

General derivation of Runge-Kutta methods.

Use fundamental theorem of calculus:

$$y(t+h) - y(t) = h \int_0^1 y'(t+\theta h) d\theta$$

$$\Rightarrow y(t+h) = y(t) + h \int_0^1 y'(t+\theta h) d\theta$$

$y' = f(t, y)$

use quadrature to
approximate the integral.

As we know $f(t, y)$ we can use values at
several points to approximate $f(t, y)$

This is using nodes and weights.

$$\int_0^1 y'(t+\theta h) d\theta \approx \sum_{i=1}^m \underbrace{\gamma_i}_{\text{weights}} \underbrace{y'(t+d_i h)}_{\text{nodes}}$$

$$\Rightarrow y(t+h) = y(t) + h \sum_{i=1}^m \gamma_i y'(t+d_i h)$$

$$= y(t) + h \sum_{i=1}^m \gamma_i f(t+d_i h, \underbrace{y(t+d_i h)}_{\text{unknown}})$$

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$$y(t + \alpha_i h) = y(t) + h \int_0^{\alpha_i} y'(t + \theta h) d\theta$$

$i = 1, \dots, m$

use quadrature again, but use same α_i .

$$\int_0^{\alpha_i} y'(t + \theta h) d\theta \approx \sum_{j=1}^m \beta_{ij} y'(t + \alpha_j h)$$

Here $\alpha_i = \sum_{j=1}^m \beta_{ij} \alpha_j$ $i = 1, \dots, m$

Now denote $y'(t + \alpha_i h) = k_i$
 $i = 1, \dots, m$

we get $y(t + h) = y(t) + h \sum_{i=1}^m f_i k_i$

where $k_i = f(t + \alpha_i h, y(t) + h \sum_{j=1}^m \beta_{ij} k_j)$
 $i = 1, \dots, m$

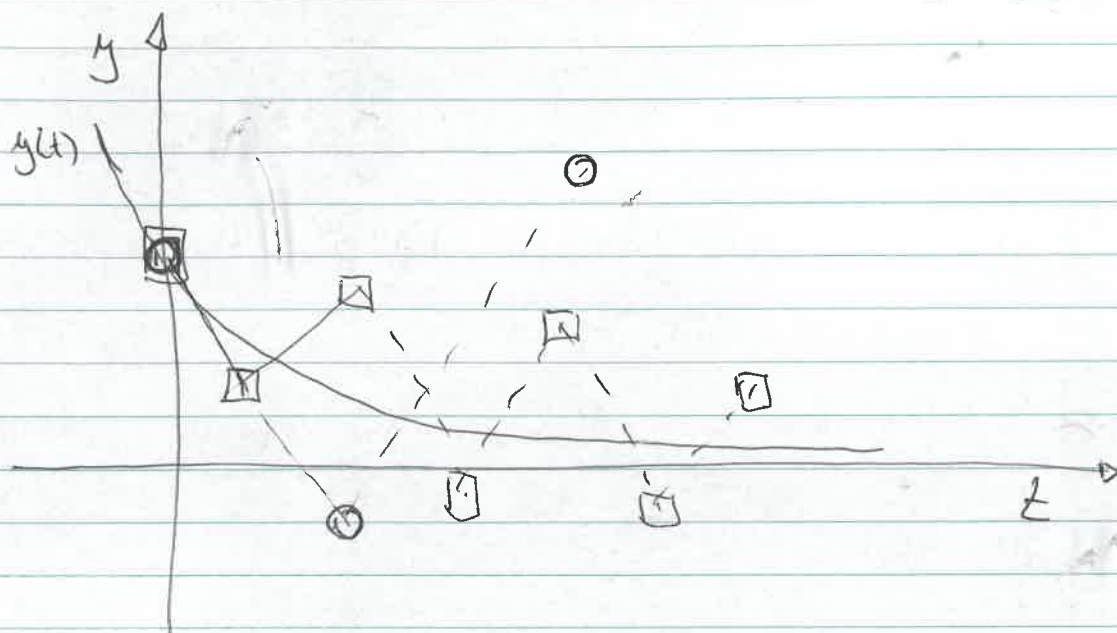
$=_0 y_{n+1} = y_n + h \sum_{i=1}^m f_i k_i$

$k_i = f(t + \alpha_i h, y_n + h \sum_{j=1}^m \beta_{ij} k_j)$
 $i = 1, \dots, m$

stiff problems - implicit methods

$$y'(t) = -15y(t) \quad t \geq 0, y(0) = 1$$

exact solution $y(t) = e^{-15t}$ with $y(t) \rightarrow 0$ as $t \rightarrow \infty$



○ Euler with $h = \frac{1}{4}$ diverges.

□ Euler with $h = \frac{1}{8}$ oscillates.

