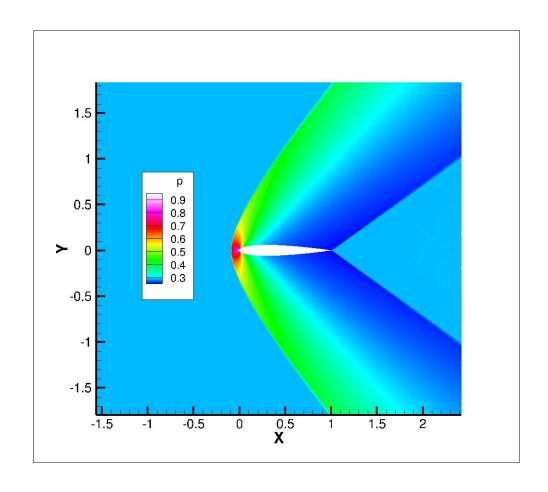


Homework 3
Development of a 2D Euler CFD solver

MEC6602E – Transonic Aerodynamics



2D Euler equations

Local form

$$\frac{\partial \rho}{\partial t} + \frac{\partial (\rho u)}{\partial x} + \frac{\partial (\rho v)}{\partial y} + \frac{\partial (\rho w)}{\partial z} = 0$$

$$\frac{\partial(\rho u)}{\partial t} + \nabla \cdot (\rho u \vec{V}) + \nabla p = 0$$

$$\frac{\partial(\rho v)}{\partial t} + \nabla \cdot (\rho v \vec{V}) + \nabla p = 0$$

$$\frac{\partial(\rho E)}{\partial t} + \nabla \cdot (\rho E \vec{V}) + \nabla \cdot (p \vec{V}) = 0$$

Continuity equation

Momentum equations

Energy equations

2D Euler equations

Integral form: used in the numerical solver

$$\int_{\Omega} \frac{\partial \vec{W}}{\partial t} + \oint_{S} \vec{F}_{c} dS = 0$$

$$\vec{W} = \begin{pmatrix} \rho \\ \rho u \\ \rho v \\ \rho w \end{pmatrix}$$
3D
$$\vec{F}_{c} = \begin{pmatrix} \rho V_{c} \\ \rho u V_{c} + n_{x} p \\ \rho v V_{c} + n_{y} p \\ \rho w V_{c} + n_{z} p \\ \rho E V_{c} + p V_{c} \end{pmatrix}$$

Contravariant velocity:
$$V_{c} = \vec{V} \cdot \vec{n}$$

Code overview

- **Language** : Python
 - Cons:

Lack of low-level optimizations: No direct memory management or hardware-level optimizations. Higher memory usage: Inefficient for handling large-scale simulations compared to low-level languages. Interpreted language: Slower execution compared to compiled languages like C or Fortran.

• Pros:

High level language: User-friendly.

Object-oriented programming language: not the case of C language

Possibility of relying on pre-compiled libraries (e.g. Numpy) to accelerate numerical computations

- Structure: Oriented object
 - Classes: Mesh, ConservedVariables, FluxDiscretizationScheme, TimeIntegrationMethod, Monitor

Code overview

- Type of CFD solver : structured, cell-centered
- Numerical methods
 - Flux discretization: Central scheme with Artificial Dissipation (order 1,2)
 - Time Integration : Explicit Euler (order 1), RK2 (order 2)
 - Global & Local Time stepping
- Inputs: Mesh (plot3D format), AOA, Mach number, Numerical Parameters
- Outputs: Flow solution (.dat file), CL, CD, CM_{c/4} coefficients, residuals evolution, Cp curve, computational time

Validation case: NACA0012 airfoil in freestream flow

- Symmetrical airfoil: CL = 0, CMc/4 = 0 @ 0 deg. AOA
- Comparison with results from Vassbert et Jameson [1] for different flow conditions (see Tab 1)
- Family of grids used: O-grids, from (8x8 to 2049x2049)
- BCs: wall, farfield, connect

	THAIL TEB	<u> </u>
(M,α)	Nonlifting	Lifting
Subcritical Transonic	(0.5M, 0 deg) (0.8M, 0 deg)	(0.5M, 1.25 deg) (0.8M, 1.25 deg)

