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1 Introduction and functional overview

This specification specifies the functionality, API and the configuration of the AUTOSAR Basic Software module Wireless Ethernet driver.

In the AUTOSAR Layered Software Architecture, the Wireless Ethernet driver belongs to the *Microcontroller Abstraction Layer*, or more precisely, to the *Communication Drivers*.

This indicates the main task of the Wireless Ethernet driver:
Provide to the upper layer (Ethernet Interface) a hardware independent interface comprising multiple equal controllers. This interface shall be uniform for all controllers. Thus, the upper layer (Ethernet Interface) may access the underlying bus system in a uniform manner. The interface provides functionality for initialization, configuration and data transmission. The configuration of the Wireless Ethernet Driver however is bus specific, since it takes into account the specific features of the communication controller.

A single Wireless Ethernet driver module supports only one type of controller hardware. The Wireless Ethernet driver's prefix requires a unique namespace. The Ethernet Interface can access different controller types using different Wireless Ethernet drivers using this prefix. The decision which driver to use to access a particular controller is a configuration parameter of the Ethernet Interface.

Figure 1-1 depicts the lower part of the Wireless Ethernet stack. One Ethernet Interface can access several radios using several Wireless Ethernet Transceiver drivers. Each radio may support multiple contexts i.e. multiple radio channel configurations.

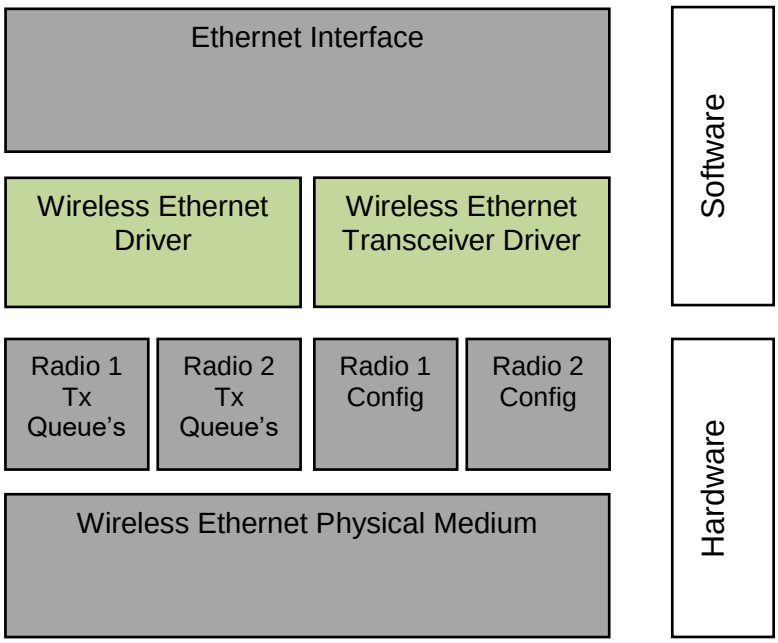


Figure 1-1: Wireless Ethernet stack module overview

Note: The Wireless Ethernet driver is specified in a way that allows for object code delivery of the code module, following the "one-fits-all" principle, i.e. the entire configuration of the Ethernet Interface can be carried out without modifying any source code. Thus, the configuration of the Wireless Ethernet driver can be carried out largely without detailed knowledge of the Wireless Ethernet driver software.

2 Acronyms and abbreviations

Abbreviation / Acronym:	***Description:***
FCS	Frame Check Sequence
EthIf	Ethernet Interface (AUTOSAR BSW module)
Eth	Ethernet Driver (AUTOSAR BSW module)
ISR	Interrupt Service Routine
MCG	Module Configuration Generator
WEth	Wireless Ethernet Driver (AUTOSAR BSW module)
WEthTrcv	Wireless Ethernet Transceiver (AUTOSAR BSW module)

3 Related documentation

3.1 Input documents

[1] AUTOSAR Layered Software Architecture
AUTOSAR_EXP_LayeredSoftwareArchitecture.pdf

[2] AUTOSAR General Requirements on Basic Software Modules
AUTOSAR_SRS_BSWGeneral.pdf

[3] AUTOSAR General Specification for Basic Software Modules
AUTOSAR_SWS_BSWGeneral.pdf

[4] Specification of Communication
AUTOSAR_SWS_COM.pdf

[5] Specification of Ethernet Interface
AUTOSAR_SWS_EthernetInterface.pdf

[6] Specification of Wireless Ethernet Transceiver
AUTOSAR_SWS_WirelessEthernetTransceiverDriver.pdf

[7] Specification of ECU State Manager
AUTOSAR_SWS_ECUStateManager.pdf

[8] Specification of Ethernet Driver
AUTOSAR_SWS_EthernetDriver.pdf

[9] BSW Scheduler Specification
AUTOSAR_SWS_Scheduler.pdf

[10] Specification of ECU Configuration
AUTOSAR_TPS_ECUConfiguration.pdf

[11] Specification of Memory Mapping
AUTOSAR_SWS_MemoryMapping.pdf

[12] Specification of Standard Types
AUTOSAR_SWS_StandardTypes.pdf

[13] Specification of Default Error Tracer
AUTOSAR_SWS_DefaultErrorTracer.pdf

[14] Specification of Diagnostics Event Manager
AUTOSAR_SWS_DiagnosticsEventManager.pdf

[15] Requirements on Vehicle-2-X communication
AUTOSAR_SRS_V2XCommunication.pdf

3.2 Related standards and norms

[16] IEC 7498-1 The Basic Model, IEC Norm, 1994

[17] IEEE 802.11-2012

[18] Intelligent Transport Systems (ITS); Harmonized Channel Specifications for Intelligent Transport Systems operating in the 5 GHz frequency band between access layer and network and transport layer
ETSI TS 102 724 V1.1.1 (2012-10)

3.3 Related specification

AUTOSAR provides a General Specification on Basic Software (SWS BSW General) [3] which is also valid for Wireless Ethernet Driver.

Thus, the specification SWS BSW General [3] shall be considered as additional and required specification for Wireless Ethernet Driver.

Furthermore, this document uses the Ethernet Driver as a base for the requirements, APIs and configuration, because the wired and the wireless use case have many things (but not all) in common. The term “Ethernet Driver“ as used in this document describes the class of Ethernet drivers regardless of the used physical layer and means Wireless as well as Wired Ethernet Drivers.

4 Constraints and assumptions

4.1 Limitations

- It is not possible to transmit data which exceeds the available buffer size of the used controller.
- AUTOSAR supports currently only wireless communication using IEEE 802.11p. Other 802.11 standards (e.g. for infrastructure networks and integration with TCP/IP) can be extended in future releases of the AUTOSAR standard.
- The V2X modules follow the guidance regarding the Day-1 scenarios defined by the Basic System Standards Profile from Car-2-Car-Consortium.
- AUTOSAR R20-11 only focuses on the European version of car-to-car communication as defined by ETSI. Extension to other regions are planned for future releases of the AUTOSAR standard.
- The Microcontroller Abstraction Layer Multi-Core Distribution Concept is implemented as “draft” in this software specification. Refer to chapter 10 for more information.

4.2 Applicability to car domains

The Wireless Ethernet Driver is intended to be used for wireless access of customer hardware (Access Point) and for wireless access of Vehicle-2-X (V2X) applications / BSW Modules (using a meshed network).

5 Dependencies to other modules

This chapter lists the modules interacting with the Wireless Ethernet Driver module.

Modules that use Wireless Ethernet Driver module:
- Ethernet Interface (EthIf)
- Wireless Ethernet Transceiver (WEthTrcv)

Modules used by the Wireless Ethernet Driver module:
- Typically, the wireless radio hardware is an external device that is accessed by an existing communication driver such as SPI.

5.1 Driver Services

[SWS_WEth_10001] ⌈ If the Wireless Ethernet controller is on-chip, the Wireless Ethernet Driver module shall not use any service of other drivers.⌋()

[SWS_WEth_10003] ⌈ If an off-chip Wireless Ethernet controller is used[1], the Wireless Ethernet driver shall use services of other MCAL drivers (e.g. SPI).⌋()

Implementation hint: If the Wireless Ethernet driver uses services of other MCAL drivers (e.g. SPI), it must be ensured that these drivers are up and running before initializing the Wireless Ethernet driver. The sequence of initialization of different drivers is partly specified in [7].

[SWS_WEth_10004] ⌈ All the Wireless Ethernet driver interfaces shall be implemented in a non-blocking manner. In cases where the action can be performed immediately and atomically, the confirmation is reported in the request function's return code. Alternatively, the initiation of an action is performed by a call to a 'request' function and the result of the action is reported by a corresponding 'confirm' callback. ⌋()

[1] In this case the Wireless Ethernet driver is not any more part of the µC abstraction layer but put part of the ECU abstraction layer. Therefore it is (theoretically) allowed to use any µC abstraction layer driver it needs

6 Requirements traceability

Note:
Requirement IDs within this document have an encoding to state where each requirement has its origin:

- SWS items starting with a leading 0 (SWS_WEth_0xxxx) are inherited from the SWS Ethernet Driver [8].
- SWS items starting with a leading 1 (SWS_WEth_1xxxx) are module specific and not inherited.
- SWS items starting with a leading 2 (SWS_WEth_2xxxx) are inherited from C2C-CC Basic System Profile

Requirement	Description	Satisfied by
SRS_BSW_00487	Errors for module initialization shall follow a naming rule	SWS_WEth_10039, SWS_WEth_10046
SRS_V2X_00010	The implementation of the V2X system shall follow additional guidance given by C2C-CC requirements	SWS_WEth_20235
SRS_V2X_00242	The V2Xsystem shall manage CAM transmission in such a way, that no outdated CAM will be transmitted	SWS_WEth_20242
SRS_V2X_00245	The V2X system shall support per-packet transmission power control	SWS_WEth_10013, SWS_WEth_10051
SRS_V2X_00451	The V2X system's access layer shall be compliant to the ETSI Harmonized Channel Specifications	SWS_WEth_10069

7 Functional specification

The Wireless Ethernet driver provides communications access to the radio for wireless communications. On transmission the driver writes the packet into an appropriate buffer inside the Wireless Ethernet driver, on packet reception the Wireless Ethernet driver calls the receive packet callback function with the packet contents as a parameter.

