

Step 0: Recursive structure.

Consider an arbitrary optimum solution $s_1 \cdots s_{p_\ell} / s_{p_\ell+1} \cdots s_m$ (for some $1 \leq \ell \leq k$). Then breaks $p_1, \dots, p_{\ell-1}$ must be performed in some optimum order on $s_1 \cdots s_{p_\ell}$ and breaks $p_{\ell+1}, \dots, p_k$ must be performed in some optimum order on $s_{p_\ell+1} \cdots s_m$ —otherwise we would get a better overall solution.

Step 1: Array definition.

Let $T[i, j]$ be the minimum time to perform all the breaks on substring $s_{p_i+1} \cdots s_{p_j}$, for $0 \leq i < j \leq k+1$ (where we set $p_0 = 0$ and $p_{k+1} = m$).

Step 2: Recurrence relation.

- $T[i, i+1] = 0$ for $0 \leq i \leq k$ (no break in between positions p_i and p_{i+1}).
- $T[i, j] = \min_{\ell=i+1}^{j-1} \{(p_j - p_i + 1) + T[i, \ell] + T[\ell, j]\}$ for $0 \leq i < j-1 \leq k$ (by the reasoning in Step 0, where $p_j - p_i + 1$ is the cost for the break at p_ℓ).

Step 3: Iterative algorithm.

Compute values for decreasing i to ensure smaller subproblems solved first.

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for  $i \leftarrow k, k-1, \dots, 0$ :
     $T[i, i+1] \leftarrow 0$ 
    for  $j \leftarrow i+2, i+3, \dots, k+1$ :
         $T[i, j] \leftarrow \infty$ 
        for  $\ell \leftarrow i+1, i+2, \dots, j-1$ :
             $t \leftarrow T[i, \ell] + T[\ell, j] + p_j - p_i + 1$ 
            if  $t < T[i, j]$ :
                 $T[i, j] \leftarrow t$ 

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Step 4: Solution reconstruction.

Use second array $U[i, j]$ to record value of ℓ that makes $T[i, j] = T[i, \ell] + T[\ell, j] + p_j - p_i + 1$, then recursively build break order using values of U .

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MINCOST( $p_0 = 0, p_1, \dots, p_k, p_{k+1} = m$ ):
    for  $i \leftarrow k, k-1, \dots, 0$ :
         $T[i, i+1] \leftarrow 0$ ;  $U[i, i+1] \leftarrow 0$ 
        for  $j \leftarrow i+2, i+3, \dots, k+1$ :
             $T[i, j] \leftarrow \infty$ ;  $U[i, j] \leftarrow 0$ 
            for  $\ell \leftarrow i+1, i+2, \dots, j-1$ :
                 $t \leftarrow T[i, \ell] + T[\ell, j] + p_j - p_i + 1$ 
                if  $t < T[i, j]$ :
                     $T[i, j] \leftarrow t$ ;  $U[i, j] \leftarrow \ell$ 
    return BREAKORDER( $U, 0, k+1$ )

BREAKORDER( $U, i, j$ ):
    if  $U[i, j] = 0$ :
        return []
    else:
        return [ $U[i, j]$ ] + BREAKORDER( $U, i, U[i, j]$ ) + BREAKORDER( $U, U[i, j], j$ )

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Total running time is $\Theta(k^3 + k) = \Theta(k^3)$.