Tab.1: Comparison cases with [1]

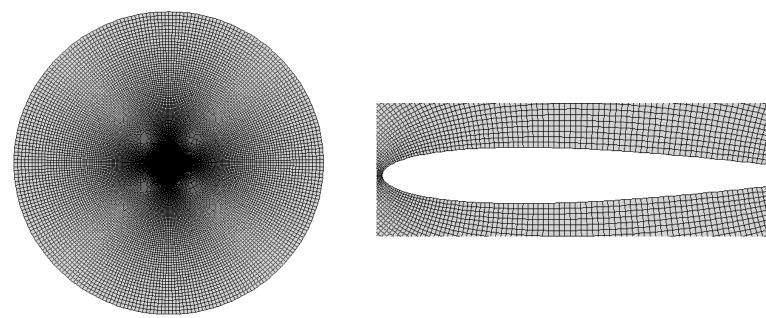
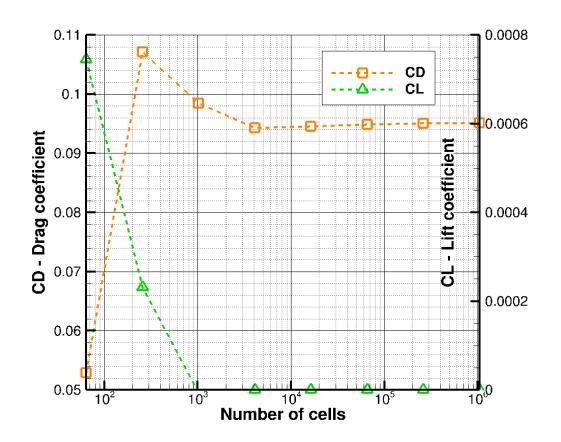
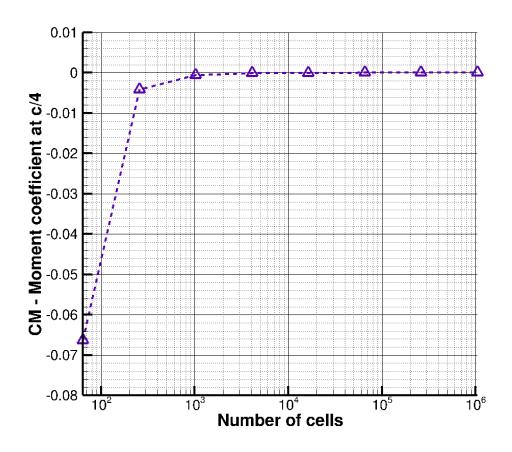


Fig: Overview of the whole mesh (256x256)

Fig: Closeup view of the mesh near the airfoil (256x256)

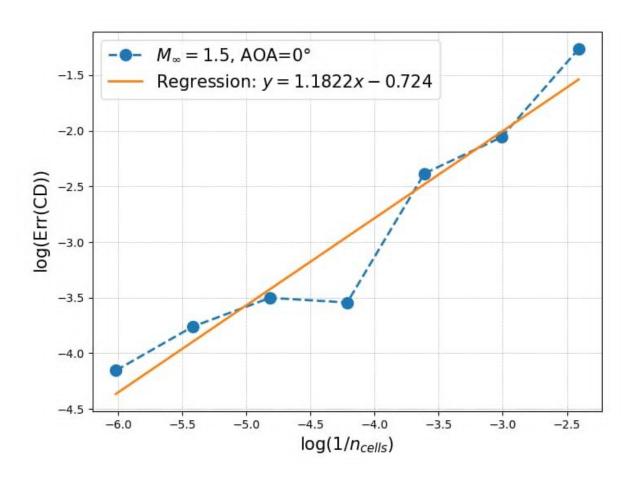
- Performed for supersonic flow: M=1.5, AOA=0°
- Numerical parameters (CFL, dissipation constants) are kept constant across the cases to compare convergence and computational time
- Time Integration : RK2 (CFL = 1)
- Flux discretization : Central scheme with AD $(k_2 = \frac{1}{2}, k_4 = \frac{1}{64})$
- Residual decrease (density): 10⁻¹⁰ to consider the case as converged





- Convergence in aerodynamic coefficients reached for the 128x128 mesh
- Converged values: CL = 0, CMc/4 = 0, CD = 0.095134 (due to shock)

Order of Convergence



 Exponential rise in computational time observed at grid sizes of 1024 and 2048 cells.

