

User Guide

For V2IP Development

TCCxxx-Android-ICS-ALL-V1.00E-User Guide-for V2IP-multi-way Development

Aug. 14, 2013.

TeleChips

Preliminary

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Revision History

Date	Version	Description
2012-03-28	1.00	Initial Release
2013-08-14	1.10	Modified for Jelly Bean

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1 Introduction

This document provides guideline for users to implement V2IP(Video Voice over IP) using their own V2IP engine on Telechips Android platform quickly.

Note> Telechips supports various multimedia function which is required to implement Video/Audio Engine.

Telechips's Android platform also support V2IP engine itself using Unicoi solution which was developed by using these functions.

2 How to implement Video over IP function.

Manufacturer is responsible for V2IP App, JNI and native V2IP Engine.

The V2IP engine is in charge of many things: network communication using RTP, buffer management, data unpack/pack, A/V sync and etc.

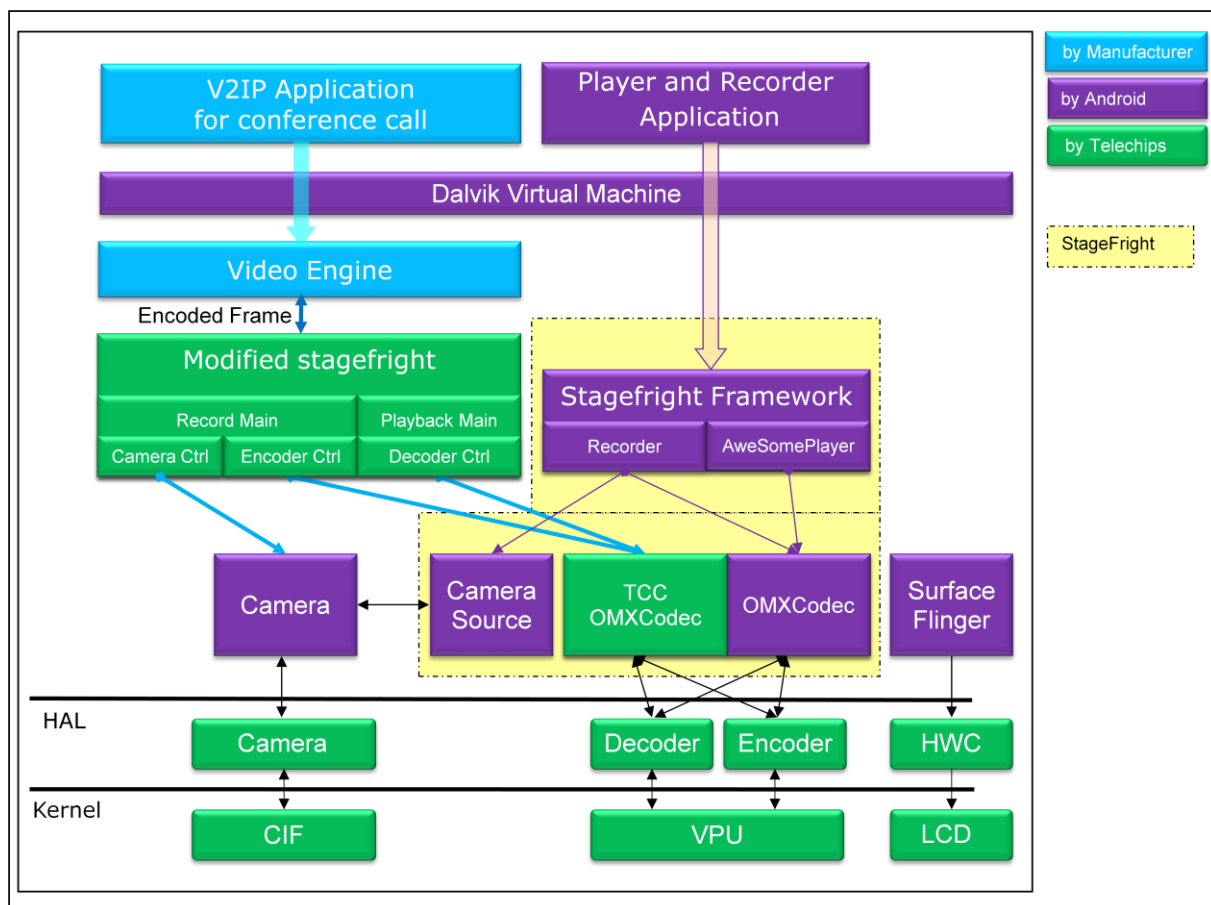
Telechips provide the interface using Modified StageFright to implement Video engine.

It is very easy to implement. But, these interfaces only can support 2-way video call.

In other words, it is not suitable for multi-way video call because one of all peers has to be server to gather all those together in one frame.

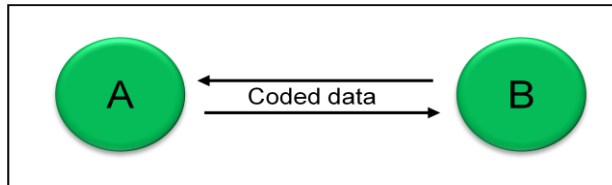
Please refer another document(TC-TCCxxx-Android-ICS-ALL-V1.00E-User Guide-for V2IP-2way only Development.pdf) if your engine only support 2-way video call.

Below diagram shows simple operation related with 2-way video call using it.



Telechips also provide the interface using direct API related to Camera, Encoder, Decoder, Renderer and Merger to implement multi-way video call.

(Most function related to video will be provided by **libtcc.video.call.direct.interface.so** library.)

