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meshcat_visualizer	
lcm_visualization	

drake/geometry/SceneGraph@0000000003e21530	
Source_84_pose	lcm_visualization
	query

drake/multibody/MultibodyPlant@00000000037f1b70	
geometry_query	geometry_pose
	continuous_state
acrobot_actuation	acrobot_continuous_state
	acrobot_generalized_contact_forces
	contact_results

drake/pydrake/(anonymous)/Impl@0000000003c48b70	
NN_in	NN_out