Mesh Size	Convergence	Runtime [hh:mm:ss]
1024	10 ⁻¹⁰	8:58:23
2048	10-6	51:52:42

 Optimized parallel processing or advanced algorithms are necessary for scalability in industrial applications

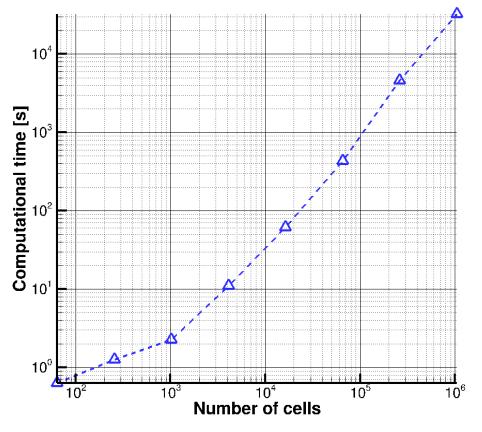
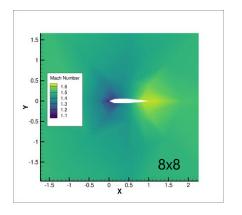
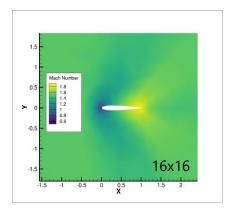
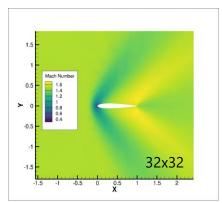


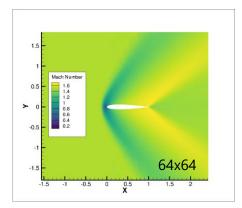
Figure: Computational Time vs. Grid Size: Impact of Increasing Resolution ¹.

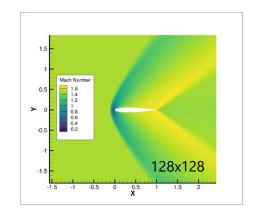
¹Results for grid convergence have not been presented for the largest mesh. That mesh was only computed till a residual of 10⁻⁶.

