

# 1 Stochastic Optimization

We are interested in constrained minimization of  $f : \mathbb{R}^n \rightarrow \mathbb{R}$

$$\text{minimize}_{x \in \mathcal{X}} [f(x) = \mathbb{E}[F(x, \xi)]]$$

where  $\mathcal{X} \subset \mathbb{R}^n$  is closed, bounded convex set.  $\xi$  is a random variable, and  $F(\cdot, \xi)$  is convex for all  $\xi \in \Xi$ , and therefore  $f(\cdot)$  is convex. For uniform  $p_\xi$  over finite alphabets of size  $n$ , the problem reduces to finite sum problem

$$\text{minimize}_{x \in \mathcal{X}} \left[ f(x) = \frac{1}{n} \sum_{i=1}^n f_i(x) \right]$$

Assume we can

1. Sample  $\xi_1, \xi_2, \dots \stackrel{i.i.d.}{\sim} p_\xi$
2. Given  $(x, \xi) \in \mathcal{X} \times \Xi$ , a first order oracle that returns a subgradient vector  $G(x, \xi) \in \partial_x F(x, \xi)$ . We also assume that  $G$  is unbiased, i.e.  $g(x) := \mathbb{E}[G(x, \xi)] \in \partial f(x)$

## 1.1 Stochastic Gradient Method

We can show that if  $f \in \mathcal{S}_{L, \mu}^1$ , the choice of  $\alpha_k = \mathcal{O}(1/k)$  yields sublinear convergence of  $\mathcal{O}(\frac{1}{\epsilon})$  for last iterates. If  $f \in \mathcal{F}_L^1$ , the choice of  $\alpha_k = \mathcal{O}(\frac{1}{\sqrt{k}})$  yields a sublinear convergence of  $\mathcal{O}(\frac{1}{\epsilon^2})$  for average iterates. Stochastic gradient method (or Stochastic Approximation (SA) algorithms) solves the problem by

$$x^{k+1} = \mathcal{P}_{\mathcal{X}} \left( x^k - \alpha_k G(x^k, \xi_k) \right)$$

where  $\alpha_k > 0$  are stepsizes,  $\mathcal{P}_{\mathcal{X}}(y) = \arg \min_{x \in \mathcal{X}} \frac{1}{2} \|x - y\|_2^2$  is the euclidean projection onto a convex set. It is important to note that the current iterate  $x^k$  are functions of random variables  $x^k := x^k(\xi_{[k-1]})$  where  $\xi_{[k-1]} = (\xi_1, \dots, \xi_{k-1})$ , and therefore are random variables themselves. In addition,  $x^k \perp \xi_k$ .

## 1.2 Convergence

Derivations copied from [7], [8] and slides. We assume

1. bounded variance for stochastic subgradient, which translates to  $\mathbb{E}_\xi [G(x, \xi)] \leq M^2$  given  $x \in \mathcal{X}$ .
2. bounded  $\mathcal{X}$  where radius given by  $D_{\mathcal{X}} = \max_{x \in \mathcal{X}} \|x - x^*\|_2$ .

We outline implications of some assumptions

1. If  $f$  is convex, then

$$f(x') \geq f(x) + \langle g(x), x' - x \rangle \quad \forall x, x' \in \mathcal{X} \quad (1)$$

2. If  $f$  has  $L$  lipschitz continuous gradients, then

$$\begin{aligned} \|\nabla f(x') - \nabla f(x)\| &\leq L \|x' - x\| & \forall x, x' \in \mathcal{X} \\ f(x) - f(x^*) &\leq \frac{1}{2} L \|x - x^*\|^2 & \forall x \in \mathcal{X} \end{aligned} \quad (2)$$

(descent lemma)

3. If  $f$  is  $\mu$ -strongly convex, then

$$\langle \nabla f(x') - \nabla f(x), x' - x \rangle \geq \mu \|x' - x\|_2^2 \quad \forall x \in \mathcal{X} \quad (3)$$

$$\mu \|x - x^*\|^2 \leq \mu \langle g(x) - g(x^*), x - x^* \rangle = \langle g(x), x - x^* \rangle \quad \forall x \in \mathcal{X}, g(x) \in \partial f(x) \quad (4)$$

We first derive some preliminary results. Using iterated expectation, we have

$$\begin{aligned} \mathbb{E} \left[ \langle G(x^k, \xi_k), x^k - x^* \rangle \right] &= \mathbb{E}_{\xi_{[k-1]}} \left[ \mathbb{E}_{\xi_k} \left[ \langle G(x^k(\xi_{[k-1]}), \xi_k), x^k(\xi_{[k-1]}) - x^* \rangle \mid \xi_{[k-1]} \right] \right] \\ &= \mathbb{E}_{\xi_{[k-1]}} \left[ \langle \mathbb{E}_{\xi_k} [G(x^k(\xi_{[k-1]}), \xi_k) \mid \xi_{[k-1]}], x^k(\xi_{[k-1]}) - x^* \rangle \right] \\ &= \mathbb{E} \left[ \langle g(x^k), x^k - x^* \rangle \right] \end{aligned} \quad (5)$$

where the expectation is taken w.r.t  $\xi_{[k-1]}$ . We first derive a bound on  $R_k = \|x^k - x^*\|_2^2$  and  $r_k = \mathbb{E}[R_k]$ ,

