An Implementation of Sin and Cos Using Gal's Accurate Tables

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This document describes the implementation of functions Sin and Cos in Principia. The goals of that implementation are to be portable (including to machines that do not have a fused multiply-add instruction), achieve good performance, and ensure correct rounding.

Overview

The implementation follows the ideas described by [GB91] and uses accurate tables produced by the method presented in [SZ05]. It guarantees correct rounding with a high probability. In circumstances where it cannot guarantee correct rounding, it falls back to the (slower but correct) implementation provided by the CORE-MATH project [SZG22] [ZSG+24]. More precisely, the algorithm proceeds through the following steps:

- perform argument reduction using Cody and Waite's algorithm in double precision (see [Mul+10, p. 379]);
- if argument reduction loses too many bits (i.e., the argument is close to a multiple of $\frac{\pi}{2}$), fall back to cr_sin or cr_cos;
- otherwise, uses accurate tables and a polynomial approximation to compute Sin or Cos with extra accuracy;
- if the result has a "dangerous rounding configuration" (as defined by [GB91]), fall back to cr_sin or cr_cos;
- otherwise return the rounded result of the preceding computation.

In this document we assume a base-2 floating-point number system with M significand bits¹ similar to the IEEE formats. We define a real function \mathfrak{m} and an integer function \mathfrak{e} denoting the *significand* and *exponent* of a real number, respectively:

$$x = \pm \operatorname{m}(x) \times 2^{\operatorname{e}(x)}$$
 with $2^{M-1} \le \operatorname{m}(x) \le 2^M - 1$

Note that this representation is unique. Furthermore, if x is a floating-point number, $\mathfrak{m}(x)$ is an integer.

The distance between 1 and the next larger floating-point number is:

$$\epsilon_M \coloneqq 2^{1-M}$$

and the distance between 1 and the next smaller floating-point number is $\frac{\epsilon_M}{2}$. The *unit of the last place* of x is defined as:

$$\mathfrak{u}(x)\coloneqq 2^{\mathfrak{e}(x)}$$

In particular, $\mathfrak{u}(1) = \epsilon_M$.

We ignore the exponent bias, overflow and underflow as they play no role in this

Finally, for error analysis we use the accuracy model of [Higo2], equation (2.4): unless otherwise indicated, δ_i is a roundoff factor such that $\delta_i < u = \epsilon_M/2 = 2^{-M}$ (see pages 37 and 38). We also use θ_n and γ_n with the same meaning as in [Higo2], lemma 3.1.

 $^{^{1}}$ In binary64, M = 53.

Argument Reduction

Given an argument x, the purpose of argument reduction is to compute a pair of floating-point numbers $(\hat{x}, \delta \hat{x})$ such that:

$$\begin{cases} \hat{x} + \delta \hat{x} \cong x \pmod{\frac{\pi}{2}} \\ \hat{x} \text{ is approximately in } \left[-\frac{\pi}{4}, \frac{\pi}{4} \right] \\ |\delta \hat{x}| < \mathfrak{u}(\hat{x}) \end{cases}$$

Approximation of π

We approximate $\frac{\pi}{2}$ as the sum of two floating-point numbers:

$$\frac{\pi}{2} \cong C + \delta C$$

where *C* is obtained by dropping the last κ_1 mantissa bits of $\frac{\pi}{2}$:

$$C \coloneqq \left[2^{-\kappa_1} \operatorname{m}\left(\frac{\pi}{2}\right)\right] 2^{\kappa_1} \operatorname{u}\left(\frac{\pi}{2}\right)$$

and δC is defined as $\left[\left[\frac{\pi}{2} - C \right] \right]$. Obviously we have:

$$0<\frac{\pi}{2}-C<2^{\kappa_1}\,\mathfrak{u}\!\left(\frac{\pi}{2}\right)$$

but if κ_1 is chosen to cut the significand of $\frac{\pi}{2}$ at a place where it has zeroes, we can actually have a stricter bound:

$$\frac{\pi}{2} - C < 2^{\kappa_2} \mathfrak{u}\left(\frac{\pi}{2}\right) \quad \text{with} \quad \kappa_2 \le \kappa_1 \tag{1}$$

and therefore:

$$\mathfrak{u}\left(\frac{\pi}{2}-C\right)<\frac{2^{\kappa_2}\,\mathfrak{u}\left(\frac{\pi}{2}\right)}{\mathfrak{m}\left(\frac{\pi}{2}-C\right)}\leq 2^{\kappa_2-M+1}\,\mathfrak{u}\left(\frac{\pi}{2}\right)$$