So far $y_{n+1} = y_n + h f(t_n, y_n; h)$ explicit

$$y = x^2 + 1 \quad \text{or} \quad y = x^3 + 3x - 2 \quad y = f(x_1, x_2, \dots, x_n)$$

$$2x^3y + y^3 = x + 3 \quad \text{implicit}$$

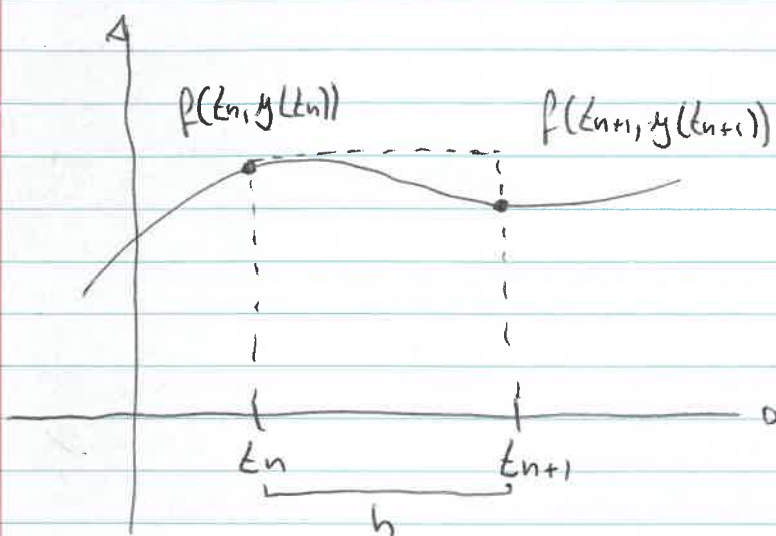
Q8

Ex 6 L1

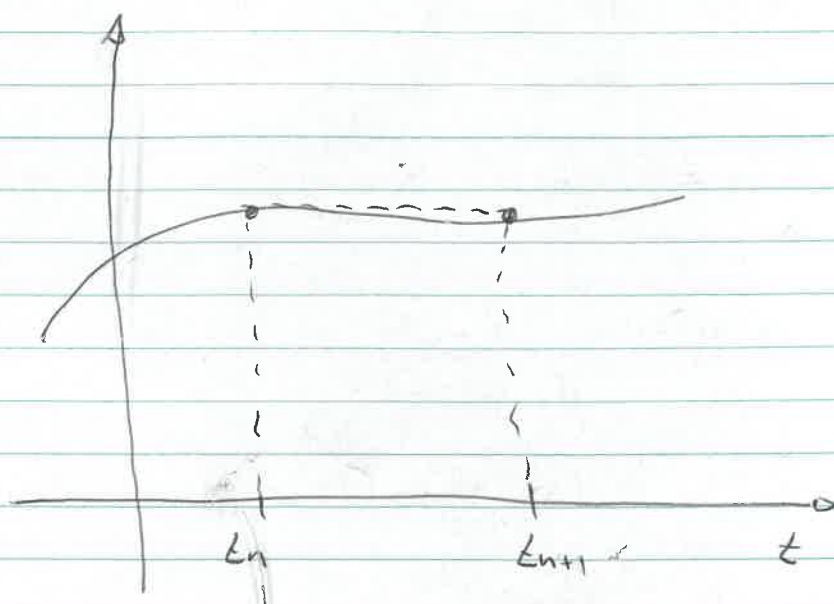
Use fundamental theorem of calculus:

$$\int_{t_n}^{t_{n+1}} f(t, y) dt = y(t_{n+1}) - y(t_n)$$

To get update rule for $y(t_{n+1})$ we can approximate the integral by a rectangle.



Can use height at left side: $f(t_n, y(t_n))$
 $\Rightarrow y(t_{n+1}) - y(t_n) \approx h f(t_n, y(t_n))$
 $\Rightarrow y(t_{n+1}) \approx y(t_n) + h f(t_n, y(t_n))$ explicit
which is Euler's method. It is sometimes
called forward Euler due to this.



Can also use the height at the right side,
so at t_{n+1} . Then we get

$$y(t_{n+1}) - y(t_n) \approx h f(t_{n+1}, y(t_{n+1}))$$

$$\Rightarrow y(t_{n+1}) = y(t_n) + h f(t_{n+1}, y(t_{n+1}))$$

$$\Rightarrow y_{n+1} = y_n + h f(t_{n+1}, y_{n+1}) \quad \text{implicit} \quad \rightarrow O(h^2)$$

This is the implicit Euler method, which
also called the backward Euler due to this.
This leads to a system of equations to
solve, so need something like Newton
or similar to do this. This means implicit
method require more effort but are essential
for some problems.

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w6 L1

$$y' = y^3$$

$$y_{n+1} = y_n + h \cdot y_{n+1}^3$$

$$h y_{n+1}^3 + y_n - y_{n+1} = 0$$

So we need to solve this cubic equation for y_{n+1} at each step.

Example of stiff ODE:

$$y' = -\alpha y \quad \alpha > 0, \quad y(0) = y_0$$

$$\Rightarrow y = y_0 e^{-\alpha t}$$

