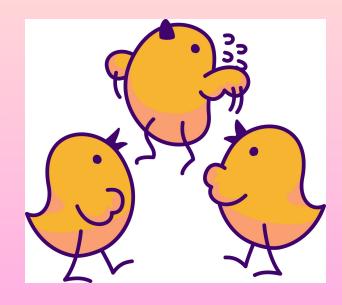


# Transformer 구현하기

현청천 / cchyun@gmail.com

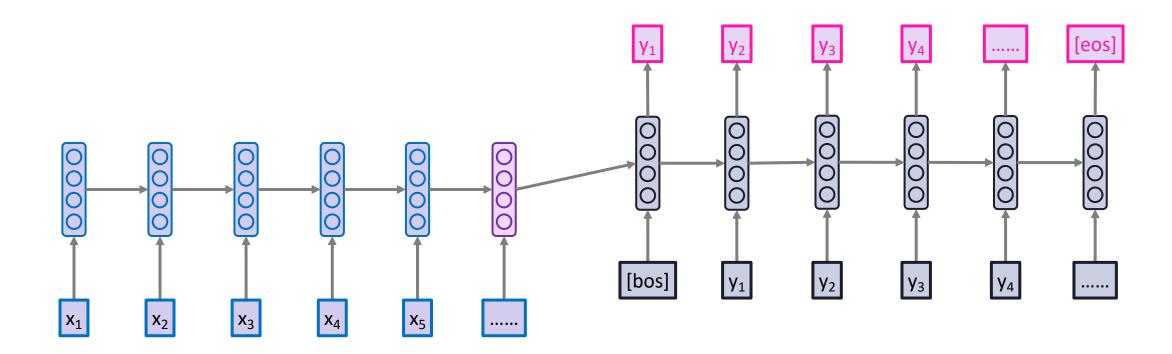


- 1. Why Transformer
- 2. Embedding
  - 1. Weight Shared Embedding
  - 2. Positional Encoding
- 3. Scaled Dot-Product Attention
- 4. Scaled Dot-Product Attention (masked)
- 5. Multi-Head Attention
- 6. Position-wise Feed-Forward Network
- 7. Reference



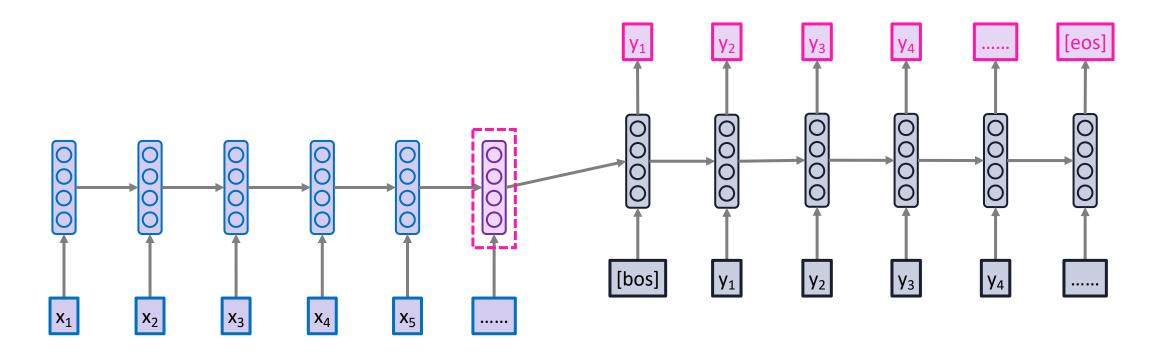
# Why Transformer

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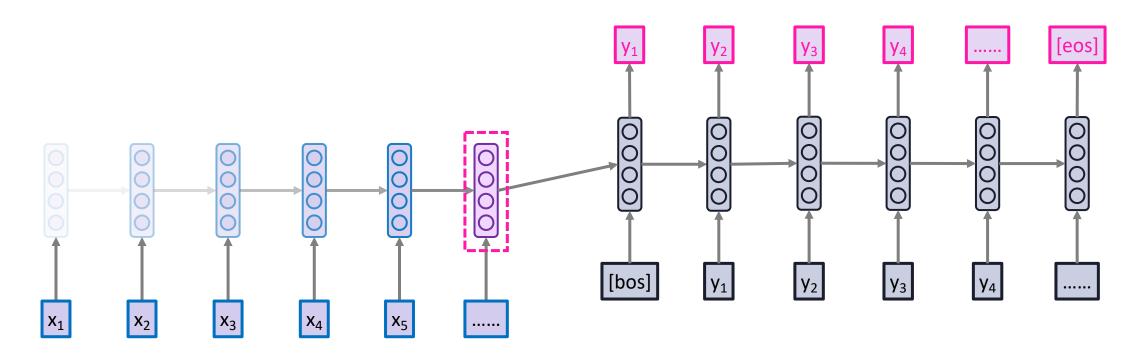
#### Source Sentence Encoding

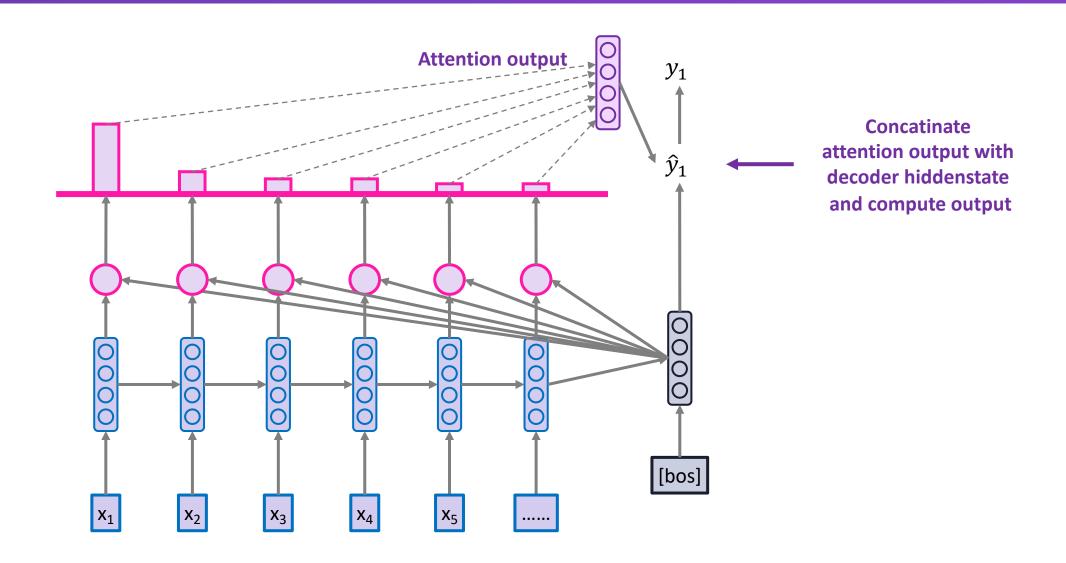
#### Source Sentence의 모든 정보를 저장 해야 함 (Information bottleneck)



