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Working with the GrovePi + RaspberryPi + Java8

Java and the Internet of Things

Eduardo Moranchel
Java Curriculum Developer

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Program Agenda

1. Hardware and software requirements
2. Setup
3. The GrovePi Java libary
4. Build your own project

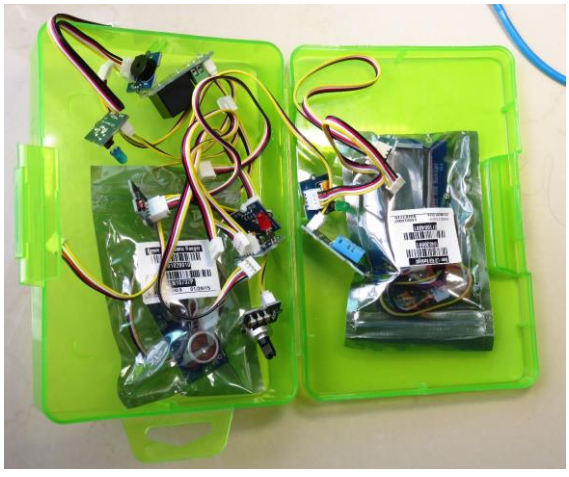
Hardware and software requirements

Boards, sensors and cables

Hardware Requirements

- GrovePi Starter Kit
- Raspberry Pi B (or later)
- SDCard (or MicroSD) 2gb or more.
- Ethernet cable
  - USB Ethernet adapter for some PCs
- MicroUSB power cable

Inside the GrovePi Starter Kit



- GrovePi + board
- Temperature & humidity
- Relay
- Ultrasonic Ranger
- LCD RGB Backlight
- Buzzer
- Sound Sensor
- Light sensor
- Button
- Potenciometer
- Leds

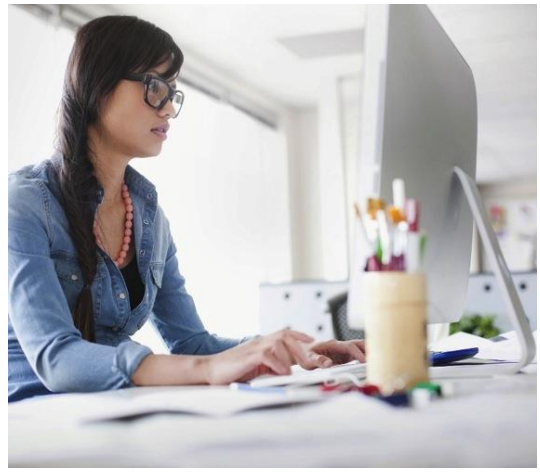
Software Requirements

- In your PC:
  - JDK 8
  - NetBeans 8
  - Maven
- In the Raspberry:
  - JDK8 for ARM
  - Device I/O
  - GrovePi examples and libraries.

Setup

PC Setup

- Install JDK 8
- Install Maven
- Install NetBeans 8



RaspberryPi Configuration

- Install Raspbian in the SD
- Connect pi to screen, keyboard, mouse and setup static IP
  - Install DHCP (optional)
- Install JDK8 for ARM
- Enable i2c, install i2c utils.
- Install the DeviceIO library
- Install GrovePi examples

RaspberryPi easy configuration

- Download the RaspberryPi SD card image from
  https://github.com/emoranchel/IoTDevices
- Use Win32DiskImager to copy ready to use raspbian into the raspberry pi.

Links and QR Codes

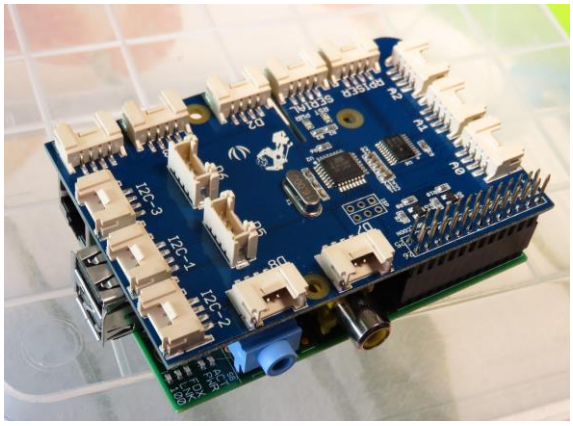
GitHub Repository:

https://github.com/emoranchel/IoTDevices

Win32DiskImager

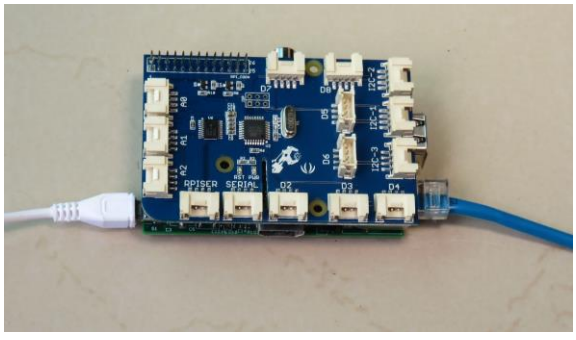
http://sourceforge.net/projects/win32diskimager/

Connect GrovePi



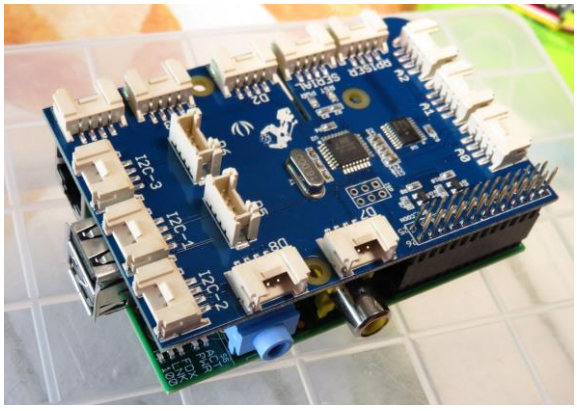
Connect cables

- Ethernet
- USB Cable



Putty (ssh) to 192.168.127.1

Username: pi
Password: raspberry



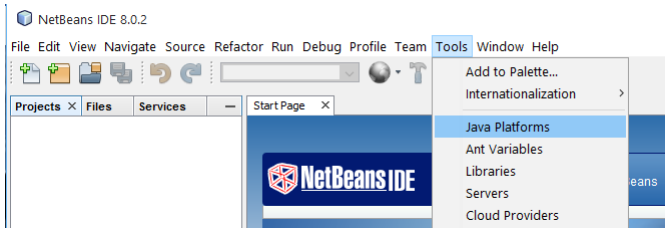
The Pi has already installed:

- Java 8 with Device IO
- I2C tools
- DHCP server and static IP
- Automatic IP in Wireless
- Security policy for DIO
- dio.jar

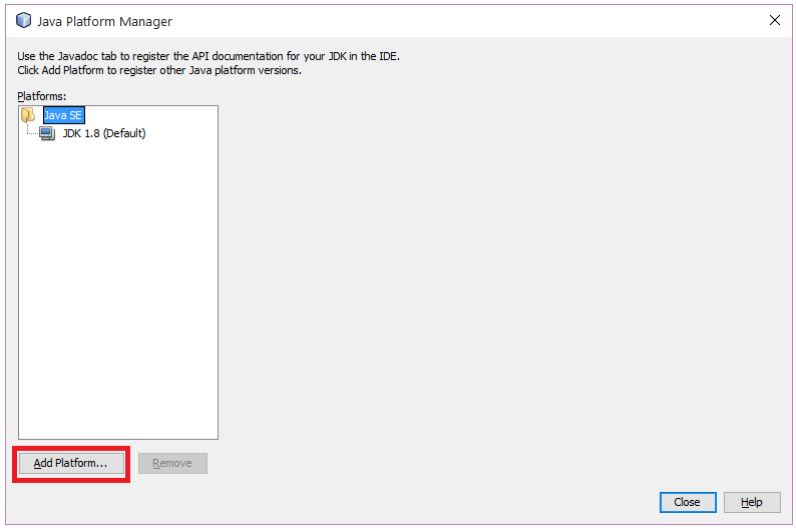
* The raspbian distribution does not have GUI components (X server)

