

Practical no.

Aim- Starting Raspbian OS, familiarizing with Raspberry Pi Components and interfacing , Connecting to ethernet , Monitor , USB

Requirements -

Hardware Requirements -

- 1] Raspberry Pi 3 B + model
- 2] MicroSD card
- 3] Power Supply
- 4] HDMI cable
- 5] Monitor
- 6] USB Keyboard and Mouse
- 7] Ethernet cable (optional)

Software Requirements -

- 1] Raspberry Pi OS (Raspbian)
- 2] ~~Raspberry Pi~~
- 2] NOOB'S (New Out of Box Software)

Circuit Diagram

Procedure-

Step 1 - Format the SD card

Step 2 - Download NOOBS from the official Raspberry Pi website

Step 3 - Extract the zip folder to access the files

Step 4 - Copy all the extracted files directly to the root directory of the formatted SD card

Step 5 - Safely Eject the SD card

Step 6 - Insert SD card into Raspberry Pi

Step 7 - Connect Monitor, keyboard and mouse using HDMI and USB cable

Step 8 - Power up Raspberry Pi

Step 9 - In the NOOBS interface, choose Raspbian and Install the OS

Step 10 - On first boot, Raspbian will guide you through an initial setup of language, timezone, etc.

Step 11 - Finish

Practical no. 2

Aim- Displaying different LED patterns with Raspberry Pi

Requirements -

Software Requirements -
1] Raspberry Pi OS (Raspbian)

2] Python3

3] RPi.GPIO library for Controlling GPIO Pins

Hardware Requirements -
1] Raspberry Pi 3 B+ model

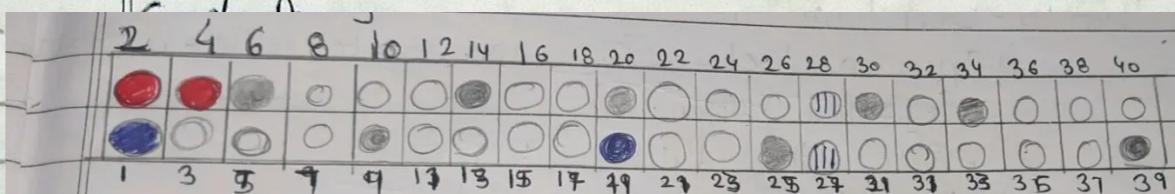
2] LED

3] Resistor - 220Ω to 330Ω

4] BreadBoard

5] Jumper wires

6] Power Supply



Raspberry Pi A+/B+ and Raspberry Pi 2 Physical pin numbers

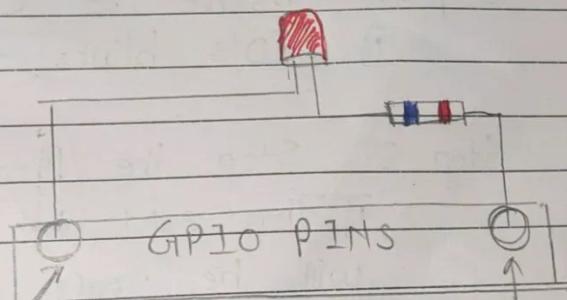
○ → GPIO

○ → GROUND

○ → 3.3V

○ → 5V

○ → 1D EEPROM



Procedure -

Step 1 - Hardware Setup

- 1] Place the LED on the Breadboard
- 2] Connect anode to a separate GPIO pin on the Raspberry Pi using a resistor.
- 3] Connect cathode of LED to a ground pin on the Raspberry Pi

Step 2 - Install Required Software

- 1] Boot your Raspberry Pi and open a terminal
- 2] Update the system and install the necessary libraries:
 - sudo apt update
 - sudo apt install python3-pip
 - sudo pip3 install RPi.GPIO

Step 3 - Set up the Python Script

- 1] Open a text editor and create a Python script
(eg - led-pattern.py)
- 2] Save the Python script
- 3] Run the Python script

Step 4 - Observe the LED Pattern (Blinking)

- 1] LED's blinks for one second

Step 5 - Stop the Program

- 1] Then exit the program and the GPIO pins will be reset to a safe state.