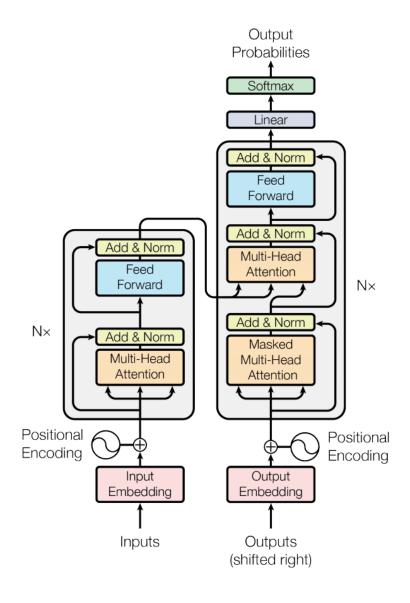
#### Source Sentence Encoding

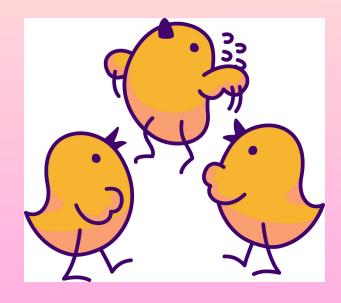
#### 과거 step의 정보는 최신 step의 보다 덜 사용 됨(Vanishing Gradient)





## Why Transformer (Transformer)

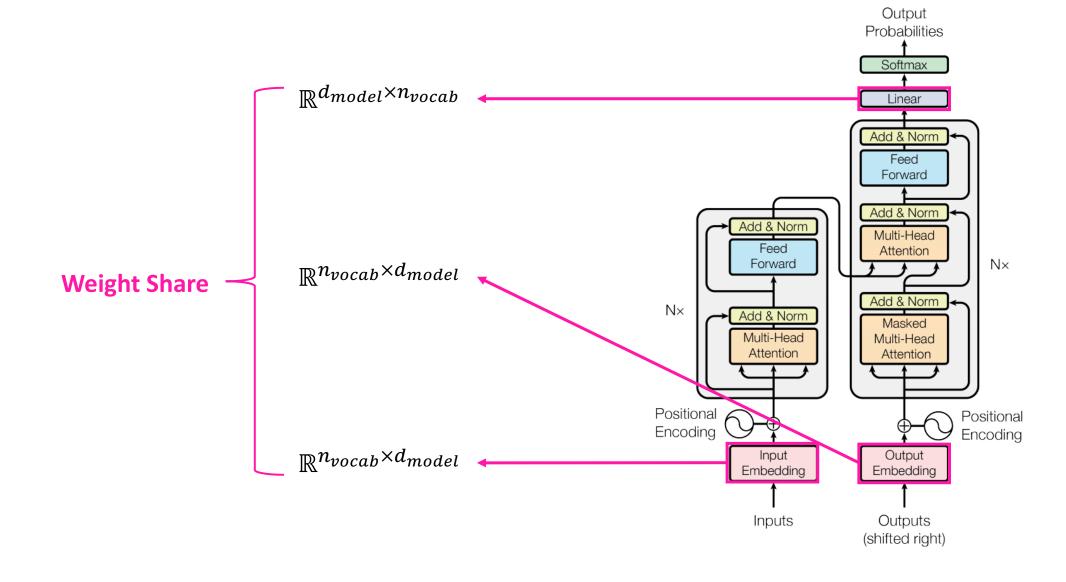




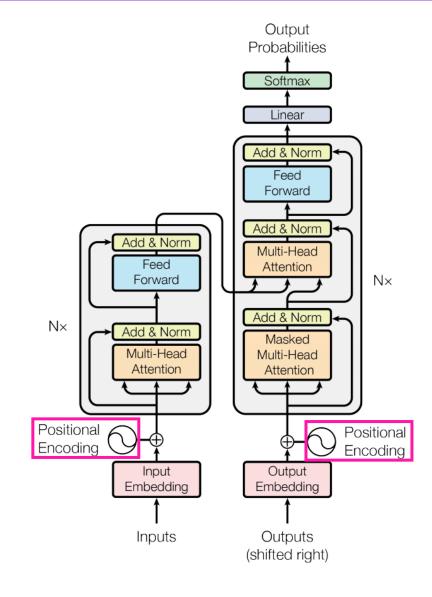
# **Embedding**

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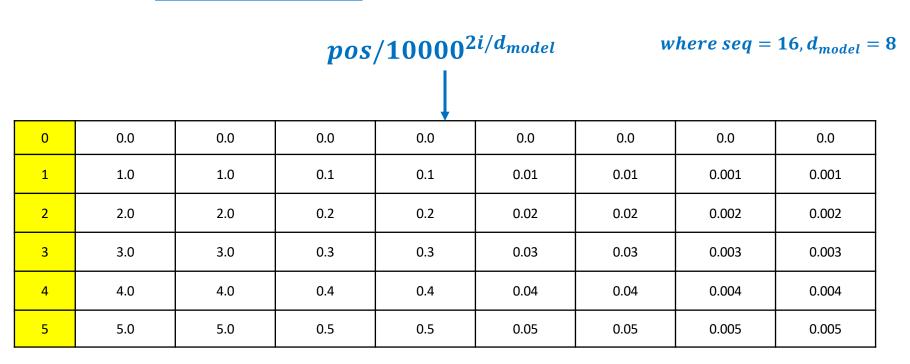


$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$
  
 $PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$ 





$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$
 $PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$ 

