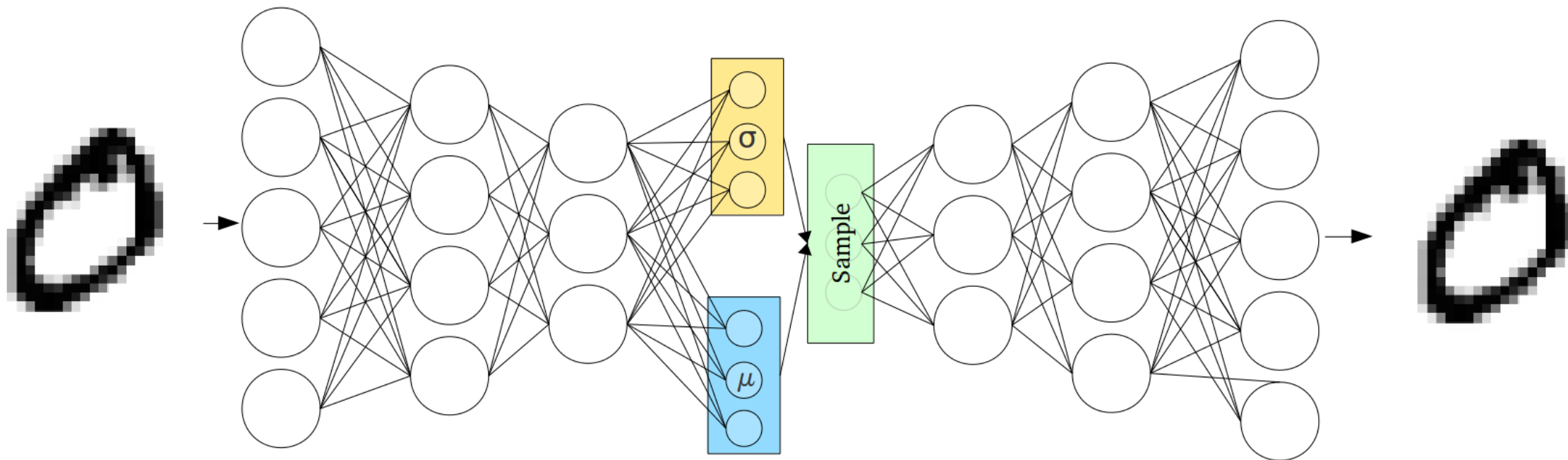


Variational Autoencoders (VAEs)

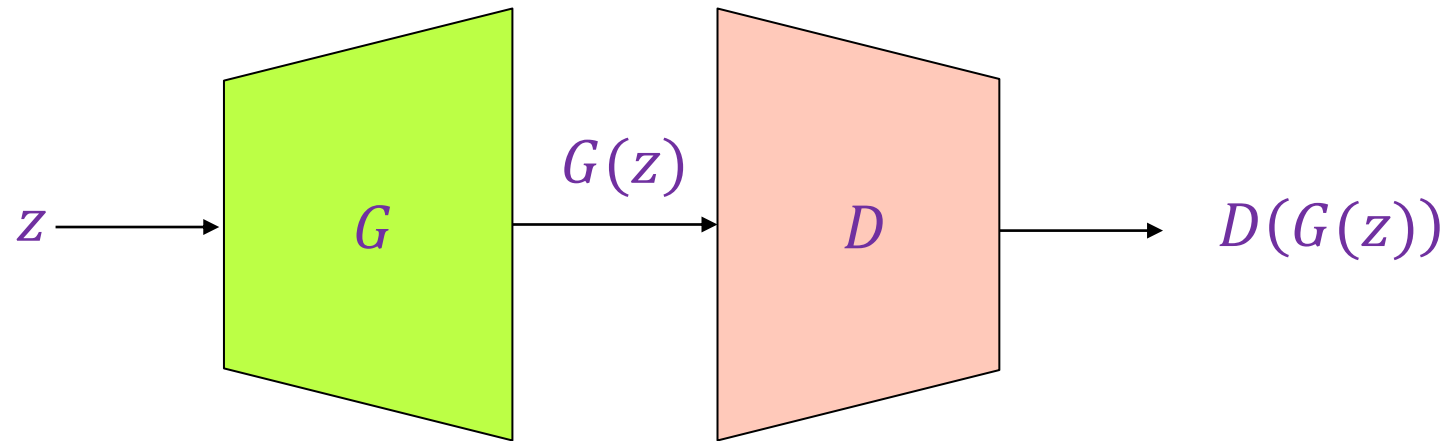


Outline

- Basic VAE formulation
- Highlights of recent work

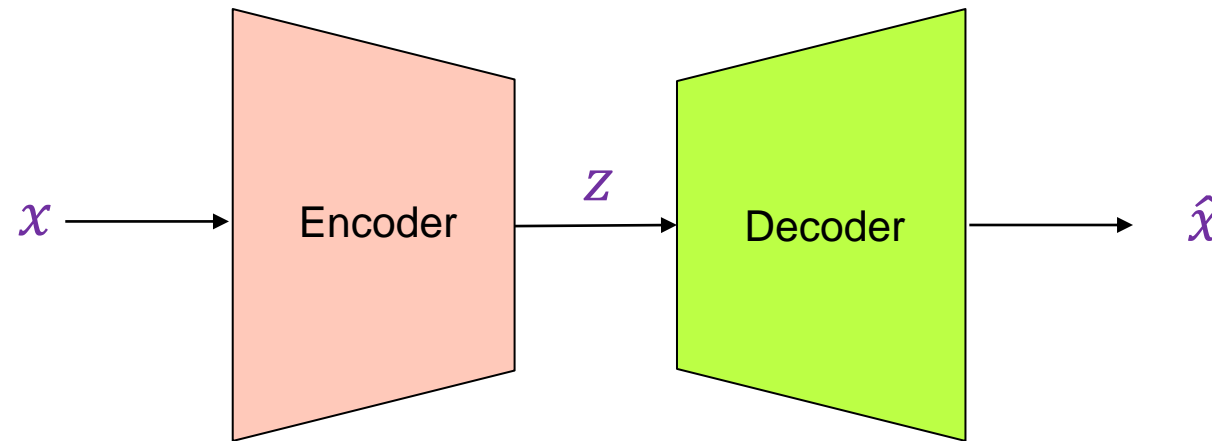
Recall: GANs

- Training:
 - Discriminator: low scores for fake data, high scores for real data
 - Generator: increase discriminator score on fake data
- Test time: discard discriminator and use generator to sample from learned distribution