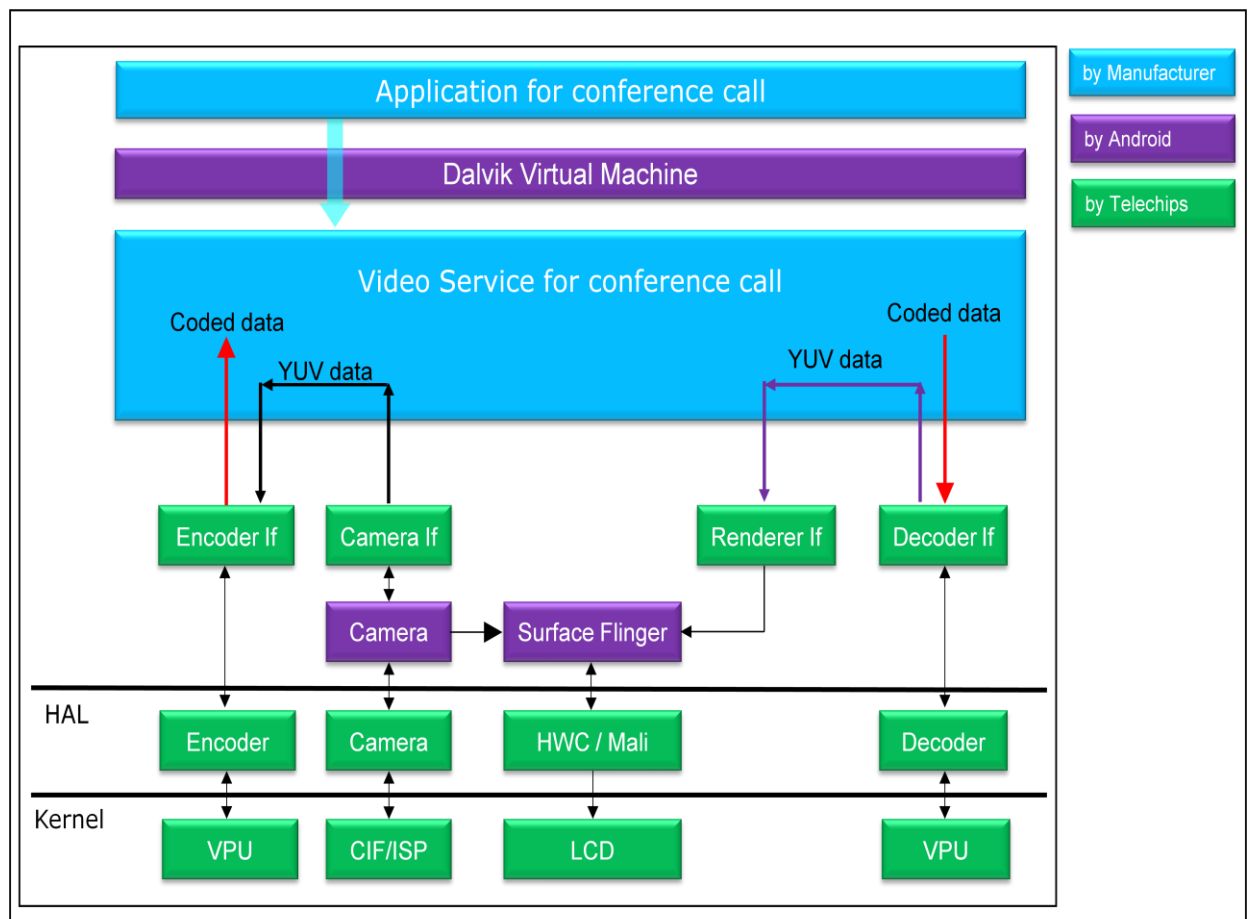


Simple 2-way call diagram

In case of 2-way video call,

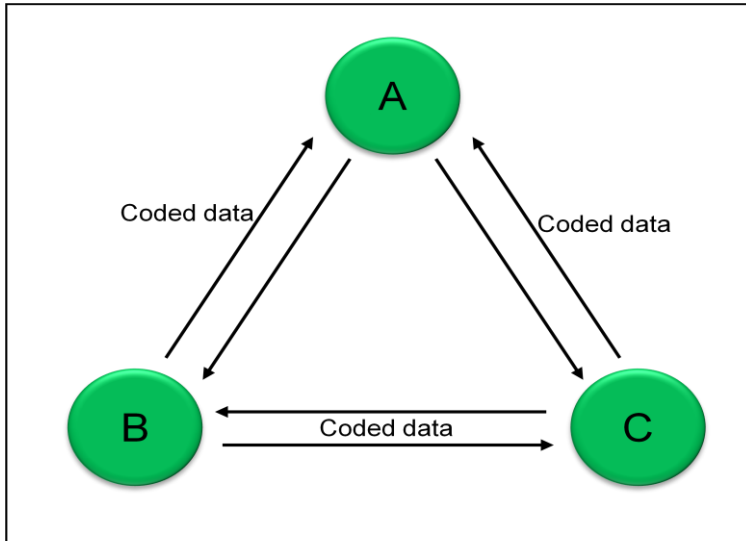
- Each peer has to display own frame from camera.
- Each peer also has to display frame received through RTP.

Below diagram shows overall operation related with 2-way interface on Remote and Local peer.



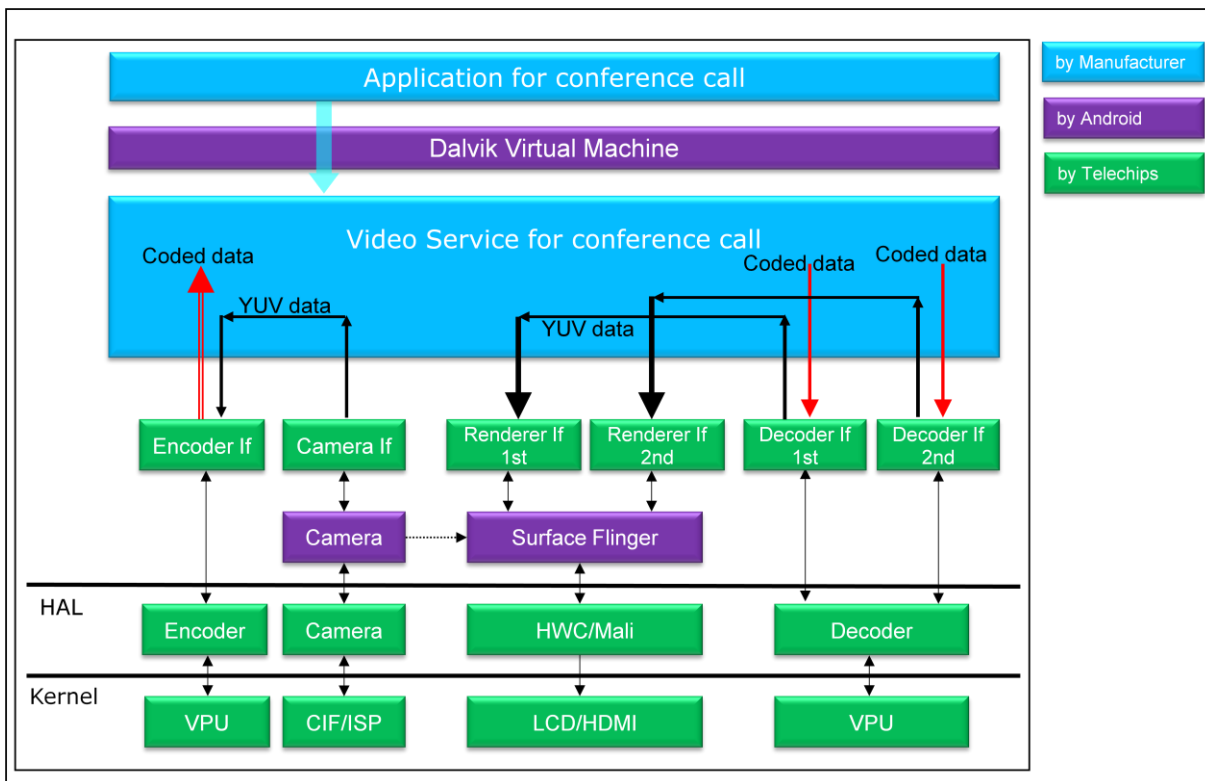
In case of 2way call. (Remote and Local peer)