$$\begin{aligned} R_{k+1} &= \|x^k - x^*\|^2 \\ &= \left\| \mathcal{P}_{\mathcal{X}} \left( x^k - \alpha_k G(x^k, \xi_k) \right) - \mathcal{P}_{\mathcal{X}}(x^*) \right\| \quad (\mathcal{P}_{\mathcal{X}}(x^*) = x^*) \\ &\leq \left\| x^k - \alpha_k G(x^k, \xi_k) - x^* \right\|^2 \quad (\text{nonexpansive of } \mathcal{P}(\cdot) \text{ } \|\mathcal{P}_{\mathcal{X}}(x') - \mathcal{P}_{\mathcal{X}}(x)\| \leq \|x' - x\|) \\ &\leq R^k - 2\alpha_k \langle G(x^k, \xi_k), x^k - x^* \rangle + \alpha_k^2 \|G(x^k, \xi_k)\|^2 \\ r_{k+1} &\leq r_k - 2\alpha_k \mathbb{E} \left[ \langle G(x^k, \xi_k), x^k - x^* \rangle \right] + \alpha_k^2 \mathbb{E} \left[ \|G(x^k, \xi_k)\|^2 \right] \quad (\text{Take expectation w.r.t. } \xi_{[k]}) \\ &= r_k - 2\alpha_k \mathbb{E} \left[ \langle g(x^k), x^k - x^* \rangle \right] + \alpha_k^2 M^2 \quad (\text{By (5) and bounded variance}) \end{aligned}$$

### 1.2.1 Strongly Convex Case

If  $f \in \mathcal{S}_{L,\mu}^1$ , using (4), we have

$$r_{k+1} \leq r_k - 2\alpha_k \mathbb{E} \left[ \|x^k - x^*\|^2 \right] + \alpha_k^2 M^2 = (1 - 2\mu\alpha_k)r_k + \alpha_k^2 M^2$$

If we choose  $\alpha_k = \theta/(k+1)$ , where  $\theta > 1/(2\mu)$ . It could be shown by induction that [7]

$$r_k \leq \frac{c_\theta}{k+1} \quad \text{where} \quad c_\theta = \max \left\{ \frac{2\theta^2 M^2}{2\mu\theta - 1}, r_0 \right\}$$

By (descent lemma), we derive bound on the objective value

$$\mathbb{E} [f(x^k) - f(x^*)] \leq \frac{1}{2} L \mathbb{E} \left[ \|x^k - x^*\|^2 \right] \leq \frac{Lc_\theta}{2(k+1)}$$

Therefore, the choice of  $\alpha_k = \mathcal{O}(\frac{1}{\epsilon})$  yields last iterate convergence rate of  $\mathcal{O}(\frac{1}{\epsilon})$

### 1.2.2 Convex Case

[7] indicates that we need to increase the stepsize ( $\mathcal{O}(\frac{1}{k})$  to  $\mathcal{O}(\frac{1}{\sqrt{k}})$ ) to ensure faster convergence rate for general convex problems, at the cost of *more noisy* trajectory. To suppress the noise, we use average iterates  $\{x^k\}$  rather than last iterates as solution to the problem.

$$\begin{aligned}
r_{k+1} &\leq r_k - 2\alpha_k \mathbb{E} \left[ \left\langle g(x^k), x^k - x^* \right\rangle \right] + \alpha_k^2 M^2 \\
2\alpha_k \mathbb{E} \left[ f(x^k) - f(x^*) \right] &\leq 2\alpha_k \mathbb{E} \left[ \left\langle g(x^k), x^k - x^* \right\rangle \right] \leq r_k - r_{k+1} + \alpha_k^2 M^2 \quad (\text{Rearrange, and by 1}) \\
\sum_{i=1}^k (2\alpha_i \mathbb{E} [f(x^i) - f(x^*)]) &\leq \sum_{i=1}^k (r_i - r_{i+1} + \alpha_i M^2) = r_1 + \sum_{i=1}^k \alpha_i^2 \quad (\text{Telescope}) \\
\sum_{i=1}^k \gamma_i \mathbb{E} [f(x^i) - f(x^*)] &= \mathbb{E} \left[ \sum_{i=1}^k \gamma_i (f(x^i) - f(x^*)) \right] \leq \frac{r_1 + M^2 \sum_{i=1}^k \alpha_i^2}{2 \sum_{i=1}^k \alpha_i} \\
&\quad (\text{Let } \gamma_i = \alpha_i / \sum_i \alpha_i. \text{ Divide by } 2 \sum_i \alpha_i. \text{ Use linearity of expectation}) \\
\mathbb{E} [f(\tilde{x}^k) - f(x^*)] &\leq \frac{r_1 + M^2 \sum_{i=1}^k \alpha_i^2}{2 \sum_{i=1}^k \alpha_i} \\
&\quad (\text{Let } \tilde{x}^k = \sum_{i=1}^k \gamma_i x^i. \text{ } f(\tilde{x}^k) \leq \sum_i \gamma_i f(x^i) \text{ by convexity of } f. \sum_i \gamma_i = 1)
\end{aligned}$$

We derive tightest bound by finding minimal value of  $\alpha_k = \alpha$  of the bound.

$$\mathbb{E} [f(\tilde{x}^k) - f(x^*)] \leq \frac{D_{\mathcal{X}} M}{\sqrt{k}} \quad \alpha_k = D_{\mathcal{X}} / (M\sqrt{k})$$

Therefore, the choice of  $\alpha_k = \mathcal{O}(\frac{1}{\sqrt{k}})$  yields average iterate convergence rate of  $\mathcal{O}(\frac{1}{\sqrt{k}})$