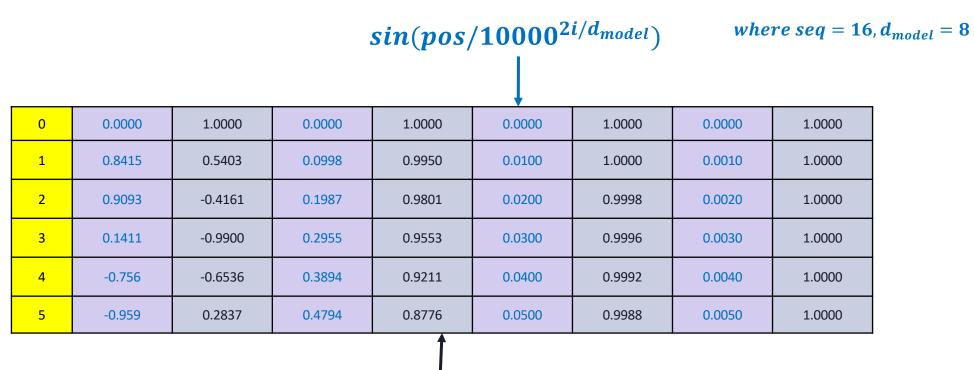


## Embedding - Positional Encoding



$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$

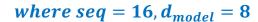
$$PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$$

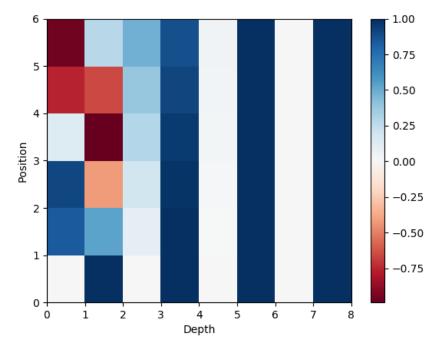


 $\cos(pos/10000^{2i/d_{model}})$ 

$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$

$$PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$$



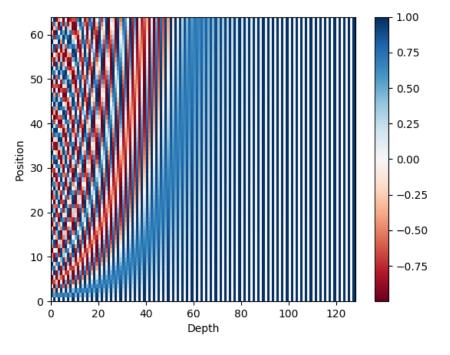


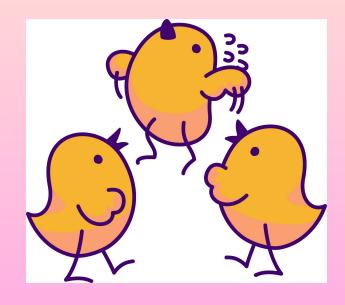
# Embedding - Positional Encoding

$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$

$$PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$$

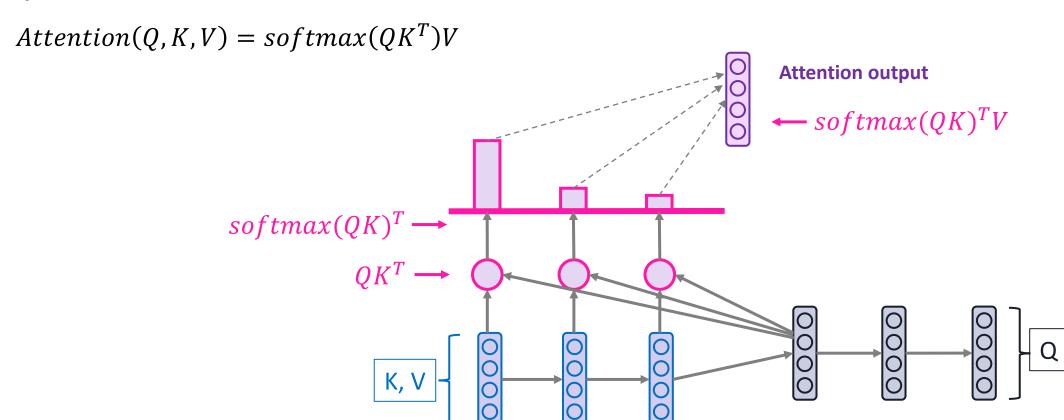






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#### **Dot-product Attention**





#### **Dot-product Attention**

 $Attention(Q, K, V) = softmax(QK^T)V$ 

- $Q \in \mathbb{R}^{|Q| \times d_k}$
- $K \in \mathbb{R}^{|K| \times d_k}$
- $V \in \mathbb{R}^{|K| \times d_v}$
- $QK^T = [|Q| \times d_k] \times [d_k \times |K|]$

#### **Problem of Dot-product Attention**

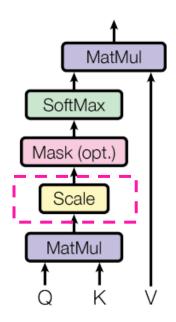
- $d_k$ 가 커지면  $QK^T$ 의 결과값의 편차가 커짐
- $softmax(QK^T)$ 의 결과 값이 편차가 커짐
- Gradient가 작아짐
- 학습이 잘 안됨



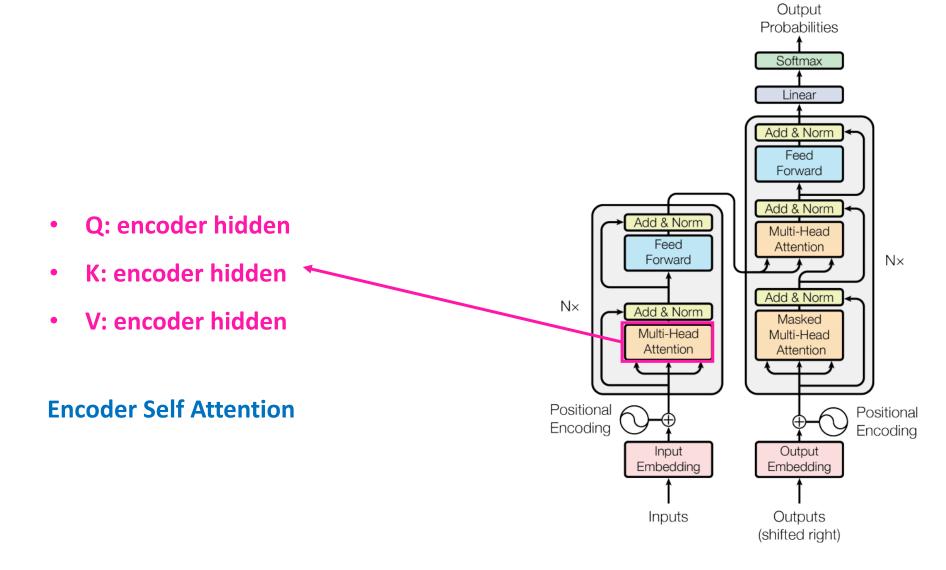
$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$