Generally, It is easy to think that below diagram show multi-way video call.
But, It is not right way to implement multi-way video call.



Not right 3-way call diagram

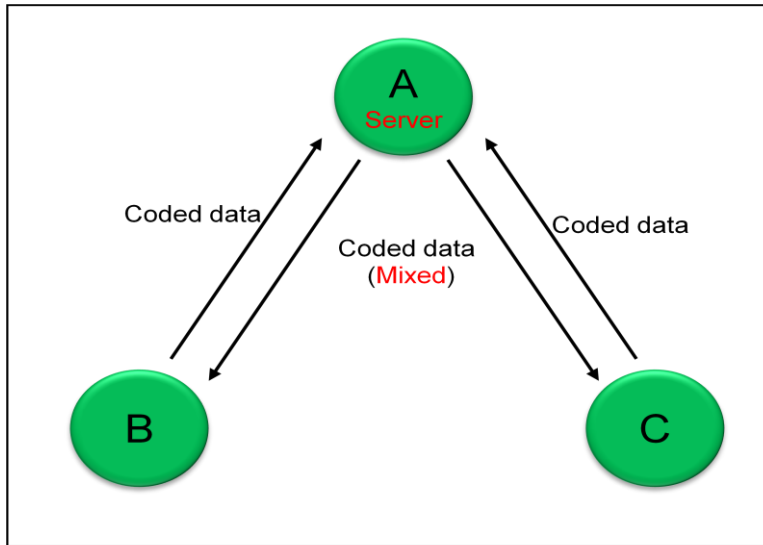
Even though this is not right way, it can be used if all peers's devices has enough performance to encode and decode simultaneously.



In case of multi-way call. (not right way)

If this way is used to implement multi-way call, the displayed region of each peer can be changed.

Below diagram shows right way for multi-way call.