7.1 Wireless Ethernet BSW stack

As part of the AUTOSAR Layered Software Architecture (see Figure 1-1), the Wireless Ethernet BSW modules also form a layered software stack. The Ethernet Interface (EthIf) module accesses several controllers using the Wireless Ethernet Driver layer, which can be made up of several Wireless Ethernet Driver modules. The Wireless Ethernet Driver supports Multi Core distribution for improved performance.

7.1.1 Indexing scheme

Users of the Wireless Ethernet Driver identify controller resources using an indexing scheme as described in the Ethernet Driver, [8].

[SWS_WEth_00003] ⌈The Wireless Ethernet Driver is using a zero-based index to abstract the access for upper software layers. The parameter WEth_CtrlId within configuration corresponds to parameter CtrlId used in the API. ⌋()

[SWS_WEth_00004] ⌈A buffer index (BufId) indentifies a Wireless Ethernet buffer processed by Wireless Ethernet Driver API functions. Each controller's buffers are identified by buffer indexes 0 to (n-1) where n is the number of buffers processed by the corresponding controller. Buffer indexes are valid within a tuple <CtrlId, BufId> only. A BufId uniquely identifies the buffer used for a Wireless Ethernet Driver. ⌋()

7.1.2 Transceiver configuration

[SWS_WEth_10007] ⌈The Wireless Ethernet Driver shall provide an API that enables the Wireless Ethernet Transceiver to set the general radio specific parameters via an API WEth_WriteTrcvRegs to the transceiver.⌋()

[SWS_WEth_10008] ⌈The Wireless Ethernet Driver shall provide an API that enables the Wireless Ethernet Transceiver to get the general radio specific parameters via an API WEth_ReadTrcvRegs from the transceiver.⌋()

7.1.3 General Requirements

This chapter lists requirements that shall be fulfilled by Wireless Ethernet Driver module implementations.

The Wireless Ethernet Driver module environment comprises all modules which are calling interfaces of the Wireless Ethernet Driver module.

[SWS_WEth_10009] ⌈For reception the Wireless Ethernet Controller shall enable hardware capabilities to discard frames with incorrect Frame Check Sequence (FCS). ⌋()

[SWS_WEth_00243] ⌈Wireless Ethernet Driver shall call EthIf_TxConfirmation to indicate a successful transmission from the Interrupt routine (if the notification has been enabled).⌋()

[SWS_WEth_00244] ⌈Wireless Ethernet Driver shall call EthIf_RxIndication to indicate a successful reception from the Interrupt routine.⌋()

7.1.4 Controller on-packet-base parameters

For the Wireless Ethernet Driver it is important to be able to configure the transmission and the reception parameters for a destined radio of the Wireless Ethernet Transceiver. This is not only needed as general configuration for the radio (e.g. for access points), it is also necessary to be able to configure the parameters on a per-packet-base (e.g. for 802.11p meshed networks).

[SWS_WEth_10005] ⌈
The Wireless Ethernet Driver shall provide an API WEth_GetBufWRxParams that can provide a list of buffer based reception parameters. ⌋()

[SWS_WEth_10038] ⌈
The API WEth_GetBufWRxParams shall read properties of type WEth_BufWRxParamIdType of the access layer properties of a received packet. ⌋ ( )

[SWS_WEth_10037] ⌈
The Wireless Ethernet Driver shall provide an API WEth_GetBufWTxParams that can provide a list of buffer based transmission parameters. ⌋()

[SWS_WEth_10045] ⌈
The API WEth_GetBufWTxParams shall read properties of type WEth_BufWTxParamIdType of the access layer properties of a received packet. ⌋ ( )

[SWS_WEth_10006] ⌈
The Wireless Ethernet Driver shall provide an API WEth_SetBufWTxParams that sets a list of buffer based transmission parameters. ⌋()

[SWS_WEth_10052] ⌈
The API WEth_SetBufWTxParams shall set properties of type WEth_BufWTxParamIdType of the access layer properties for a packet to be sent. ⌋ ( )

7.1.5 Key/Value Parameter Mapping

[SWS_WEth_10064] ⌈
For unique reference to transmission and reception parameters of a sent or received WEth packet, unique enumeration IDs shall be used within this module.
⌋ ( )

[SWS_WEth_10065] ⌈
Functions using the type WEth_BufWRxParamIdType shall use a list of uint32 values for the list of corresponding values.
⌋ ( )

[SWS_WEth_10066] ⌈
Functions using the type WEth_BufWRxParamIdType shall use the following type mapping for the corresponding values:

ParamId	*ParamValue Type*
WETH_BUFWRXPID_RSSI	uint8
WETH_BUFWRXPID_CHANNEL_ID	uint16
WETH_BUFWRXPID_FREQ	uint16
WETH_BUFWRXPID_TRANSACTION_ID_32	uint32
WETH_BUFWRXPID_ANTENNA_ID	uint8

⌋ ( )

[SWS_WEth_10067] ⌈
Functions using the type WEth_BufWTxParamIdType shall use a list of uint32 values for the list of corresponding values.
⌋ ( )

[SWS_WEth_10068] ⌈
Functions using the WEth_BufWTxParamIdType shall use the following type mapping for the corresponding values:

ParamId	*ParamValue Type*
WETH_BUFWTXPID_POWER	uint8
WETH_BUFWTXPID_CHANNEL_ID	uint16
WETH_BUFWTXPID_QUEUE_ID	uint8
WETH_BUFWTXPID_TRANSACTION_ID_16	uint16
WETH_BUFWTXPID_ANTENNA_ID	uint8

⌋ ( )

7.1.6 V2X Specific Controller Requirements

[SWS_WEth_10069] ⌈
The following requirements are only valid for WEth Controllers used within the V2X Communication Stack [15].
⌋ (SRS_V2X_00451)

[SWS_WEth_20235] ⌈
The WEth module shall support at least the following DCC-Profiles defined inside [18]: DP0, DP1, DP2 and DP3.

- DP0, used for TC = 0
- DP1: used for TC = 1
- DP2: used for TC = *2*
- DP3: used for other low priority messages with TC > 2

⌋ (SRS_V2X_00010)

[SWS_WEth_20242] ⌈
The WEth module shall discard a message with the DCC-Profile ID DP2 in the DCC_Access queues if a new message with the DCC-Profile ID DP2 arrives in the DCC_Access queues.⌋ (SRS_V2X_00242)

[SWS_WEth_10073] ⌈
The Wireless Ethernet Driver shall flush the transmit queues during a pseudonym change (call of WEth_SetPhysAddr), to avoid transmitting packets with an old pseudonym. ⌋ ( )

7.2 Error classification

Section 7.x "Error Handling" of the document "General Specification of Basic Software Modules" describes the error handling of the Basic Software in detail. Above all, it constitutes a classification scheme consisting of five error types, which may occur in BSW modules.

Based on this foundation, the following section specifies particular errors arranged in the respective subsections below.

7.2.1 Development Errors

[SWS_WEth_00008] ⌈
In case development error detection is enabled for the Wireless Ethernet Driver module: The Wireless Ethernet Driver module shall check API parameters for validity and report detected errors to the DET. ⌋()

[SWS_WEth_00016]⌈

Type of error	*Related error code*	*Error value*
Invalid controller index	WETH_E_INV_CTRL_ID	0x01
WEth module was not initialized	WETH_E_UNINIT	0x02
Invalid pointer in parameter list	WETH_E_PARAM_POINTER	0x03

⌋()

7.2.2 Runtime Errors

There are no runtime errors.

7.2.3 Transient Faults

There are no transient faults.

7.2.4 Production Errors

There are no production errors.

7.2.5 Extended Production Errors

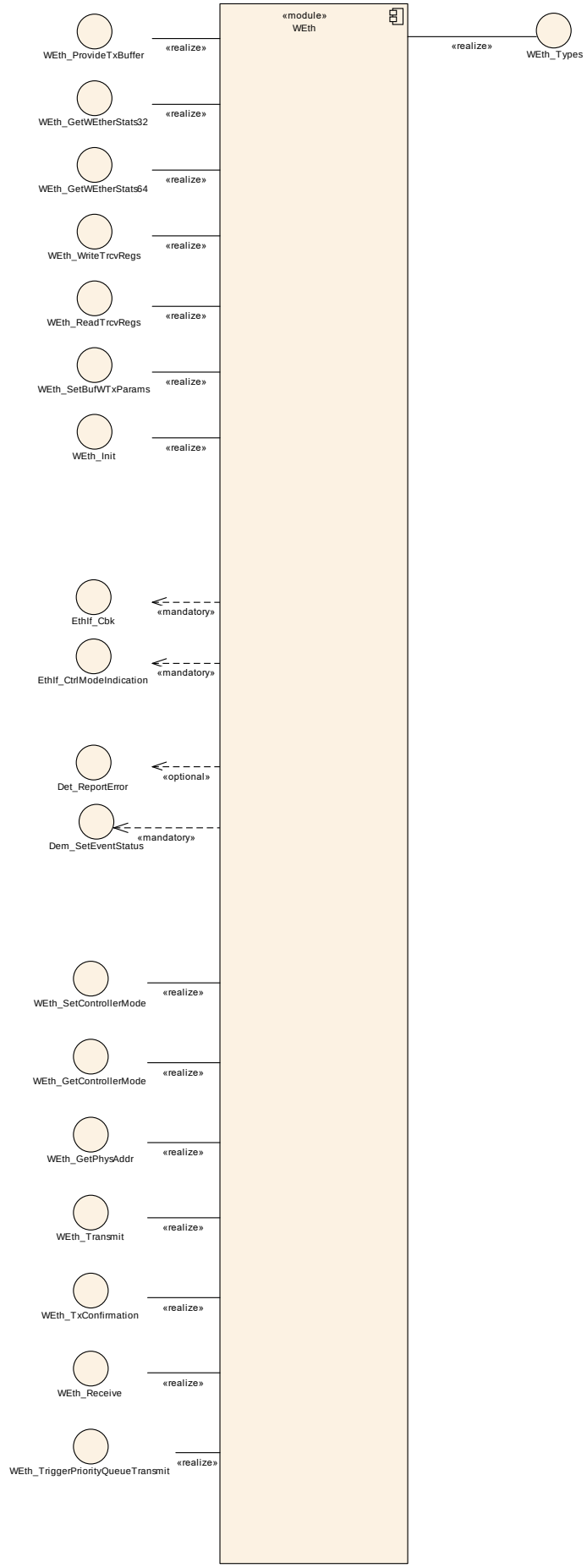
Extended production errors are handled as events of the Diagnostic Event Manager. The event IDs are defined in the following tables, while the actual values are assigned externally by the configuration of the Diagnostic Event Manager, and are included in the module via Dem.h.

