

An Implementation of Sin and Cos Using Gal's Accurate Tables

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This document describes the implementation of functions `Sin` and `Cos` in Principia. The goals of that implementation are to be portable (including to machines that do not have a fused multiply-add instruction), achieve good performance, and ensure correct rounding.

Overview

The implementation follows the ideas described by [GB91] and uses accurate tables produced by the method presented in [SZ05]. It guarantees correct rounding with a high probability. In circumstances where it cannot guarantee correct rounding, it falls back to the (slower but correct) implementation provided by the CORE-MATH project [SZG22] [ZSG+24]. More precisely, the algorithm proceeds through the following steps:

- perform argument reduction using Cody and Waite's algorithm in double precision (see [Mul+10, p. 379]);
- if argument reduction loses too many bits (i.e., the argument is close to a multiple of $\frac{\pi}{2}$), fall back to `cr_sin` or `cr_cos`;
- otherwise, uses accurate tables and a polynomial approximation to compute `Sin` or `Cos` with extra accuracy;
- if the result has a “dangerous rounding configuration” (as defined by [GB91]), fall back to `cr_sin` or `cr_cos`;
- otherwise return the rounded result of the preceding computation.

In this document we assume a base-2 floating-point number system with M significand bits¹ similar to the IEEE formats. We define a real function `m` and an integer function `e` denoting the *significand* and *exponent* of a real number, respectively:

$$x = \pm m(x) \times 2^{e(x)} \quad \text{with} \quad 2^{M-1} \leq m(x) \leq 2^M - 1$$

Note that this representation is unique. Furthermore, if x is a floating-point number, $m(x)$ is an integer.

The distance between 1 and the next larger floating-point number is:

$$\epsilon_M := 2^{1-M}$$

and the distance between 1 and the next smaller floating-point number is $\frac{\epsilon_M}{2}$. The *unit of the last place* of x is defined as:

$$u(x) := 2^{e(x)}$$

In particular, $u(1) = \epsilon_M$ and:

$$\frac{2x}{\epsilon_M} < \frac{x}{2^{M-1}} \leq u(x) \leq \frac{x}{2^{M-1}} = \frac{x}{\epsilon_M}$$

We ignore the exponent bias, overflow and underflow as they play no role in this discussion.

Finally, for error analysis we use the accuracy model of [Higo2], equation (2.4): unless otherwise indicated, δ_i is a roundoff factor such that $\delta_i < u = \epsilon_M/2 = 2^{-M}$ (see pages 37 and 38). We also use θ_n and γ_n with the same meaning as in [Higo2], lemma 3.1.

¹In binary64, $M = 53$.

Approximation of $\frac{\pi}{2}$

To perform argument reduction, we need to build approximations of $\frac{\pi}{2}$ with extra accuracy and analyse the circumstances under which they may be used and the errors that they entail on the reduced argument.

We start by defining the truncation function $\text{Tr}(\kappa, z)$ which clears the last κ bits of the significand of z :

$$\text{Tr}(\kappa, z) := \lfloor 2^{-\kappa} m(z) \rfloor 2^\kappa u(z)$$

The definition of the floor function implies:

$$0 \leq z - \text{Tr}(\kappa, z) < 2^\kappa u(z)$$

Furthermore if the bits that are being truncated start with k zeros we have the stricter inequality:

$$0 \leq z - \text{Tr}(\kappa, z) < 2^{\kappa'} u(z) \quad \text{with} \quad \kappa' = \kappa - k$$

This leads to the following upper bound for the unit of the last place of the truncation error:

$$u(z - \text{Tr}(\kappa, z)) < \frac{2^{\kappa'} u(z)}{m(z - \text{Tr}(\kappa, z))} \leq 2^{\kappa' - M + 1} u(z)$$

which can be made more precise by noting that the function u is always a power of 2:

$$u(z - \text{Tr}(\kappa, z)) = 2^{\kappa' - M} u(z) \tag{1}$$

Two-Term Approximation

In this scheme we approximate $\frac{\pi}{2}$ as the sum of two floating-point numbers:

$$\frac{\pi}{2} \simeq C_1 + \delta C_1$$

which are defined as:

$$\begin{cases} C_1 &:= \text{Tr}\left(\kappa_1, \frac{\pi}{2}\right) \\ \delta C_1 &:= \left\lfloor \frac{\pi}{2} - C_1 \right\rfloor \end{cases}$$