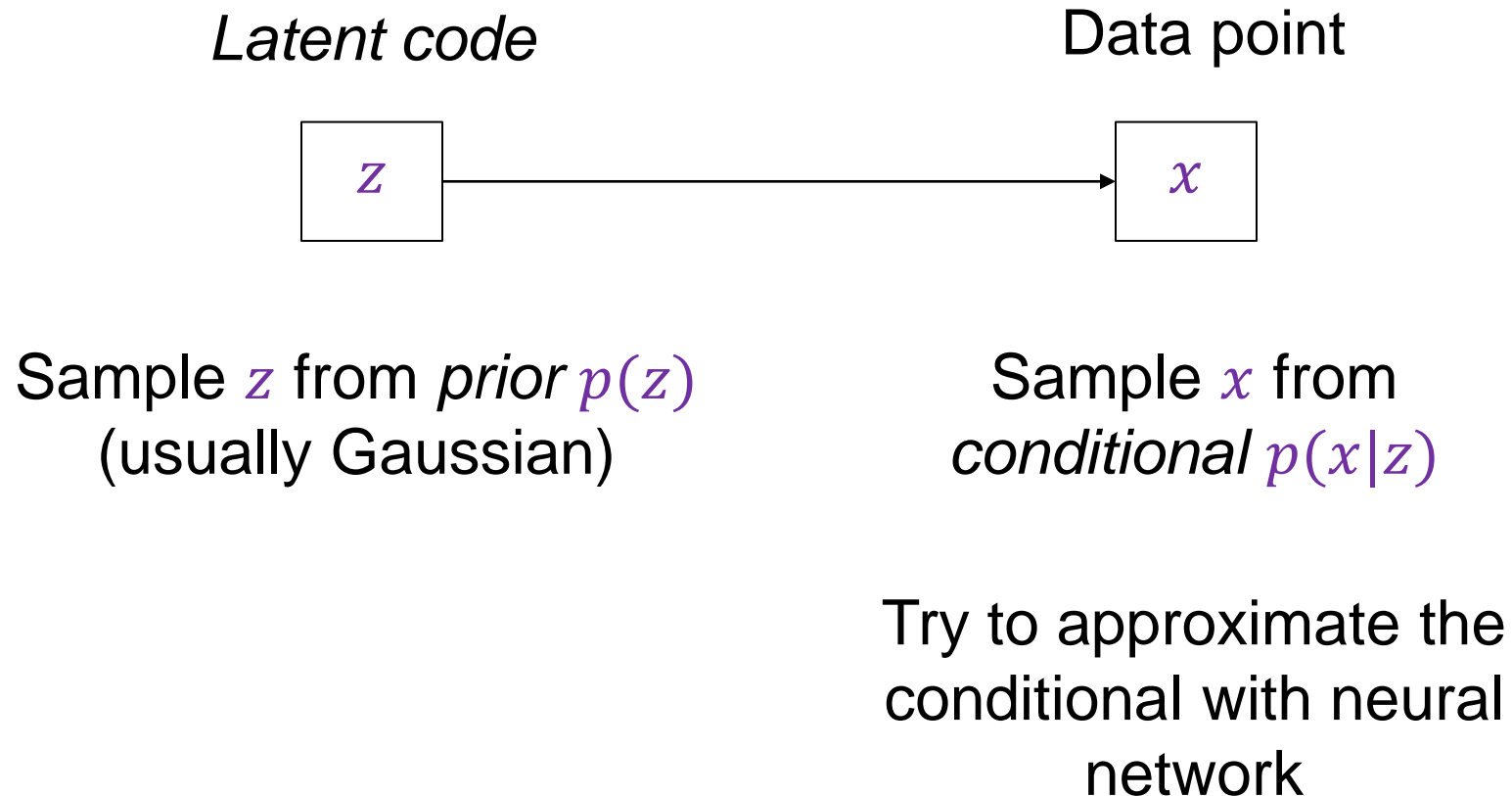
Variational autoencoders: Overview

- Probabilistic formulation based on *variational Bayes* framework
- At training time, jointly learn *encoder* and *decoder* by maximizing (a bound on) the data likelihood
- At test time, discard encoder and use decoder to sample from the learned distribution



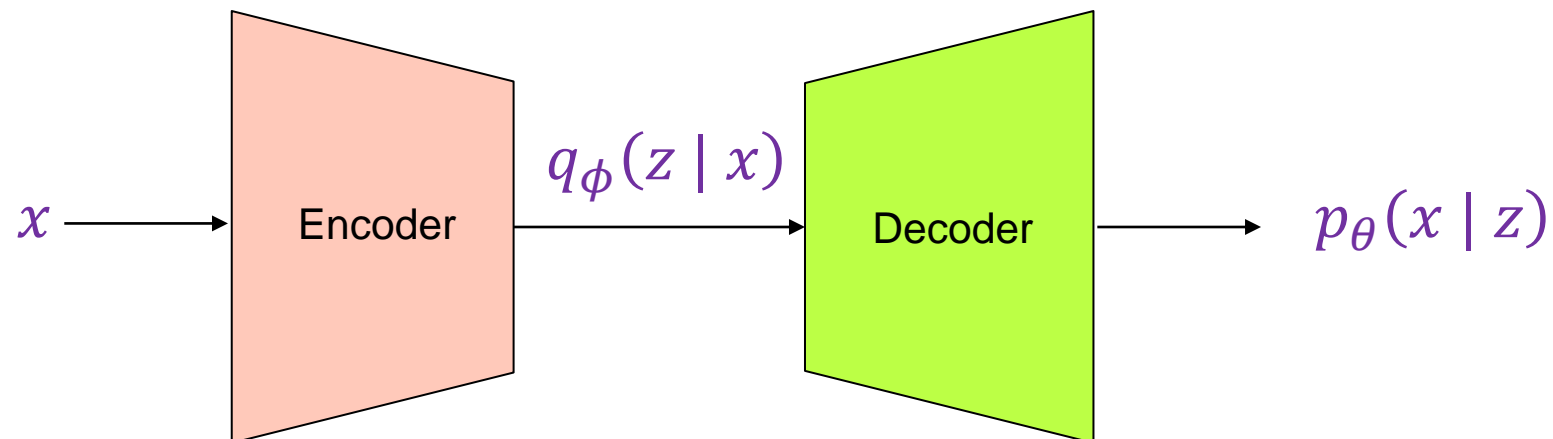
Variational autoencoders: Overview

- Probabilistic generative model of the data distribution:



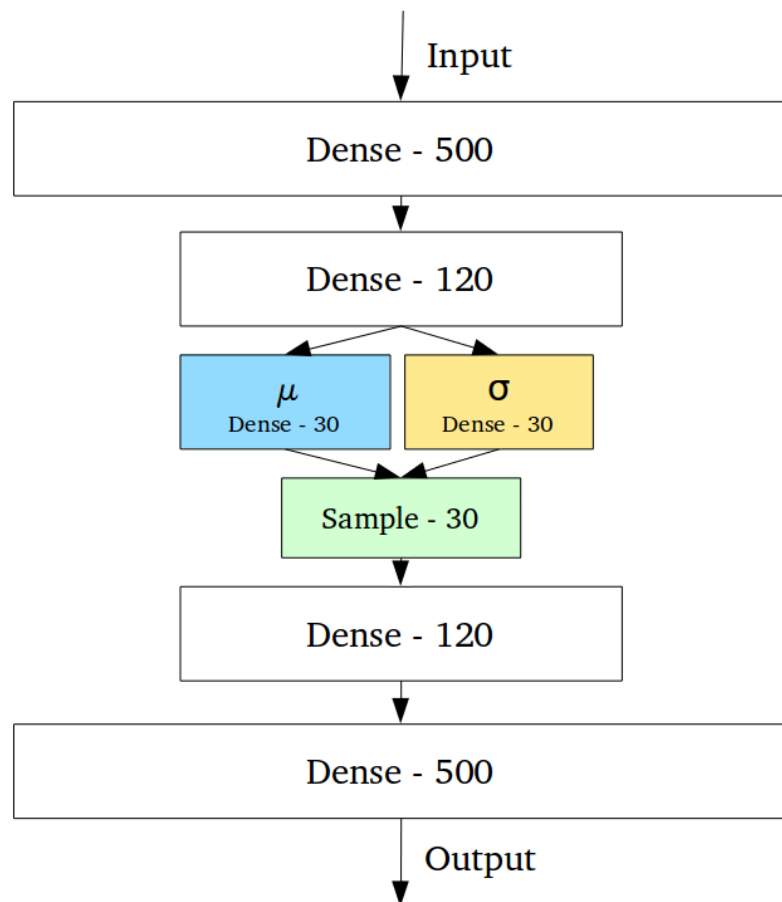
Variational autoencoders: Overview

- At training time, jointly learn *encoder* and *decoder*
- **Encoder:** given inputs x , output $q_{\phi}(z | x)$
 - Specifically, output mean and (diagonal) covariance, or $\mu_{z|x}$ and $\Sigma_{z|x}$, so that $q_{\phi}(z | x) = N(\mu_{z|x}, \Sigma_{z|x})$
- **Decoder:** given z , output $p_{\theta}(x | z)$
 - Specifically, output $\mu_{x|z}$ and $\Sigma_{x|z}$ so that $p_{\theta}(x | z) = N(\mu_{x|z}, \Sigma_{x|z})$
- **Training objective:** (a bound on) data likelihood under the model



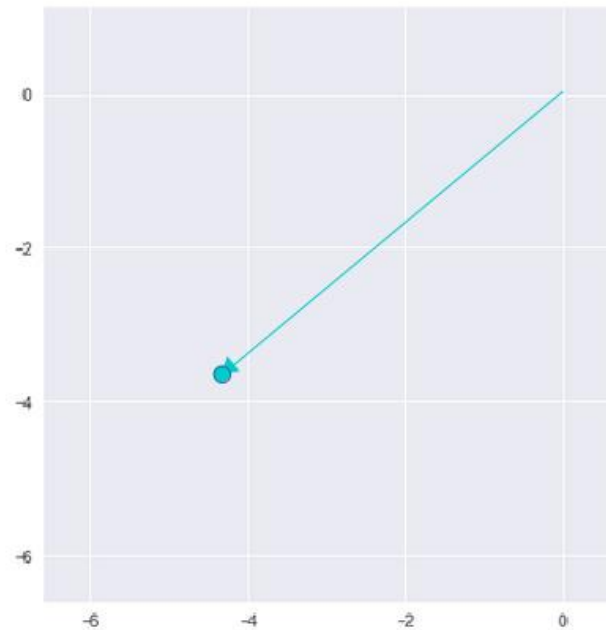
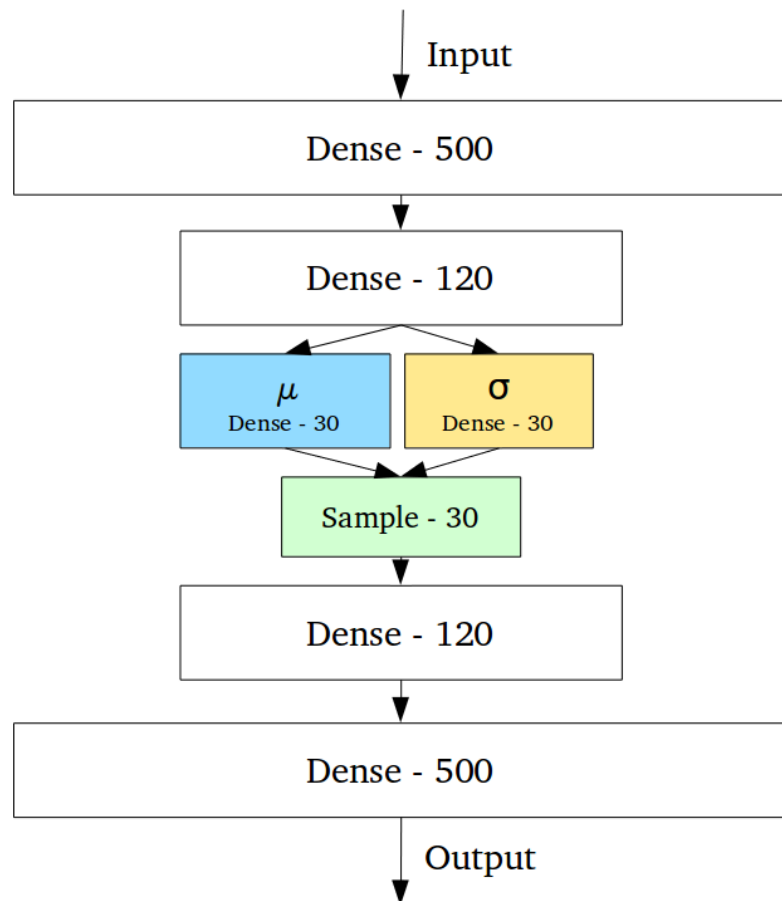
Variational autoencoders: Overview

- VAE makes its encoder not output an encoding vector of size n , rather, outputting two vectors of size n : a vector of means, μ , and another vector of standard deviations, σ .