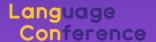
- $QK^T$ 의 결과를  $\sqrt{d_k}$ 로 나눔
- 값의 편차가 줄어듬

$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$



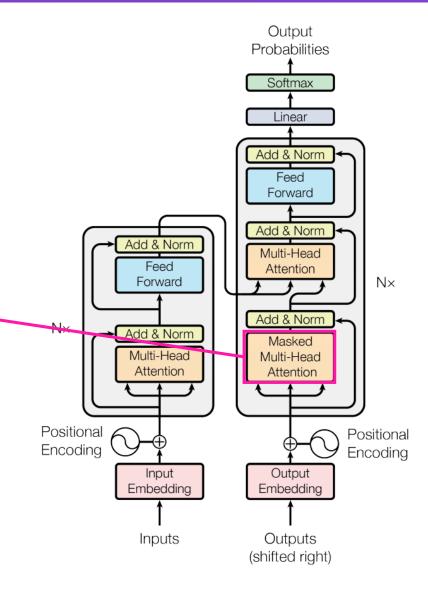




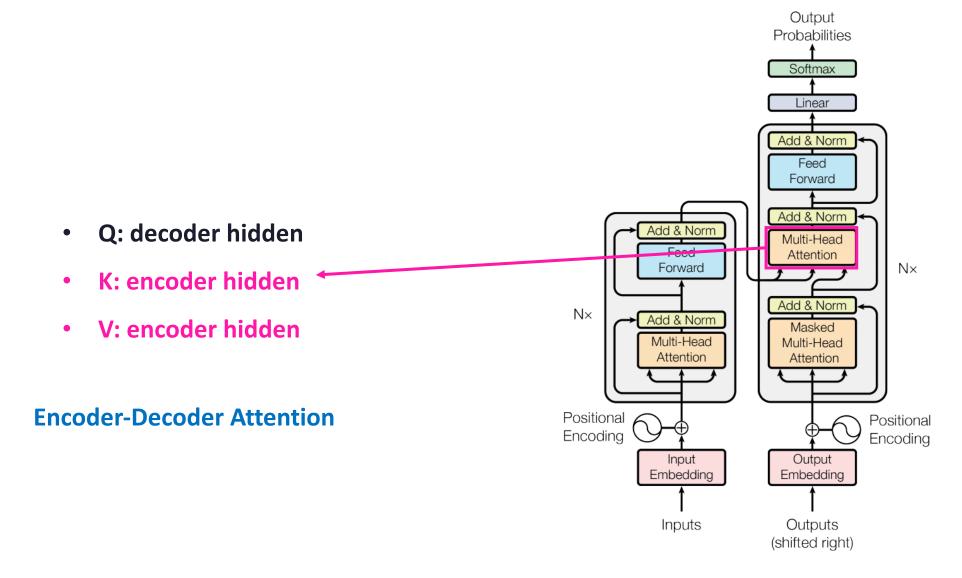


- Q: decoder hidden
- K: decoder hidden
- V: decoder hidden

**Decoder Self Attention (masked)** 

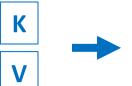








$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$



Education	0.1	0.2	0.3	0.4
is	0.2	0.3	0.4	0.5
most	0.3	0.4	0.5	0.6
powerful	0.4	0.3	0.2	0.1
weapon	0.5	0.4	0.3	0.2
[pad]	0.1	0.1	0.1	0.1



교육은	0.1	0.2	0.3	0.4
가장	0.2	0.3	0.4	0.5
중요한	0.3	0.4	0.5	0.6
무기이다	0.4	0.3	0.2	0.1
[pad]	0.1	0.1	0.1	0.1

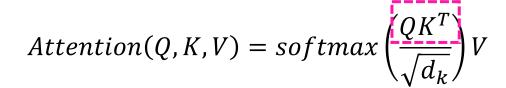
 $[seq_K \times d_{model}]$ 

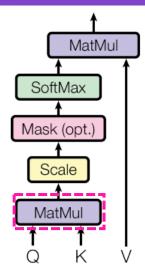
- $seq_K$ : 6
- $d_{model}$ : 4

 $[seq_Q \times d_{model}]$ 

- $seq_Q$ : 5
- $d_{model}$ : 4





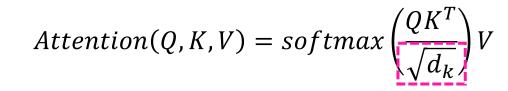


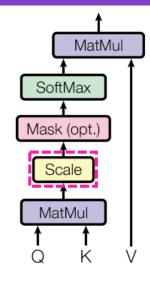


	Education	is	most	powerful	weapon	[pad]
교육은	0.3	0.4	0.5	0.2	0.3	0.1
가장	0.4	0.54	0.68	0.3	0.44	0.14
중요한	0.5	0.68	0.86	0.4	0.58	0.18
무기이다	0.2	0.3	0.4	0.3	0.4	0.1
[pad]	0.1	0.14	0.18	0.1	0.14	0.04

$$[seq_Q \times d_{model}] \times [d_{model} \times seq_K] = [seq_Q \times seq_K]$$





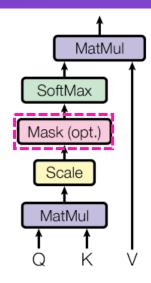


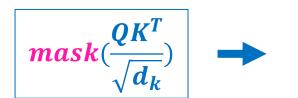


	Education	is	most	powerful	weapon	[pad]
교육은	0.15	0.2	0.25	0.1	0.15	0.05
가장	0.2	0.27	0.34	0.15	0.22	0.07
중요한	0.25	0.34	0.43	0.2	0.29	0.09
무기이다	0.1	0.15	0.2	0.15	0.2	0.05
[pad]	0.05	0.07	0.09	0.05	0.07	0.02