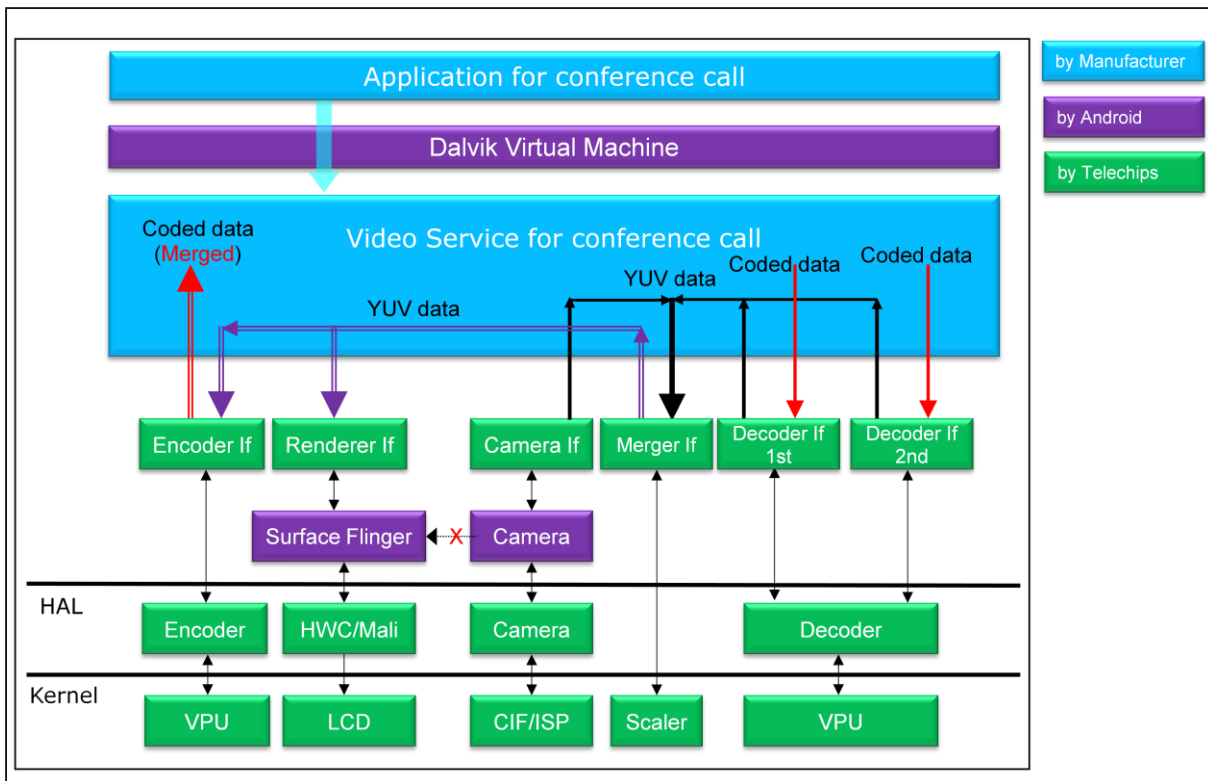


Simple 3-way call diagram

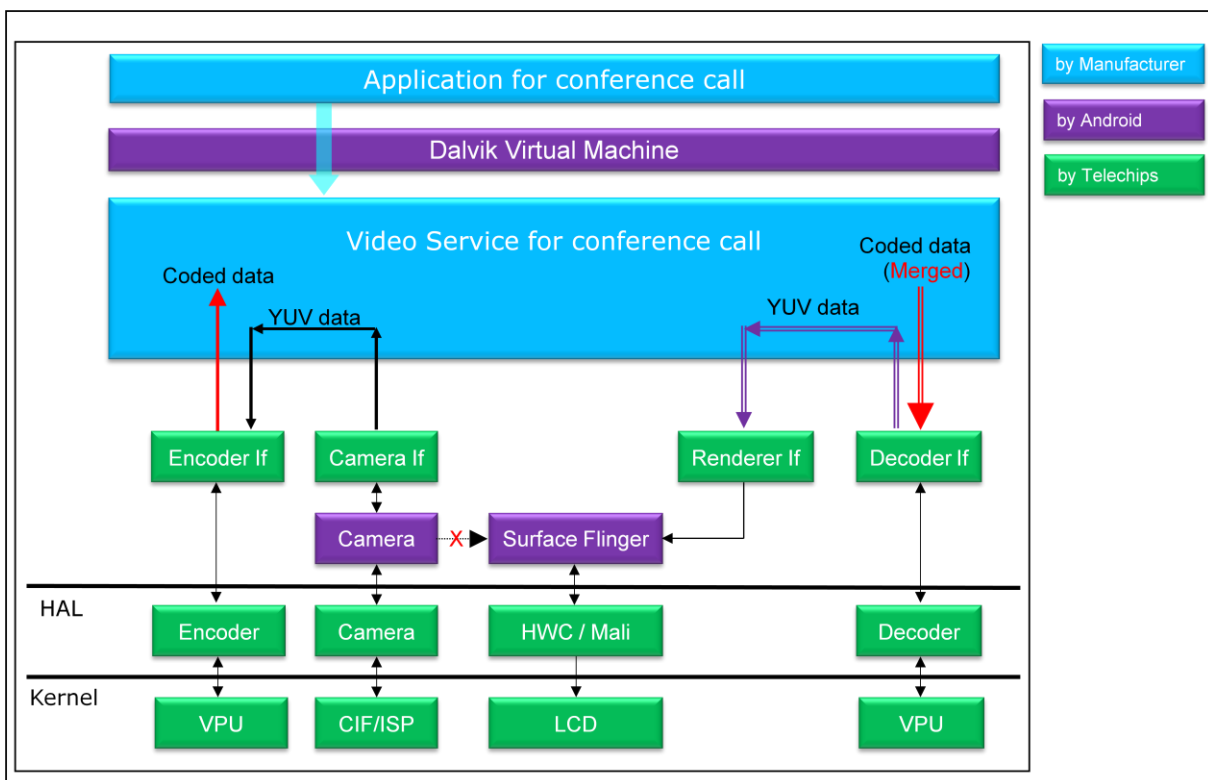
In case of multi-way video call,

- One of peers has to be server peer.
- Server peer has to provide function to merge frames from clients and own camera.
- All peers don't have to display own frame from camera because of below reason.
 - Server peer only display merged frame which already have own frame and client's frames.
 - Client peers only display frame received through RTP.
- This concept has disadvantage like below:
 - The displayed region of each peer is fixed.
 - The server peer has to have enough performance to merge and decode several frames.
 - ⇒ Telechips provides Merger function using h/w operation.

Next diagram shows overall operation related with 3-way interface on Server and Client sides.



In case of multi-way call. (Server peer)



In case of multi-way call. (Client peers)

3 Camera interface class.

3.1 C++ API header and library include

- Camera_if.h
 - API for Cameralf class.
 - Path: /hardware/telechips/common/tcc-interface/tccif_direct/
- Shared library : libtcc.video.call.direct.interface.so

3.2 Initialization and Startup

```
Cameralf *_camera = new Cameralf((CameraFrameCallBack*)this);
```

```
_camera->Init(pSurface, 1280, 720, 20, 0);
```

```
_camera->Start();
```

Below function can be called after calling start ().

```
_camera->GetFrame_Format();
```

```
_camera->SetFramerate(10);
```

```
_camera->ReleaseFrame(frame);
```

```
_camera->GetVirtual_Address(0);
```

3.3 Shutdown and Cleanup

```
_camera->Stop();
```

```
delete _camera;
```

3.4 Reference

Cameralf ()

This is the constructor of Cameralf class.

After camera is started, the callback delivered by argument will be called whenever captured frame from camera is ready.

Prototype	Cameralf (CameraFrameCallBack *callback)
Parameters	Callback
Return value	None

~ Cameralf ()

This is the destructor of Cameralf class.

Prototype	~ Cameralf ()
Parameters	None
Return value	None

Init ()

This is the method to initialize Camera.

Prototype	int Init(const sp<Surface> pSurface, int frame_width, int frame_height, int default_framerate, int no_preview)
Parameters	const sp<Surface> pSurface <ul style="list-style-type: none"> - This surface pointer has to be provided although the frame from Camera don't want to be displayed by itself. - If the frame from Camera don't want to be displayed by itself, call Start() function with no_display, "1". int frame_width : frame width int frame_height : frame height int default_framerate : framerate int no_preview <ul style="list-style-type: none"> - If the frame from Camera don't want to be displayed by itself, call Start() function with no_preview, "1". In this case, minimize region of Camera Surface. - Otherwise, set the value into "0".
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

Start ()

This is the method to start Camera.

Prototype	int Start()
Parameters	None
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

Stop ()

This is the method to stop Camera.

Prototype	int Stop()
Parameters	None
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

ReleaseFrame ()

This is the method to release it after frame from Camera is encoded.

Prototype	void ReleaseFrame(const sp<IMemory>& frame)
-----------	---

Parameters	const sp<IMemory>& frame - This pointer is same with received one from callback provided when calling constructor of this class.
Return value	None

SetFramerate ()

This is the method to change framerate.

Prototype	int SetFramerate(int fps)
Parameters	int fps - framerate value to change.
Return value	If successful, return fps value applied actually. - (The applied fps can be differed with given one because the Camera can't support all kinds of framerate.) - Use this returned value for encoder because same fps value have to set between camera and encoder.