Equation (1) becomes:

$$u\left(\frac{\pi}{2} - C_1\right) = 2^{\kappa'_1 - M} u\left(\frac{\pi}{2}\right)$$

where $\kappa'_1 \leq \kappa_1$ accounts for any leading zeroes in the bits of $\frac{\pi}{2}$ that are being truncated. The absolute error on the two-term approximation is therefore:

$$\left| \frac{\pi}{2} - C_1 - \delta C_1 \right| \leq \frac{1}{2} u\left(\frac{\pi}{2} - C_1\right) = 2^{\kappa'_1 - M - 1} u\left(\frac{\pi}{2}\right) \tag{2}$$

In other words, we have a representation with a significand that has effectively $2M - \kappa'_1$ bits and is such that multiplying C_1 by an integer less than or equal to $2^{\kappa'_1}$ is exact.

Three-Term Approximation

In this scheme we approximate $\frac{\pi}{2}$ as the sum of three floating-point numbers:

$$\frac{\pi}{2} \simeq C_2 + C'_2 + \delta C_2$$

which are defined as:

$$\begin{cases} C_2 &:= \text{Tr}\left(\kappa_2, \frac{\pi}{2}\right) \\ C'_2 &:= \text{Tr}\left(\kappa_2, \frac{\pi}{2} - C_2\right) \\ \delta C_2 &:= \left\lfloor \frac{\pi}{2} - C_2 - C'_2 \right\rfloor \end{cases}$$

Applying equation (1) to the definition of C_2 yields:

$$u\left(\frac{\pi}{2} - C_2\right) = 2^{\kappa'_2 - M} u\left(\frac{\pi}{2}\right)$$

where $\kappa'_2 \leq \kappa_2$ accounts for any leading zeroes in the bits of $\frac{\pi}{2}$ that are being truncated. Similarly, applying equation (1) to the definition of C'_2 yields:

$$\begin{aligned} u\left(\frac{\pi}{2} - C_2 - C'_2\right) &= 2^{\kappa''_2 - M} u\left(\frac{\pi}{2} - C_2\right) \\ &= 2^{\kappa'_2 + \kappa''_2 - 2M} u\left(\frac{\pi}{2}\right) \end{aligned}$$

where $\kappa''_2 \leq \kappa_2$ accounts for any leading zeroes in the bits of $\frac{\pi}{2} - C_2$ that are being truncated. Note that normalization of the significand of $\frac{\pi}{2} - C_2$ effectively drops the zeroes at positions κ_2 to κ'_2 and therefore the computation of C'_2 applies to a significand aligned on position κ'_2 .

In other words, we have a representation with a significand that has effectively $3M - \kappa'_2 - \kappa''_2$ bits and is such that multiplying C_2 and C'_2 by an integer less than or equal to 2^{κ_2} is exact.

Argument Reduction

Given an argument x , the purpose of argument reduction is to compute a pair of floating-point numbers $(\hat{x}, \delta\hat{x})$ such that:

$$\begin{cases} \hat{x} + \delta\hat{x} \cong x \pmod{\frac{\pi}{2}} \\ \hat{x} \text{ is approximately in } \left[-\frac{\pi}{4}, \frac{\pi}{4}\right] \\ |\delta\hat{x}| < u(\hat{x}) \end{cases}$$

Argument Reduction for Small Angles

If $|x| < \left\lfloor \frac{\pi}{4} \right\rfloor$ then $\hat{x} = x$ and $\delta\hat{x} = 0$.