$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$

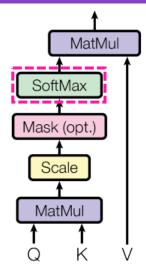




	Education	is	most	powerful	weapon	[pad]
교육은	0.15	0.2	0.25	0.1	0.15	-inf
가장	0.2	0.27	0.34	0.15	0.22	-inf
중요한	0.25	0.34	0.43	0.2	0.29	-inf
무기이다	0.1	0.15	0.2	0.15	0.2	-inf
[pad]	0.05	0.07	0.09	0.05	0.07	-inf



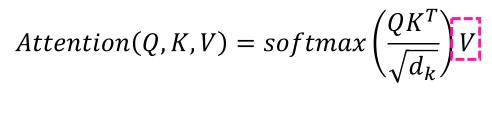
$$Attention(Q, K, V) = softmax \left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$





		Education	is	most	powerful	weapon	[pad]
교육은	<u> </u>	0.19	0.20	0.21	0.18	0.10	0
가장		0.19	0.20	0.22	0.18	0.19	0
중요현	한	0.18	0.20	0.22	0.18	0.19	0
무기이	다	0.18	0.19	0.20	0.19	0.20	0
[pad]	l	0.19	0.20	0.20	0.19	0.20	0



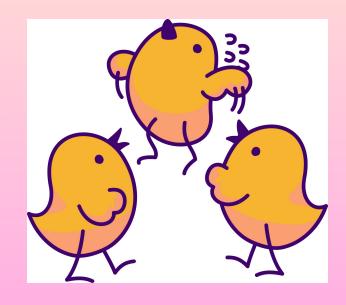


Mativial
<del></del>
SoftMax
1
Mask (opt.)
Scale
MatMul
† † V
of V

softmax	$\frac{QK^T}{\sqrt{d_k}}$ $V$	-
---------	-------------------------------	---

교육은	0.29	0.32	0.34	0.36
가장	0.29	0.32	0.34	0.37
중요한	0.29	0.32	0.34	0.37
무기이다	0.30	0.32	0.34	0.36
[pad]	0.30	0.32	0.34	0.36

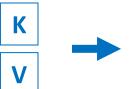
$$[seq_Q \times seq_K] \times [seq_K \times d_{model}] = [seq_Q \times d_{model}]$$



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$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$



Education	0.1	0.2	0.3	0.4
is	0.2	0.3	0.4	0.5
most	0.3	0.4	0.5	0.6
powerful	0.4	0.3	0.2	0.1
weapon	0.5	0.4	0.3	0.2
[pad]	0.1	0.1	0.1	0.1

Q -

교육은	0.1	0.2	0.3	0.4
가장	0.2	0.3	0.4	0.5
중요한	0.3	0.4	0.5	0.6
무기이다	0.4	0.3	0.2	0.1
[pad]	0.1	0.1	0.1	0.1

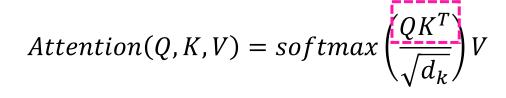
 $[seq_K \times d_{model}]$ 

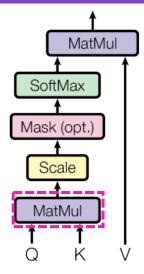
- $seq_K$ : 6
- $d_{model}$ : 4

 $[seq_Q \times d_{model}]$ 

- $seq_Q$ : 5
- $d_{model}$ : 4





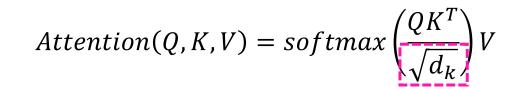


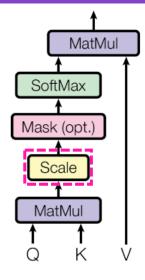


	Education	is	most	powerful	weapon	[pad]
교육은	0.3	0.4	0.5	0.2	0.3	0.1
가장	0.4	0.54	0.68	0.3	0.44	0.14
중요한	0.5	0.68	0.86	0.4	0.58	0.18
무기이다	0.2	0.3	0.4	0.3	0.4	0.1
[pad]	0.1	0.14	0.18	0.1	0.14	0.04

$$[seq_Q \times d_{model}] \times [d_{model} \times seq_K] = [seq_Q \times seq_K]$$



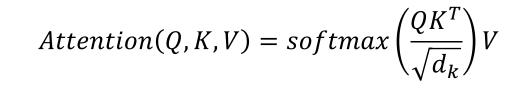


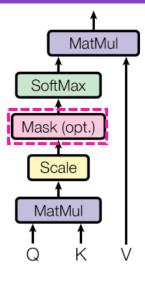




		Education	is	most	powerful	weapon	[pad]
	교육은	0.15	0.2	0.25	0.1	0.15	0.05
	가장	0.2	0.27	0.34	0.15	0.22	0.07
	중요한	0.25	0.34	0.43	0.2	0.29	0.09
	무기이다	0.1	0.15	0.2	0.15	0.2	0.05
	[pad]	0.05	0.07	0.09	0.05	0.07	0.02







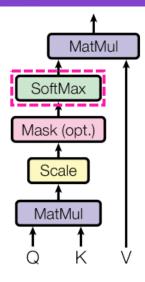


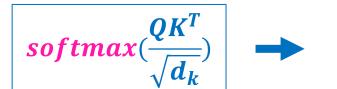
	Education	is	most	powerful	weapon	[pad]
교육은	0.15	-inf	-inf	-inf	-inf	-inf
가장	0.2	0.27	-inf	-inf	-inf	-inf
중요한	0.25	0.34	0.43	-inf	-inf	-inf
무기이다	0.1	0.15	0.2	0.15	-inf	-inf
[pad]	0.05	0.07	0.09	0.05	0.07	-inf

—— Can't see next value



$$Attention(Q, K, V) = softmax \left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$





