) + I(W_2; Y_2^N | \underline{S}^N) \\ &\stackrel{(a)}{=} H(Y_1^N | \underline{S}^N) - H(V_1^N, \tilde{V}_2^N | W_2, \underline{S}^N) + H(Y_2^N | \underline{S}^N) \\ &\quad - H(V_2^N, \tilde{V}_1^N | W_1, \underline{S}^N) \\ &\leq H(Y_1^N | V_1^N, \tilde{V}_2^N, \underline{S}^N) + I(W_2; V_1^N, \tilde{V}_2^N | \underline{S}^N) \\ &\quad + H(Y_2^N | V_2^N, \tilde{V}_1^N, \underline{S}^N) + I(W_1; V_2^N, \tilde{V}_1^N | \underline{S}^N) \\ &\stackrel{(b)}{\leq} N \{\text{Right-Hand Side of (4)}\}. \end{aligned}$$

Here $\epsilon_N \rightarrow 0$ as $N \rightarrow \infty$. (a) is due to Fact 5.2. (b) is due to Fact 5.3 and 5.4. Hence (4) holds.

B. Proof of Outer Bound (5)

If (R_1, R_2) is achievable,

$$\begin{aligned} N(2R_1 + R_2 - \epsilon_N) &\leq I(W_1; Y_1^N | \underline{S}^N) + I(W_2; Y_2^N | \underline{S}^N) + I(W_1; Y_1^N | \underline{S}^N) \\ &\stackrel{(a)}{\leq} H(Y_1^N | \underline{S}^N) - H(V_2^N, \tilde{V}_1^N | W_1, \underline{S}^N) + H(Y_2^N | \underline{S}^N) \\ &\quad - H(V_1^N, \tilde{V}_2^N | W_2, \underline{S}^N) + I(W_1; Y_1^N | W_2, \underline{S}^N) \\ &= H(Y_1^N | \underline{S}^N) - H(V_2^N, \tilde{V}_1^N | \underline{S}^N) + H(Y_2^N | \underline{S}^N) \end{aligned}$$

$$\begin{aligned} &+ I(W_1; V_2^N, \tilde{V}_1^N | \underline{S}^N) - H(V_1^N, \tilde{V}_2^N | W_2, \underline{S}^N) \\ &+ H(Y_1^N | W_2, \underline{S}^N) \\ &\leq H(Y_1^N | \underline{S}^N) + H(Y_2^N | V_2^N, \tilde{V}_1^N, \underline{S}^N) \\ &\quad + I(W_1; V_2^N, \tilde{V}_1^N | \underline{S}^N) + H(Y_1^N | V_1^N, \tilde{V}_2^N, W_2, \underline{S}^N) \\ &\stackrel{(b)}{\leq} N \{\text{Right-Hand Side of (5)}\}. \end{aligned}$$

Here $\epsilon_N \rightarrow 0$ as $N \rightarrow \infty$. (a) is due to Fact 5.2. (b) is due to Fact 5.3 and 5.4, and

$$\begin{aligned} &H(Y_1^N | V_1^N, \tilde{V}_2^N, W_2, \underline{S}^N) \\ &= H(Y_1^N | V_1^N, \tilde{V}_2^N, W_2, \underline{S}^N, X_2^N) \\ &= H(\mathbf{H}_{11} X_1^N | V_1^N, \tilde{V}_2^N, W_2, \underline{S}^N, X_2^N) \leq H(\mathbf{H}_{11} X_1^N | V_1^N) \\ &\leq N(n_{11} - n_{21})^+ \end{aligned}$$

due to Fact 5.1. Hence, (5) holds.

Remark 5.1: In the above proof, we do not make use of the assumption that the realization of the feedback states (S_1^N, S_2^N) is known to the transmitters causally. In other words, even if we allow some genie to provide the whole state sequence (S_1^N, S_2^N) to all four terminals beforehand, the capacity region remains the same.

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