Code -

led_pattern.py

import RPi.GPIO as IO

import time

IO.setup(IO.BOARD)

~~IO~~ IO.setup(40, IO.OUT)

IO.output(40, 1)

time.sleep(1)

IO.cleanup()

time.sleep(1)

loop is executed second time

IO.setmode(IO.BOARD)

IO.setup(40, IO.OUT)

IO.output(40, 1)

time.sleep(1)

IO.cleanup()

time.sleep(1)

loop is executed third time

IO.setmode(IO.BOARD)

IO.setup(40, IO.OUT)

IO.output(40, 1)

time.sleep(1)

Practical no. 3

Aim - Displaying Time over 4-Digit 7-Segment Display using Raspberry Pi

Requirements -

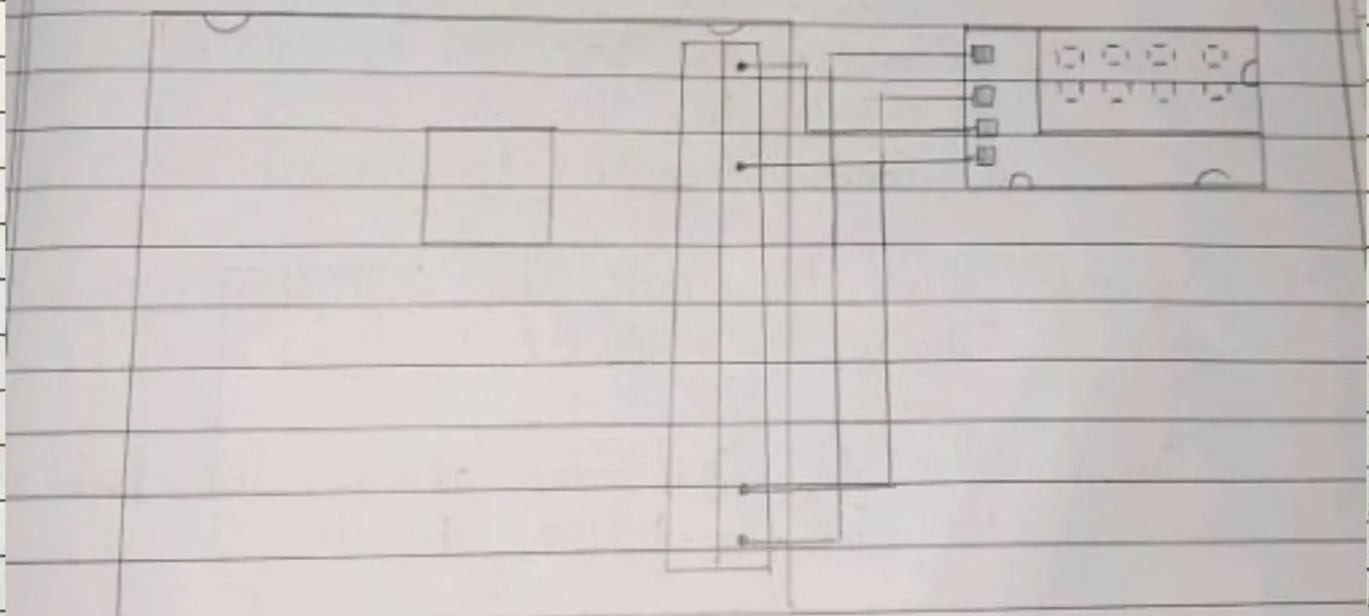
Software Requirements -

- 1] Raspberry Pi OS (Raspbian)
- 2] Python 3
- 3] RPi.GPIO library
- 4] tm1637 library
- 5] datetime module

Hardware Requirements -

- 1] Raspberry Pi 3 B+ model
- 2] 4digit 7-Segment Display
- 3] Jumper wires
- 4] Power Supply

Circuit Diagram:-



Procedure -

Step 1 - Update your Raspbian

\$ sudo apt update

\$ sudo apt upgrade

Step 2 - Config the Raspberry Pi

\$ sudo raspi-config

Step 3 - Change To your Local TimeZone.
Tab to Finish

Step 4 - Reboot the OS

Step 5 - Hardware setup

i] Connect 4-digit 7-segment display to Raspberry Pi GPIO pins

a] Connect the CLK to GPIO 21

b] Connect the DIO pin to GPIO 20

c] Connect the VCC pin to 3.3 V

d] Connect the ground to ground pin

Step 6 - Write the code for 4-digit 7Segment in Thonny Python IDE

Step 7 - Run the code and observe the time which will be in HH:MM format

Code -

```
from time import sleep  
import tm1637
```

try :

```
    import thread  
except ImportError:  
    import _thread as thread
```

```
Display = tm1637.TM1637(CLK=21, DIO=20, Brightness=1, 0)
```

try :

```
    print("Starting clock in Background (press Ctrl + C  
          to Stop):")
```

```
    Display.StartClock(military_time=False)
```

```
    print("Continue Python-Script and Tweak Display!")  
    sleep(5)
```

```
    Display.showDoublepoint(False)
```

```
    sleep(5)
```

```
    loops = 3
```

```
    while loops > 0:
```

```
        for i in range(0, 10):
```

```
            Display.SetBrightness(i/100)
```

```
            sleep(0.5)
```

```
        loops -= 1
```

```
    Display.StopClocks()
```

```
    thread.interrupt_main()
```

except KeyboardInterrupt:
 print("preferably closing the clock and open
 Gpio10 pins: ")
 Display.clear()

Practical no.