	Education	is	most	powerful	weapon	[pad]
교육은	1.00	0	0	0	0	0
가장	0.48	0.51	0	0	0	0
중요한	0.30	0.33	0.36	0	0	0
무기이다	0.23	0.24	0.26	0.24	0	0
[pad]	0.19	0.20	0.20	0.19	0.20	0

교육은

가장

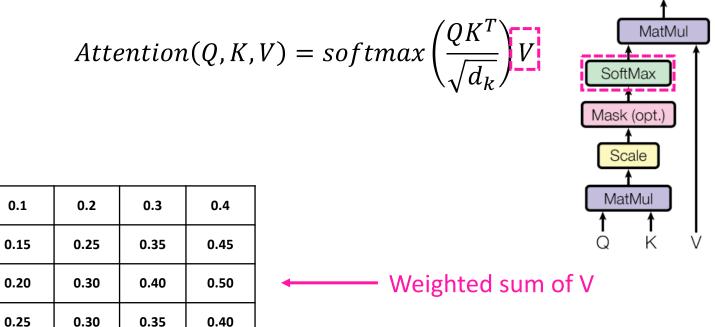
중요한

무기이다

[pad]

0.30





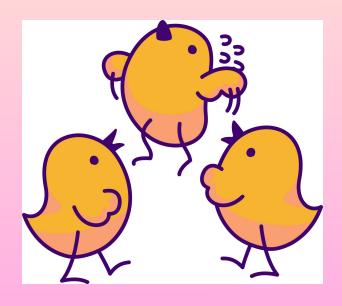


$seq_0 \times seq_K$	$] \times [seq_K \times d_{mo}]$	$_{del}] = [se$	$q_0 \times d_{model}$

0.32

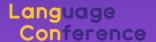
0.34

0.36

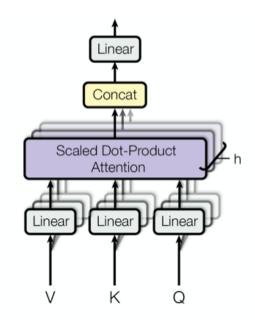


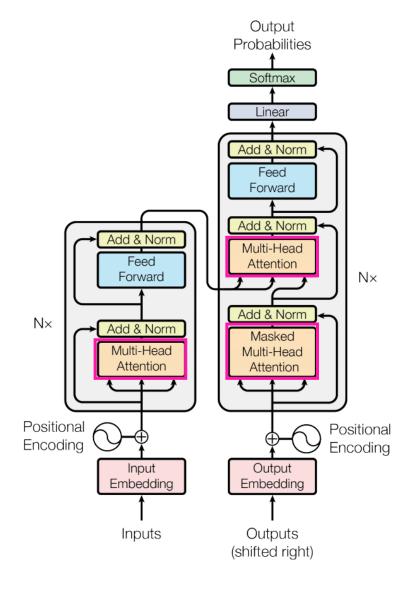
# Multi-Head Attention

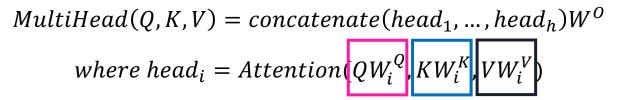
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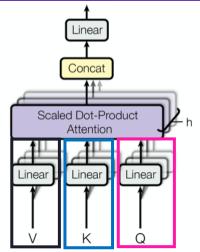


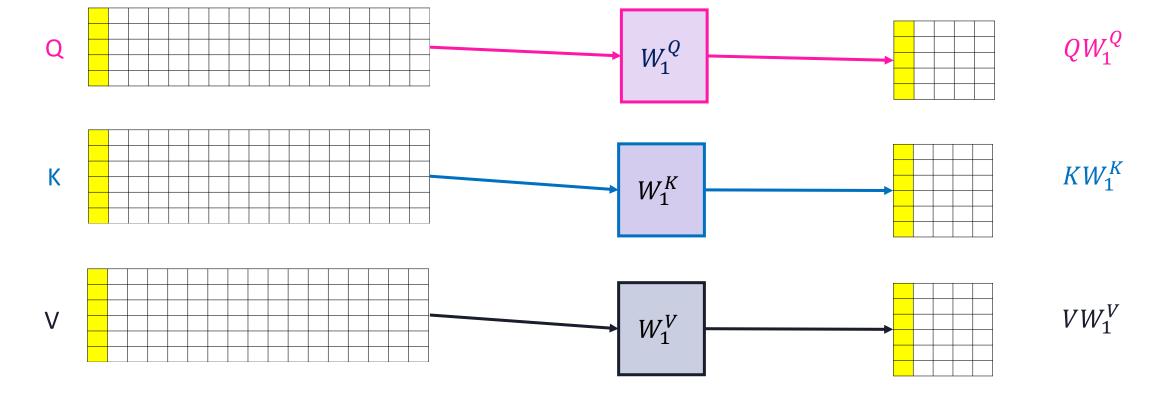
 $MultiHead(Q, K, V) = concatenate(head_1, ..., head_h)W^O$  $where\ head_i = Attention(QW_i^Q, KW_i^K, VW_i^V)$ 