GetVirtual_Address ()

This is the method to get virtual address that can be matched with physical address given by Callback.

The physical address can be got like below:

```
- enc_metadata_t* pEncMetadataInfo = (enc_metadata_t*)dataPtr->pointer();
  unsigned int phyAddr = (unsigned int)pEncMetadataInfo->fd_0;
  Above phyAddr can be used for Encoder and Merger.
```

Prototype	unsigned int GetVirtual_Address(unsigned int phyAddr)
Parameters	unsigned int phyAddr - This address is what get from given frame's pointer by callback function when calling constructor of this class.
Return value	If successful, return virtual address. Otherwise it return NULL.

GetFrame_Format ()

This is the method to get frame format from camera..

Prototype	tFRAME_BUF_FORMAT GetFrame_Format(void)
Parameters	None
Return value	If successful, return format value.

4 Encoder interface class.

4.1 C++ API header and library include

- Encoder_if.h
 - API for EncoderIf class.
 - Path: /hardware/telechips/common/tcc-interface/tccif_direct/
- Shared library : libtcc.video.call.direct.interface.so

4.2 Initialization and Startup

```
EncoderIf* _encoder = new EncoderIf();
```

Call below function after configuring tENC_INIT_PARAMS parameters.

```
_encoder->Init(plnit);
```

Below function can be called with configuring tENC_FRAME_INPUT parameters after calling Init().

```
_encoder->Encode(pInput, pOutput);
```

4.3 Shutdown and Cleanup

```
_encoder->Close();
```

```
delete _encoder;
```

4.4 Reference

EncoderIf ()

This is the constructor of EncoderIf class.

Prototype	EncoderIf()
Parameters	None
Return value	None

~ EncoderIf ()

This is the destructor of EncoderIf class.

Prototype	~ EncoderIf ()
Parameters	None
Return value	None

Init ()

This is the method to initialize Encoder

Prototype	int Init(tENC_INIT_PARAMS *pInit)
Parameters	tENC_INIT_PARAMS *pInit - pointer of encoder initial parameters ● refer Encoder_if.h file in detail.
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

Encode ()

This is the method to encode frame.

Prototype	int Encode(tENC_FRAME_INPUT *pInput, tENC_FRAME_OUTPUT *pOutput)
Parameters	tENC_FRAME_INPUT *pInput - pointer of encoder input parameters ● refer Encoder_if.h file in detail. tENC_FRAME_OUTPUT *pOutput - pointer of encoder output parameters ● refer Encoder_if.h file in detail.
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

Close ()

This is the method to close Encoder.

Prototype	int Close(void)
Parameters	None
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

5 Decoder interface class.

5.1 C++ API header and library include

- Decoder_if.h
 - API for DecoderIf class.
 - Path: /hardware/telechips/common/tcc-interface/tccif_direct/
- Shared library : libtcc.video.call.direct.interface.so

5.2 Initialization and Startup

```
DecoderIf* _decoder = new DecoderIf();
```

Call below function after configuring tDEC_INIT_PARAMS parameters.

```
_decoder->Init(pInit);
```

Below function should be called with configuring tDEC_FRAME_INPUT parameters after calling Init().

```
_decoder->Decode(pInput, pOutput, pResult);
```

5.3 Shutdown and Cleanup

```
_decoder->Close();
```

```
delete _decoder;
```

5.4 Reference

DecoderIf ()

This is the constructor of DecoderIf class.

Prototype	DecoderIf ()
Parameters	None
Return value	None

~ DecoderIf ()

This is the destructor of DecoderIf class.

Prototype	~ DecoderIf ()
Parameters	None
Return value	None

Init ()

This is the method to initialize Decoder

Prototype	int Init(tDEC_INIT_PARAMS *pInit)
Parameters	tDEC_INIT_PARAMS *pInit - pointer of decoder initial parameters ● refer Decoder_if.h file in detail.
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

Decode ()

This is the method to decode frame.

Prototype	int Decode(tDEC_FRAME_INPUT *pInput, tDEC_FRAME_OUTPUT *pOutput , tDEC_RESULT *pResult)
Parameters	tDEC_FRAME_INPUT *pInput - pointer of decoder input parameters ● refer Decoder_if.h file in detail. tDEC_FRAME_OUTPUT *pOutput - pointer of decoder output parameters ● refer Decoder_if.h file in detail. tDEC_RESULT *pResult - pointer of decode result parameters ● refer Decoder_if.h file in detail.
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value. If successful, check *pResult.

Close ()

This is the method to close Decoder.

Prototype	int Close(void)
Parameters	None
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

6 Renderer interface class.

6.1 C++ API header and library include

- `Renderer_if.h`
 - API for `RendererIf` class.
 - Path: `/hardware/telechips/common/tcc-interface/tccif_direct/`
- Shared library : `libtcc.video.call.direct.interface.so`

6.2 Initialization and Startup

```
RendererIf *_renderer = new RendererIf(surfaceTexture, NULL, width, height, format);
```

Check if the `RendererIf` class is created properly or not.

```
If(false == _renderer->IsInit_OK())  
    return error;
```

Call the `Render()` function whenever the frame is ready.

```
_renderer->Render(Y, U, V, 1, 233,private_data);
```

6.3 Shutdown and Cleanup

```
delete _renderer;
```

6.4 Reference

RendererIf ()

This is the constructor of `RendererIf` class.

Prototype	<code>RendererIf (const sp<ISurfaceTexture> &surfaceTexture, void *pNativeWindow, unsigned int inFrame_width, unsigned int inFrame_height, tFRAME_BUF_FORMAT inBuffer_format, int outbuffer_count = DEF_BUFFER_CNT)</code>
Parameters	<div>const sp<ISurfaceTexture> &surfaceTexture<ul style="list-style-type: none">- pointer of <code>ISurfaceTexture</code></div> <div>void *pNativeWindow<ul style="list-style-type: none">- pointer of <code>NativeWindow</code></div> <div><ul style="list-style-type: none">• The two argument(<code>surfaceTexture</code>, <code>pNativeWindow</code>) are mutually exclusive. So, one of those arguments should be <code>NULL</code>.</div> <div>unsigned int inFrame_width<ul style="list-style-type: none">- width of input frame</div> <div>unsigned int inFrame_height<ul style="list-style-type: none">- height of input frame</div> <div>tFRAME_BUF_FORMAT inBuffer_format<ul style="list-style-type: none">- format of input frame (raw data)</div>

	int outbuffer_count - buffer count allocated
Return value	None

~ RendererIf ()

This is the destructor of RendererIf class.