[SWS_WEth_00173] ⌈

Error Name:	WETH_E_ACCESS	
Short Description:	Wireless Ethernet Controller Access Failure.	
Long Description:	Monitors the access to the Wireless Ethernet Controller in the context of the WEth_MainFunction..	
Detection Criteria:	Fail	When polling for state changes of the Wireless Ethernet Controller fails the module shall report the extended production error with event status DEM_EVENT_STATUS_PREFAILED to DEM.
	Pass	When polling for state changes of the Wireless Ethernet Controller succeeds the module shall report the extended production error with event status DEM_EVENT_STATUS_PREPASSED to DEM.
Secondary Parameters:	None.	
Time Required:	None.	
Monitor Frequency	None.	

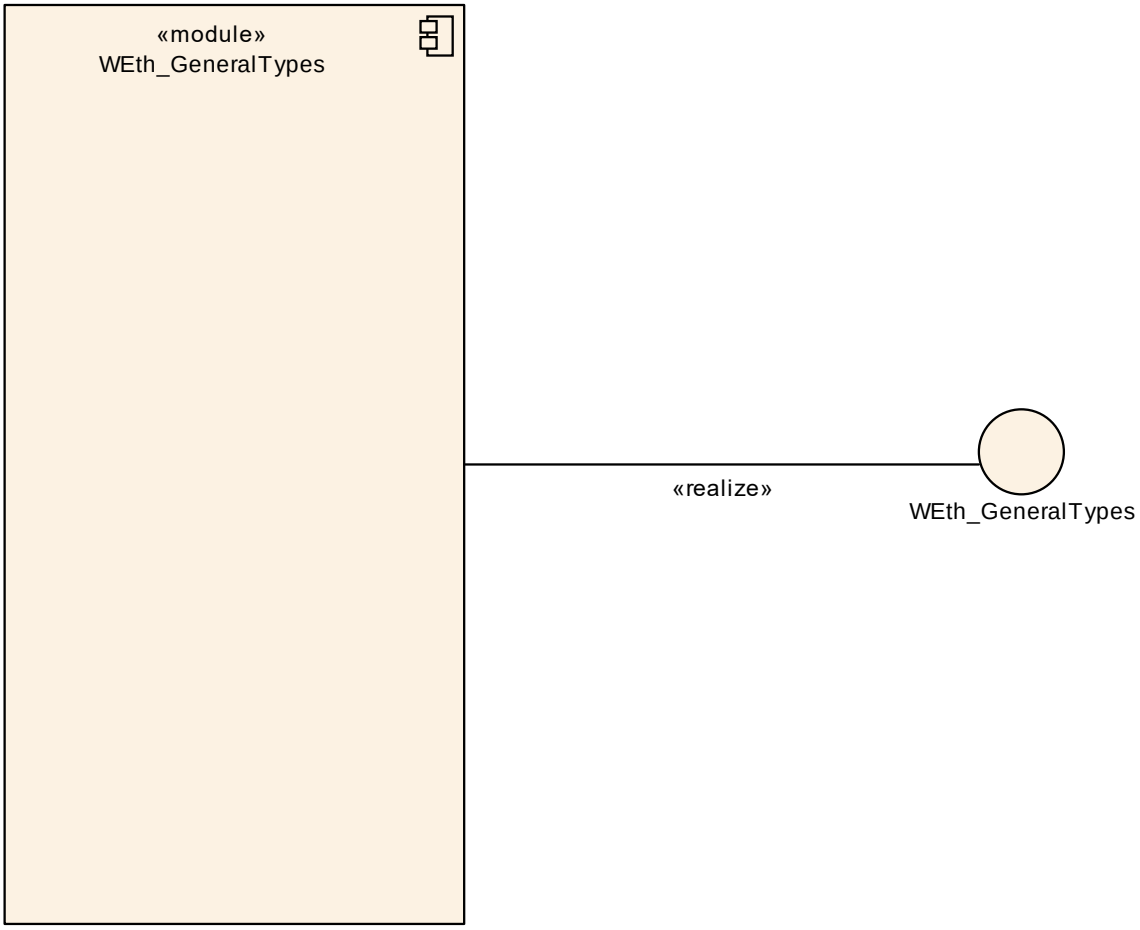
⌋()

8 API specification


«module»
WEth
WEth_Types
«realize»
WEth_ProvideTxBuffer
WEth_GetWEtherStats32
WEth_GetWEtherStats64
WEth_WriteTrcvRegs
WEth_ReadTrcvRegs
WEth_SetBufWTxParams
WEth_Init
EthIf_Cbk
EthIf_CtrlModeIndication
Det_ReportError
Dem_SetEventStatus
«mandatory»
«optional»
WEth_SetControllerMode
WEth_GetControllerMode
WEth_GetPhysAddr
WEth_Transmit
WEth_TxConfirmation
WEth_Receive
WEth_TriggerPriorityQueueTransmit

8.1 Imported types

In this chapter all types included from the following modules are listed:



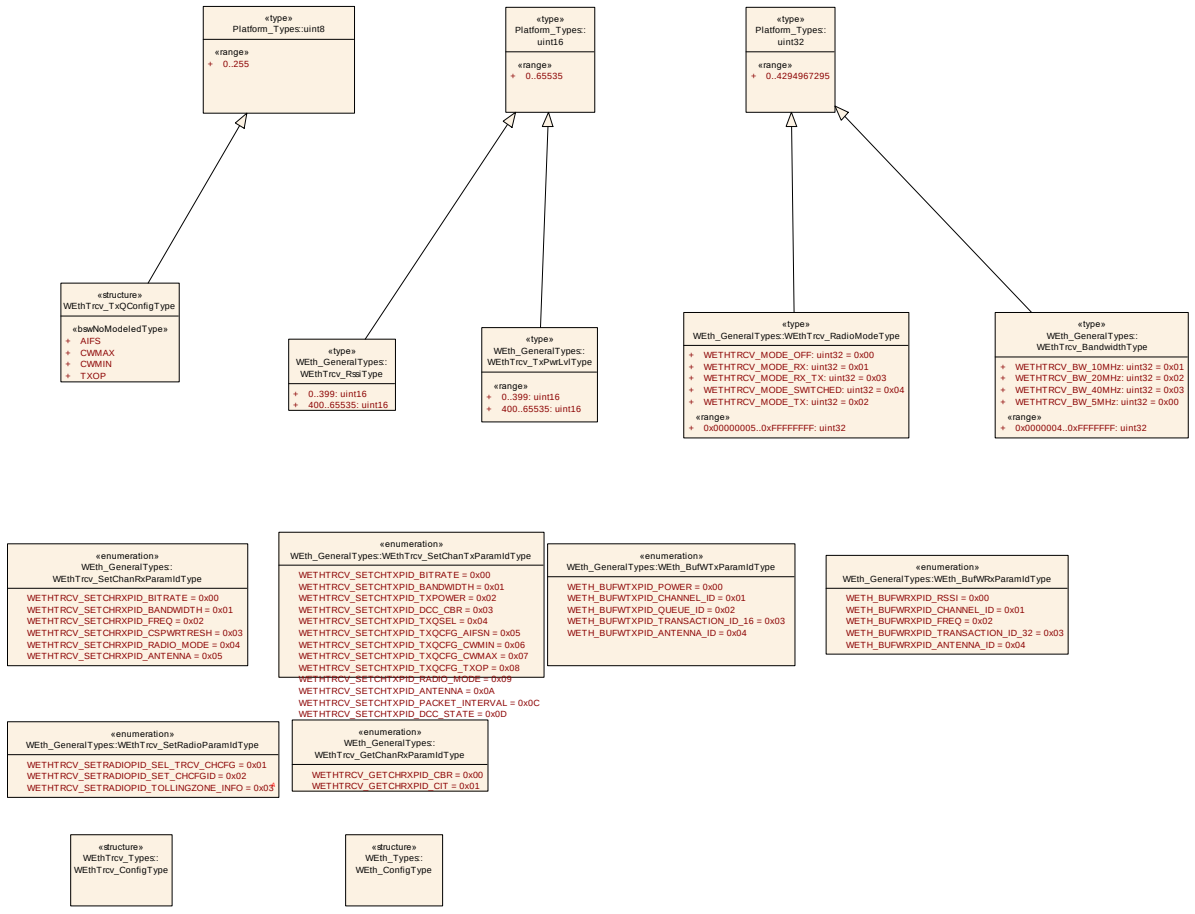
[SWS_WEth_00026]⌈

Module	*Header File*	*Imported Type*
ComStack_Types	ComStack_Types.h	BufReq_ReturnType
Dem	Rte_Dem_Type.h	Dem_EventIdType
	Rte_Dem_Type.h	Dem_EventStatusType
Eth	Eth_GeneralTypes.h	Eth_BufIdxType

	Eth_GeneralTypes.h	Eth_DataType
	Eth_GeneralTypes.h	Eth_FilterActionType
	Eth_GeneralTypes.h	Eth_FrameType
	Eth_GeneralTypes.h	Eth_ModeType
	Eth_GeneralTypes.h	Eth_RxStatusType
Std	Std_Types.h	Std_ReturnType
	Std_Types.h	Std_VersionInfoType

]()

8.2 Type definitions



8.2.1 WEth_ConfigType

[SWS_WEth_10011][

Name	WEth_ConfigType
Kind	Structure
Description	Implementation specific structure of the post build configuration
Available via	WEth.h

]()

8.2.2 WEth_BufWRxParamIdType

[SWS_WEth_10012]⌈

Name	WEth_BufWRxParamIdType		
Kind	Enumeration		
Range	WETH_BUFWRXPID_RSSI	0x00	Parameter Id for RSSI value
	WETH_BUFWRXPID_ CHANNEL_ID	0x01	Parameter Id for Channel Id. Channel Id values are specified within IEEE 802.11-2012 Annex E.
	WETH_BUFWRXPID_FREQ	0x02	Frequency on the channel with that the packet has been received
	WETH_BUFWRXPID_ TRANSACTION_ID_32	0x03	Unique id of a frame that has been received
	WETH_BUFWRXPID_ ANTENNA_ID	0x04	Index of the used antenna
Description	Wireless radio parameters for a packet that has been received.		
Available via	WEth_GeneralTypes.h		

⌋()

8.2.3 WEth_BufWTxParamIdType

[SWS_WEth_10013]⌈

Name	WEth_BufWTxParamIdType		
Kind	Enumeration		
Range	WETH_BUFWTXPID_ POWER	0x00	Parameter Id for transmit power
	WETH_BUFWTXPID_ CHANNEL_ID	0x01	Parameter Id for Channel Id. Channel Id values are specified within IEEE 802.11-2012 Annex E.
	WETH_BUFWTXPID_ QUEUE_ID	0x02	Queue index for ECDA / DCC queues

	WETH_BUFWTXPID_ TRANSACTION_ID_16	0x03	Unique id of a frame to be transmitted
	WETH_BUFWTXPID_ ANTENNA_ID	0x04	Index of the used antenna
Description	Wireless radio parameters for a packet that has to be transmitted.		
Available via	WEth_GeneralTypes.h		

](SRS_V2X_00245)

8.3 Function definitions

This is a list of functions provided for upper layer modules.