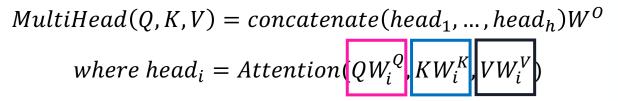


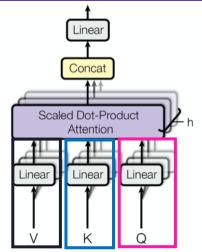


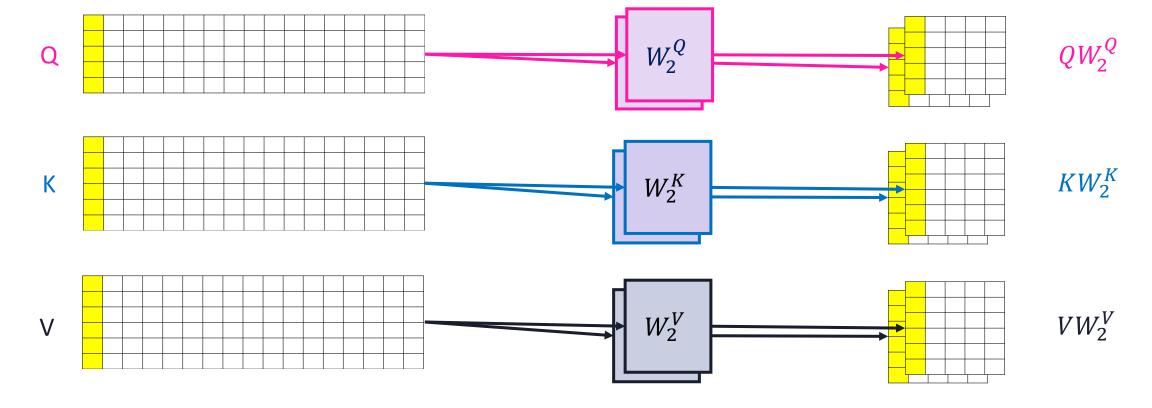


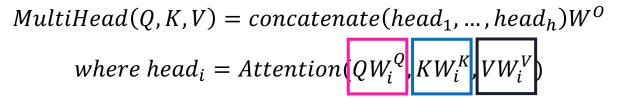


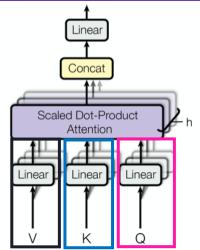


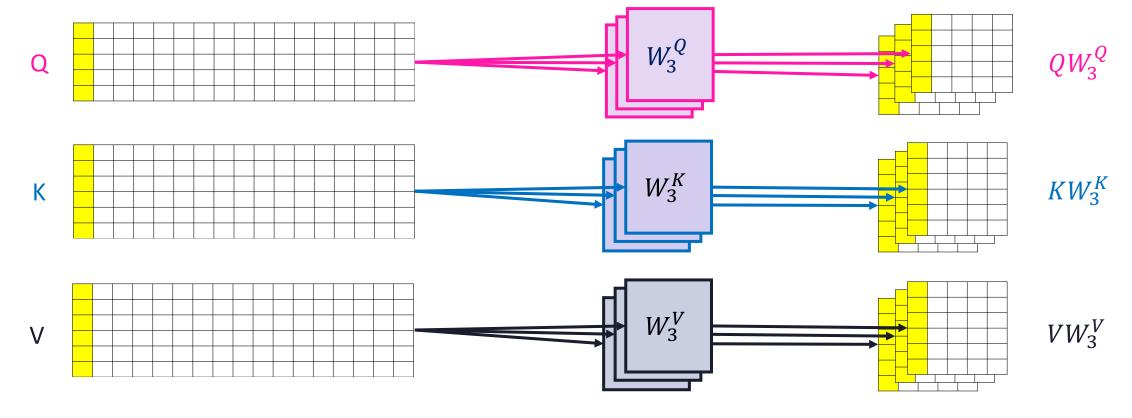


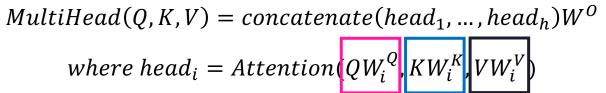




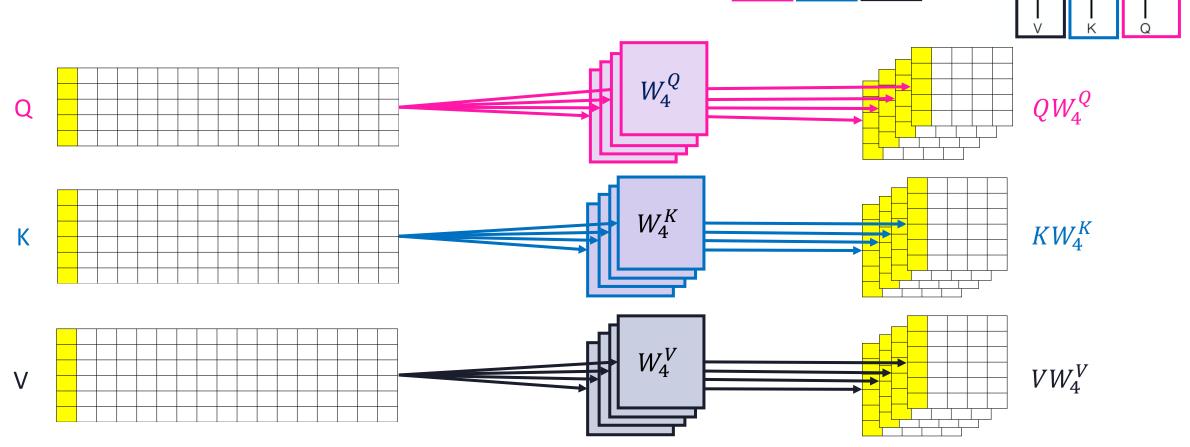


