

1. (b.b.1) show that  $u^T v \equiv -v^T u$  for any two  $3 \times 1$  cols  $u$  and  $v$

$$u = \begin{bmatrix} 0 & -u_3 & u_2 \\ u_3 & 0 & -u_1 \\ -u_2 & u_1 & 0 \end{bmatrix}$$

$$v = \begin{bmatrix} 0 & -v_3 & v_2 \\ v_3 & 0 & -v_1 \\ -v_2 & v_1 & 0 \end{bmatrix}$$

$$\begin{aligned} \therefore LHS &= u^T v = \begin{bmatrix} 0 & -u_3 & u_2 \\ u_3 & 0 & -u_1 \\ -u_2 & u_1 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \\ &= \begin{bmatrix} -u_3 v_2 + u_2 v_3 \\ u_3 v_1 - u_1 v_3 \\ -u_2 v_1 + u_1 v_2 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} RHS &= -v^T u = \begin{bmatrix} 0 & v_3 & -v_2 \\ -v_3 & 0 & v_1 \\ v_2 & -v_1 & 0 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \\ &= \begin{bmatrix} v_3 u_2 - v_2 u_3 \\ -v_3 u_1 + v_1 u_3 \\ v_2 u_1 - v_1 u_2 \end{bmatrix} \end{aligned}$$

$$\therefore LHS = RHS$$

$\therefore$  Q.E.D.

2. (b.b.2) show that  $C^{-1} = C^T$  from

$$C = \cos \theta I + (-\sin \theta) \hat{a} \hat{a}^T + \sin \theta \hat{a}^{\wedge}$$

$$\therefore (\hat{a}^{\wedge})^T = -\hat{a}^{\wedge}$$

$$\therefore C^T = \cos \theta I + (-\cos \theta) \hat{a} \hat{a}^T - \sin \theta \hat{a}^{\wedge}$$

$$\therefore \text{to prove } C^{-1} = C^T$$

$$\text{is to prove } C \cdot C^T = I$$

$$\begin{aligned} \therefore RHS &= C \cdot C^T = (\cos \theta I + (-\sin \theta) \hat{a} \hat{a}^T + \sin \theta \hat{a}^{\wedge}) \cdot (\cos \theta I + (-\cos \theta) \hat{a} \hat{a}^T - \sin \theta \hat{a}^{\wedge}) \\ &= \cos^2 \theta I + \cos \theta (-\cos \theta) \hat{a} \hat{a}^T - \cancel{\cos \theta \sin \theta \hat{a}^{\wedge}} \\ &\quad + \cos \theta (-\cos \theta) \hat{a} \hat{a}^T + (-\sin \theta)^2 \left( \sum_{i=1}^n \hat{a}_i^2 \right) \hat{a} \hat{a}^T - \cancel{\sin \theta (-\cos \theta) \hat{a} \hat{a}^T} \\ &\quad + \cancel{\sin \theta \cos \theta} + \sin \theta (-\cos \theta) \hat{a}^{\wedge} \hat{a} \hat{a}^T - \sin^2 \theta \hat{a}^{\wedge} \hat{a}^{\wedge} \\ &\quad \left( \hat{a} \hat{a} = \underline{0} \quad \hat{a}^T \hat{a} = \underline{0}^T \right) \\ &= \cos^2 \theta I + 2 \cos \theta (-\cos \theta) \hat{a} \hat{a}^T + \sin^2 \theta \left( \sum_{i=1}^n \hat{a}_i^2 \right) \hat{a} \hat{a}^T - \sin^2 \theta \hat{a}^{\wedge} \hat{a}^{\wedge} \\ &= \cos^2 \theta I + (2 \cos^2 \theta - \sin^2 \theta \sum_{i=1}^n \hat{a}_i^2) \hat{a} \hat{a}^T - \sin^2 \theta \hat{a}^{\wedge} \hat{a}^{\wedge} = I \end{aligned}$$

$$\text{let } \hat{a} \hat{a}^T = \frac{\hat{a} \hat{a}^T}{\hat{a}^T \hat{a}} = P_{||}, \hat{a} \text{ is unit vector,}$$

$$v = v_{||} + v_{\perp}, \quad v_{||} = P_{||} v, \quad v_{||} \perp v_{\perp}$$

$$\therefore v_{\perp} = v - v_{||} = -\hat{a} \times (\hat{a} \times v)$$

$$\text{and } \hat{a} \times v = \hat{a}^{\wedge} v \quad \hat{a} \times (\hat{a} \times v) = \hat{a}^{\wedge} \hat{a}^{\wedge} v$$

$$\therefore (-v) = \cos \theta v + (-\cos \theta) \hat{a} \hat{a}^T v + \sin \theta \hat{a}^{\wedge} v$$