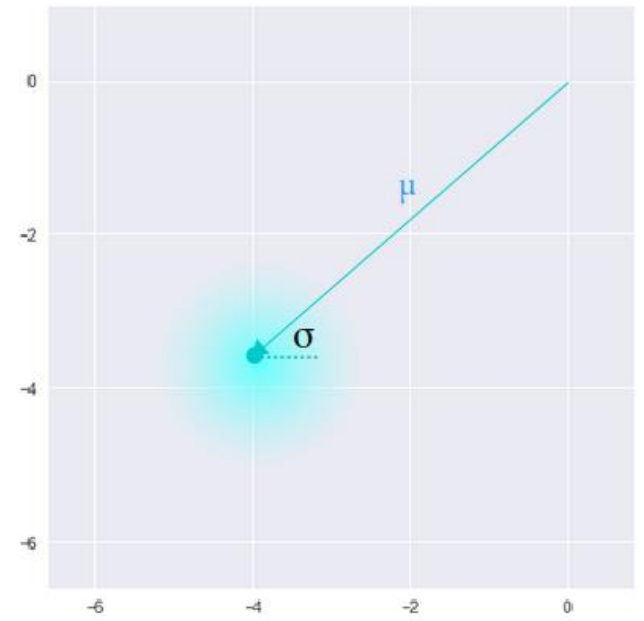


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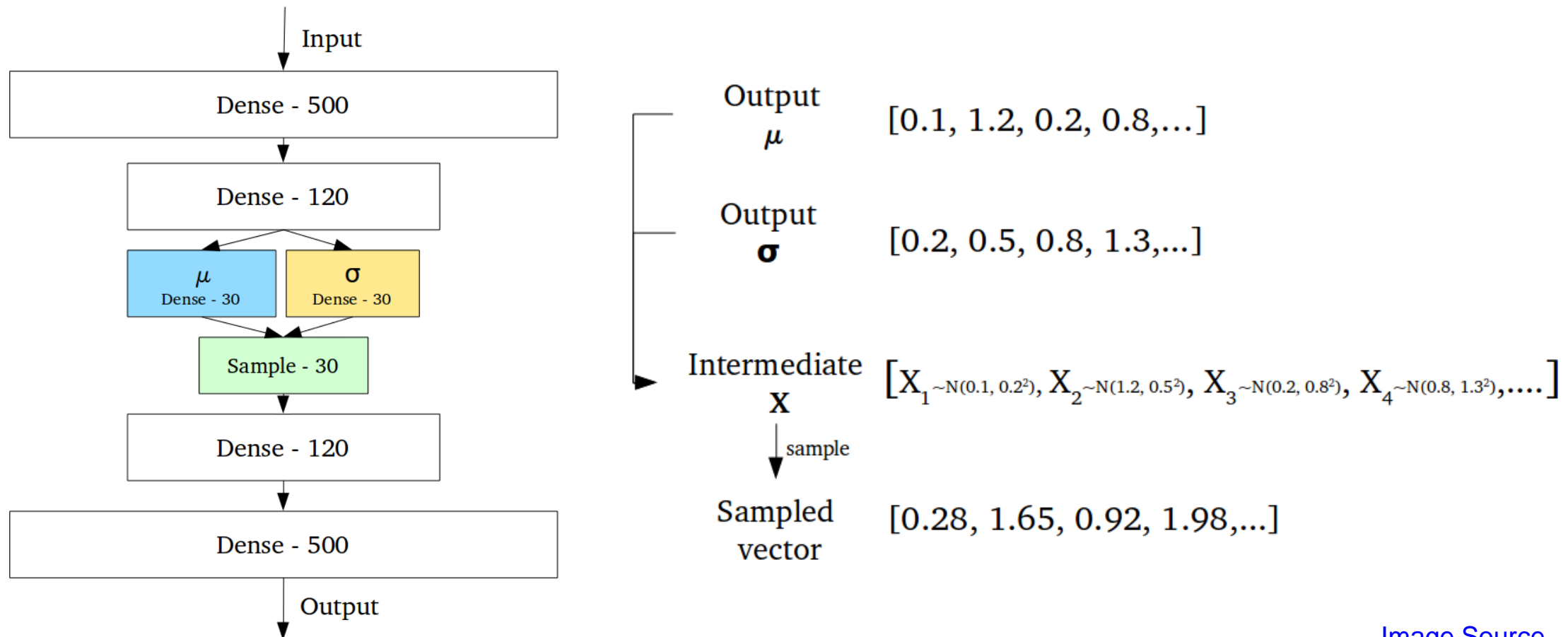
Standard Autoencoder
(direct encoding coordinates)



Variational Autoencoder
(μ and σ initialize a probability distribution)

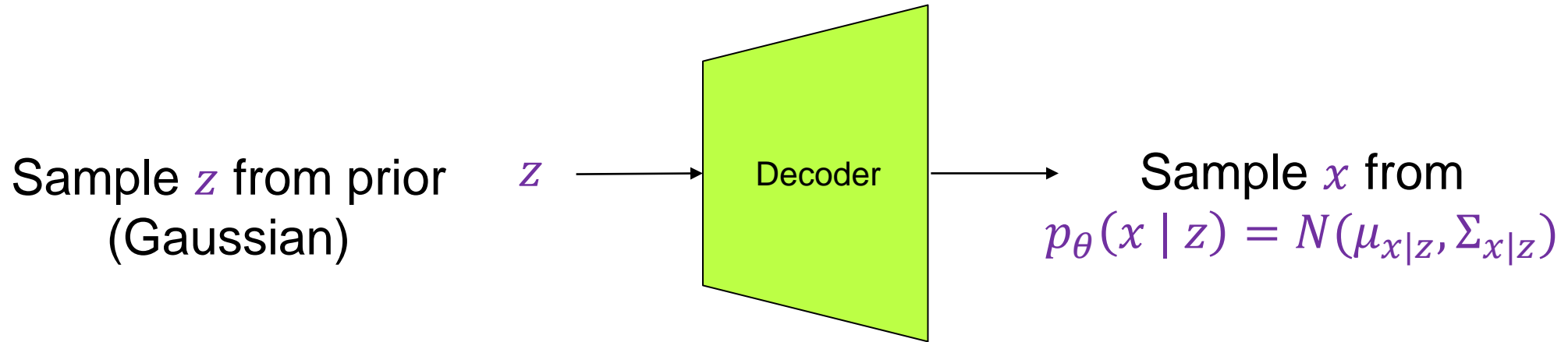
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Variational autoencoders: Overview

- At test time, discard encoder and use decoder to sample from $p_{\theta}(x | z) = N(\mu_{x|z}, \Sigma_{x|z})$



Variational autoencoders: Training

- Objective: maximize the *variational lower bound* on the data likelihood:

$$\log p_{\theta}(x) \geq \mathbb{E}_{z \sim q_{\phi}(z|x)} [\log p_{\theta}(x|z)] - D_{KL}(q_{\phi}(z|x), p(z))$$

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4. Run sampled z through decoder to get a distribution over data samples
5. Original input should be likely under the distribution output in (4)

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- Objective: maximize the *variational lower bound* on the data likelihood:

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Variational autoencoders: Training

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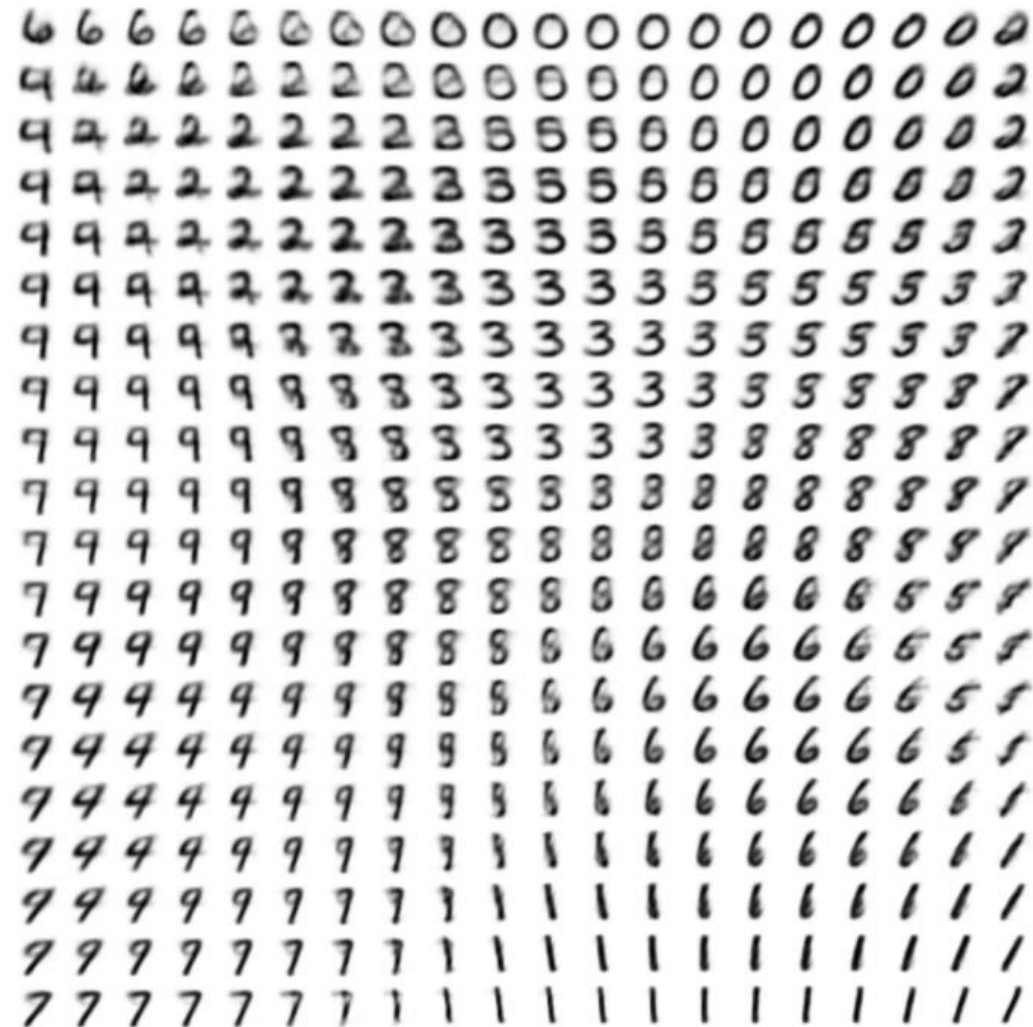
$$\log p_{\theta}(x) \geq \underbrace{\mathbb{E}_{z \sim q_{\phi}(z|x)} [\log p_{\theta}(x|z)]}_{\text{Data likelihood}} - \underbrace{D_{KL}(q_{\phi}(z|x), p(z))}_{\text{Regularization}}$$