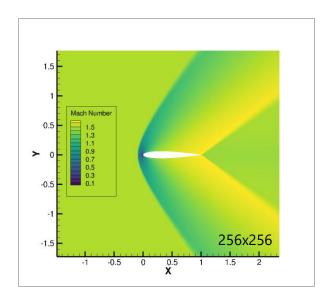


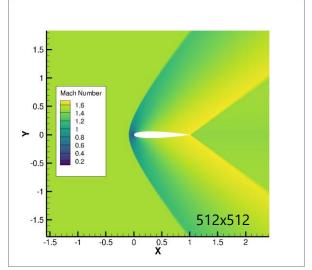


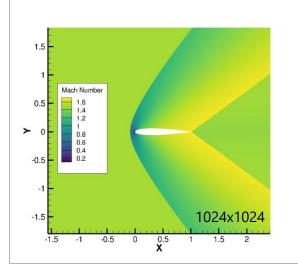


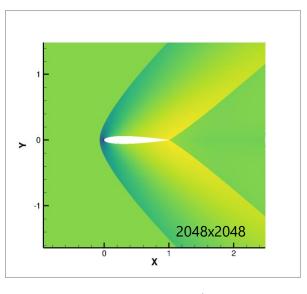






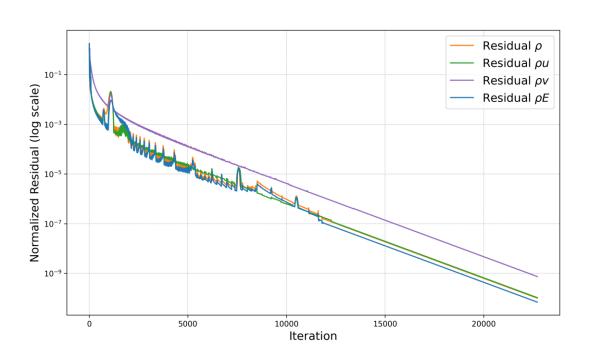


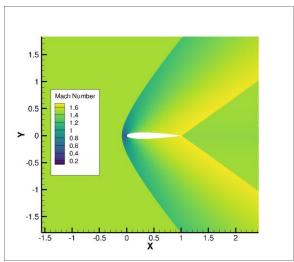


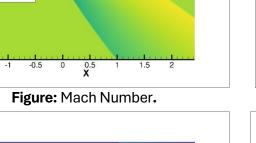


Analysis of Results for the 1024x1024 Grid

- Bow shock at LE and shock at TE
- Symmetrical solution since the problem is symmetric







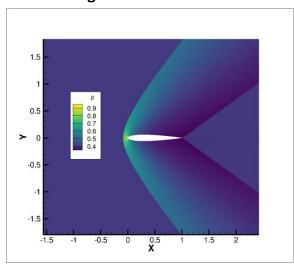


Figure: Pressure.

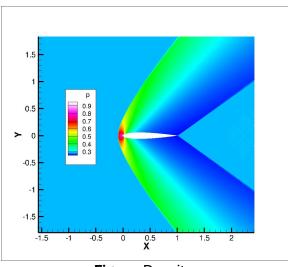


Figure: Density.

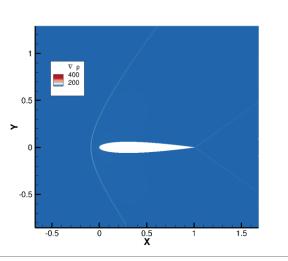
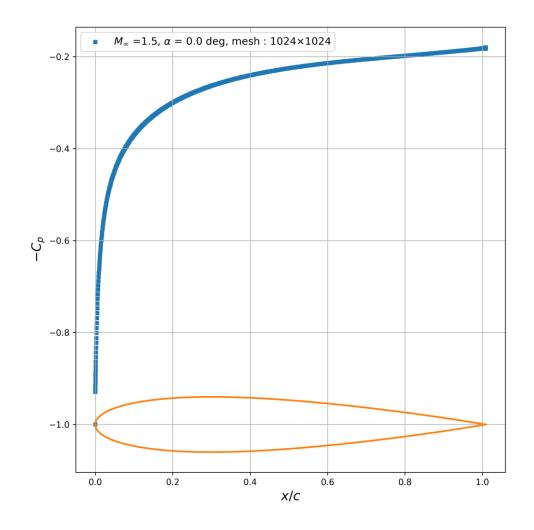


Figure: Density gradient.

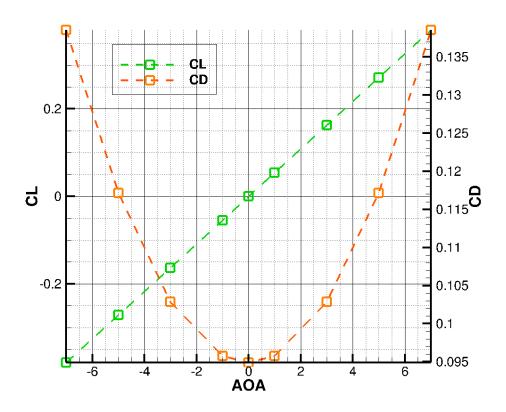
Analysis of Results for the 1024x1024 Grid

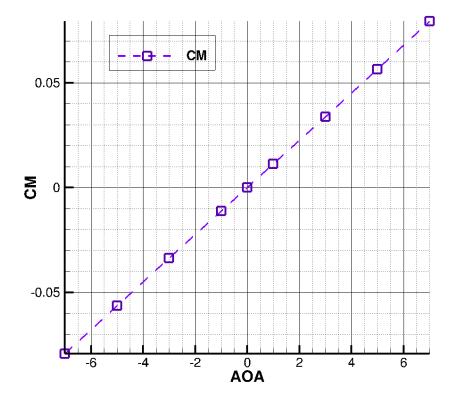
- Pressure distribution on the airfoil physically coherent with the case studied
- Pressure distribution is identic for lower and upper surfaces : CL = 0