Argument Reduction Using the Two-Term Approximation

If $|x| \leq 2^{\kappa_1} \left\lfloor \frac{\pi}{2} \right\rfloor$ we compute:

$$\begin{cases} n &= \left\lfloor \left\lfloor x \left\lfloor \frac{2}{\pi} \right\rfloor \right\rfloor \right\rfloor \\ y &= x - n C_1 \\ \delta y &= \llbracket n \delta C_1 \rrbracket \\ \hat{x} &= \llbracket y - \delta y \rrbracket \\ \delta\hat{x} &= (y - \hat{x}) - \delta y \end{cases}$$

Let's first show that $|n| \leq 2^{\kappa_1}$. :

$$\begin{aligned} |x| &\leq 2^{\kappa_1} \frac{\pi}{2} (1 + \delta_1) \\ |n| &\leq \left\lceil 2^{\kappa_1} \frac{\pi}{2} (1 + \delta_1) \frac{2}{\pi} (1 + \delta_2) (1 + \delta_3) \right\rceil \\ &\leq \lceil 2^{\kappa_1} (1 + \gamma_3) \rceil \end{aligned}$$

As long as $2^{\kappa_1} \gamma_3$ is small enough (less than $1/2$), the rounding cannot cause n to exceed 2^{κ_1} .

The product $n C_1$ is exact thanks to the κ_1 trailing zeroes of C_1 . The subtraction $x - n C_1$ is exact by Sterbenz's Lemma. Finally, the last two steps form a compensated summation so that $\hat{x} + \delta\hat{x} = y + \delta y$.

To compute the overall error on argument reduction, first remember that, from equation (2) we have:

$$C_1 + \delta C_1 = \frac{\pi}{2} + \delta_5 \quad \text{with} \quad |\delta_5| \leq 2^{\kappa'_1 - M - 1} u\left(\frac{\pi}{2}\right)$$

The error computation proceeds as follows:

$$\begin{aligned} y + \delta y &= x - n C_1 - n \delta C_1 (1 + \delta_4) \\ &= x - n(C_1 + \delta C_1) - n \delta C_1 \delta_4 \\ &= x - n \frac{\pi}{2} - n(\delta_5 + \delta C_1 \delta_4) \end{aligned}$$

from which we can deduce an upper bound on the absolute error:

$$\left| y + \delta y - \left(x - n \frac{\pi}{2} \right) \right| < 2^{\kappa_1} 2^{\kappa_2} u\left(\frac{\pi}{2}\right) (2^{-M-1} + 2^{-M}) = \frac{3}{2} 2^{\kappa_1 + \kappa'_1 - M} u\left(\frac{\pi}{2}\right)$$

where we have used the upper bound for δC_1 given by equation ??.

If we want $\hat{x} + \delta \hat{x}$ to have κ_3 extra bits of accuracy, we must have:

$$\frac{3}{2} 2^{\kappa_1 + \kappa'_1 - M} u\left(\frac{\pi}{2}\right) \leq 2^{-\kappa_3} |u(\hat{x})| \leq 2^{-\kappa_3 - M + 1} |\hat{x}|$$

which leads to the following condition on the reduced angle:

$$|\hat{x}| \geq \frac{3}{2} 2^{\kappa_1 + \kappa'_1 + \kappa_3} u\left(\frac{\pi}{2}\right) = \frac{3}{2} 2^{1 + \kappa_1 + \kappa'_1 + \kappa_3 - M}$$

Argument Reduction for Large Angles

Accurate Tables and Their Generation

Computation of the Functions

Sin

Near Zero

For \hat{x} near zero we evaluate:

$$\begin{aligned} \widehat{x^2} &= \llbracket \hat{x}^2 \rrbracket = \hat{x}^2 (1 + \delta_1) \\ \widehat{x^3} &= \llbracket \hat{x} \widehat{x^2} \rrbracket = \hat{x}^3 (1 + \delta_1)(1 + \delta_2) \\ \hat{p} &= \llbracket a \widehat{x^2} + b \rrbracket = (a \hat{x}^2 (1 + \delta_1) + b)(1 + \delta_3) \\ s(x) &:= \hat{x} + \llbracket \llbracket \widehat{x^3} \hat{p} \rrbracket + \delta \hat{x} \rrbracket \\ &= \hat{x} + (\hat{x}^3 (1 + \delta_1)(1 + \delta_2)(a \hat{x}^2 (1 + \delta_1) + b)(1 + \delta_3)(1 + \delta_4) + \delta \hat{x})(1 + \delta_5) \\ &= \hat{x} + a \hat{x}^5 (1 + \theta_5) + b \hat{x}^5 (1 + \theta_4) + \delta \hat{x} (1 + \delta_5) \end{aligned}$$

References

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