



# Data Structure: **Review**

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# Complexity Review

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Any problem has some **input**.

Consider a set of all possible values for different input that makes the **sample space**:

- **Best Case**: Minimum complexity
- **Average Case**: Expected value over the sample space by considering the probability distribution over inputs.  $E(X) = \sum x_i P(x_i)$
- **Worst case**: Maximum complexity

For **randomized algorithm** the algorithm makes random variable itself.

- **Expected running time**: expected value over the random variable generated by the algorithm
- **Amortized Analysis**: A sequence of operations
  - Aggregate, Accounting method

# Asymptotic notations

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$$f(n) = O(g(n)) \rightarrow \exists n_0, c_0 \text{ such that for } n > n_0 \quad f(n) \leq c_0 g(n)$$

$$f(n) = \Omega(g(n)) \rightarrow \exists n_0, c_0 \text{ such that for } n > n_0 \quad f(n) \geq c_0 g(n)$$

$$f(n) = \Theta(g(n)) \rightarrow \exists n_0, c_1, c_2 \text{ such that for } n > n_0 \quad c_1 g(n) \leq f(n) \leq c_2 g(n)$$

## Order of growth of some common functions

$$O(1) < O(\log^* n) < O(\log n) < O(\sqrt{n}) < O(n) < O(n \log n) < O(n^2) < O(n^3) < O(2^n)$$

## Examples:

$$10n^2 + 3 = O(n^2) = O(n^3)$$

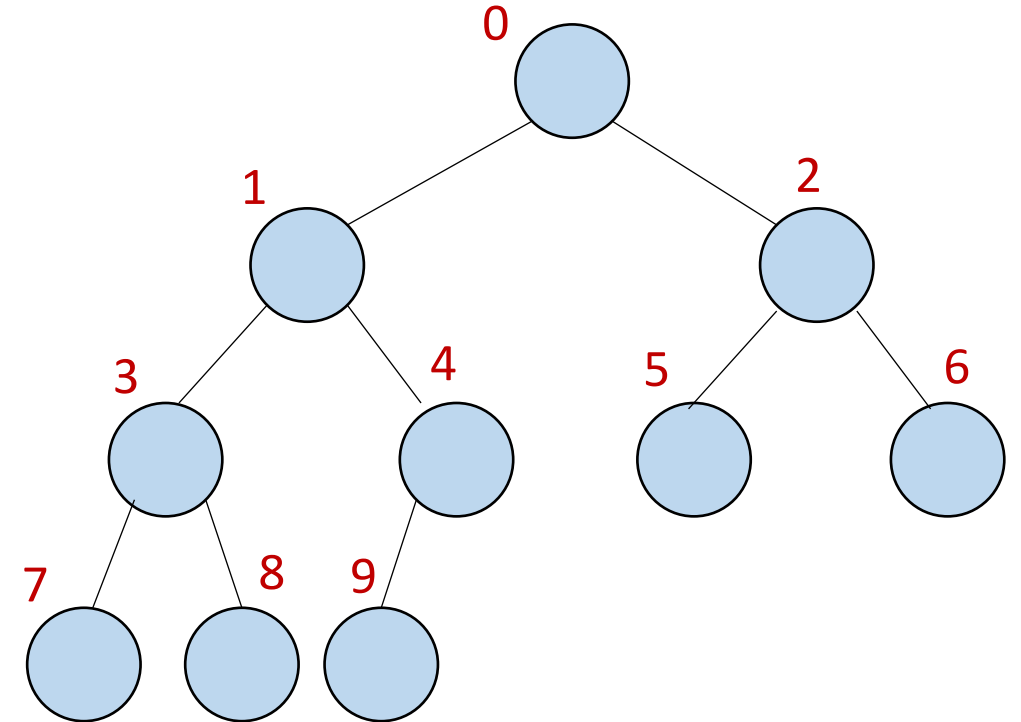
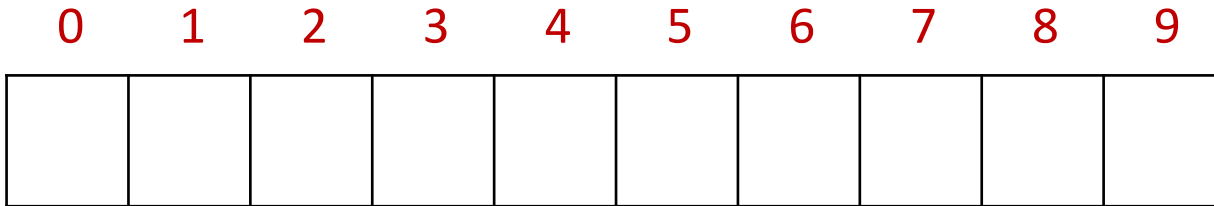
$$10n^2 + 3 = \Omega(n^2) = \Omega(n) = \Omega(1)$$