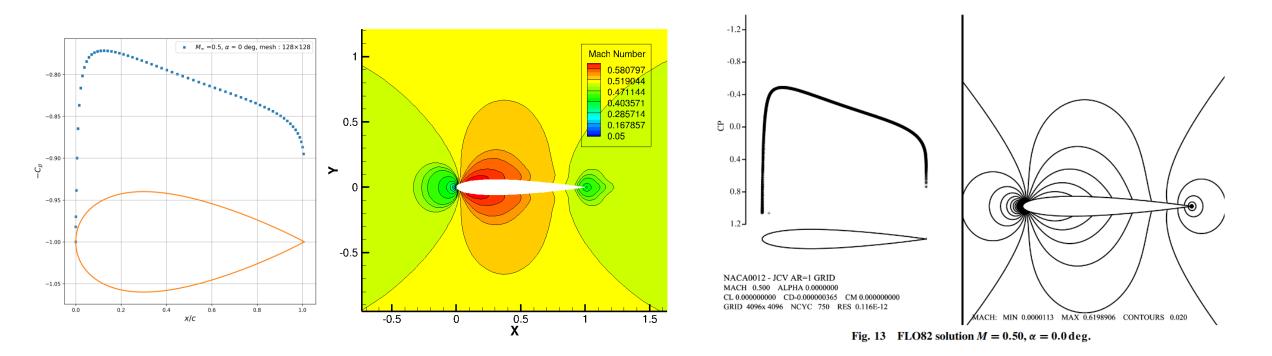
CL/CD/CM vs AOA curves

- Three flow regimes studied : subsonic (M=0.5), transonic (M=0.8), supersonic (M=1.5)
- Results for supersonic case (M=1.5) using 256x256 grid



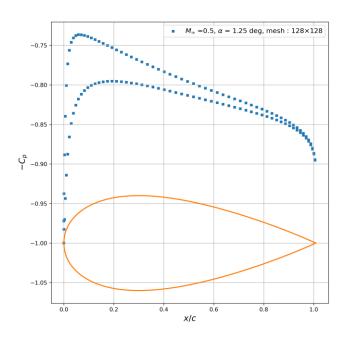


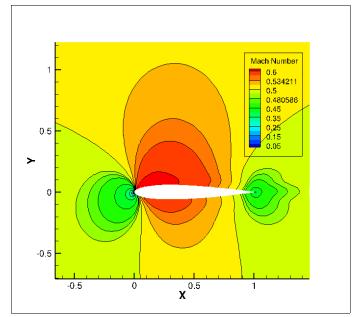
Results for subsonic case (M=0.5) using 128x128 grid – AOA = 0°



Results agree well with the reference publication

Results for subsonic case (M=0.5) using 128x128 grid – AOA = 1.25°





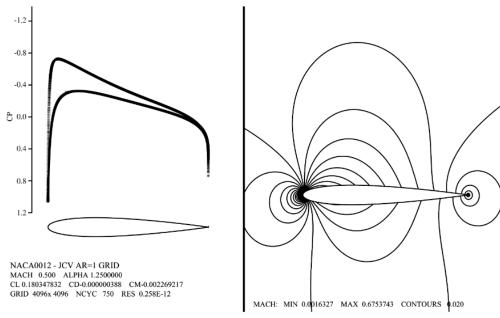
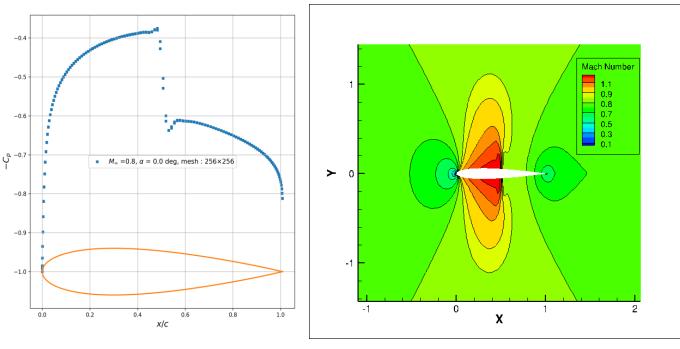