NetBeans Configuration

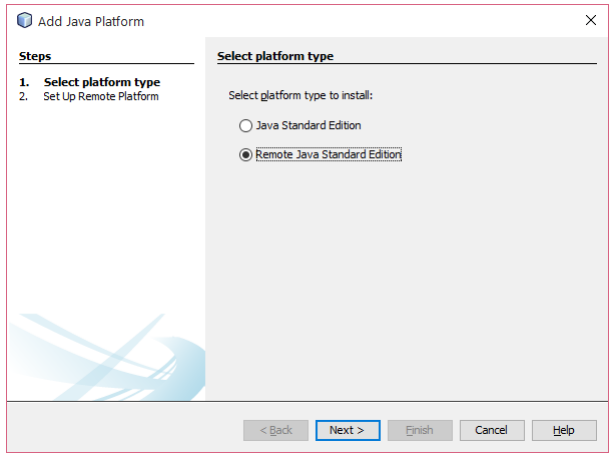
- Setup Java Platforms



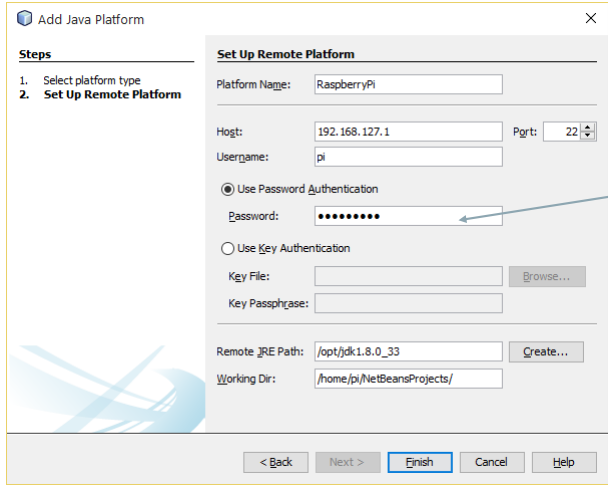
NetBeans Configuration



NetBeans Configuration



NetBeans Configuration



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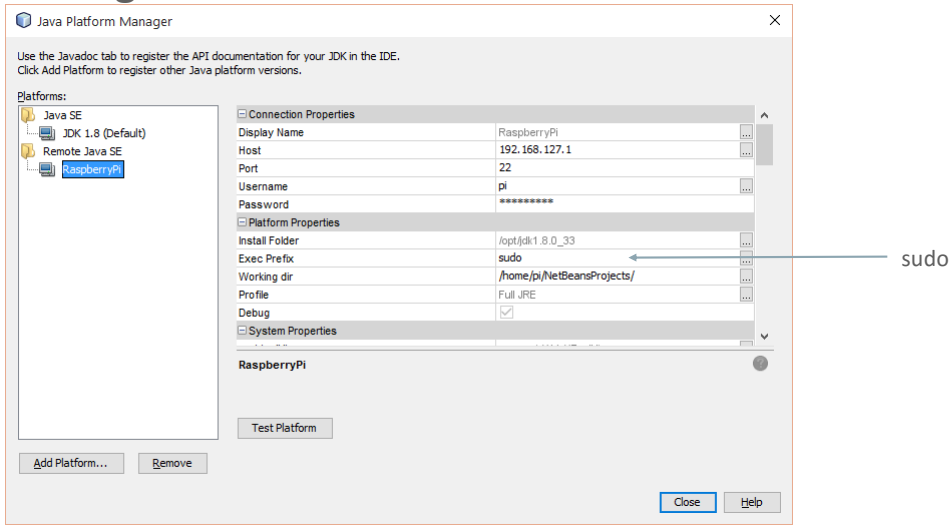
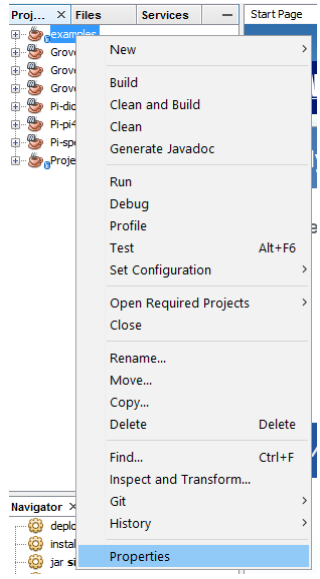


Deploy Project to the raspberry



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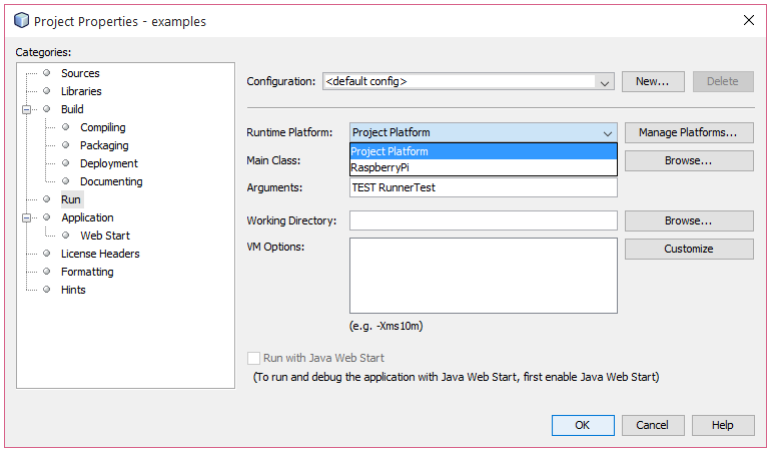

