

1 Stochastic Optimization

We are interested in constrained minimization of $f : \mathbb{R}^n \rightarrow \mathbb{R}$

$$\text{minimize}_{x \in \mathcal{X}} [f(x) = \mathbb{E}[F(x, \xi)]]$$

where $\mathcal{X} \subset \mathbb{R}^n$ is closed, bounded convex set. ξ is a random variable, and $F(\cdot, \xi)$ is convex for all $\xi \in \Xi$, and therefore $f(\cdot)$ is convex. For uniform p_ξ over finite alphabets of size n , the problem reduces to finite sum problem

$$\text{minimize}_{x \in \mathcal{X}} \left[f(x) = \frac{1}{n} \sum_{i=1}^n f_i(x) \right]$$

Assume we can

1. Sample $\xi_1, \xi_2, \dots \stackrel{i.i.d.}{\sim} p_\xi$
2. Given $(x, \xi) \in \mathcal{X} \times \Xi$, a first order oracle that returns a subgradient vector $G(x, \xi) \in \partial_x F(x, \xi)$. We also assume that G is unbiased, i.e. $g(x) := \mathbb{E}[G(x, \xi)] \in \partial f(x)$

1.1 Stochastic Gradient Method

We can show that if $f \in \mathcal{S}_{L, \mu}^1$, the choice of $\alpha_k = \mathcal{O}(\frac{1}{k})$ yields sublinear convergence of $\mathcal{O}(\frac{1}{\epsilon})$ for last iterates. If $f \in \mathcal{F}_L^1$, the choice of $\alpha_k = \mathcal{O}(\frac{1}{\sqrt{k}})$ yields a sublinear convergence of $\mathcal{O}(\frac{1}{\epsilon^2})$ for average iterates. Stochastic gradient method (or Stochastic Approximation (SA) algorithms) has updates of the form

$$x^{k+1} = \mathcal{P}_{\mathcal{X}} \left(x^k - \alpha_k G(x^k, \xi_k) \right)$$

where $\alpha_k > 0$ are stepsizes, $\mathcal{P}_{\mathcal{X}}(y) = \arg \min_{x \in \mathcal{X}} \frac{1}{2} \|x - y\|_2^2$ is the euclidean projection onto a convex set. It is important to note that the current iterate x^k are functions of random variables $x^k := x^k(\xi_{[k-1]})$ where $\xi_{[k-1]} = (\xi_1, \dots, \xi_{k-1})$, and therefore are random variables themselves. In addition, $x^k \perp \xi_k$.

1.2 Convergence

Derivations copied from [7], [8] and slides. We assume

1. bounded variance for stochastic subgradient, $\mathbb{E}_\xi [G(x, \xi)] \leq M^2$ given $x \in \mathcal{X}$.
2. bounded \mathcal{X} where radius given by $D_{\mathcal{X}} = \max_{x \in \mathcal{X}} \|x - x^*\|_2$.

We first derive some preliminary results. Using iterated expectation, we have

$$\begin{aligned} \mathbb{E} \left[\left\langle G(x^k, \xi_k), x^k - x^* \right\rangle \right] &= \mathbb{E}_{\xi_{[k-1]}} \left[\mathbb{E}_{\xi_k} \left[\left\langle G(x^k(\xi_{[k-1]}), \xi_k), x^k(\xi_{[k-1]}) - x^* \right\rangle \right] \mid \xi_{[k-1]} \right] \\ &= \mathbb{E}_{\xi_{[k-1]}} \left[\left\langle \mathbb{E}_{\xi_k} \left[G(x^k(\xi_{[k-1]}), \xi_k) \mid \xi_{[k-1]} \right], x^k(\xi_{[k-1]}) - x^* \right\rangle \right] \\ &= \mathbb{E} \left[\left\langle g(x^k), x^k - x^* \right\rangle \right] \end{aligned} \tag{1}$$

where the expectation is taken w.r.t $\xi_{[k-1]}$. We first derive a bound on residual $R_k^2 = \|x^k - x^*\|_2^2$ and expected residual $r_k^2 = \mathbb{E}[R_k^2]$ for a single update,