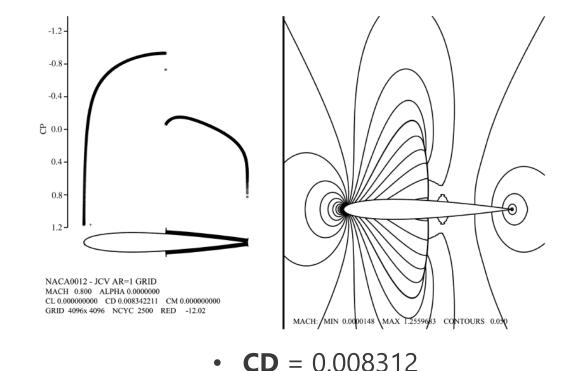
Fig. 14 FLO82 solution
$$M = 0.50$$
, $\alpha = 1.25 \deg$

• CL = 0.180, CD = 0.000298, $CM_{c/4} = 0.00229$

- CL = 0.177, CD = 0.000358, $CM_{c/4} = 0.00211$
- Results agree well with the reference publication

Results for transonic case (M=0.8) using 256x256 grid – AOA = 0°

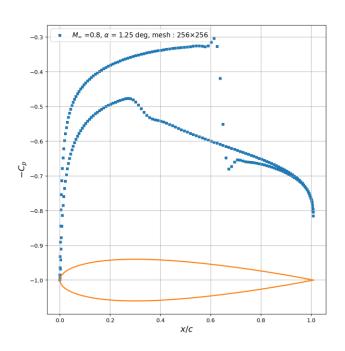


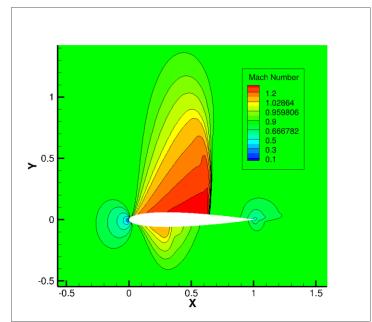


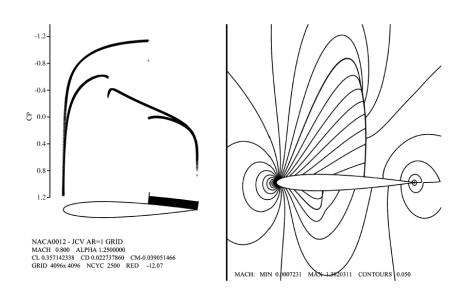
• CD = 0.008131

Results agree well with the reference publication

Results for transonic case (M=0.8) using 256x256 grid – AOA = 1.25°







• CL = 0.364, CD = 0.0226, CM_{c/4} = 0.0415

- CL = 0.357, CD = 0.0227, CM_{c/4} = 0.0391
- Results agree well with the reference publication

Improvements

- Development of implicit time integration schemes to enable faster convergence through the use of higher CFL numbers.
- Development of acceleration techniques, such as multigrid methods and preconditioning, to enhance computational efficiency.
- Optimization of the code, including rewriting it in a low-level language, implementing parallelization strategies, and exploring GPU acceleration to improve performance.
- Verify the implementation of subsonic far-field boundary conditions.
- Incorporate additional validation cases and design the code with greater abstraction to ensure it is not specialized solely for the NACA0012 problem.

References

[1] Vassberg, J. & Jameson, Antony. (2010). In Pursuit of Grid Convergence, Part I: Two-Dimensional Euler Solutions. Journal of Aircraft - J AIRCRAFT. 47. 1152-1166. 10.2514/1.46737.

[2] Blazek, J. (2005). Computational Fluid Dynamics: Principles and Applications. 10.1016/B978-0-08-044506-9.X5000-0.