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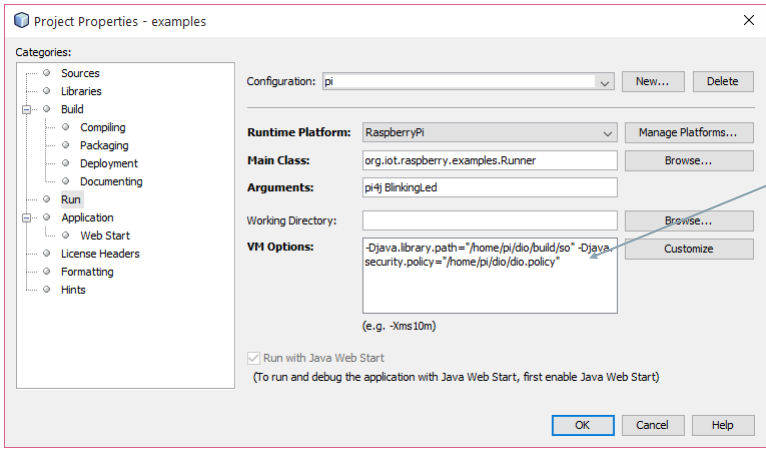

-Djava.library.path=
"/home/pi/dio/build/so"
-Djava.security.policy=
"/home/pi/dio/dio.policy"

The GrovePi Java library

How to use the GrovePi board and sensors using Java

Download

https://github.com/emoranchel/IoTDevices

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Control GrovePi using Pi4J or DeviceIO
Maven projects!
Easy build, config and expand.

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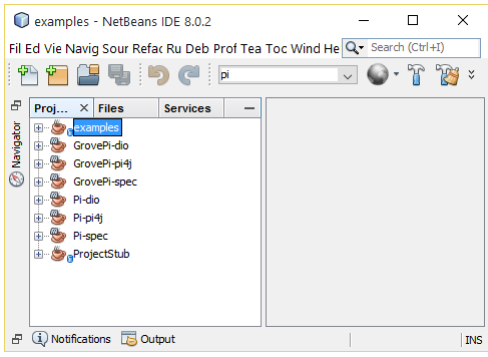
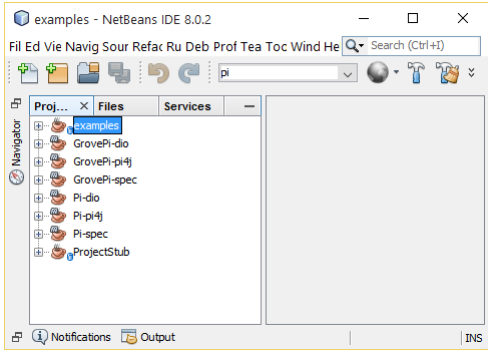
Projects



Pi-*: Projects to control the raspberry pi GPIO pins

GrovePi-*: Projects to control the grovepi board and connected devices.

Projects



*-spec: the specification libraries, defines operations on devices.

*-pi4j: Implementations using the pi4j library

*-dio: Implementation using the DeviceIO library

Library overview

- The GrovePi is an i2c arduino-like board.
  - Can read and write bytes to a bus to send commands and get state from devices.
  - Concurrent operations not supported.
    - You need to synchronize read and write operations so they don't overlap
  - To read you have to write first what you want to read, sleep and then read.
  - Commands are sent usually in sequences of 4 bytes: Command, Pin#, Data1, Data2
  - The library takes care of all this and more

The i2c synchronization with Java8 lambdas! - Interfaces

- Need to run a piece of code locking the i2c bus.

```
public interface GrovePi extends AutoCloseable {
…
  public <T> T exec(GrovePiSequence<T> sequence) throws IOException;
  public void execVoid(GrovePiSequenceVoid sequence) throws IOException;
…
}

public interface GrovePiSequence<T> {
  T execute(GroveIO io) throws IOException;
}

public interface GrovePiSequenceVoid<T> {
  void execute(GroveIO io) throws IOException;
}
```