8.3.1 WEth_Init

[SWS_WEth_00027][

Service Name	WEth_Init	
Syntax	`void WEth_Init ( const WEth_ConfigType* CfgPtr )`	
Service ID [hex]	0x01	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CfgPtr	Points to the implementation specific structure
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Initializes the Wireless Ethernet Driver	
Available via	WEth.h	

]()

[SWS_WEth_00028][
The function shall store the access to the configuration structure for subsequent API calls.]()

[SWS_WEth_00034] [
The function shall for all configured Wireless Ethernet controllers in the current WEthConfigSet:

- Disable all controller
- Clear pending Wireless Ethernet interrupts
- Configure all controller configuration parameters (e.g. interrupts, frame length, frame filter, ...)
- Configure all transmit / receive resources (e.g. buffer initialization)
- delete all pending transmit and receive requests]()

[SWS_WEth_00029][
The function shall change the state of the component from WETH_STATE_UNINIT to WETH_STATE_INIT.]()

[SWS_WEth_00039] [
The function shall check the access to the Wirless Ethernet controller. If the check fails, the function shall raise the production error WETH_E_ACCESS.]()

[SWS_WEth_00031][
Caveat: The API has to be called during initialization.]()

[SWS_WEth_10002] [The function WEth_Init shall initialize all on-chip hardware resources that are used by the Wireless Ethernet controller.]()

8.3.2 WEth_SetControllerMode

[SWS_WEth_00041][

Service Name	WEth_SetControllerMode
Syntax	`Std_ReturnType WEth_SetControllerMode ( uint8 CtrlId, Eth_ModeType CtrlMode )`
Service ID [hex]	0x03
Sync/Async	Asynchronous
Reentrancy	Non Reentrant

Parameters (in)	CtrlId	Index of the controller within the context of the Wireless Ethernet Driver
	CtrlMode	ETH_MODE_DOWN: disable the controller ETH_MODE_ ACTIVE: enable the controller
Parameters (inout)	None	
Parameters (out)	None	
Return value	Std_Return-Type	E_OK: success E_NOT_OK: controller mode could not be changed
Description	Enables / disables the indexed controller	
Available via	WEth.h	

](

[SWS_WEth_00042] ⌈
The function shall:

- Put the controller in the specified mode given in the parameter ‘CtrlMode’
  - Upon mode ETH_MODE_DOWN the driver shall:
    - Disable the Wireless Ethernet controller
    - Reset all transmit and receive buffers (i.e. ignore all pending transmission and reception requests)
  - Upon mode ETH_MODE_ACTIVE:
    - Enable all transmit and receive buffers
    - Enable the Wireless Ethernet controller⌋()

[SWS_WEth_00043] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋()

[SWS_WEth_00044] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_00168] ⌈
The function shall check the access to the Wireless Ethernet controller. If the check fails, the function shall raise the production error WETH_E_ACCESS and return E_NOT_OK.⌋()

[SWS_WEth_00045] ⌈
Caveat: The function requires previous controller initialization (WEth_Init). ⌋()

8.3.3 WEth_GetControllerMode

[SWS_WEth_00046]⌈

Service Name	WEth_GetControllerMode	
Syntax	`Std_ReturnType WEth_GetControllerMode ( uint8 CtrlId, Eth_ModeType* CtrlModePtr )`	
Service ID [hex]	0x04	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the controller within the context of the Wireless Ethernet Driver
Parameters (inout)	None	
Parameters (out)	CtrlModePtr	ETH_MODE_DOWN: the controller is disabled ETH_MODE_ ACTIVE: the controller is enabled
Return value	Std_Return-Type	E_OK: success E_NOT_OK: controller mode could not be obtained
Description	Obtains the state of the indexed controller	
Available via	WEth.h	

⌋()

[SWS_WEth_00047] ⌈
The function shall read the current controller mode. ⌋()

[SWS_WEth_00048] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋()

[SWS_WEth_00049] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_00050] ⌈
If development error detection is enabled: the function shall check the parameter CtrlModePtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_00051] ⌈
Caveat: The function requires previous controller initialization (WEth_Init). ⌋()

8.3.4 WEth_GetPhysAddr

[SWS_WEth_00052]⌈

Service Name	WEth_GetPhysAddr	
Syntax	`void WEth_GetPhysAddr ( uint8 CtrlId, uint8* PhysAddrPtr )`	
Service ID [hex]	0x08	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the controller within the context of the Wireless Ethernet Driver
Parameters (inout)	None	
Parameters (out)	PhysAddr Ptr	Physical source address (MAC address) in network byte order.
Return value	void	None
Description	Obtains the physical source address used by the indexed controller	
Available via	WEth.h	

⌋()

[SWS_WEth_00053] ⌈
The function shall read the source address used by the indexed controller. ⌋()

[SWS_WEth_00054] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋()

[SWS_WEth_00055] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_00056] ⌈
If development error detection is enabled: the function shall check the parameter PhysAddrPtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_00057] ⌈
Caveat: The function requires previous controller initialization (WEth_Init). ⌋()

8.3.5 WEth_SetPhysAddr

[SWS_WEth_00151]⌈

Service Name	WEth_SetPhysAddr	
Syntax	`void WEth_SetPhysAddr ( uint8 CtrlId, const uint8* PhysAddrPtr )`	
Service ID [hex]	0x13	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant for the same CtrlId, reentrant for different	
Parameters (in)	CtrlId	Index of the controller within the context of the Wireless Ethernet Driver
	PhysAddrPtr	Pointer to memory containing the physical source address (MAC address) in network byte order.
Parameters (inout)	None	

Parameters (out)	None
Return value	None
Description	Sets the physical source address used by the indexed controller
Available via	WEth.h

⌋()

[SWS_WEth_00139] ⌈
The function shall update the source address used by the indexed controller. ⌋()

[SWS_WEth_00140] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋()

[SWS_WEth_00141] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_00142] ⌈
If development error detection is enabled: the function shall check the parameter PhysAddrPtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_00143] ⌈
Caveat: The function requires previous controller initialization (WEth_Init). ⌋()

8.3.6 WEth_UpdatePhysAddrFilter

[SWS_WEth_00152]⌈

Service Name	WEth_UpdatePhysAddrFilter
Syntax	`Std_ReturnType WEth_UpdatePhysAddrFilter ( uint8 CtrlId, const uint8* PhysAddrPtr, const uint8* PhysMaskPtr, Eth_FilterActionType Action )`
Service ID [hex]	0x12

Sync/Async	Synchronous	
Reentrancy	Non Reentrant for the same CtrlId, reentrant for different	
Parameters (in)	CtrlId	Index of the context within the Wireless Ethernet Driver
	PhysAddr Ptr	Pointer to memory containing the physical destination address (MAC address) in network byte order. This is the multicast destination address of the layer 2 Ethernet packet.
	PhysMask Ptr	Pointer to memory containing the mask value in network byte order.
	Action	Add or remove the address from the Wireless Ethernet controllers filter.
Parameters (inout)	None	
Parameters (out)	None	
Return value	Std_-Return-Type	E_OK: filter was successfully changed E_NOT_OK: filter could not be changed
Description	Update the physical source address to/from the indexed context filter. If the Wireless Ethernet Controller is not capable to do the filtering, the software has to do this.	
Available via	WEth.h	

⌋()

[SWS_WEth_00150] ⌈
The function shall update the physical address receive filter of the indexed controller.
⌋()

[SWS_WEth_00245]⌈
The Wireless Ethernet driver module will receive a frame when the destination Address match the PhyAddrPtr passed here. (e.g matching can be done via hash table or simple pattern matching) ⌋()

Note: Underlying HW mechanism can be used if available. Otherwise the Ethernet driver needs to do this by software.