$$= \cos \theta v + (-\cos \theta) v_{||} + \sin \theta \hat{a}^{\wedge} v$$

$$= \cos \theta (v - v_{||}) + \sin \theta \hat{a}^{\wedge} v$$



$$\begin{aligned}
&= \cos \theta v + (\sin \theta) \hat{a}_1 v + \sin \theta \hat{a}^1 v \\
&= \cos \theta v + (\sin \theta)(v + \hat{a}^2 v) + \sin \theta \hat{a}^1 v \\
&= (\cos \theta + (\sin \theta)(1 + \hat{a}^2) + \sin \theta \hat{a}^1) v \\
&= (\cos \theta + 1 + \hat{a}^2 - \sin \theta \hat{a}^2 + \sin \theta \hat{a}^1) v \\
&= (1 + \sin \theta \hat{a}^1 + (1 - \cos \theta) \hat{a}^2) v \\
\therefore C &= 1 + \sin \theta \hat{a}^1 + (1 - \cos \theta) \hat{a}^2 \\
C^T &= 1 - \sin \theta \hat{a}^1 + (1 - \cos \theta) \hat{a}^2 \quad ((\hat{a}^1)^T = -\hat{a}^1, (\hat{a}^1 \hat{a}^1)^T = \hat{a}^1 \hat{a}^1 = (\hat{a}^1)^2) \\
\therefore RHS &= C \cdot C^T = (1 + \sin \theta \hat{a}^1 + (1 - \cos \theta) \hat{a}^2) \cdot (1 - \sin \theta \hat{a}^1 + (1 - \cos \theta) \hat{a}^2) \\
&= 1 - \sin \theta \hat{a}^1 + (1 - \cos \theta) \hat{a}^2 + \sin \theta \hat{a}^1 - \sin^2 \theta \hat{a}^1 \hat{a}^1 + \sin \theta (1 - \cos \theta) \hat{a}^1 \hat{a}^2 \\
&\quad + (1 - \cos \theta) \hat{a}^2 - \sin \theta (1 - \cos \theta) \hat{a}^2 \hat{a}^1 + (1 - \cos \theta)^2 \hat{a}^2 \hat{a}^2 \\
&= 1 + 2(1 - \cos \theta) \hat{a}^2 - \sin^2 \theta \hat{a}^1 \hat{a}^1 + (1 - \cos \theta) \hat{a}^1 \hat{a}^2 \\
&= 1 + (1 - \cos \theta)^2 \hat{a}^1 \hat{a}^1 + 2(1 - \cos \theta) \hat{a}^2 + (1 - \cos^2 \theta) \hat{a}^2 \\
&= 1 \\
&\therefore Q.E.D.
\end{aligned}$$

3. (b.6.3) show that  $(Cv)^T = Cv^T C^T$  for any  $3 \times 1$  coln  $v$  and rot mat  $C$

$$\begin{aligned}
\text{let } C &= \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix} \quad v = [v_1, v_2, v_3]^T \\
LHS &= \begin{bmatrix} c_{11}v_1 + c_{12}v_2 + c_{13}v_3 \\ c_{21}v_1 + c_{22}v_2 + c_{23}v_3 \\ c_{31}v_1 + c_{32}v_2 + c_{33}v_3 \end{bmatrix}^T \\
&= \begin{bmatrix} 0 & -c_{31}v_1 - c_{32}v_2 - c_{33}v_3 & c_{21}v_1 + c_{22}v_2 + c_{23}v_3 \\ c_{31}v_1 + c_{32}v_2 + c_{33}v_3 & 0 & -c_{11}v_1 - c_{12}v_2 - c_{13}v_3 \\ -c_{11}v_1 - c_{12}v_2 - c_{13}v_3 & c_{11}v_1 + c_{12}v_2 + c_{13}v_3 & 0 \end{bmatrix} \\
RHS &= \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix} \begin{bmatrix} 0 & -v_3 & v_2 \\ v_3 & 0 & -v_1 \\ -v_2 & v_1 & 0 \end{bmatrix} \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{12} & c_{22} & c_{23} \\ c_{13} & c_{23} & c_{33} \end{bmatrix} \\
&= \begin{bmatrix} c_{12}v_3 - c_{13}v_2 & -c_{11}v_3 + c_{13}v_1 & c_{11}v_2 - c_{12}v_1 \\ c_{22}v_3 - c_{23}v_2 & -c_{21}v_3 + c_{23}v_1 & c_{21}v_2 - c_{22}v_1 \\ c_{32}v_3 - c_{33}v_2 & -c_{31}v_3 + c_{33}v_1 & c_{31}v_2 - c_{32}v_1 \end{bmatrix} \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{12} & c_{22} & c_{23} \\ c_{13} & c_{23} & c_{33} \end{bmatrix} \\
&= \begin{bmatrix} 0 & (c_{13}c_{22} - c_{12}c_{23})v_1 + (c_{11}c_{23} - c_{13}c_{31})v_2 + (c_{12}c_{21} - c_{11}c_{22})v_3, & (c_{13}c_{32} - c_{12}c_{33})v_1 + (c_{11}c_{33} - c_{13}c_{31})v_2 + (c_{12}c_{31} - c_{11}c_{32})v_3 \\ (c_{12}c_{33} - c_{13}c_{32})v_1 + (c_{11}c_{31} - c_{12}c_{33})v_2 + (c_{11}c_{22} - c_{12}c_{21})v_3, & 0 & (c_{23}c_{32} - c_{22}c_{33})v_1 + (c_{21}c_{33} - c_{23}c_{31})v_2 + (c_{22}c_{31} - c_{21}c_{32})v_3 \\ (c_{12}c_{31} - c_{13}c_{32})v_1 + (c_{13}c_{31} - c_{11}c_{33})v_2 + (c_{11}c_{22} - c_{12}c_{21})v_3, & (c_{22}c_{33} - c_{23}c_{32})v_1 + (c_{23}c_{31} - c_{21}c_{33})v_2 + (c_{21}c_{32} - c_{22}c_{31})v_3, & 0 \end{bmatrix} \\
&= LHS \\
&\therefore Q.E.D.
\end{aligned}$$