

We have $(n-1) + (n-2) + (n-3) + 2 = 3n-3$ equations with $3n-3$ unknowns.

$$\underbrace{3(n-1)}_{b_i, c_i, d_i} \rightarrow n-1 \text{ segments}$$

We set $\delta_i = x_{i+1} - x_i$

$$\Delta_i = y_{i+1} - y_i$$

Equations (3) can be solved for d_i :
$$d_i = \frac{c_{i+1} - c_i}{3\delta_i} \quad (5) \quad (i=1, \dots, n-1)$$

Equations (1) can be solved for b_i :

$$\begin{aligned} b_i &= \frac{\Delta_i}{\delta_i} - c_i \delta_i - d_i \delta_i^2 \\ &= \frac{\Delta_i}{\delta_i} - c_i \delta_i - \frac{\delta_i}{3} (c_{i+1} - c_i) \\ &= \frac{\Delta_i}{\delta_i} - \frac{\delta_i}{3} (2c_i + c_{i+1}) \quad (6) \end{aligned}$$

Substituting (5) and (6) into (2) results in $n-2$ equations in c_2, \dots, c_{n-1} :

$$\delta_1 c_1 + 2(\delta_1 + \delta_2) c_2 + \delta_2 c_3 = 3 \left(\frac{\Delta_2}{\delta_2} - \frac{\Delta_1}{\delta_1} \right)$$

\vdots

$$\delta_{n-2} c_{n-2} + 2(\delta_{n-2} + \delta_{n-1}) c_{n-1} + \delta_{n-1} c_n = 3 \left(\frac{\Delta_{n-1}}{\delta_{n-1}} - \frac{\Delta_{n-2}}{\delta_{n-2}} \right)$$

Matrix form

$$\begin{bmatrix} 1 & 0 & 0 \\ \delta_1 & 2(\delta_1 + \delta_2) & \delta_2 \\ 0 & \delta_2 & 2(\delta_2 + \delta_3) & \delta_3 \\ & \ddots & \ddots & \ddots \\ 0 & & 0 & 1 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \\ \vdots \\ C_n \end{bmatrix} = \begin{bmatrix} 0 \\ 3\left(\frac{\Delta_2}{\delta_2} - \frac{\Delta_1}{\delta_1}\right) \\ \vdots \\ 3\left(\frac{\Delta_{n-1}}{\delta_{n-1}} - \frac{\Delta_{n-2}}{\delta_{n-2}}\right) \\ 0 \end{bmatrix} \quad (2)$$

Solving this matrix form (Gauss elimination or LU decomposition), you will get C_i, b_i, d_i (from (5) and (6)).

Then, you have segments $S_i(x)$ for cubic spline.

Example:

Find natural cubic spline that interpolates three data points: $(0, 3), (1, -2)$, and $(2, 1)$.

$$\delta_1 = \delta_2 = 1, \quad \Delta_1 = -5, \quad \Delta_2 = +3$$

$$\text{Matrix: } \begin{bmatrix} 1 & 0 & 0 \\ 1 & 4 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \\ C_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 3(3+5) = 24 \\ 0 \end{bmatrix}$$

$$\text{Solution: } \begin{bmatrix} C_1 \\ C_2 \\ C_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 6 \\ 0 \end{bmatrix}$$

Natural spline: $C_1 = C_3 = 0$

$$d_1 = \frac{C_2 - C_1}{3\delta_1} = 2, \quad d_2 = \frac{C_3 - C_2}{3\delta_2} = -2$$

$$b_1 = \frac{\Delta_1}{\delta_1} - \frac{\delta_1}{3} (2\cancel{d_1} + C_2) = -5 - \frac{1}{3}(6) = -7$$

$$b_2 = \frac{\Delta_2}{\delta_2} - \frac{\delta_2}{3} (2C_2 + \cancel{d_3}) = 3 - \frac{1}{3}(12) = -1$$

$$S_i(x) = a_i + b_i(x - x_i) + c_i(x - x_i)^2 + d_i(x - x_i)^3 \quad (3)$$

$$i = 1, 2$$

$$S_1(x) = 3 - 7(x) + 0 \cdot x^2 + 2x^3 \quad \text{on } [0, 1]$$

$$S_2(x) = -2 - 1(x-1) + 6(x-1)^2 - 2(x-1)^3 \quad \text{on } [1, 2]$$

Question: Assume n data points from a function $f(x)$ are given (x_i, y_i)

You are asked to estimate the function value at

x_k where $(\min\{x_i\} < x_k < \max\{x_i\})$.