The i2c synchronization with Java8 lambdas! - GroveIO

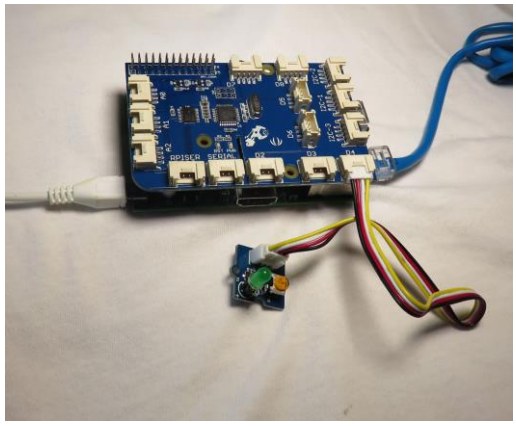
```
public interface GroveIO {

  public void write(int... command) throws IOException;

  public int read() throws IOException;

  public byte[] read(byte[] buffer) throws IOException;

  default public void sleep(long millis) {
    try {
      Thread.sleep(millis);
    } catch (InterruptedException ex) {
    }
  }
}
```

The i2c synchronization with Java8 lambdas! – Implementation

```
public byte[] get() throws IOException {
  byte[] value = grovePi.exec((io) -> {
    io.write(aRead_cmd, pin, unused, unused);
    io.sleep(100);
    return io.read(new byte[bufferSize]);
  });
  if (listener != null) {
    listener.onChange(value);
  }
  return value;
}
```

GrovePi in action: Blinking led

Hardware setup

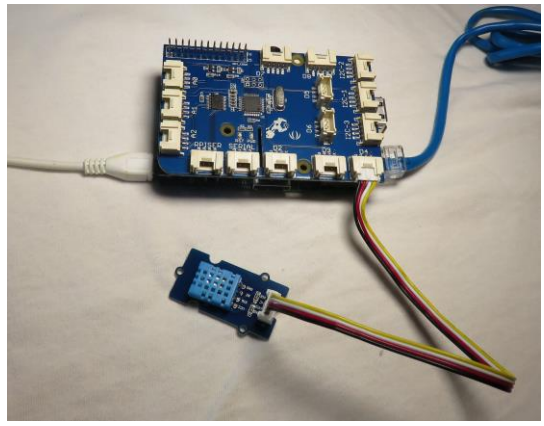


GrovePi in action: Blinking led

```
GrovePi grovePi = new GrovePiDio();
GroveDigitalOut led = grovePi.getDigitalOut(4);

boolean running = true;
boolean state = false;

while (running) {
  state = !state;
  led.set(state);
  Thread.sleep(500);
}
led.set(false);
```

GrovePi in action: Temperature and Humidity

Hardware setup

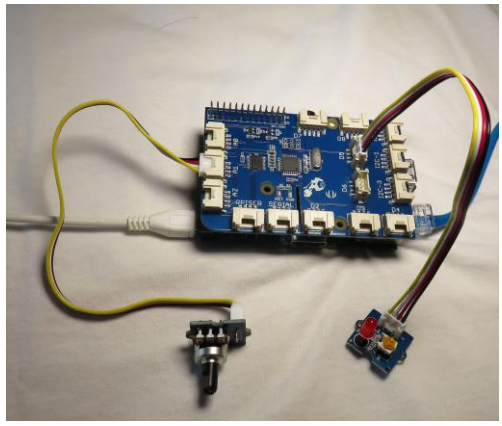


GrovePi in action: Temperature and Humidity

```
GrovePi grovePi = new GrovePiDio();
boolean running = true;

GroveTemperatureAndHumiditySensor dht = new GroveTemperatureAndHumiditySensor(
        grovePi, 4, GroveTemperatureAndHumiditySensor.Type.DHT11);
while (running) {
  try {
    System.out.println(dht.get());
  } catch (IOException ex) { }
}
```


GrovePi in action: Dim a led (Rotary + Led)