Prototype	~ RendererIf ()
Parameters	None
Return value	None

IsInit_OK ()

This is the method to check if Renderer instance is created properly..

Prototype	bool IsInit_OK()
Parameters	NONE
Return value	If successful, it returns true. Otherwise, it returns false.

Render ()

This is the method to display frame.

Prototype	status_t Render(unsigned int Yaddr, unsigned int Uaddr, unsigned int Vaddr, char bAddrPhy, int64_t timestamp_ms, TCC_PLATFORM_PRIVATE_PMEM_INFO *plat_priv = NULL)
Parameters	unsigned int Yaddr - Y(Luminance) address of frame that will be displayed. unsigned int Uaddr - U/UV(Chrominance) address of frame that will be displayed. unsigned int Vaddr - V(Chrominance) address of frame that will be displayed. - This can be NULL. char bAddrPhy - It indicates if Yaddr/Uaddr/Vaddr is physical address or not. int64_t timestamp_ms - Timestamp of current frame (unit is milliseconds.) TCC_PLATFORM_PRIVATE_PMEM_INFO *plat_priv - If the frame is from h/w decoder, it should be delivered.
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

7 Merger interface class.

7.1 C++ API header and library include

- Merger_if.h
 - API for MergerIf class.
 - Path: /hardware/telechips/common/tcc-interface/tccif/
- Shared library : libtcc.video.call.interface.so

7.2 Initialization and Startup

```
MergerIf* _merger = new MergerIf();  
If(_merger == NULL)  
    return error;
```

Allocate target buffer for the Merger.

```
int ret = _merger->Allocate_TargetBuffer(width, height, format);  
If(_ret < 0)  
    return error;
```

Call the Merge() function whenever there is a frame to be merged.

```
_merger->Merge(320,240, input_physical_address, input_format, 0,0,320,240);
```

Use below function if there is need to get the buffer's address mixed.

```
_merger->Get_BufferAddress(1, 0);
```

7.3 Shutdown and Cleanup

```
_merger->Close();
```

```
delete _merger;
```

7.4 Reference

MergerIf ()

This is the constructor of MergerIf class.

Prototype	MergerIf()
Parameters	None
Return value	None

~ MergerIf ()

This is the destructor of MergerIf class.

Prototype	~ MergerIf ()
Parameters	None
Return value	None

Alloc_TargetBuffer ()

This is the method to initialize Merger.

Prototype	int Alloc_TargetBuffer (int width, int height, tFRAME_BUF_FORMAT format)
Parameters	<ul style="list-style-type: none"> - These are the function to allocate final target buffer that input images are merged in. Based on these parameters, target buffer can be allocated. int width : width of target buffer. int height : height of target buffer. tFRAME_BUF_FORMAT format : format of target buffer.
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

Get_BufferAddress ()

This is the method to get buffer address.

Prototype	unsigned int Get_BufferAddress(bool isPhyAddr, bool previous_buffer)
Parameters	bool isPhyAddr <ul style="list-style-type: none"> - Set this value to get physical address, otherwise virtual address will be returned. bool previous_buffer <ul style="list-style-type: none"> - Set this value to get previous buffer's address, otherwise current buffer's address will be returned.
Return value	Target buffer's address (virtual or physical address)

This is the example how to set arguments to get proper address.

1. In order to get physical address of current buffer..
[_merger->Get_BufferAddress\(1, 0\).](#)
2. In order to get virtual address of current buffer.
[_merger->Get_BufferAddress \(0, 0\).](#)
3. In order to get physical address of previous buffer.
[_merger->Get_BufferAddress \(1, 1\).](#)
4. In order to get virtual address of previous buffer.
[_merger->Get_BufferAddress \(0, 1\).](#)

Close ()

This is the method to close Merger.

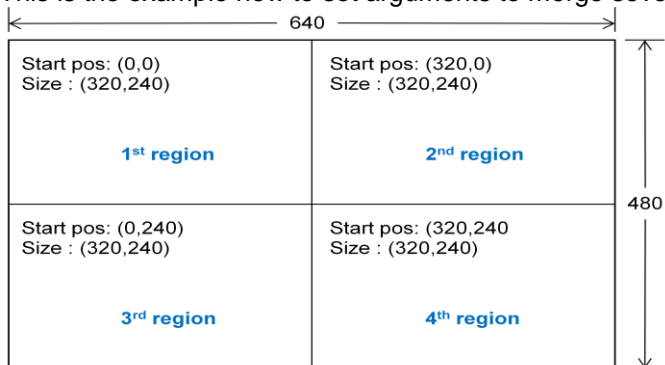
Prototype	int Close(void)
Parameters	None
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

Merge ()

This is the method to merge frames.

Prototype	int Merge(int in_width, int in_height, tFRAME_BUF_FORMAT in_format, unsigned int in_address, int out_sx, int out_sy, int out_width, int out_height, int new_buffer)
Parameters	<ul style="list-style-type: none"> These are the information related to input frames from Camera and Decoders. <p>int in_width : width of input frame int in_height : height of input frame tFRAME_BUF_FORMAT in_format : format of input frame unsigned int in_address : physical address of buffer having raw data.</p> <ul style="list-style-type: none"> These are the information related to region in target buffer where input frames are merged in. <p>int out_sx : start x-position int out_sy : start y-position int out_width : width int out_height : height</p> <p>int new_buffer - to replace the target buffer into new one.</p>
Return value	If successful, it returns 0 or plus. Otherwise, it returns a minus value.

This is the example how to set arguments to merge several frames in one frame.



- In case target resolution is VGA(640x480). -

1. if the QVGA frame with YUV420P want to be displayed in 2nd region, set like below
`_merger->Merge(320, 240, FRAME_BUF_FORMAT_YUV420P, in_address, 320, 0, 320, 240, 0);`
2. if the VGA frame with YUV420I want to be displayed in 3rd region, set like below
`_merger->Merge(640, 480, FRAME_BUF_FORMAT_YUV420I, in_address, 0, 240, 320, 240, 0);`
In case of this, input VGA frame will be scaled down into QVGA.
3. if the QCIF frame with YVU420P want to be displayed in 4th region, set like below
`_merger->Merge(176, 144, FRAME_BUF_FORMAT_YVU420P, in_address, 320, 240, 320, 240, 0);`
In case of this, input QCIF frame will be scaled up into QVGA.