Which $S_i(x)$ will you compute?

Example:

Given the velocity of a rocket over time in following table, find the velocity at time $t = 16$ s, using cubic spline interpolation.

$t(s)$	$v(m/s)$
\vdots	\vdots
10	227
15	367
20	517
22.5	602
30	901

16 \rightarrow segment ~~20~~ $v(t)$

Will solve this on Friday workshop.

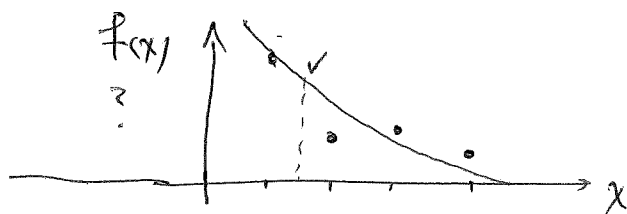
Extrapolation:

(4)

For a given n data points (x_i, y_i) , where $i=1, \dots, n$, produced by a function $f(x)$:

Interpolation: estimates the value of $f(x)$ within the range of x_i .

Extrapolation: estimates $f(x)$ beyond the range of x_i .



Richardson extrapolation method:

Idea is given a sequence of approximations, it combines the approximations to obtain much better estimation.

Richardson extrapolation for differentiation:

Improves the convergence rate of a sequence of approximations for differentiation with central formula.

$$f'(x) \sim \frac{f(x+h) - f(x-h)}{2h} + O(h^2)$$

$$\text{Error: } E_t = O(h^2) \quad \rightarrow \quad E_t = c_2 h^2 + c_3 h^3 + \dots$$

$$E_t \propto h^2$$

$$E_t \approx K h^2, \text{ where } K \text{ is constant over } h.$$

Recall: $\text{Error}_t = (\text{True value} - \text{approximate value})$

(5)

$$E_t = V_t - V_a \longrightarrow V_t = V_a + E_t \longrightarrow \underbrace{V_t}_{\text{unknown}} \approx \underbrace{V_a(h)}_{\text{known}} + \underbrace{Kh^2}_{\text{unknown}}$$

$V_a(h)$: approximate value with step size h .

$$\left. \begin{aligned} V_t &\approx V_a(h) + Kh^2 \\ V_t &\approx V_a\left(\frac{h}{2}\right) + K\left(\frac{h}{2}\right)^2 \end{aligned} \right\} \text{ finding } V_t$$

$$V_t \approx V_a(h) + Kh^2$$

$$4V_t \approx 4V_a\left(\frac{h}{2}\right) + Kh^2$$

$$\hline -3V_t \approx V_a(h) - 4V_a\left(\frac{h}{2}\right) \longrightarrow V_t \approx V_a\left(\frac{h}{2}\right) + \frac{V_a\left(\frac{h}{2}\right) - V_a(h)}{3}$$

Richardson extrapolation for order n approximation $O(h^n)$

$$\begin{aligned} \text{True value: } V_t &\approx V_a(h) + Kh^n \\ V_t &\approx V_a\left(\frac{h}{2}\right) + K\left(\frac{h}{2}\right)^n \end{aligned} \left\{ \begin{aligned} &V_t \approx V_a(h) + Kh^n \\ &2^n V_t \approx 2^n V_a\left(\frac{h}{2}\right) + Kh^n \end{aligned} \right.$$
$$\hline V_t(1 - 2^n) \approx V_a(h) - 2^n V_a\left(\frac{h}{2}\right)$$

Extrapolated approximation: $V_t \approx V_a\left(\frac{h}{2}\right) + \frac{V_a(h/2) - V_a(h)}{2^n - 1}$

Use this for integration.