- Objective for the entire dataset:

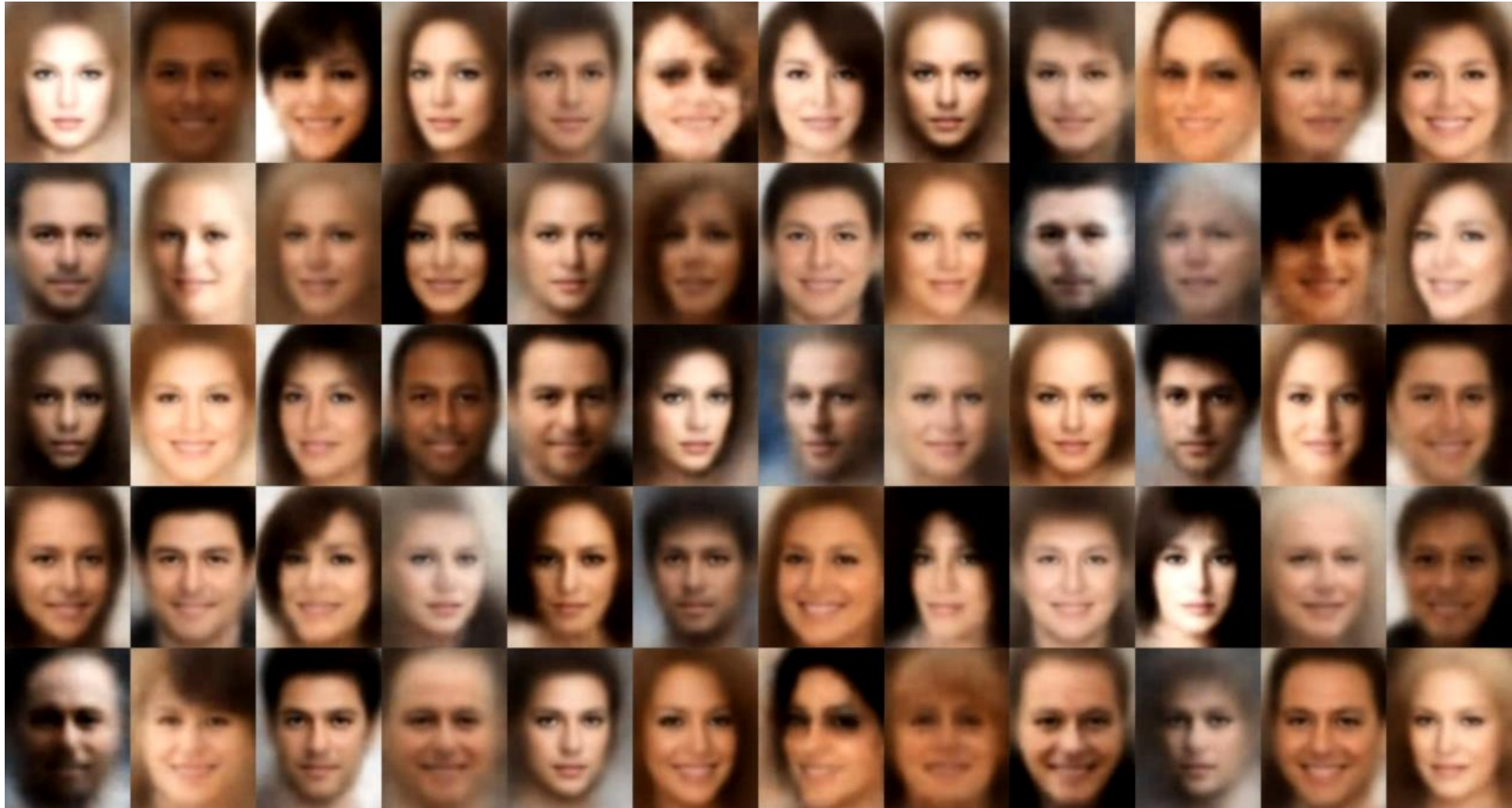
$$\mathbb{E}_{x \sim D} \left[\mathbb{E}_{z \sim q_{\phi}(z|x)} [\log p_{\theta}(x|z)] - D_{KL}(q_{\phi}(z|x), p(z)) \right]$$

Original results

- Learned 2D manifolds:



Variational autoencoders: Generating data

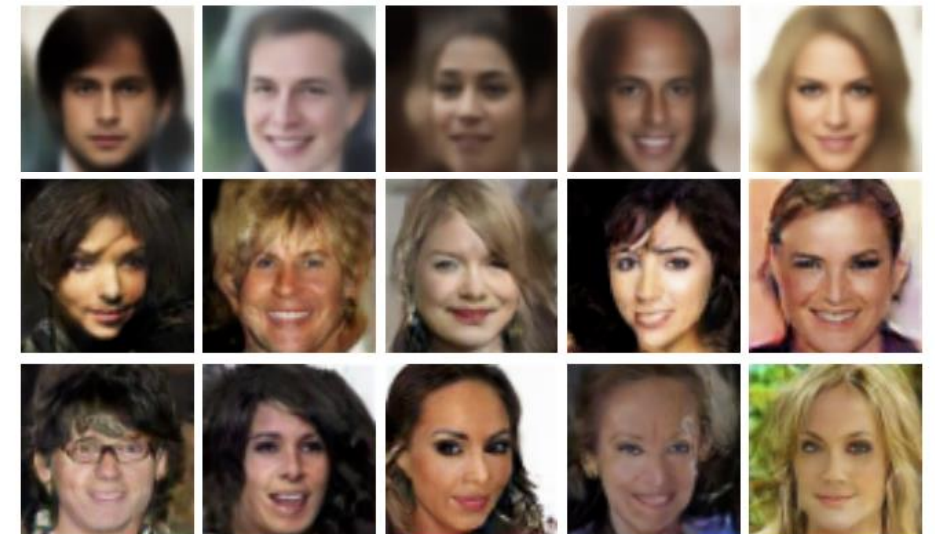
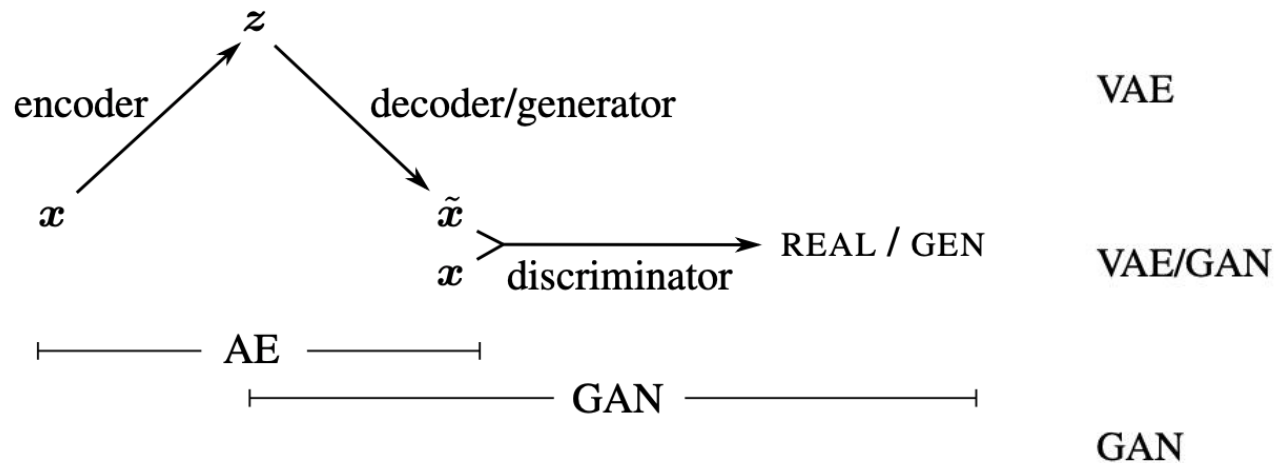


Basic VAE framework: Summary

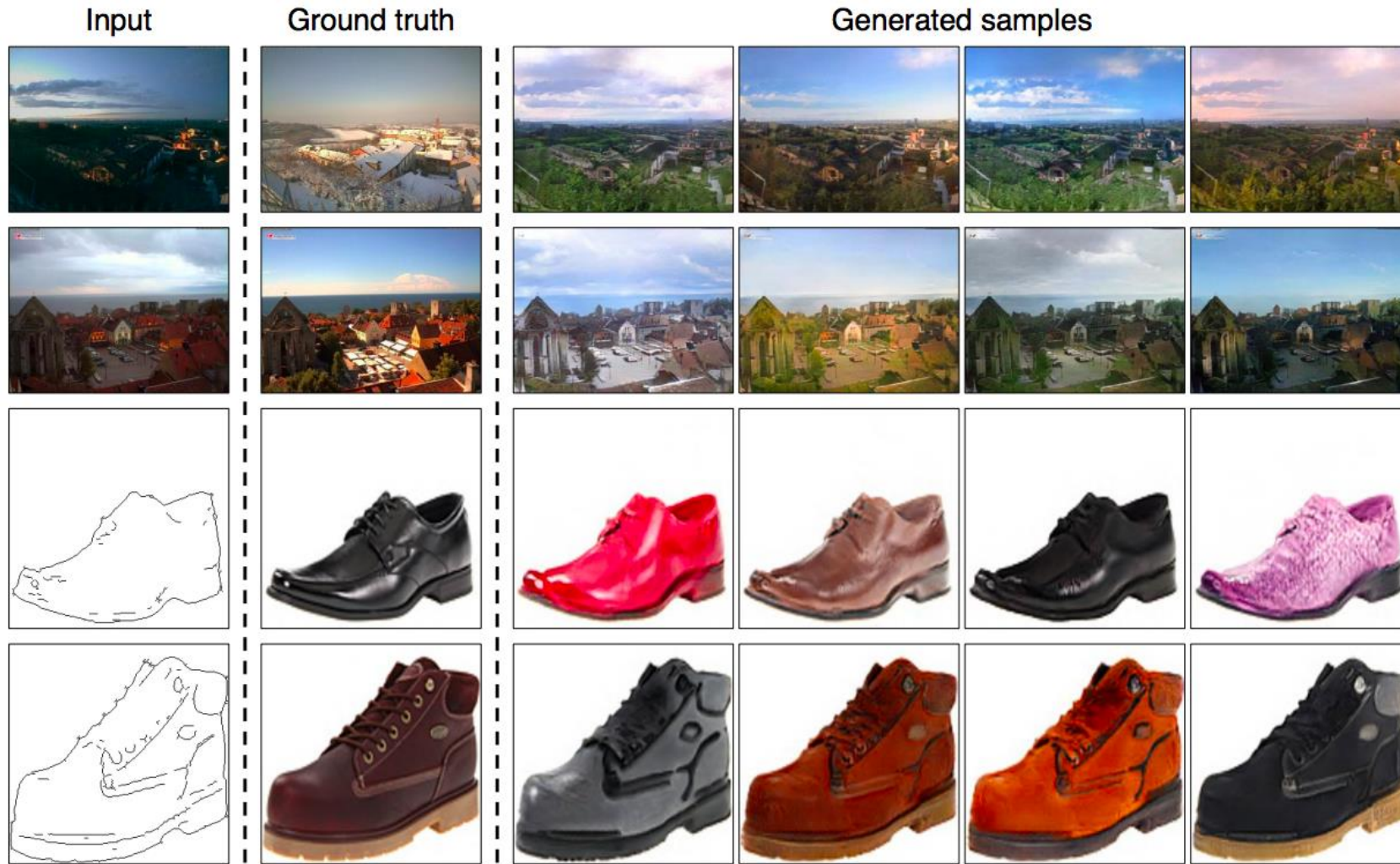
- Pros:
 - Principled mathematical formalism for generative models
 - Allows inference of code given image, can be useful for controlling the latent space
- Cons:
 - Samples blurrier and lower quality compared to GANs
- Active areas of research:
 - More powerful and flexible approximations for relevant probability distributions
 - Combining VAEs and GANs
 - Incorporating structure in latent variables, e.g., hierarchical or categorical distributions

Combining VAEs and GANs

- Define decoder probability model $p_{\theta}(x|z)$ not in terms of reconstruction errors in pixel space, but in terms of errors in discriminator feature space