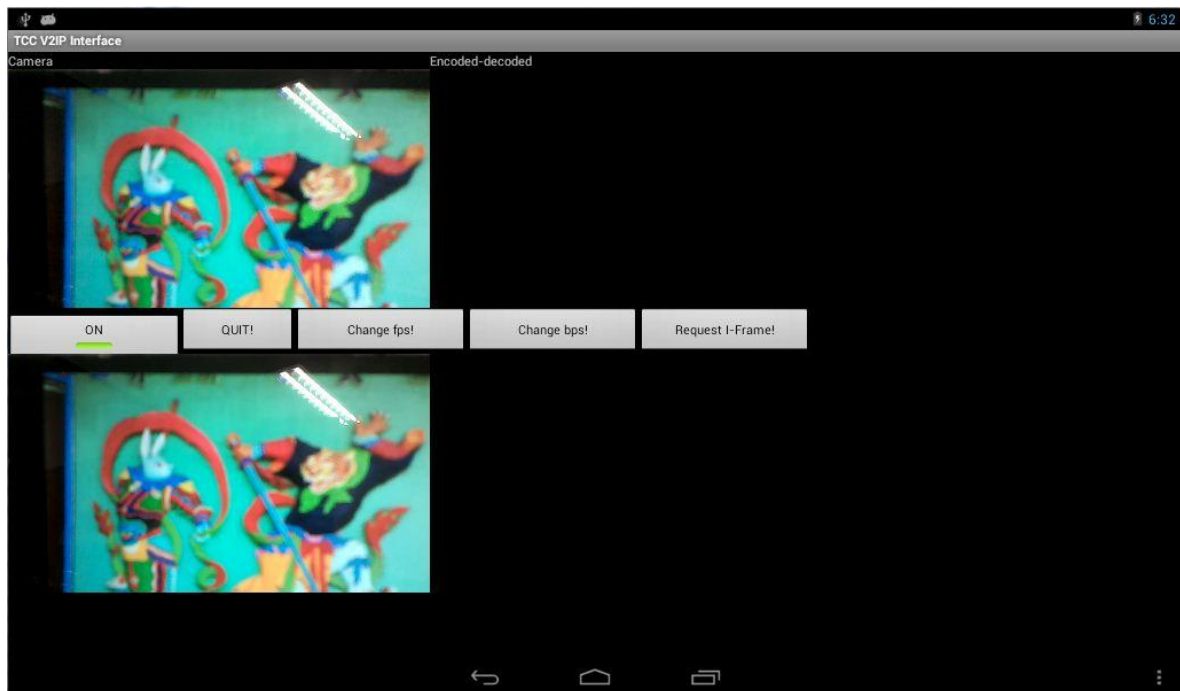
8 Sample codes.

This section describes the sample codes to test if the V2IP interface works well or not.

This apk is very simple loopback application.

The application records from camera -> sends to encoder -> sends to decoder -> displays with renderer.

Changing bitrate and framerate and requesting the I-Frame can be also tested.



To start, press left “OFF” button to make “ON”.

In order to build simple application

You can find the source codes related to sample application.

- Path: hardware/telechips/common/tcc-interface/jniTccif
Apk source: [TCC_Interface_sample_apk_src.zip](#)

You should choose the interface type between direct-if and modified-stagefright-if.

- Path: hardware/telechips/common/tcc-interface/jniTccif/[jniTccif.cpp](#)
- Enable [TEST_TCCIF_DIRECT_INTERFACE](#) Feature to use the direct-if.

1). Put the 3 so library into proper folder after building Android SDK.

- From out/target/product/tcc893x/obj/lib
: [libjniTccif.so](#), [libtcc.video.call.interface.so](#), [libtcc.video.call.direct.interface.so](#)
- To TCC_Interface/jni/jniTccif/[libjniTccif.so](#)
TCC_Interface/jni/libtccif/[libtcc.video.call.interface.so](#)
TCC_Interface/jni/libtccifdirect/[libtcc.video.call.direct.interface.so](#)

2). Run ndk-build on TCC_Interface.

3). Build using Eclipse and run.

9 Limitation.

This section describes performance limitation related with displaying through HDMI.

In order to prevent the performance issue

* First issue

TCC Android platform supports DVFS(Dynamic Voltage Frequency Scaling). However DVFS is based on CPU load and does not consider other factors – for example VPU(Video Process Unit)/Camera h/w block.

For example, the operating clock is decided according to resolution and bit rate during video playback or camera operation, But it is not enough for V2IP because video playback and camera operation are done simultaneously.

To clear this problem, TCC use specific clock table as below.

Path: kernel/arch/arm/mach-tcc892x/tcc_clocktbl_ddr2.h or tcc_clocktbl_ddr3.h
kernel/arch/arm/mach-tcc88xx/tcc_clocktbl_ddr2.h or tcc_clocktbl_ddr3.h

The name of clock table: [gtJpegMaxClockLimitTable](#)

Each value means minimum clock of each h/w block including CPU.

So, User can adjust each value if user meet performance problem.

* Second issue

Flickering or tearing can be happened during displaying via HDMI because it needs more memory access than builtin LCD.

If user meet this kind of problems, HDMI resolution will have to be fixed into 720p to clear it. Change below property by the own application while V2IP function use.