$$40n^2 + 10n \log 5n + 100\sqrt{n} \log n + 5n + 200 = \Theta(n^2)$$

# Priority Queues: Heaps

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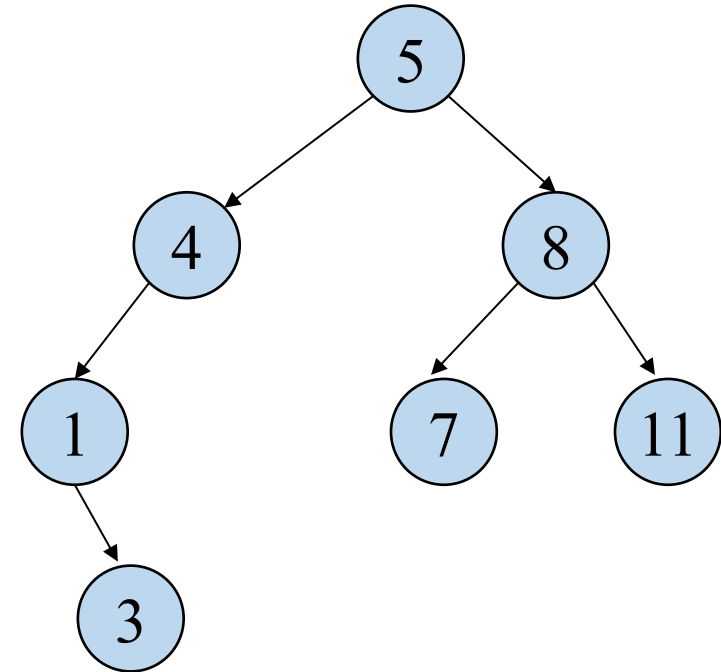
- Data structure: an **array** that represents a **full tree**
- Extract-Max, Insert, Delete:  $O(\log n)$
- Decrease key:  $O(\log n)$
- Build max-heap:  $O(n)$



# Dictionaries: BSTs

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- **Data structure:** a **linked structure** that represents a **tree** which is not always full or balanced

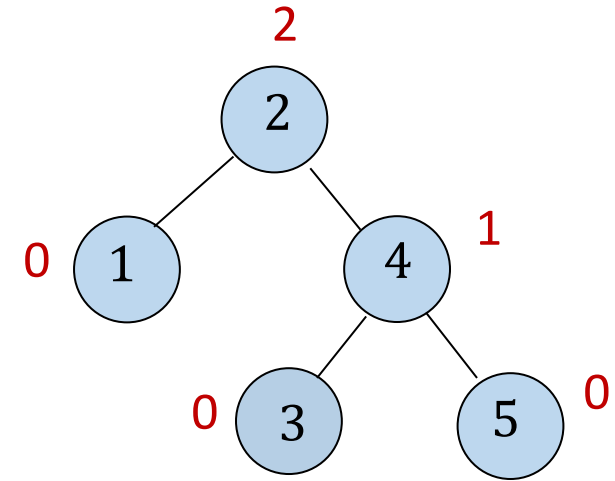


- **Successor and predecessor**  $O(h) = O(n)$
- **Insert, Search, Delete:**  $O(h) = O(n)$