Since the function u is always a power of 2 this implies:

$$\mathfrak{u}\left(\frac{\pi}{2}-C\right)=2^{\kappa_2-M}\,\mathfrak{u}\left(\frac{\pi}{2}\right)$$

and:

$$\left|\frac{\pi}{2} - C - \delta C\right| \le \frac{1}{2} \operatorname{u}\left(\frac{\pi}{2} - C\right) = 2^{\kappa_2 - M - 1} \operatorname{u}\left(\frac{\pi}{2}\right) \tag{2}$$

In other words, we have a representation with a significand that has effectively $2M - \kappa_2$ bits and is such that multiplying C by an integer less than or equal to 2^{κ_1} is exact. The representation of $\frac{\pi}{2}$ has three zeroes after the 18th bit of its significand, so by taking $\kappa_1 = 18$ we have $\kappa_2 = 14$.

Argument Reduction for Small Angles

If
$$|x| < \left[\frac{\pi}{4}\right]$$
 then $\hat{x} = x$ and $\delta \hat{x} = 0$.

Argument Reduction for Medium Angles

If $|x| \le 2^{\kappa_1} \left[\frac{\pi}{2} \right]$ then we compute:

$$\begin{cases} n &= \left\| \left\| x \right\| \frac{2}{\pi} \right\| \right\| \\ y &= x - n \ C \\ \delta y &= \left[\left[n \ \delta C \right] \right] \\ \hat{x} &= \left[y - \delta y \right] \\ \delta \hat{x} &= (y - \hat{x}) - \delta y \end{cases}$$

Let's first show that $|n| \le 2^{\kappa_1}$.:

$$|x| \le 2^{\kappa_1} \frac{\pi}{2} (1 + \delta_1)$$

$$|n| \le \left[2^{\kappa_1} \frac{\pi}{2} (1 + \delta_1) \frac{2}{\pi} (1 + \delta_2) (1 + \delta_3) \right]$$

$$\le \left[2^{\kappa_1} (1 + \gamma_3) \right]$$

Because $2^{\kappa_1}\gamma_3$ is very small (less that 2^{-33}), the rounding cannot cause n to exceed 2^{κ_1} .

The product n C is exact thanks to the κ_1 trailing zeroes of C. The subtraction x-n C is exact by Sterbenz's Lemma. Finally, the last two steps form a compensated summation so that $\hat{x} + \delta \hat{x} = y + \delta y$.

To compute the overall error on argument reduction, first remember that, from equation 2 we have:

$$C + \delta C = \frac{\pi}{2} + \delta_5$$
 with $|\delta_5| \le 2^{\kappa_2 - M - 1} \operatorname{u}\left(\frac{\pi}{2}\right)$

The error computation proceeds as follows:

$$y + \delta y = x - n C - n \delta C (1 + \delta_4)$$
$$= x - n(C + \delta C) - n \delta C \delta_4$$
$$= x - n \frac{\pi}{2} - n(\delta_5 + \delta C \delta_4)$$

from which we can deduce an upper bound on the absolute error:

$$\left| y + \delta y - \left(x - n \frac{\pi}{2} \right) \right| < 2^{\kappa_1} 2^{\kappa_2} \operatorname{u} \left(\frac{\pi}{2} \right) (2^{-M-1} + 2^{-M}) = \frac{3}{2} 2^{\kappa_1 + \kappa_2 - M} \operatorname{u} \left(\frac{\pi}{2} \right)$$

where we have used the upper bound for δC given by equation 1.

Argument Reduction for Large Angles

Accurate Tables and Their Generation

Computation of the Functions

Sin

Near Zero

For \hat{x} near zero we evaluate:

$$\widehat{x^{2}} = [[\hat{x}^{2}]] = \hat{x}^{2}(1 + \delta_{1})$$

$$\widehat{x^{3}} = [[\hat{x} \hat{x^{2}}]] = \hat{x}^{3}(1 + \delta_{1})(1 + \delta_{2})$$

$$\widehat{p} = [[a\widehat{x^{2}} + b]] = (a\hat{x}^{2}(1 + \delta_{1}) + b)(1 + \delta_{3})$$

$$s(x) := \hat{x} + [[[\widehat{x^{3}}\widehat{p}]]] + \delta \hat{x}]$$

$$= \hat{x} + (\hat{x}^{3}(1 + \delta_{1})(1 + \delta_{2})(a\hat{x}^{2}(1 + \delta_{1}) + b)(1 + \delta_{3})(1 + \delta_{4}) + \delta \hat{x})(1 + \delta_{5})$$

$$= \hat{x} + a\hat{x}^{3}(1 + \theta_{5}) + b\hat{x}^{5}(1 + \theta_{4}) + \delta \hat{x}(1 + \delta_{5})$$

References

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