Combining VAEs and GANs: BicycleGANs

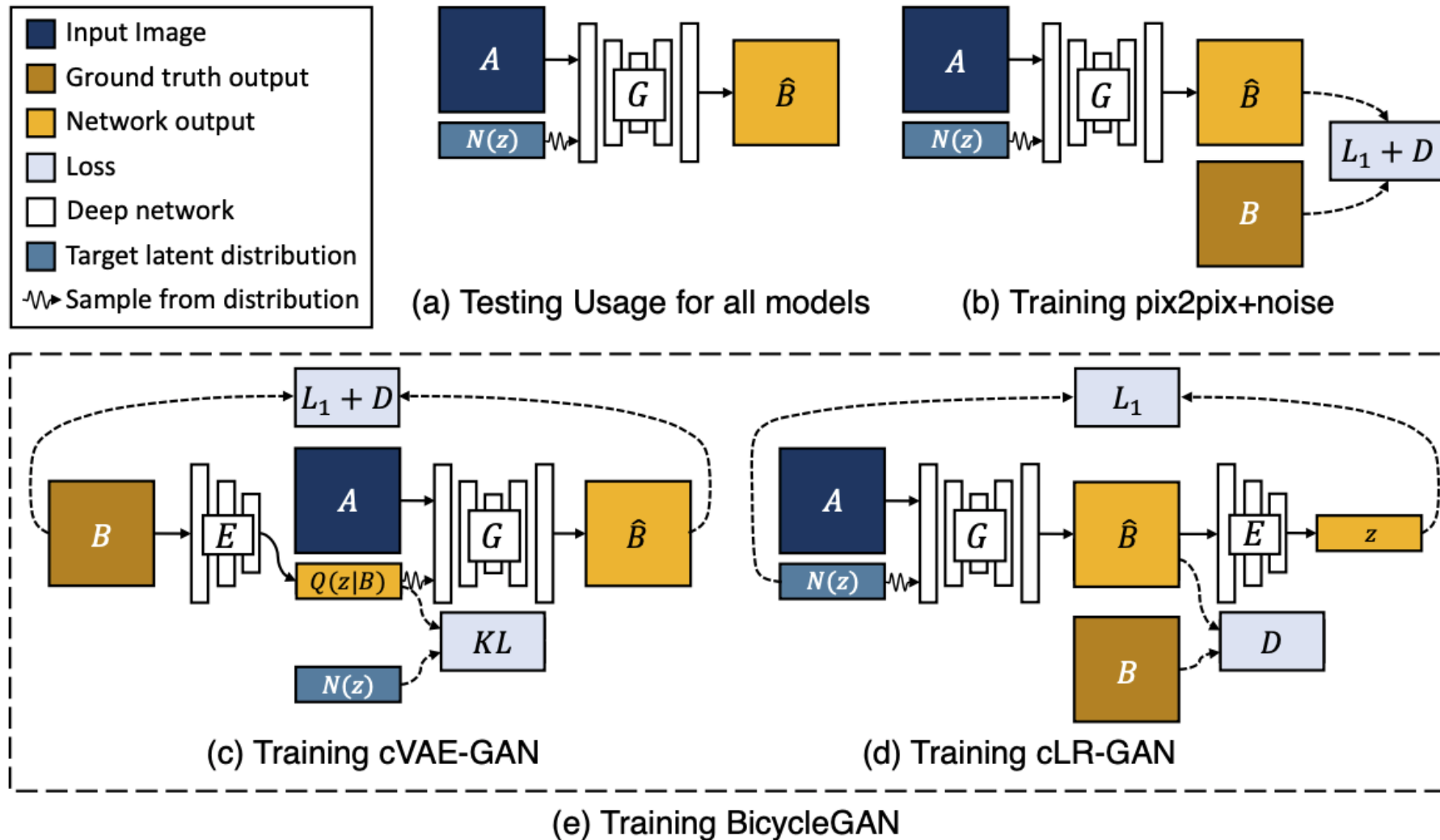


J.Y. Zhu, R. Zhang, D. Pathak, T. Darrell, A. A. Efros, O. Wang, E. Shechtman,
[Toward Multimodal Image-to-Image Translation](#), NIPS 2017

Combining VAEs and GANs: BicycleGANs

- Key ideas:
 - Image-to-image translation is a *one-to-many* problem. Need to model conditional distribution of output given input parametrized by z
 - To prevent mode collapse (or many-to-one mapping from z to output), need to encourage the mapping between output and latent code to be invertible
 - Propose BicycleGAN framework to simultaneously learn mappings in both directions

Combining VAEs and GANs: BicycleGANs

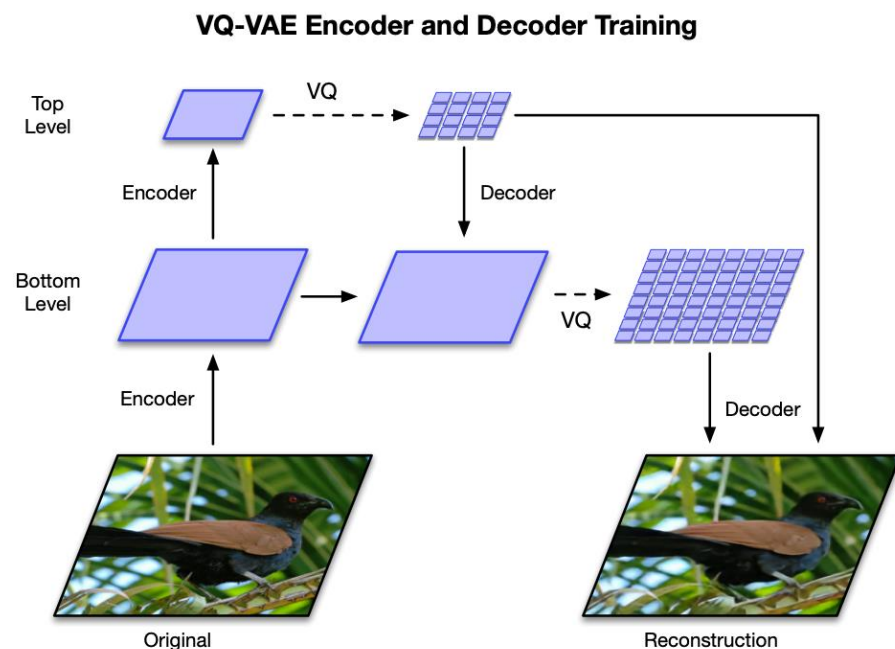


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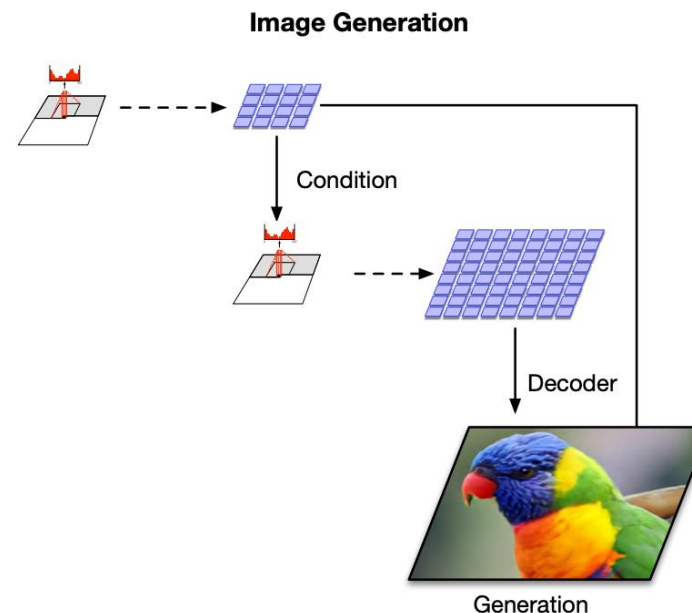
Generating better samples: VQ-VAE-2