# Balanced Trees, BST Augmentation

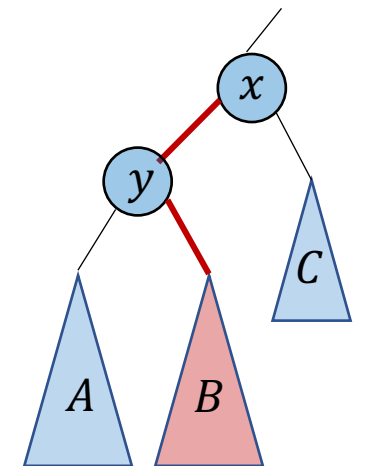
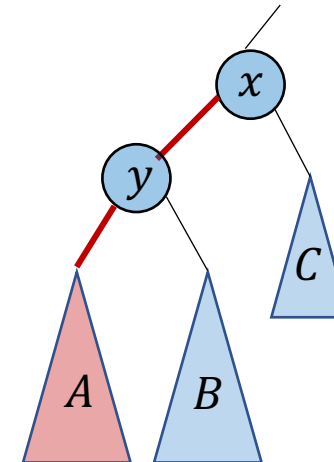
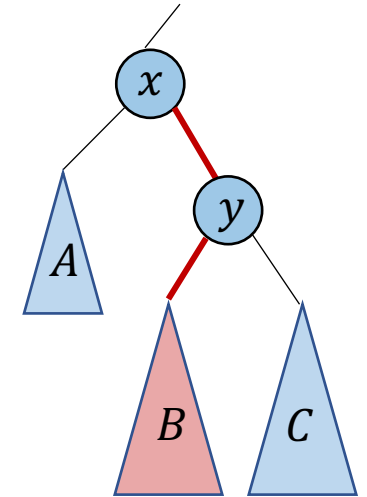
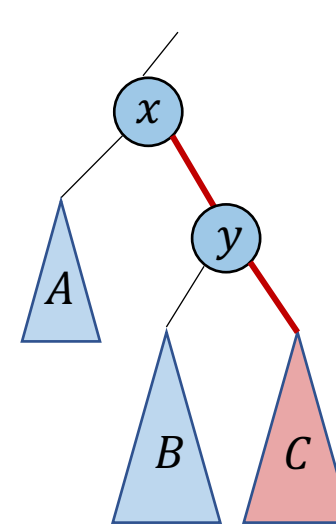
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- **AVL trees:** For all the nodes the difference between the height of left and right subtree is at most 1.
- Successor and predecessor  $O(\log n)$
- Insert, Search, Delete:  $O(\log n)$
- For each insert or delete  
at most **2 rotations**
- Each rotation:  $O(1)$