Aim- Pi Camera Module Interface with Raspberry Pi using Python

Requirements -

Hardware Requirements -

- 1] Raspberry Pi 3B+ model
- 2] Pi Camera module
- 3] Ribbon cable (for camera connection)

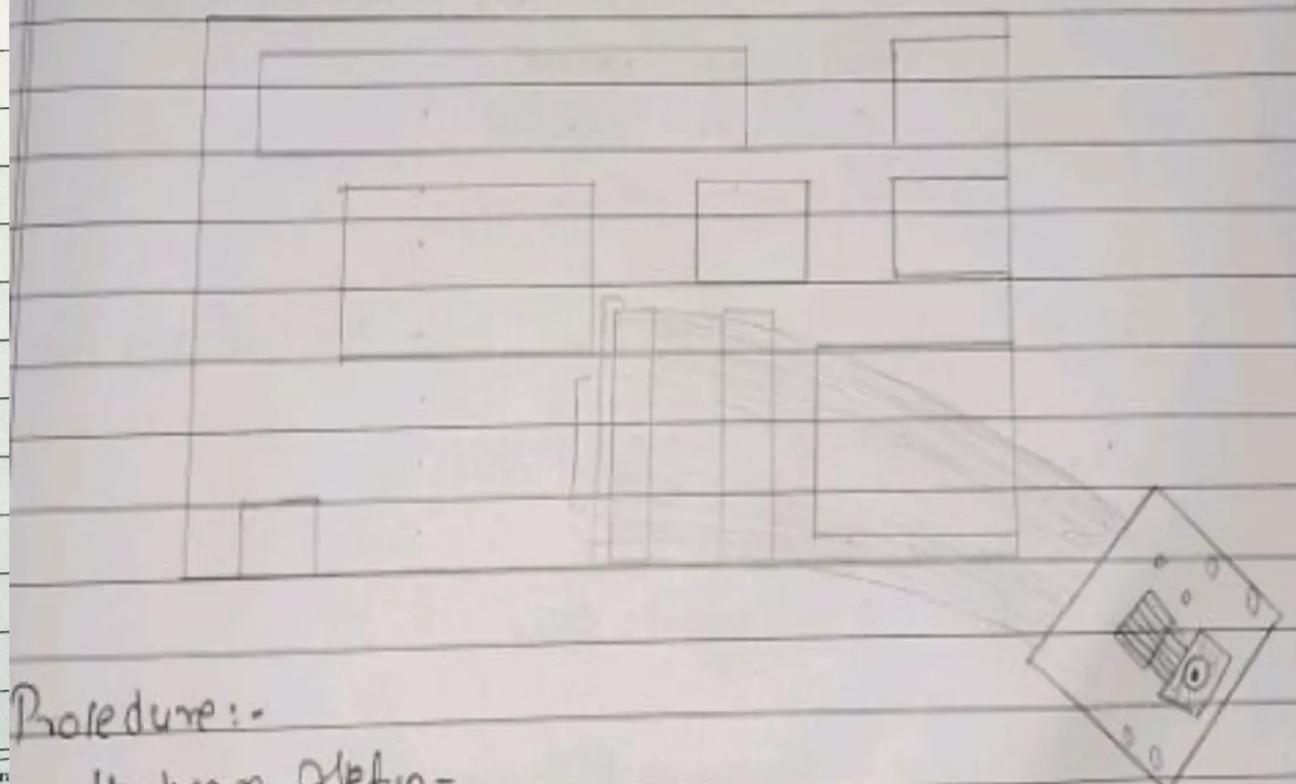
Software Requirements -

- 1] Raspberry Pi OS (Raspbian)

- 2] Python 3

- 3] picamera library for camera control

Circuit Diagram :-



Procedure :-

1) Hardware Connection -

Procedure-

Hardware Setup -

Step 1 - Locate the camera port on the Raspberry Pi board

Step 2 - Insert the ribbon cable from the camera module into the camera port

Software setup -

Step 1 - Open the terminal on the Raspberry Pi

Step 2 - Run the command -
`sudo raspi-config`

Step 3 - Select Interfacing Options > Camera > Enable

Step 4 - Restart the Raspberry Pi to apply changes

Step 5 - open the terminal and install the piamera library -

```
sudo apt update  
sudo apt upgrade  
python3-piamera
```

Step 6 - Open the text-editor, write the code and run it.

Code -

```
import piCamera  
from time import sleep
```

```
camera = piCamera.PiCamera()
```

```
camera.resolution = (1024, 768)
```

```
camera.brightness = 60  
camera.start_preview()
```

```
camera.annotate_text = 'Hi Pi User'  
sleep(5)
```

```
camera.capture('image1.jpeg')  
camera.stop_preview()
```

Practical no.

