

84049264

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| meshcat_visualizer | |
| lcm_visualization | |

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|--|-------------------|
| drake/geometry/SceneGraph@0000000004ce4230 | |
| Source_138_pose | lcm_visualization |
| | query |

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|---|------------------------------------|
| drake/multibody/MultibodyPlant@00000000049a72c0 | |
| geometry_query | geometry_pose |
| | continuous_state |
| acrobot_actuation | acrobot_continuous_state |
| | acrobot_generalized_contact_forces |
| | contact_results |

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|---|--------|
| drake/pydrake/(anonymous)/Impl@0000000004e08750 | |
| NN_in | NN_out |