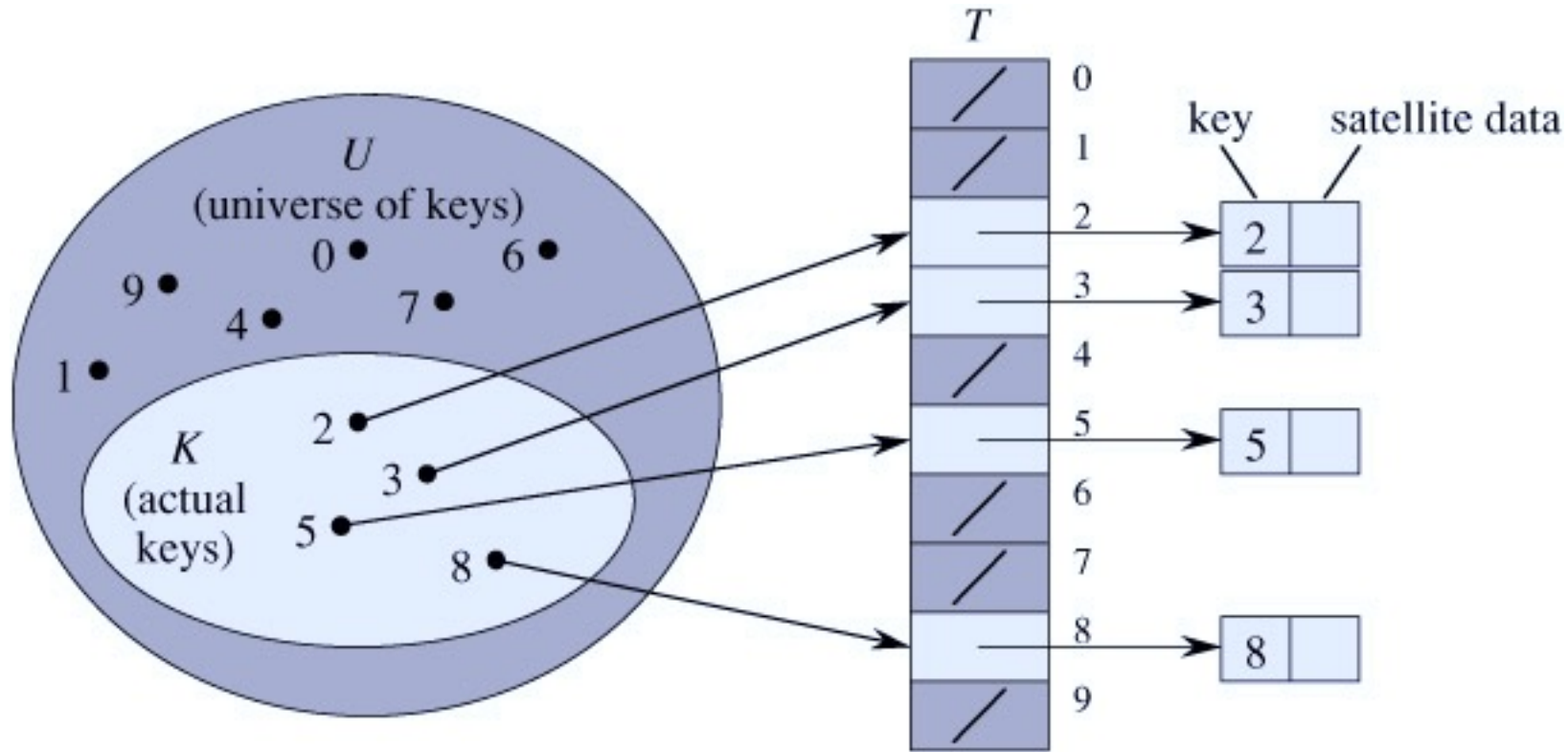
# AVL-rebalancing

- Lowest unbalanced node:
  - **Right** heavy, right child: **right** heavy:  
single **left** rotation
  - **Right** heavy, right child: **left** heavy (Zig zag):  
double **right-left** rotation
- The other case is symmetric



# Hashing

- Direct access table

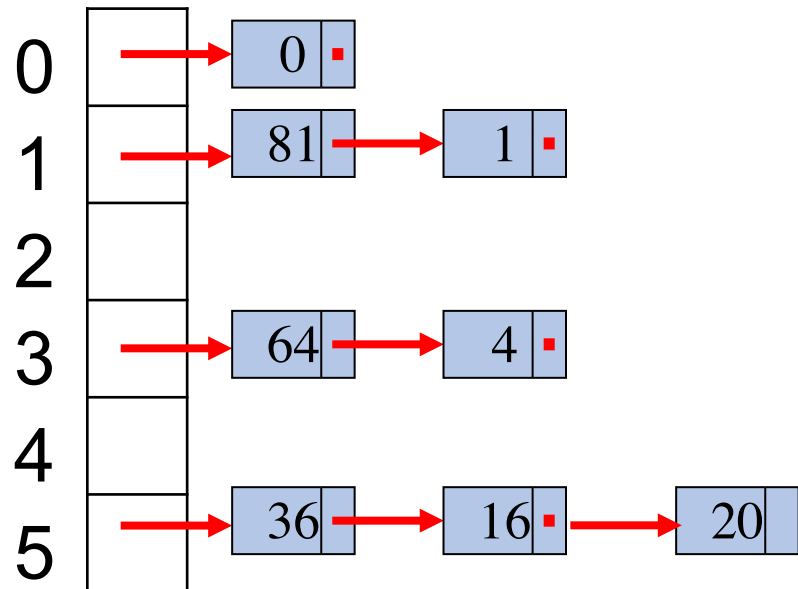




# Hashing

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- Hash function maps a key to a value
- Collision handling
  - Chaining



- Open addressing
  - Linear probing
$$h(k, i) = (h'(k) + i) \bmod m$$
  - Quadratic probing
$$h(k, i) = (h'(k) + c_1 i + c_2 i^2) \bmod m$$
  - Double hashing
$$h(k, i) = (h_1(k) + i h_2(k)) \bmod m$$

# Quicksort

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- Running time
  - Worst case:  $\Theta(n^2)$
  - Average case for randomized version:  $\Theta(n \log n)$
  - Best case:  $\Theta(n \log n)$

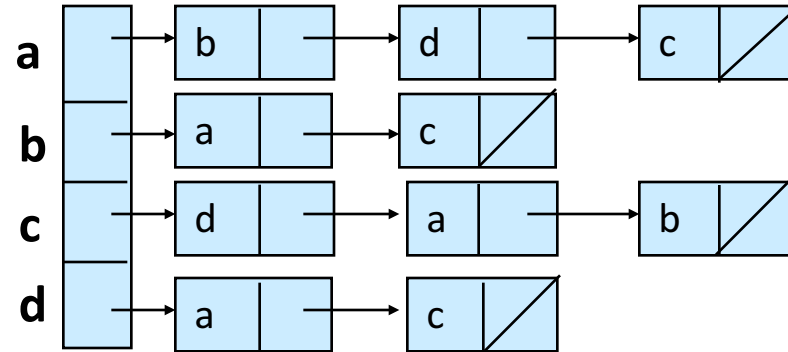
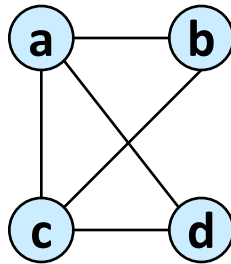
# Graphs