- Combining VAE and autoregressive models:

Train a VAE-like model to generate multiscale grids of latent codes



Use a multiscale autoregressive model (PixelCNN) to sample in latent code space



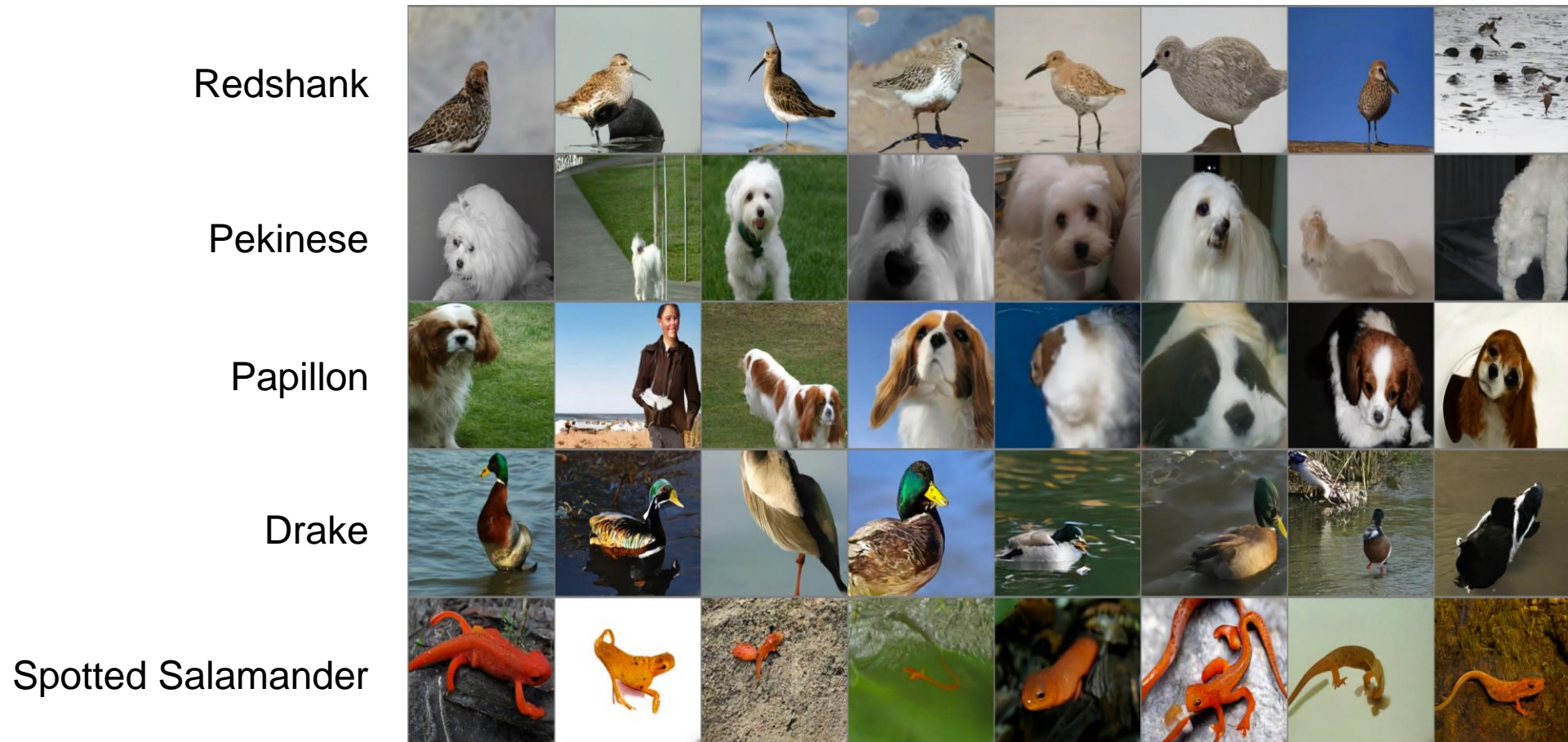
Generating better samples: VQ-VAE-2

- 256 x 256 class-conditional samples, trained on ImageNet:



Generating better samples: VQ-VAE-2

- 256 x 256 class-conditional samples, trained on ImageNet:



Generating better samples: VQ-VAE-2

- 1024 x 1024 generated faces, trained on FFHQ:



Generating better samples: Hierarchical VAE

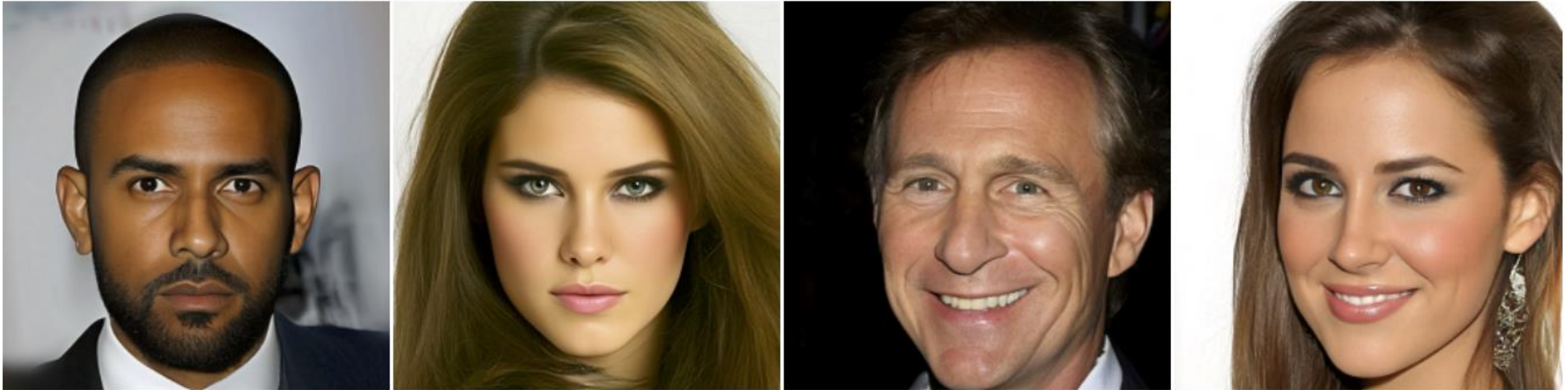


Figure 1: 256×256 -pixel samples generated by NVAE, trained on CelebA HQ [28].

Acknowledgement

Thanks to the following courses and corresponding researchers for making their teaching/research material online

- Deep Learning, Stanford University
- Introduction to Deep Learning, University of Illinois at Urbana-Champaign
- Introduction to Deep Learning, Carnegie Mellon University
- Convolutional Neural Networks for Visual Recognition, Stanford University
- Natural Language Processing with Deep Learning, Stanford University
- And Many More