[SWS_WEth_00246]⌈
If the matching is positive, the upper layer shall be notified by calling RxIndication() callback.
If the matching is negative, the frame shall be discarded. ⌋()

[SWS_WEth_00164] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋()

[SWS_WEth_00165] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_00166] ⌈
If development error detection is enabled the function shall check the parameter PhysAddrPtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_00167] ⌈
Caveat: The function requires previous controller initialization (Eth_Init). ⌋()

[SWS_WEth_00144] ⌈
If the physical source address (MAC address) is set to FF:FF:FF: FF:FF:FF, this shall completely open the filter. ⌋()

[SWS_WEth_00146] ⌈
If this API is used and the hardware does not support filtering, promiscuous mode shall be enabled during initialization. ⌋()

[SWS_WEth_00147] ⌈
If the physical source address (MAC address) is set to 00:00:00: 00:00:00, this shall reduce the filter to the controllers unique unicast MAC address and end promiscuous mode if it was turned on. ⌋()

8.3.7 WEth_ProvideTxBuffer

[SWS_WEth_00077]⌈

Service Name	WEth_ProvideTxBuffer

Syntax	`BufReq_ReturnType WEth_ProvideTxBuffer (`
	`  uint8 CtrlId,`
	`  uint8 Priority,`
	`  Eth_BufIdxType* BufIdPtr,`
	`  uint8** BufPtr,`
	`  uint16* LenBytePtr`
	`)`

Service ID [hex]	0x09	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the context within the Wireless Ethernet Driver
	Priority	Priority value used for selection of different wireless transmit queues
Parameters (inout)	LenBytePtr	In: desired length in bytes, out: granted length in bytes
Parameters (out)	BufIdPtr	Index to the granted buffer resource. To be used for subsequent requests
	BufPtr	Pointer to the granted buffer
Return value	BufReq_Return-Type	BUFREQ_OK: success BUFREQ_E_NOT_OK: default error detected BUFREQ_E_BUSY: all buffers in use BUFREQ_E_OVFL: requested buffer too large
Description	Provides access to a transmit buffer of the specified controller	
Available via	WEth.h	

](

[SWS_WEth_00078] [
The function shall provide a transmit buffer resource. The Wireless Ethernet Driver shall lock the buffer until it receives a subsequent call of WEth_Transmit service with the buffer index returned in the BufIdxPtr parameter.]()

[SWS_WEth_00137] [
All locked transmit buffers shall be released if the controller is disabled via WEth_SetControllerMode.]()

[SWS_WEth_00079] [
If a buffer requested with WEth_ProvideTxBuffer that is larger than the available buffer length, the buffer shall not be locked but return the available length and BUFREQ_E_OVFL.]()

[SWS_WEth_00080] [
If all available buffers are in use the component shall return BUFREQ_E_BUSY.]()

[SWS_WEth_00081] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋()

[SWS_WEth_00082] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_00083] ⌈
If development error detection is enabled: the function shall check the parameter BufIdxPtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_00084] ⌈
If development error detection is enabled: the function shall check the parameter BufPtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_00085] ⌈
If development error detection is enabled: the function shall check the parameter LenBytePtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_00086] ⌈
Caveat: The function requires previous controller initialization (WEth_Init). ⌋()

8.3.8 WEth_Transmit

[SWS_WEth_00087]⌈

Service Name	WEth_Transmit

Syntax	`Std_ReturnType WEth_Transmit (`
	`  uint8 CtrlId,`
	`  Eth_BufIdxType BufId,`
	`  Eth_FrameType FrameType,`
	`  boolean TxConfirmation,`
	`  uint16 LenByte,`
	`  const uint8* PhysAddrPtr`
	`)`

Service ID [hex]	0x14
Sync/Async	Synchronous
Reentrancy	Non Reentrant

Parameters (in)	CtrlId	Index of the context within the Wireless Ethernet Driver
	BufId	Index of the buffer resource
	FrameType	Ethernet frame type
	TxConfirmation	Activates transmission confirmation
	LenByte	Data length in byte (802.11 Header + Body, not including FCS)
	PhysAddrPtr	Physical target address (MAC address) in network byte order
Parameters (inout)	None	
Parameters (out)	None	
Return value	Std_Return-Type	E_OK: success E_NOT_OK: transmission failed
Description	Triggers transmission of a previously filled transmit buffer	
Available via	WEth.h	

](

[SWS_WEth_00088] [
The function shall build the Ethernet header with the given physical target address (MAC address) and trigger the transmission of a previously filled transmit buffer.]()

After transmission, the driver needs to release the allocated buffer. It is up to the implementation when the actual buffer release shall occur, e.g. within the context of the WEth_TxConfirmation, the WEth_MainFunction, or during the next WEth_ProvideTxBuffer.

[SWS_WEth_00138] [
All pending transmit buffers shall be released if the controller is disabled via WEth_SetControllerMode.]()

[SWS_WEth_00090] [
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT.]()

[SWS_WEth_00091] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_00092] ⌈
If development error detection is enabled: the function shall check the parameter BufIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_PARAM. ⌋()

[SWS_WEth_00093] ⌈
If development error detection is enabled: the function shall check the parameter PhysAddrPtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_00129] ⌈
If development error detection is enabled: the function shall check the controller mode for being active (ETH_MODE_ACTIVE). If the check fails, the function shall raise the development error WETH_E_INV_MODE. ⌋()

[SWS_WEth_00094] ⌈
Caveat: The function requires previous buffer request (WEth_ProvideTxBuffer). ⌋()

8.3.9 WEth_TxConfirmation

[SWS_WEth_00100]⌈

Service Name	WEth_TxConfirmation	
Syntax	`void WEth_TxConfirmation ( uint8 CtrlId )`	
Service ID [hex]	0x02	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the controller within the context of the Wireless Ethernet Driver
Parameters (inout)	None	
Parameters (out)	None	

Return value	None
Description	Triggers frame transmission confirmation
Available via	WEth.h

⌋()

[SWS_WEth_00101] ⌈
The function shall check all filled transmit buffers for successful transmission. The function issues transmit confirmation for each transmitted frame using the callback function WEthIf_TxConfirmation if requested by the previous call of WEth_Transmit service. ⌋()

[SWS_WEth_00102] ⌈
If transmission confirmation was enabled by a previous call to WEth_Transmit function the function shall release the buffer resource. ⌋()

[SWS_WEth_00103] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋()

[SWS_WEth_00104] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_00134] ⌈
If development error detection is enabled: the function shall check the controller mode for being active (ETH_MODE_ACTIVE). If the check fails, the function shall raise the development error WETH_E_INV_MODE. ⌋()

[SWS_WEth_00105] ⌈
Caveat: The function requires previous initialization (WEth_Init). ⌋()

[SWS_WEth_10063] ⌈
The module must ensure that within the interrupt/polling context of this function call, transmission parameters of the wireless channel for the current buffer could be retrieved by the function WEth_GetBufWTxParams. ⌋()

8.3.10 WEth_Receive

[SWS_WEth_00095]⌈

Service Name	WEth_Receive

Syntax	`void WEth_Receive ( uint8 CtrlId, Eth_RxStatusType* RxStatusPtr )`	
Service ID [hex]	0x05	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the context within the Wireless Ethernet Driver
Parameters (inout)	None	
Parameters (out)	RxStatus Ptr	Indicates whether a frame has been received and if so, whether more frames are available or frames got lost.
Return value	void	--
Description	Triggers frame reception.	
Available via	WEth.h	

](

[SWS_WEth_00096] [
The function shall read the next frame from the receive buffers. The function passes the received frame to the Ethernet interface using the callback function WEthIf_RxIndication and indicates if there are more frames in the receive buffers.]()

[SWS_WEth_00097] [
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT.]()

[SWS_WEth_00098] [
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX.]()

[SWS_WEth_00132] [
If development error detection is enabled: the function shall check the controller mode for being active (ETH_MODE_ACTIVE). If the check fails, the function shall raise the development error WETH_E_INV_MODE.]()

[SWS_WEth_00153] ⌈
When calling the callback function WEthIf_RxIndication broadcast frames shall be indicated to the Ethernet Interface (see [6]). ⌋()

[SWS_WEth_00099] ⌈
Caveat: The function requires previous controller initialization (WEth_Init). ⌋()

[SWS_WEth_10061] ⌈
The module must ensure that within the interrupt/polling context of this function call, reception parameters of the wireless channel for the current buffer could be retrieved by the function WEth_GetBufWRxParams. ⌋()

8.3.11 WEth_GetWEtherStats32

[SWS_WEth_10070]⌈

Service Name	WEth_GetWEtherStats32	
Syntax	`Std_ReturnType WEth_GetWEtherStats32 ( uint8 CtrlId, uint32* WEtherStats )`	
Service ID [hex]	0x15	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the context within the Wireless Ethernet driver
Parameters (inout)	None	
Parameters (out)	WEtherStats	List of values according to IEEE 802.11-2012
Return value	Std_ReturnType	E_OK: success E_NOT_OK: drop counter could not be obtained
Description	Returns the following list according to IEEE 802.11-2012, where the maximal possible value shall denote an invalid value, e.g. if this counter is not available: 1. dot11STAStatisticsTransmittedFragmentCount 2. dot11STAStatisticsGroup TransmittedFrameCount 3. dot11STAStatisticsFailedCount 4. dot11STAStatistics RetryCount 5. dot11STAStatisticsMultipleRetryCount 6. dot11STAStatisticsFrame DuplicateCount 7. dot11STAStatisticsRTSSuccessCount 8. dot11STAStatistics	

	RTSFailureCount 9. dot11STAStatisticsACKFailureCount 10. dot11STAStatisticsQos TransmittedFragmentCount 11. dot11STAStatisticsQosFailedCount 12. dot11STAStatisticsQosRetryCount 13. dot11STAStatisticsQosMultipleRetryCount 14. dot11STAStatisticsQosFrameDuplicateCount 15. dot11STAStatisticsQos RTSSuccessCount 16. dot11STAStatisticsQosRTSFailureCount 17. dot11STAStatisticsQosACKFailureCount 18. dot11STAStatisticsQosReceived FragmentCount 19. dot11STAStatisticsQosTransmittedFrameCount 20. dot11STAStatisticsQosDiscardedFrameCount 21. dot11STAStatisticsQosMPDUs ReceivedCount 22. dot11STAStatisticsQosRetriesReceivedCount 23. dot11STAStatisticsReceivedFragmentCount 24. dot11STAStatisticsGroupReceived FrameCount 25. dot11STAStatisticsFCSErrorCount 26. dot11STAStatistics TransmittedFrameCount 27. dot11STAStatisticsRSNAStatsCMACICVErrors 28. dot11STAStatisticsRSNAStatsCMACReplays 29. dot11STAStatisticsRSNAStats RobustMgmtCCMPReplays 30. dot11STAStatisticsRSNAStatsTKIPICVErrors 31. dot11STAStatisticsRSNAStatsTKIPReplays 32. dot11STAStatisticsRSNAStats CCMPDecryptErrors 33. dot11STAStatisticsRSNAStatsCCMPReplays 34. dot11STAStatisticsTransmittedAMSDUCount 35. dot11STAStatisticsFailed AMSDUCount 36. dot11STAStatisticsRetryAMSDUCount 37. dot11STAStatistics MultipleRetryAMSDUCount 38. dot11STAStatisticsAMSDUAckFailureCount 39. dot11STAStatisticsReceivedAMSDUCount 40. dot11STAStatisticsTransmitted AMPDUCount 41. dot11STAStatisticsTransmittedMPDUsInAMPDUCount 42. dot11STAStatisticsAMPDUReceivedCount 43. dot11STAStatisticsMPDUInReceived AMPDUCount 44. dot11STAStatisticsAMPDUDelimiterCRCErrorCount 45. dot11STAStatisticsImplicitBARFailureCount 46. dot11STAStatisticsExplicit BARFailureCount 47. dot11STAStatisticsChannelWidthSwitchCount 48. dot11STAStatisticsTwentyMHzFrameTransmittedCount 49. dot11STAStatisticsForty MHzFrameTransmittedCount 50. dot11STAStatisticsTwentyMHzFrameReceived Count 51. dot11STAStatisticsFortyMHzFrameReceivedCount 52. dot11STAStatistics PSMPUTTGrantDuration 53. dot11STAStatisticsPSMPUTTUsedDuration 54. dot11STAStatisticsGrantedRDGUsedCount 55. dot11STAStatisticsGranted RDGUnusedCount 56. dot11STAStatisticsTransmittedFramesInGrantedRDGCount 57. dot11STAStatisticsDualCTSSuccessCount 58. dot11STAStatisticsDual CTSFailureCount 59. dot11STAStatisticsRTSLSIGSuccessCount 60. dot11STAStatisticsRTSLSIGFailureCount 61. dot11STAStatisticsBeamformingFrame Count 62. dot11STAStatisticsSTBCCTSSuccessCount 63. dot11STAStatistics STBCCTSFailureCount 64. dot11STAStatisticsnonSTBCCTSSuccessCount 65. dot11STAStatisticsnonSTBCCTSFailureCount
Available via	WEth.h