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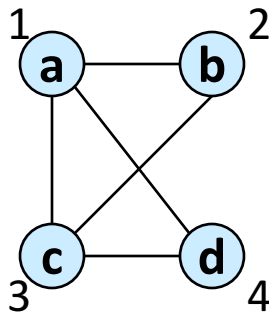
- Types of graphs
  - **Undirected:** edge  $(u, v) = (v, u)$ ; for all  $v, (v, v) \notin E$  (No self loops)
  - **Directed:**  $(u, v)$  is edge from  $u$  to  $v$ , denoted as  $u \rightarrow v$ . Self loops are allowed.
  - **Weighted:** each edge has an associated weight
- If  $G$  is **connected**:
  - There is a path between every pair of vertices.
  - $E \geq V - 1$ .
  - Furthermore, if  $E = V - 1$ , then  $G$  is a tree.
- $E = O(V^2)$

# Graphs: representation

- Adjacency Lists.



- Adjacency Matrix.



	1	2	3	4
1	0	1	1	1
2	1	0	1	0
3	1	1	0	1
4	1	0	1	0

# Graph Traverse: BFS, DFS

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- To traverse means to visit the vertices in some systematic order.
- You should be familiar with various traversal methods for binary trees:
  - **preorder**: visit each node before its children.
  - **postorder**: visit each node after its children.
  - **inorder** (for binary trees only): visit left subtree, node, right subtree
- **BFS**:
  - Traverse a connected component graph and find the **shortest path** from the source to all nodes.
  - If the graph is not connected or is directed, does not traverse all the nodes
- **DFS**
  - Could traverse all the nodes even if not connected or directed.

**BFS** and **DFS**  $\Theta(V + E)$  using the adjacency list.

# Edge classification by DFS and BFS

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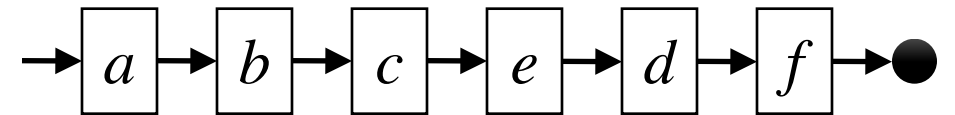
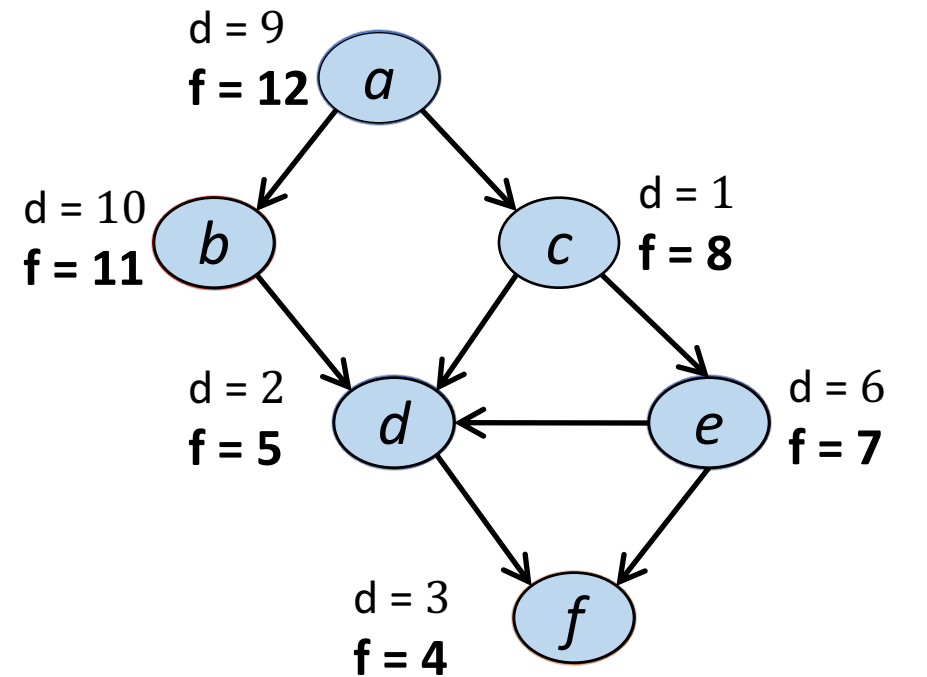
	Directed Graph	Undirected Graph
DFS	all	tree , back
BFS	tree, back, cross	tree, cross