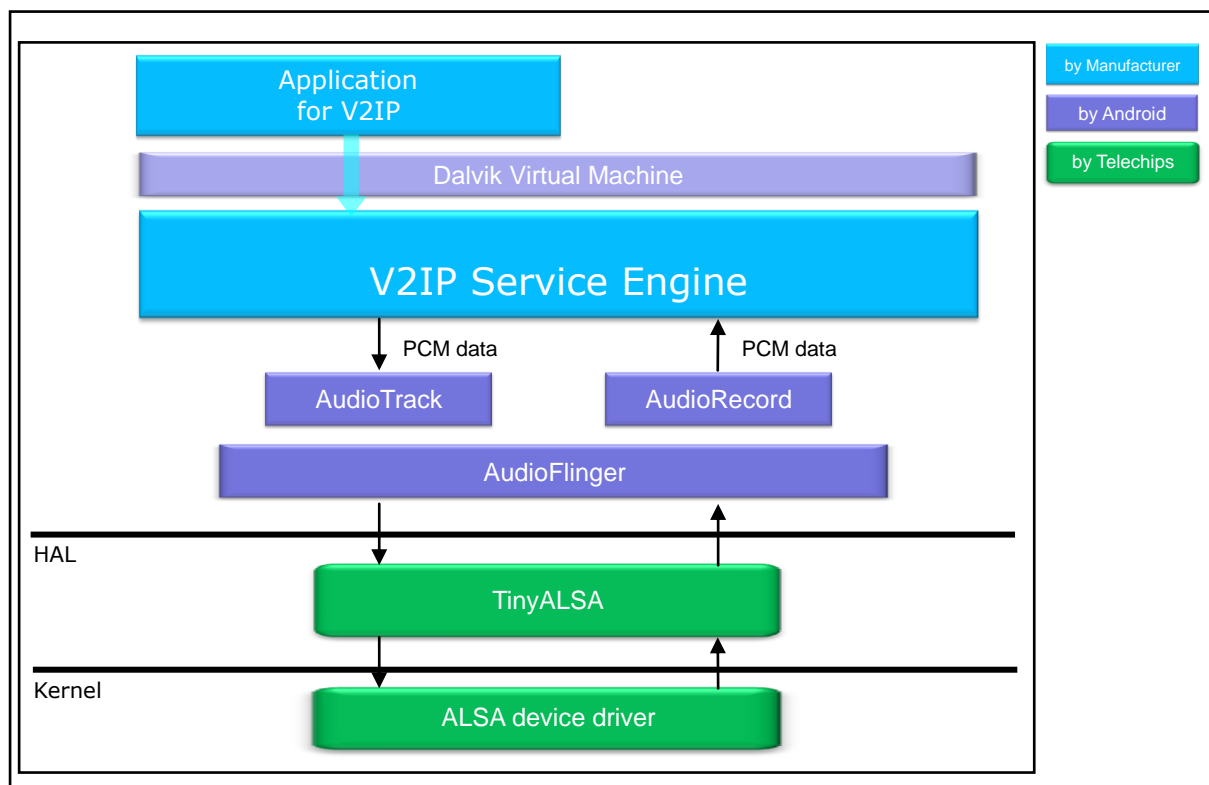
- "[tcc.all.hdmi.720p.fixed](#)" : default value is 0.
: Use this property to fix HDMI resolution into 720p.

In case of java file, use `SystemProperties.set()` function to change setting value.

In case of cpp file, use `property_set()` function to change setting value.

10 How to develop Voice over IP function.

The media framework of android supports AudioTrack and AudioRecord Class for PCM data interface. You can get and send the PCM data by it. The block diagram of this is below.



For more information about AudioTrack and AudioRecord class, visit at

<http://developer.android.com/reference/android/media/AudioRecord.html>

<http://developer.android.com/reference/android/media/AudioTrack.html>

10.1 In order to PCM data using AudioRecord.

The AudioRecord class supports many functions for PCM data management. Among those, I explain the main function that you need to get PCM data. See the below sample code.

* Sample code

```

/*****
* Initialize part
* This needs just one time.
*****/
AudioRecord mAudioRecord;
mAudioRecord = new AudioRecord();           ← Create the AudioRecord class
mAudioRecord.getMinFrameCount(&frameCount, sampleRate, format, channels);   ← get min frameCount
mAudioRecord.set(inputSource, sampleRate, format, channels, frameCount, ...); ← set parameter
    inputSource: 0 (Mic)
    sampleRate: 8000 ~ 48000
    format      : AUDIO_FORMAT_PCM_16_BIT
    channels    : AUDIO_CHANNEL_IN_MONO or AUDIO_CHANNEL_IN_STEREO
    frameCount  : the total size of the buffer.
buffer = malloc(frameCount * 4);           ← allocate memory at buffer.
mAudioRecord.start();                      ← Start getting PCM data from inputSource.
  
```

```

/*****
* Get PCM Data from input device.
*****/
while (read_stop_flag) {
    ret = mAudioRecord.read(buffer, userSize);
    buffer : buffer pointer of input PCM data
    userSize: PCM data size
    ret : actually read PCM data size.
    if(ret < 0) continue;

    /* Insert the your code */
    ...
}

/*****
* Destroy part
*****/
mAudioRecord.stop();

```

← You can get PCM data at buffer.
 ← Do not get PCM data from input device
 ← retry
 ← PCM data copy, etc...
 ← Stop getting PCM data from inputSource.

10.2 In order to play PCM data using AduioTrack.

The AudioTrack class supports many functions for PCM data management. Among those, I explain the main function that you need to write PCM data. See the below sample code.

* Sample code

```

/*****
* Initialize part
* This needs just one time
*****/
AudioTrack mAudioTrack;
mAudioTrack = new AudioTrack();
mAudioTrack.getMinFrameCount (&frameCount, streamType, sampleRate);
mAudioTrack.set(streamType, sampleRate, format, channels, frameCount, ...);
streamType: the type of audio stream. Set the AUDIO_STREAM_VOICE_CALL
sampleRate: 8000 ~ 48000
format : AUDIO_FORMAT_PCM_16_BIT
channels : AUDIO_CHANNEL_OUT_MONO or AUDIO_CHANNEL_OUT_STEREO
frameCount : the total size of the buffer.

mAudioTrack.start();
buffer = malloc(frameCount * 4);

/*****
* write pcm data to output device.
*****/
while(write_stop_flag) {
    ret = mAudioTrack.write(buffer, userSize);
    buffer : buffer pointer of output PCM data
    userSize: PCM data size
    ret : actually written PCM data size.
    if(ret < 0) continue;

    /* Insert the your code */
    ...
}

/*****
* Destroy part
*****/
mAudioTrack.flush();
mAudioTrack.stop();
delete mAudioTrack;

```

← Create the AudioTrack class
 ← Get min frameCount
 ← Set parameter
 ← Start PCM data playback
 ← allocate memory at buffer.
 ← Write PCM data to output device.
 ← Do not write pcm data to output device.
 ← retry
 ← PCM data copy, etc...
 ← Flush PCM buffer.
 ← Stop PCM data playback.
 ← destroy AudioTrack class