]()

Note: Only Counter32 values from the list Dot11STAStatisticsReportEntry in 802.11-2012 (C.3) are supported.

[SWS_WEth_00234] [The function shall read a list of values from the indexed controller according to [17].]()

[SWS_WEth_00235] [
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT.]()

[SWS_WEth_00236] [

If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX.]()

[SWS_WEth_00237] ⌈
If development error detection is enabled: the function shall check the parameter RxStats for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER.]()

[SWS_WEth_00238] ⌈
The function WEth_GetWEthertStats32 shall be pre compile time configurable On/Off by the configuration parameter: WEthGetWEtherStatsApi.]()

8.3.12 WEth_GetWEtherStats64

[SWS_WEth_10024]⌈

Service Name	WEth_GetWEtherStats64	
Syntax	`Std_ReturnType WEth_GetWEtherStats64 ( uint8 CtrlId, uint64* WEtherStats )`	
Service ID [hex]	0xe0	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the context within the Wireless Ethernet driver
Parameters (inout)	None	
Parameters (out)	WEtherStats	List of values according to IEEE 802.11-2012
Return value	Std_ReturnType	E_OK: success E_NOT_OK: drop counter could not be obtained
Description	Returns the following list according to IEEE 802.11-2012, where the maximal possible value shall denote an invalid value, e.g. if this counter is not available: 1. dot11STAStatisticsTransmittedOctetsInAMSDUCount 2. dot11STAStatisticsReceived OctetsInAMSDUCount 3. dot11STAStatisticsTransmittedOctetsInAMPDUCount 4.	

	dot11STAStatisticsReceivedOctetsInAMPDUCount 5. dot11STAStatisticsTransmitted OctetsInGrantedRDGCount
Available via	WEth.h

⌋()

Note: Only Counter64 values from the list Dot11STAStatisticsReportEntry in 802.11-2012 (C.3) are supported.

[SWS_WEth_10026] ⌈
The function shall read a list of values from the indexed controller according to [17].
⌋()

[SWS_WEth_10235] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋()

[SWS_WEth_10236] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_10237] ⌈
If development error detection is enabled: the function shall check the parameter RxStats for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_10027] ⌈
The function WEth_GetWEthertStats64 shall be pre compile time configurable On/Off by the configuration parameter: WEthGetWEtherStatsApi. ⌋()

8.3.13 WEth_WriteTrcvRegs

[SWS_WEth_10028]⌈

Service Name	WEth_WriteTrcvRegs

Syntax	`Std_ReturnType WEth_WriteTrcvRegs (`
	`  uint8 CtrlId,`
	`  uint8 TrcvId,`
	`  uint8 RadioId,`
	`  const uint32* RegIds,`
	`  const uint32* RegVals,`
	`  uint8 NumRegs`
	`)`

Service ID [hex]	0x30	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the controller within the context of the Ethernet Driver
	TrcvId	Index of the transceiver on the destined bus
	RadioId	Index of the Transceiver's Radio Module
	RegIds	List of Index of the transceiver registers
	RegVals	Value to be written into the indexed register
	NumRegs	Number of Registers/Values
Parameters (inout)	None	
Parameters (out)	None	
Return value	Std_Return-Type	E_OK: Service accepted E_NOT_OK: Service denied
Description	Configures a transceivers registers or triggers a function offered by the receiver	
Available via	WEth.h	

]()

[SWS_WEth_00059] ⌈
The function shall write the specified parameters in the transceivers registers for the indexed radio through a controller specific bus interface of the indexed controller.]()

[SWS_WEth_00060] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT.]()

[SWS_WEth_00061] ⌈

If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX.]()

[SWS_WEth_00063] [
Caveat: The function requires previous controller initialization (WEth_Init).]()

[SWS_WEth_10030] [
If development error detection is enabled: the function shall check the parameter RegIds for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER.]()

[SWS_WEth_10031] [
If development error detection is enabled: the function shall check the parameter RegVals for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER.]()

8.3.14 WEth_ReadTrcvRegs

[SWS_WEth_10032][

Service Name	WEth_ReadTrcvRegs	

Syntax	`Std_ReturnType WEth_ReadTrcvRegs (`
	`  uint8 CtrlId,`
	`  uint8 TrcvId,`
	`  uint8 RadioId,`
	`  const uint32* RegIds,`
	`  uint32* RegValsPtr,`
	`  uint8 NumRegs`
	`)`	

Service ID [hex]	0x31	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the controller within the context of the Ethernet Driver
	TrcvId	Index of the transceiver on the destined bus
	RadioId	Index of the Transceiver's Radio Module
	RegIds	Array of Index of the transceiver registers
	NumRegs	Number of Registers/Values

Parameters (inout)	None	
Parameters (out)	RegValsPtr	Value to be written into the indexed register
Return value	Std_Return-Type	E_OK: Service accepted E_NOT_OK: Service denied
Description	Reads a transceiver register	
Available via	WEth.h	

⌋()

[SWS_WEth_00065] ⌈
The function shall read the specified transceiver register through the MII of the indexed controller. ⌋()

[SWS_WEth_00066] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋()

[SWS_WEth_00067] ⌈
If development error detection is enabled: the function shall check the parameter CtrlIdx for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_IDX. ⌋()

[SWS_WEth_00068] ⌈
If development error detection is enabled: the function shall check the parameter RegValPtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_00070] ⌈
Caveat: The function requires previous controller initialization (WEth_Init). ⌋()

[SWS_WEth_10034] ⌈
If development error detection is enabled: the function shall check the parameter RegIds for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_10035] ⌈
If development error detection is enabled: the function shall check the parameter RegVals for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

8.3.15 WEth_GetBufWRxParams

[SWS_WEth_10062]⌈

Service Name	WEth_GetBufWRxParams	
Syntax	`Std_ReturnType WEth_GetBufWRxParams ( uint8 CtrlId, const WEth_BufWRxParamIdType* RxParamIds, uint32* ParamValues, uint8 NumParams )`	
Service ID [hex]	0x34	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the Ethernet controller
	RxParamIds	IDs of the Parameter that are requested
	NumParams	Number of Parameters that are requested
Parameters (inout)	None	
Parameters (out)	ParamValues	Values of the Parameters requested
Return value	Std_ReturnType	E_OK: success E_NOT_OK: failed reading parameters
Description	Read out values related to the receive direction for a received packet. For example, this could be RSSI or Channel belonging to one single packet.This API is valid only within the context of WEth_Receive	
Available via	WEth.h	

⌋()

[SWS_WEth_10039] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋(**SRS_BSW_00487**)

[SWS_WEth_10040] ⌈
If development error detection is enabled: the function shall check the parameter CtrlId for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_ID. ⌋()

[SWS_WEth_10041] ⌈
If development error detection is enabled: the function shall check the parameter RxParamIds for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_10042] ⌈
If development error detection is enabled: the function shall check the parameter ParamValues for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

8.3.16 WEth_GetBufWTxParams

[SWS_WEth_10044]⌈

Service Name	WEth_GetBufWTxParams	
Syntax	`Std_ReturnType WEth_GetBufWTxParams ( uint8 CtrlId, const WEth_BufWTxParamIdType* TxParamIds, uint32* ParamValues, uint8 NumParams )`	
Service ID [hex]	0x35	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the Ethernet controller
	TxParamIds	IDs of the Parameter that are requested
	NumParams	Number of Parameters that are requested
Parameters (inout)	None	
Parameters (out)	ParamValues	Values of the Parameters requested
Return value	Std_ReturnType	E_OK: success

		E_NOT_OK: failed reading parameters
Description	Read out values related to the transmit direction for a transmitted packet. For example, this could be transaction ID belonging to one single packet.This API is valid only within the context of WEth_TxConfirmation.	
Available via	WEth.h	

]()

[SWS_WEth_10046] ⌈
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH_E_UNINIT. ⌋(**SRS_BSW_00487**)

[SWS_WEth_10047] ⌈
If development error detection is enabled: the function shall check the parameter CtrlId for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_ID. ⌋()

[SWS_WEth_10048] ⌈
If development error detection is enabled: the function shall check the parameter TxParamIds for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

[SWS_WEth_10049] ⌈
If development error detection is enabled: the function shall check the parameter ParamValues for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER. ⌋()

8.3.17 WEth_SetBufWTxParams

[SWS_WEth_10051]⌈

Service Name	WEth_SetBufWTxParams

Syntax	`Std_ReturnType WEth_SetBufWTxParams (`
	`  uint8 CtrlId,`
	`  Eth_BufIdxType BufId,`
	`  const WEth_BufWTxParamIdType* TxParamIds,`
	`  const uint32* ParamValues,`
	`  uint8 NumParams`
	`)`

