

**Michelle Wang**  
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## Education

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**Massachusetts Institute of Technology**, Cambridge, MA Class of 2027  
*GPA:* 5.0/5.0      *Major:* Computation and Cognition      *Minor:* Mechanical Engineering  
*Relevant Coursework:* Fundamentals of Programming, Discrete Math for CS, Differential Equations

**Carbondale Community High School**, Carbondale, IL Class of 2023  
*Awards:* Valedictorian, National Merit Scholar, US Presidential Scholar Finalist, AIME 2x qualifier

## Research & Work Experience

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**Intern, John Deere Intelligent Solutions Group, Fargo, ND** Summer, 2024  
– Building Large Language Model (LLM) companion to retrieve and interpret sensor quality assurance reports from the past 20 years; cleaned, chunked, and uploaded report text into Deere’s data lake.  
– Designing real-time front-end data visualizations (React + socket.io) for sensors on Gator vehicles.

**Undergraduate Research Assistant, Improbable AI group, MIT CSAIL** 2024-present  
– Developed python programs for teleoperation and multimodal data collection (images, joint trajectories, torque sensors, etc.) on a mobile, bimanual robot; investigating Action Chunking Transformer (ACT) and diffusion policies for imitation learning; exploring implicitly learning active perception using an actuated “neck” to handle visually occluded/challenging manipulation tasks.

**Team member and Business Lead, MIT Assistive Technology Team** 2023-present  
– Recruiting/communicating with external sponsors and working with treasurer to manage budget.  
– Worked in a team of 10 to develop an assistive feeding robot for people with limited upper body mobility; designed and fabricated a novel utensil; co-led electronics and software development.

**Independent Research** 2019-2023  
– Autonomous Drone and Drone Swarm ([repo](#), 2021-2023): Built a custom X500 quadcopter with onboard Jetson Xavier GPU and RealSense camera for autonomous object detection and tracking; the developed software includes modules for vision, navigation & control, YOLOv4 convolutional neural network (CNN), a custom CNN for object pose estimation, and collaborative wingmen drone control programs.  
    ▪ *Won 2nd place oral presentation at the 2022 National Junior Science and Humanities Symposium (JSHS)*  
    ▪ *Won both 4th place grand award in robotics category and Air Force Research Labs award at ISEF 2023*  
– IMU-Based Wearable Device for Gait Analysis ([repo](#), 2019-2021): Built an Arduino and IMU-based wearable device, developed Python programs to process sensor data to track knee angle, and designed and trained an artificial neural network (ANN) to classify running forms.  
    ▪ *Won 1<sup>st</sup> place at 2021 IL JSHS and 3<sup>rd</sup> place at 2020 IL JSHS, respectively.*

## Other Activities

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**MIT Edgerton Center** 2023-2024  
• *Edgerton Outreach Instructor:* Teach hands-on STEM activities to students from nearby schools.

**Illinois 4-H** 2019-2023  
• *Member of Statewide Youth Leadership Team (2021-2023):* Plan and implement statewide events, advise statewide committees, and lobby for 4-H to state legislators.  
• *STEM Club Organizer and Youth Teacher:* Taught Scratch programming, Python, drones, AI, and other STEM topics in 5 clubs reaching 300 plus local youth; secured \$3000 in grants to support club projects.

**Hunan Restaurant, Carbondale, IL** 01/2023-08/2023  
• *Hostess:* Interacted with customers and communicated with servers in a very fast-paced environment

## Skills & Interests

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**Software:** Python, Tensorflow/Keras, ROS1/ROS2, Arduino, OpenCV, Git, Unix, Docker, Unity/C#

**Other:** 3D modeling/CAD (Fusion 360), 3D printing/rapid prototyping, machining (mill & lathe), Photoshop