a directed graph  $G$  is acyclic iff DFS on  $G$  yields no **Back** edges

# Topological sort

- Is it possible to execute all the tasks in  $G$  in an order that respects all the precedence requirements given by the graph edges?
- The answer is "yes" *if and only if* the directed graph  $G$  has **no cycle**.

Such a  $G$  is called a Directed Acyclic Graph, or just a **DAG**.



# Minimum Spanning Trees

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- Cut, cross edge, light edge
  - **Idea**: start with an empty set of edges and add light edges to MST
  - 1. **Prim's Algorithm**: Using minheap  $O(E \log V)$
  - 2. **Kruskal's algorithm**: Using disjoint forest  $O(E \log V)$
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- The lightest edge is always in MST.
  - The heaviest edge is not always in MST.
  - In general there might be more than one MST.
  - If the weights are distinct there is a unique MST.



# Disjoint Sets

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- Link list Implementation

1. Make-Set(x):  $\Theta(1)$
2. Find-Set(x):  $\Theta(1)$
3. Union(x,y):  $\Theta(n)$

Total time  $m$  operations:  $\Theta(m+n^2)$

Heuristics:

Union by weight:

Union(x,y):  $O(\log n)$  Amortized cost  
 $O(m + n \log n)$

- Disjoint forest Implementation

1. Make-Set(x):  $\Theta(1)$
2. Find-Set(x):  $\Theta(n)$
3. Union(x,y):  $\Theta(n)$

Heuristics:

Union by ranks:

Find-Set(x):  $O(\log n)$     Union(x,y):  $O(\log n)$

Union by ranks and Path Compression:

Total time  $m$  operations:  $\Theta(m \log^* n)$

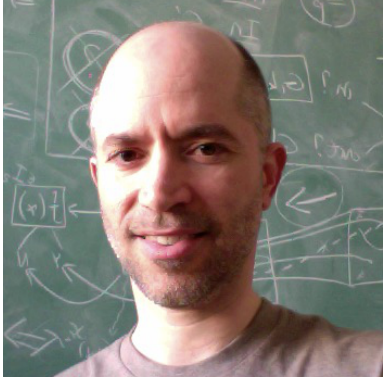
# Lower Bounds

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- For problem  $P$ ,  $C(P)$  = best (minimum) worst-case running time of **any algorithm** that solves  $P$ .
- Techniques:
  - ✓ Information theory lower bounds
  - ✓ Adversary arguments
  - ✓ Reductions
- Finding the **minimum** in a set of  $n$  element cannot be better than  $\Theta(n)$ .
- **Searching** in a sorted list cannot be better than  $\Theta(\log n)$ .
- Comparison **sort** cannot be better than  $\Theta(n \log n)$ .
- **Extract-max** cannot be better than  $\Theta(\log n)$ .

# Acknowledgements

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**François Pitt**



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## TAs

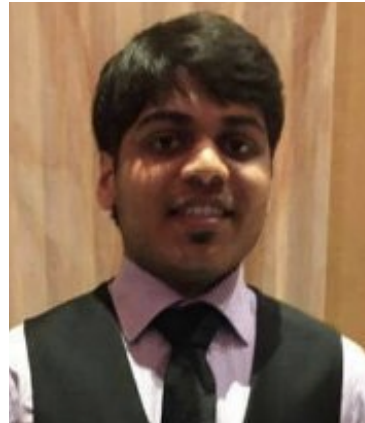
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**Robin Swanson**



**Sasa Milic**



**Roleen Nunes**

- Tristan Aumentado-Armstrong
- Ruowei Jiang
- Morgan Shirley
- Ziqiao Meng
- Mohammad Amin Beiruti

# Good luck 😊

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- Final exam
- Internship and job Interviews
- Developing excellent software in your Start-up
- Impressing your boss