Service ID [hex]	0x36
Sync/Async	Synchronous

Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the Ethernet controller
	BufId	Index of the buffer resource
	TxParamIds	IDs of the Parameter that are provided to the transmit radio
	ParamValues	Values of the Parameters that are provided to the transmit radio
	NumParams	Number of Parameters that are provided to the transmit radio
Parameters (inout)	None	
Parameters (out)	None	
Return value	Std_ReturnType	E_OK: success E_NOT_OK: failed setting parameter
Description	Set values related to the transmit direction for a specific buffer (packet to be sent). For example, this can be the desired transmit power or the channel belonging to one single packet.	
Available via	WEth.h	

](SRS_V2X_00245)

[SWS_WEth_10053] [
If development error detection is enabled: the function shall check that the service WEth_Init was previously called. If the check fails, the function shall raise the development error WETH _E_NOT_INITIALIZED.]()

[SWS_WEth_10054] [
If development error detection is enabled: the function shall check the parameter CtrlId for being valid. If the check fails, the function shall raise the development error WETH_E_INV_CTRL_ID.]()

[SWS_WEth_10055] [
If development error detection is enabled: the function shall check the parameter BufId for being valid. If the check fails, the function shall raise the development error WETH_E_INV_PARAM.]()

[SWS_WEth_10056] [

If development error detection is enabled: the function shall check the parameter TxParamIds for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER.]()

[SWS_WEth_10057] [
If development error detection is enabled: the function shall check the parameter ParamValues for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER.]()

8.3.18 WEth_GetVersionInfo

[SWS_WEth_00106][

Service Name	WEth_GetVersionInfo	
Syntax	`void WEth_GetVersionInfo ( Std_VersionInfoType* VersionInfoPtr )`	
Service ID [hex]	0x0d	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	None	
Parameters (inout)	None	
Parameters (out)	VersionInfo Ptr	Pointer to where to store the version information of this module.
Return value	None	
Description	Returns the version information of this module	
Available via	WEth.h	

]()

[SWS_WEth_00136] [
If development error detection is enabled: the function shall check the parameter VersionInfoPtr for being valid. If the check fails, the function shall raise the development error WETH_E_PARAM_POINTER.]()

8.3.19 WEth_TriggerPriorityQueueTransmit

[SWS_WEth_10071]⌈

Service Name	WEth_TriggerPriorityQueueTransmit	
Syntax	`Std_ReturnType WEth_TriggerPriorityQueueTransmit ( uint8 CtrlId, uint8 PriorityQueue, uint8 MaxTxPower )`	
Service ID [hex]	0x37	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	CtrlId	Index of the context within the Wireless Ethernet Driver
	PriorityQueue	Index of the Priority Queue
	MaxTxPower	Limit the Power of the packet in the Priority Queue
Parameters (inout)	None	
Parameters (out)	None	
Return value	Std_ReturnType	E_OK: success E_NOT_OK: transmission failed
Description	Triggers transmission of a previously filled transmit buffer that is waiting in a software priority queue.	
Available via	WEth.h	

⌋()

8.4 Call-back notifications

The Wireless Ethernet Driver does not provide any callback functions.

8.5 Scheduled functions

8.5.1 WEth_MainFunction

[SWS_WEth_00171]⌈

Service Name	WEth_MainFunction
Syntax	`void WEth_MainFunction ( void )`
Service ID [hex]	0x0a
Description	Support for indirect transmissions (extended frame timing constraints) and mechanisms for channel selection when using multiple channels. Used for polling state changes. Calls EthIf_CtrlModeIndication when the controller mode changed.
Available via	SchM_WEth.h

⌋()

8.6 Expected Interfaces

In this chapter, all external interfaces required from other modules are listed.

8.6.1 Mandatory Interfaces

This chapter defines all external interfaces, which are required to fulfill the core functionality of the module.

[SWS_WEth_00119]⌈

API Function	***Header File***	***Description***
Dem_Set-EventStatus	Dem.h	Called by SW-Cs or BSW modules to report monitor status information to the Dem. BSW modules calling Dem_SetEventStatus can safely ignore the return value. This API will be available only if ({Dem/DemConfigSet/ DemEventParameter/DemEventReportingType} == STANDARD_ REPORTING)

EthIf_Ctrl-Mode-Indication	EthIf.h	Called asynchronously when mode has been read out. Triggered by previous Eth_SetControllerMode call. Can directly be called within the trigger functions.
EthIf_Rx-Indication	EthIf.h	Handles a received frame received by the indexed controller
EthIf_Tx-Confirmation	EthIf.h	Confirms frame transmission by the indexed controller

](

8.6.2 Optional Interfaces

This chapter defines all external interfaces, which are required to fulfill an optional functionality of the module.

[SWS_WEth_00120][

API Function	*Header File*	*Description*
Det_ReportError	Det.h	Service to report development errors.

](

8.6.3 Configurable interfaces

The Wireless Ethernet Driver does not use configurable interfaces.

9 Sequence diagrams

The Wireless Ethernet Driver will interact with Ethernet Interface in the same way as the Ethernet Driver, see sequence diagrams in [5].

10 Configuration specification

Chapter 10.1 specifies the structure (containers) and the parameters of the WEth module.

Chapter 10.2 specifies additionally published information of the WEth module.

10.1 Containers and configuration parameters

The following chapters summarize all configuration parameters.

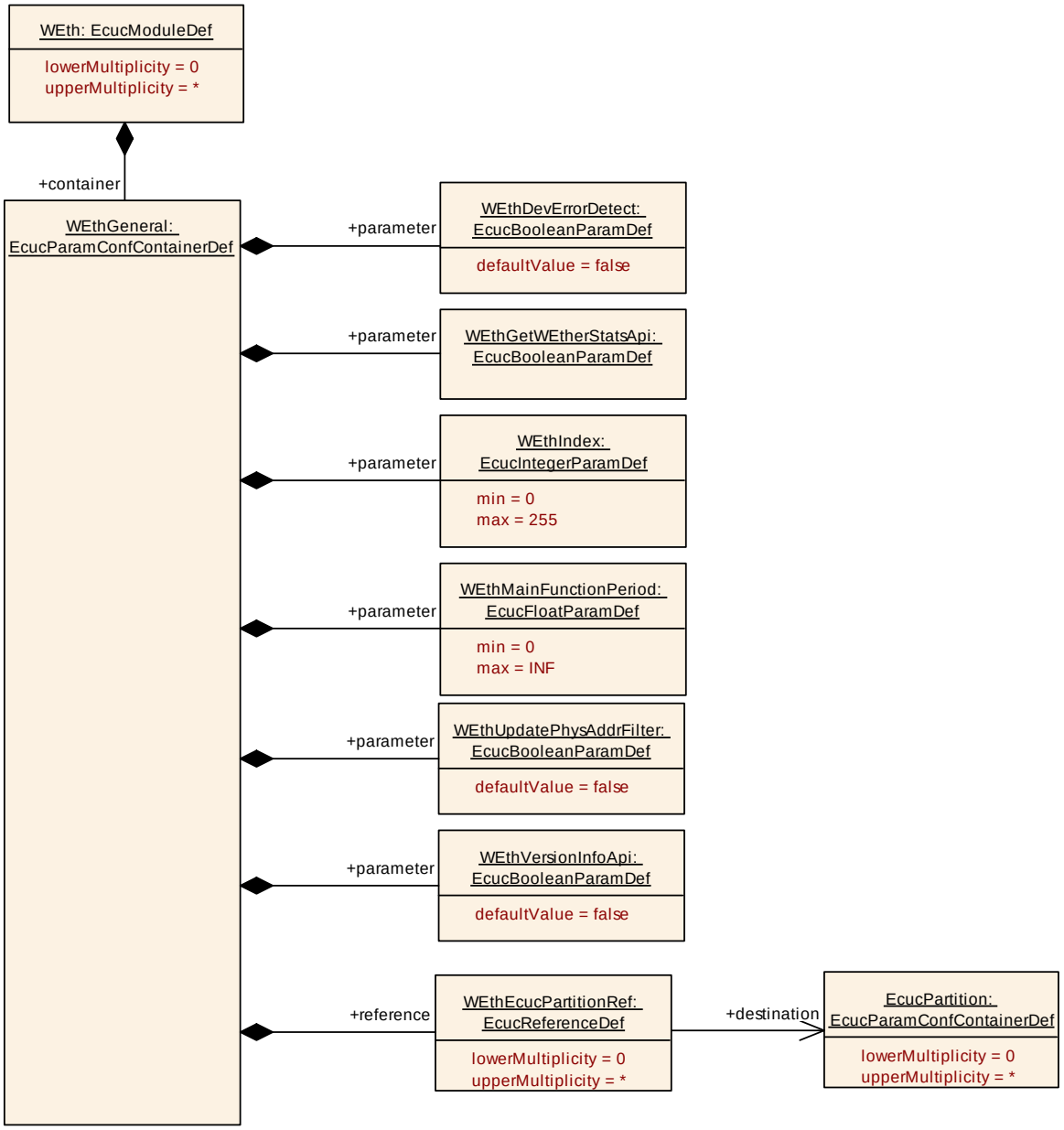
[SWS_WEth_00040] [The Wireless Ethernet Driver module shall reject configurations with partition mappings, which are not supported by the implementation.]()

10.1.1 Variants

10.1.2 WEth

SWS Item	**ECUC_WEth_00037 :**
Module Name	*WEth*
Module Description	Configuration of the WEth (Wireless Ethernet Driver) module.
Post-Build Variant Support	true
Supported Config Variants	VARIANT-LINK-TIME, VARIANT-POST-BUILD, VARIANT-PRE-COMPILE

Included Containers		
Container Name	***Multiplicity***	***Scope / Dependency***
WEthConfigSet	1	This container contains the configuration parameters and sub containers of the AUTOSAR WEth module.
WEthGeneral	1	General configuration of Wireless Ethernet Driver module.