Aim - controlling Raspberry Pi with telegram

Requirements -

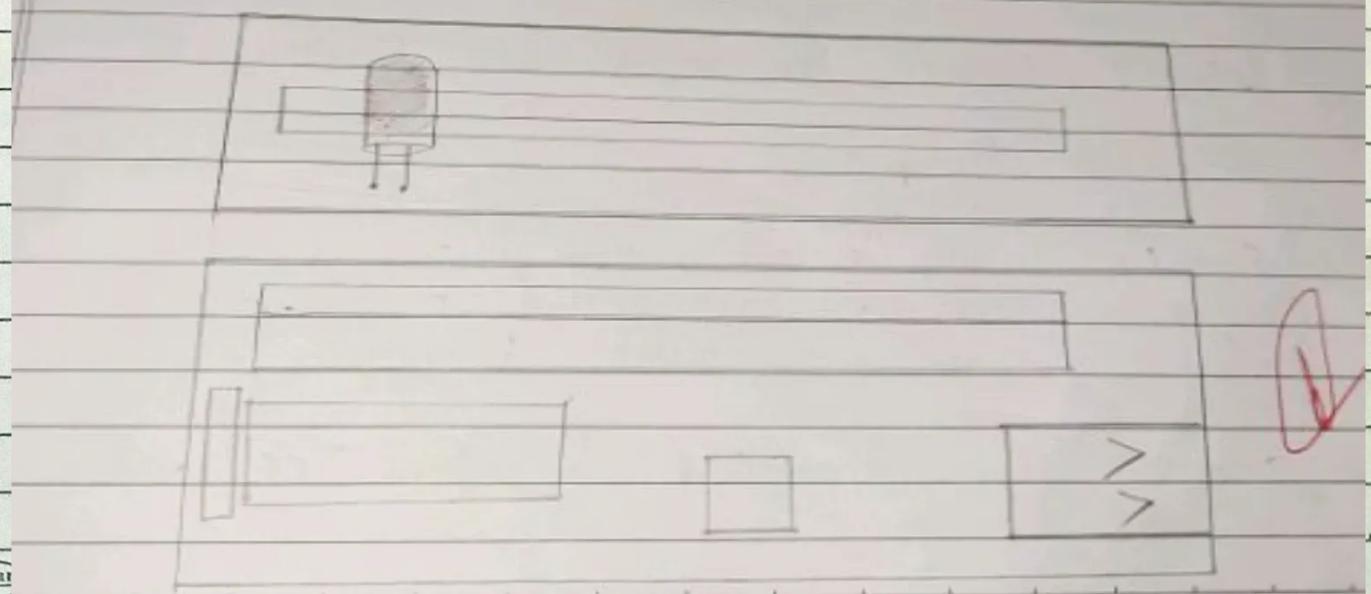
Hardware Requirements -

- 1] Raspberry Pi 3B+ model
- 2] LED
- 3] Resistor (220Ω)
- 4] Jumper wires
- 5] Breadboard (if you want use)

Software Requirements -

- 1] Raspberry Pi OS (Raspbian)
- 2] Python3
- 3] Telegram app
- 4] python-telegram-bot libraries to control the bot

Circuit Diagram -



Procedure -

Set up a Telegram Bot

Step 1- Open Telegram app

Step 2- Search for BotFather

Step 3- Create a new Bot by sending the /newbot command

Step 4- Name your bot and create username for it

Step 5- After creation a token will be generated.
Save that token.

Hardware set up -

Step 1- Connect the LED to a resistor

Step 2- Connect the resistor to Raspberry Pi

Software setup -

Step 1- Install necessary packages -

sudo apt-get install python-pip

sudo pip install telepot

Step 2 - Write the code in Python TDE and run it

Step 3 - Send the commands from your telegram and observe the LED.

Code -

```
import sys
import time
import telepot
import RPi.GPIO as GPIO

def on(pin):
    GPIO.output(pin, GPIO.HIGH)
    return

def off(pin):
    GPIO.output(pin, GPIO.LOW)
    return

GPIO.setmode(GPIO.BCM)
GPIO.setup(11, GPIO.OUT)

def handle(msg):
    chat_id = msg['chat']['id']
    command = msg['text']
    print('Got command: %s' % command)
    if command == 'On':
```

```
bot.sendMessage(chat_id, on(11))
elif command == 'off':
    bot.sendMessage(chat_id, off(11))
```

```
bot = telepot.Bot('your bot token')
```

```
bot.messageLoop(handle)
print('I am listening')
```

```
while 1:
```

```
try:
```

```
    time.sleep(10)
```

```
except KeyboardInterrupt:
```

```
    print('In program interrupted')
    GPIO.cleanup()
```

```
    exit()
```

```
except:
```

```
    print('Other error or exception occurred')
    GPIO.cleanup()
```