$$\begin{aligned}
R_{k+1}^2 &= \|x^k - x^*\|^2 \\
&= \left\| \mathcal{P}_{\mathcal{X}} \left(x^k - \alpha_k G(x^k, \xi_k) \right) - \mathcal{P}_{\mathcal{X}}(x^*) \right\|^2 \quad (x^* \text{ is fixed point of } \mathcal{P}, \mathcal{P}_{\mathcal{X}}(x^*) = x^*) \\
&\leq \|x^k - \alpha_k G(x^k, \xi_k) - x^*\|^2 \quad (\text{Nonexpansive of } \mathcal{P}, \|\mathcal{P}_{\mathcal{X}}(x') - \mathcal{P}_{\mathcal{X}}(x)\| \leq \|x' - x\|) \\
&\leq R_k^2 - 2\alpha_k \langle G(x^k, \xi_k), x^k - x^* \rangle + \alpha_k^2 \|G(x^k, \xi_k)\|^2 \\
r_{k+1}^2 &\leq r_k^2 - 2\alpha_k \mathbb{E} \left[\langle G(x^k, \xi_k), x^k - x^* \rangle \right] + \alpha_k^2 \mathbb{E} \left[\|G(x^k, \xi_k)\|^2 \right] \quad (\text{Expectation w.r.t. } \xi_{[k]}) \\
&= r_k^2 - 2\alpha_k \mathbb{E} \left[\langle g(x^k), x^k - x^* \rangle \right] + \alpha_k^2 M^2 \quad (\text{By (1) and bounded variance})
\end{aligned}$$

1.2.1 Strongly Convex Case

If $f \in \mathcal{S}_{L,\mu}^1$, using (25), we have

$$r_{k+1}^2 \leq r_k^2 - 2\alpha_k \mathbb{E} \left[\|x^k - x^*\|^2 \right] + \alpha_k^2 M^2 = (1 - 2\mu\alpha_k) r_k^2 + \alpha_k^2 M^2$$

If we choose $\alpha_k = \theta/(k+1)$, where $\theta > 1/(2\mu)$. It could be shown by induction that [7]

$$r_k^2 \leq \frac{c_\theta}{k+1} \quad \text{where} \quad c_\theta = \max \left\{ \frac{2\theta^2 M^2}{2\mu\theta - 1}, r_0 \right\}$$

By (9), we derive bound on the objective value

$$\mathbb{E} [f(x^k) - f(x^*)] \leq \frac{1}{2} L \mathbb{E} [\|x^k - x^*\|^2] \leq \frac{L c_\theta}{2(k+1)}$$

Therefore, the choice of $\alpha_k = \mathcal{O}(\frac{1}{\epsilon})$ yields last iterate convergence rate of $\mathcal{O}(\frac{1}{\epsilon})$

1.2.2 Convex Case

[7] indicates that we need to increase the stepsize ($\mathcal{O}(\frac{1}{k})$ to $\mathcal{O}(\frac{1}{\sqrt{k}})$) to ensure faster convergence rate for general convex problems, at the cost of *more noisy* trajectory. To suppress the noise, we use average iterates $\{x^k\}$ rather than last iterates as solution to the problem.

$$\begin{aligned}
r_{k+1}^2 &\leq r_k^2 - 2\alpha_k \mathbb{E} \left[\langle g(x^k), x^k - x^* \rangle \right] + \alpha_k^2 M^2 \\
2\alpha_k \mathbb{E} [f(x^k) - f(x^*)] &\leq 2\alpha_k \mathbb{E} \left[\langle g(x^k), x^k - x^* \rangle \right] \leq r_k^2 - r_{k+1}^2 + \alpha_k^2 M^2 \quad (\text{By 14}) \\
\sum_{i=1}^k (2\alpha_i \mathbb{E} [f(x^i) - f(x^*)]) &\leq \sum_{i=1}^k (r_i - r_{i+1} + \alpha_i M^2) = r_1^2 + M^2 \sum_{i=1}^k \alpha_i^2 \quad (\text{Telescope}) \\
\sum_{i=1}^k \gamma_i \mathbb{E} [(f(x^i) - f(x^*))] &= \mathbb{E} \left[\sum_{i=1}^k \gamma_i (f(x^i) - f(x^*)) \right] \leq \frac{r_1^2 + M^2 \sum_{i=1}^k \alpha_i^2}{2 \sum_{i=1}^k \alpha_i} \quad (/2 \sum_i \alpha_i)
\end{aligned}$$

where $\gamma_i = \alpha_i / \sum_i \alpha_i$. Let $\tilde{x}^k = \sum_{i=1}^k \gamma_i x^i$. $f(\tilde{x}^k) \leq \sum_i \gamma_i f(x^i)$ by convexity of f . Then,

$$\mathbb{E} \left[f(\tilde{x}^k) - f(x^*) \right] \leq \frac{r_1^2 + M^2 \sum_{i=1}^k \alpha_i^2}{2 \sum_{i=1}^k \alpha_i}$$

We derive tightest bound by finding minimal value of $\alpha_k = \alpha$ of the bound.

$$\mathbb{E} \left[f(\tilde{x}^k) - f(x^*) \right] \leq \frac{D_{\mathcal{X}} M}{\sqrt{k}} \quad \alpha_k = \frac{D_{\mathcal{X}}}{M \sqrt{k}}$$

Therefore, the choice of $\alpha_k = \mathcal{O}(\frac{1}{\sqrt{k}})$ yields average iterate convergence rate of $\mathcal{O}(\frac{1}{\epsilon^2})$