10.1.3 WEthConfigSet

SWS Item	**ECUC_WEth_00015 :**
Container Name	WEthConfigSet
Parent Container	WEth
Description	This container contains the configuration parameters and sub containers of the AUTOSAR WEth module.
Configuration Parameters	

Included Containers		
Container Name	***Multiplicity***	***Scope / Dependency***
WEthCtrlConfig	1..*	Configuration of the individual controller

10.1.4 WEthCtrlConfig

SWS Item	**ECUC_WEth_00006 :**		
Container Name	WEthCtrlConfig		
Parent Container	WEthConfigSet		
Description	Configuration of the individual controller		
Configuration Parameters			

SWS Item	**ECUC_WEth_00007 :**		
Name	WEthCtrlId		
Parent Container	WEthCtrlConfig		
Description	Specifies the instance ID of the configured controller.		
Multiplicity	1		
Type	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
Range	0 .. 255		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: ECU		

SWS Item	**ECUC_WEth_00020 :**		
Name	WEthCtrlPhyAddress		
Parent Container	WEthCtrlConfig		
Description	Specifies the unique 48-bit physical address (MAC address) of the controller in network byte order. Regular Expression: [0-9a-fA-F]{2}[[:-][0-9a-fA-F]{2}]{5}		
Multiplicity	0..1		
Type	EcucStringParamDef		
Default value	--		
maxLength	17		
minLength	17		
regularExpression	--		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	***Pre-compile time***	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	***Pre-compile time***	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	**ECUC_WEth_00008 :**		
Name	WEthCtrlRxBufLenByte		
Parent Container	WEthCtrlConfig		
Description	Limits the maximum receive buffer length (frame length) in bytes.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 1522		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	VARIANT-PRE-COMPILE

	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	**ECUC_WEth_00009 :**		
Name	WEthCtrlTxBufLenByte		
Parent Container	WEthCtrlConfig		
Description	Limits the maximum transmit buffer length (frame length) in bytes.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 1522		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

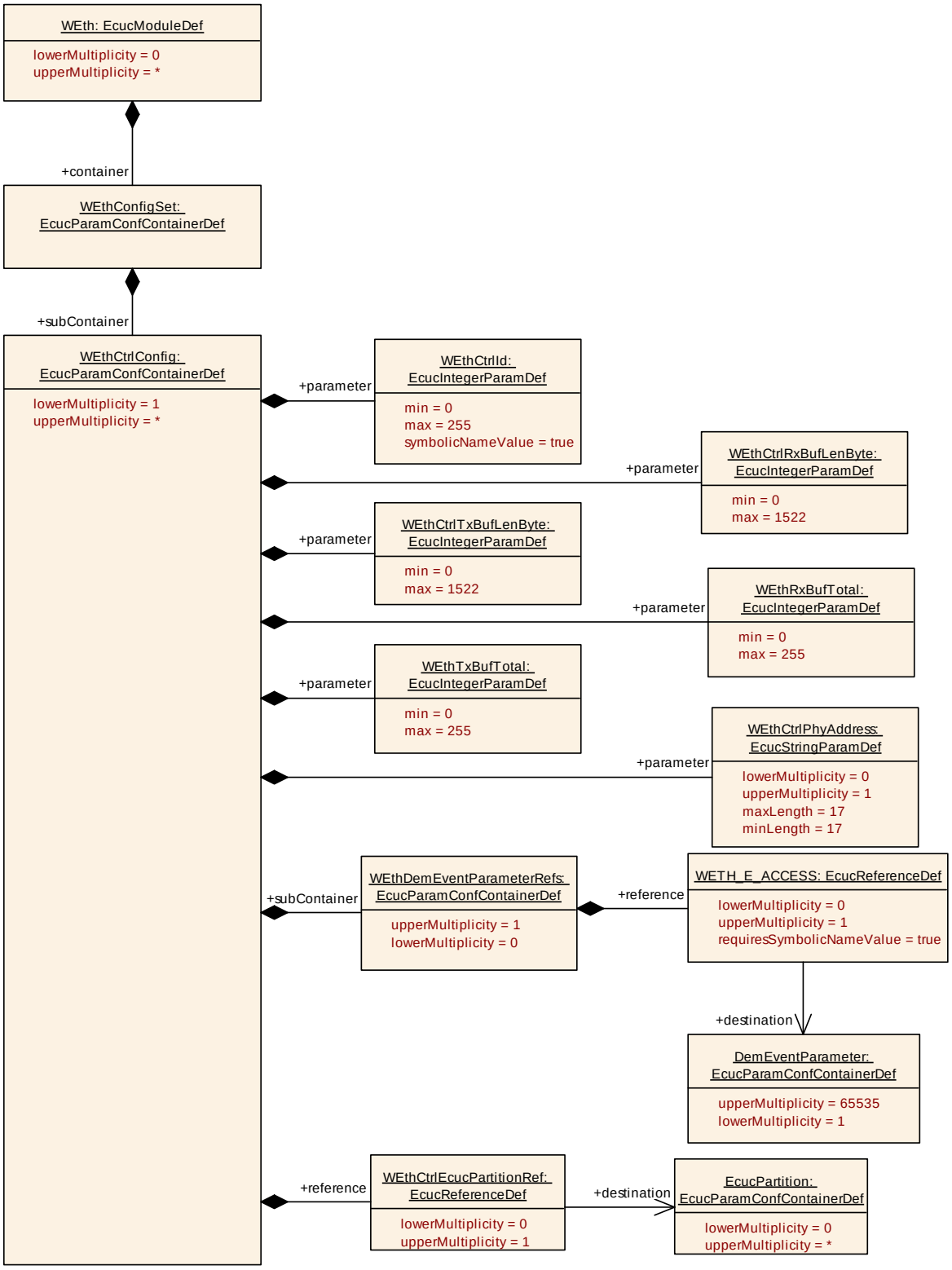
SWS Item	**ECUC_WEth_00013 :**		
Name	WEthRxBufTotal		
Parent Container	WEthCtrlConfig		
Description	Configures the number of receive buffers.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 255		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	**ECUC_WEth_00014 :**		
Name	WEthTxBufTotal		
Parent Container	WEthCtrlConfig		
Description	Configures the number of transmit buffers.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 255		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	***Pre-compile time***	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	**ECUC_WEth_00039 :**
Name	WEthCtrlEcucPartitionRef
Parent Container	WEthCtrlConfig
Description	Maps the Wireless Ethernet controller to zero or one ECUC partitions. The ECUC partition referenced is a subset of the ECUC partitions where the Wireless Ethernet driver is mapped to.
Multiplicity	0..1
Type	Reference to [EcucPartition]
Post-Build Variant Multiplicity	true

Post-Build Variant Value	true		
Multiplicity Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: ECU		

Included Containers		
Container Name	***Multiplicity***	***Scope / Dependency***
WEthDemEventParameterRefs	0..1	Container for the references to DemEventParameter elements which shall be invoked using the API Dem_SetEventStatus in case the corresponding error occurs. The EventId is taken from the referenced DemEventParameter's DemEventId symbolic value. The standardized errors are provided in this container and can be extended by vendor-specific error references.



10.1.5 WEthDemEventParameterRefs

SWS Item	**ECUC_WEth_00016 :**
Container Name	WEthDemEventParameterRefs

Parent Container	WEthCtrlConfig
Description	Container for the references to DemEventParameter elements which shall be invoked using the API Dem_SetEventStatus in case the corresponding error occurs. The EventId is taken from the referenced DemEventParameter's DemEventId symbolic value. The standardized errors are provided in this container and can be extended by vendor-specific error references.
Configuration Parameters	

SWS Item	**ECUC_WEth_00017 :**		
Name	WETH_E_ACCESS		
Parent Container	WEthDemEventParameterRefs		
Description	Reference to the DemEventParameter which shall be issued when the error "Controller access failed" has occured.		
Multiplicity	0..1		
Type	Symbolic name reference to [DemEventParameter]		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	***Pre-compile time***	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	***Pre-compile time***	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

No Included Containers

10.1.6 WEthGeneral

SWS Item	**ECUC_WEth_00001 :**
Container Name	WEthGeneral
Parent Container	WEth
Description	General configuration of Wireless Ethernet Driver module.
Configuration Parameters	

SWS Item	**ECUC_WEth_00003 :**		
Name	WEthDevErrorDetect		
Parent Container	WEthGeneral		
Description	Switches the Default Error Tracer (Det) detection and notification ON or OFF. • true: detection and notification is enabled. • false: detection and notification is disabled.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_WEth_00036 :**		
Name	WEthGetWEtherStatsApi		
Parent Container	WEthGeneral		
Description	Enables / Disables WEth_GetWEtherStats_32 and WEth_GetWEtherStats_64 API.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_WEth_00018 :**		
Name	WEthIndex		
Parent Container	WEthGeneral		
Description	Specifies the InstanceId of this module instance. If only one instance is present it shall have the Id 0.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 255		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_WEth_00022 :**		
Name	WEthMainFunctionPeriod		
Parent Container	WEthGeneral		
Description	Specifies the period of main function WEth_MainFunction in seconds. Wireless Ethernet driver does not require this information but the BSW scheduler.		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	]0 .. INF[		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_WEth_00019 :**		
Name	WEthUpdatePhysAddrFilter		
Parent Container	WEthGeneral		
Description	Enables/Disables optional API WEth_UpdatePhysAddrFilter.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	

Scope / Dependency	scope: local

SWS Item	**ECUC_WEth_00004 :**		
Name	WEthVersionInfoApi		
Parent Container	WEthGeneral		
Description	Enables / Disables version info API.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	**ECUC_WEth_00038 :**		
Name	WEthEcucPartitionRef		
Parent Container	WEthGeneral		
Description	Maps the Wireless Ethernet driver to zero or multiple ECUC partitions to make the modules API available in this partition. The Wireless Ethernet driver will operate as an independent instance in each of the partitions.		
Multiplicity	0..*		
Type	Reference to [EcucPartition]		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Value Configuration Class	***Pre-compile time***	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: ECU		

No Included Containers

[SWS_WEth_CONSTR_00241] [The module will operate as an independent instance in each of the partitions, means the called API will only target the partition it is called in.]()

[SWS_WEth_CONSTR_00242] [If WEthEcucPartitionRef references one or more ECUC partitions, WEthCtrlEcucPartitionRef shall have a multiplicity of one and reference one of these ECUC partitions as well.]()

11 Not applicable requirements

None.