Hardware setup

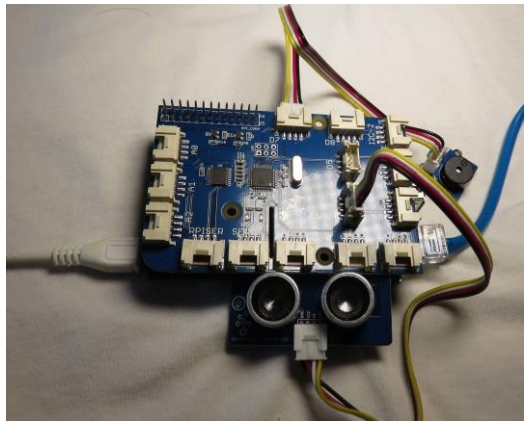


GrovePi in action: Dim a led (Rotary + Led)

```
GrovePi grovePi = new GrovePiDio();
boolean running = true;

 GroveRotarySensor rotarySensor = new GroveRotarySensor(grovePi, 1);
    GroveLed blueLed = new GroveLed(grovePi, 5);
    while (running) {
      try {
        GroveRotaryValue value = rotarySensor.get();
        int brightness = (int) (value.getFactor() * GroveLed.MAX_BRIGTHNESS);
        blueLed.set(brightness);
      } catch (IOException ex) {
        System.out.println("Error");
      }
    }
    blueLed.set(false);
```


GrovePi in action: Proximity alarm (Ultrasonic + Buzzer)

Hardware setup



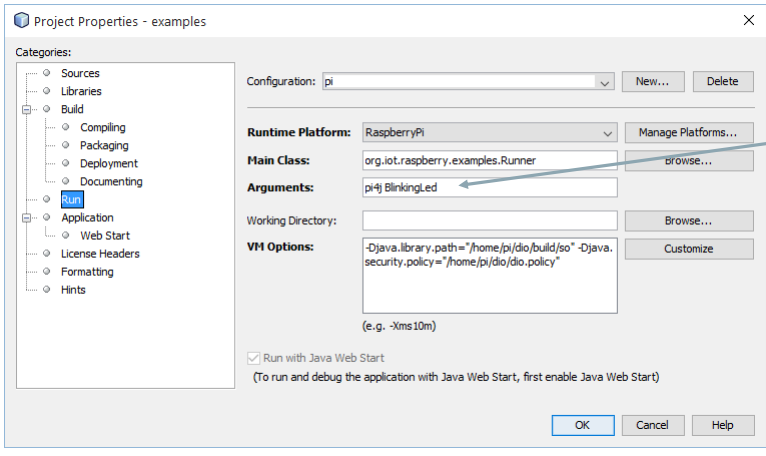
GrovePi in action: Proximity alarm (Ultrasonic + Buzzer)

```
GrovePi grovePi = new GrovePiDio();
boolean running = true;

    GroveUltrasonicRanger ranger = new GroveUltrasonicRanger(grovePi, 6);
    GroveDigitalOut buzzer = grovePi.getDigitalOut(7);
    while (running) {
      try {
        double distance = ranger.get();
        System.out.println(distance);
        buzzer.set(distance < 20);
      } catch (IOException ex) {
        System.out.println("error!");
      }
    }
```


Running the examples

- Download the IoTDevices projects
- Run the build.bat batch to build all the projects and deviceIO jar (maven)
- Open all the IoTDevices projects in NetBeans
- Open the examples Project properties
- In the run tab the arguments define
  - The implementation to use: [pi4j | dio]
  - The name of the class to run
- Run by right-clicking the Project and choosing run from the menu
- Stop by running the example again

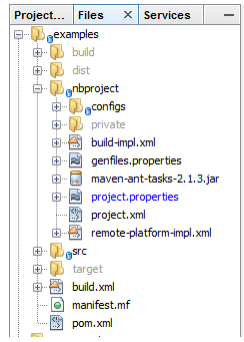
Running the examples



Runs the BlinkingLed class using the pi4j implementation

How does it work?

The examples project is a NetBeans project that uses a plugin to download and use Maven dependencies. Normally it is impossible to run a maven project in a remote platform.



Build your own projects

Easy and fast IoT prototyping using the GrovePi and Java

Build your own project

- Duplicate the ProjectStub project.
- Rename the duplicated project.
- Open the org.iot.stub.Main class (you can rename it if you want)
- Write your app in the run method.
  - You can “run forever” by checking the “running” variable, if the project has to stop the variable will be false
- Run your project in the remote platform
- Stop by running the project again or by typing quit in the console.

The run method

```
public static void run(RaspberryPi pi, GrovePi grovePi, AtomicBoolean running) {
    //Setup code before the main loop
    // Open sensors, files or sockets or HTTP resources
    while(running.get()){
      try{
        //your code goes here
      }catch(Exception ex){}
    }
    //Teardown after the main loop
    // Close opened resources
  }
```

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