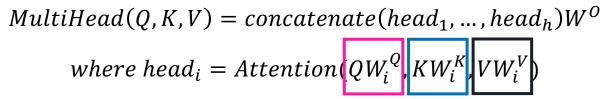


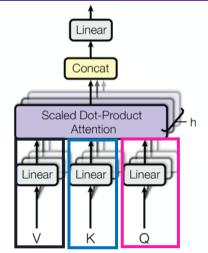


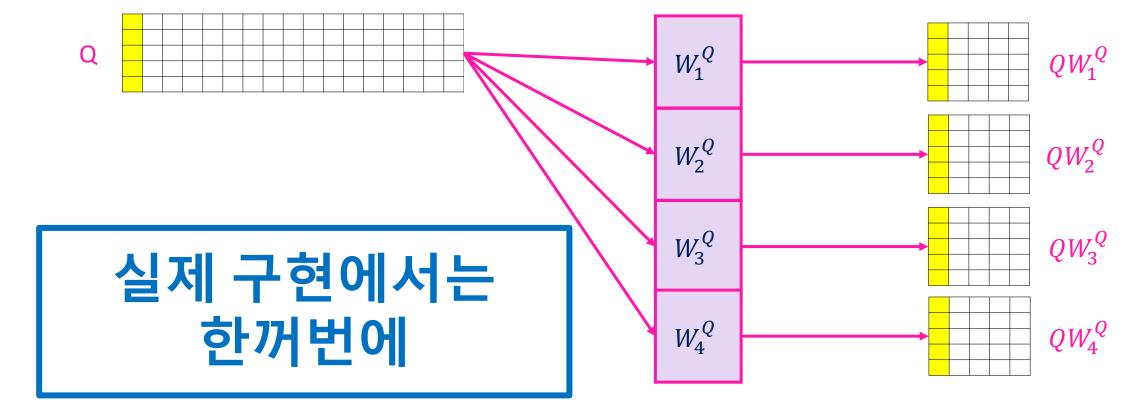


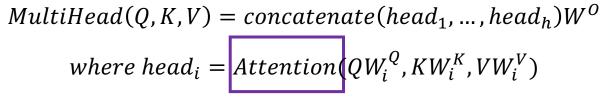
Scaled Dot-Product

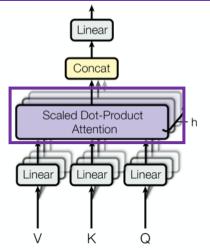




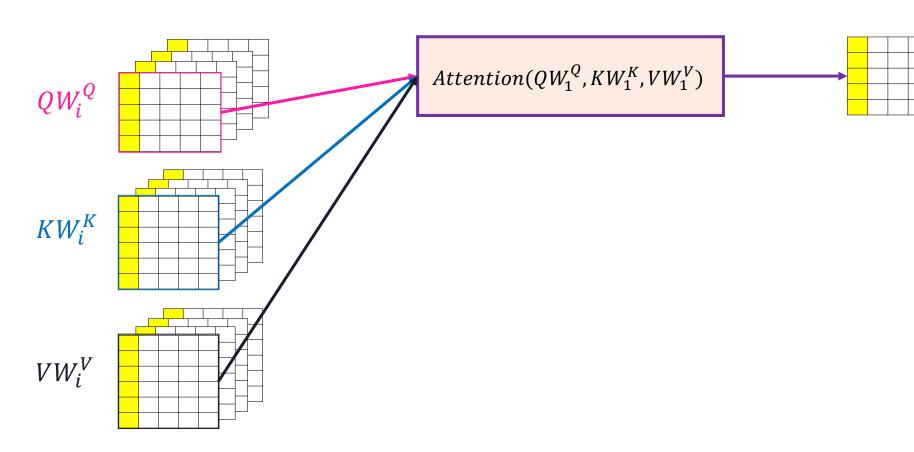




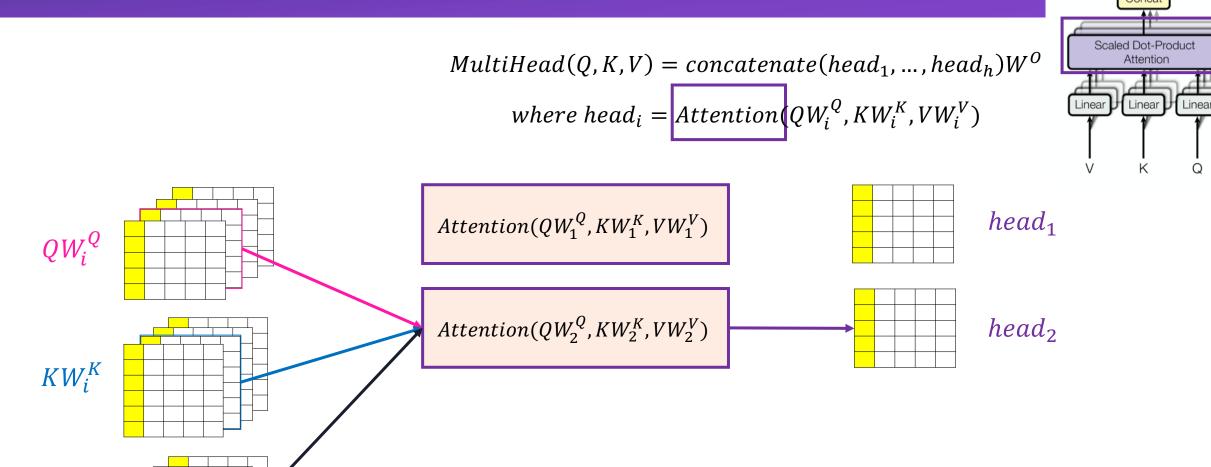


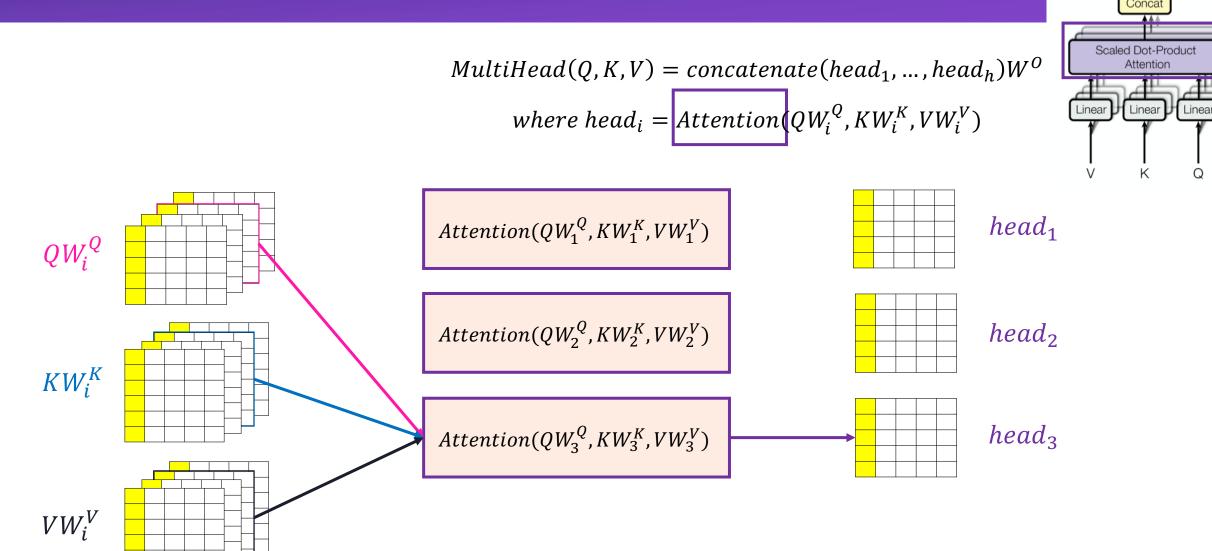


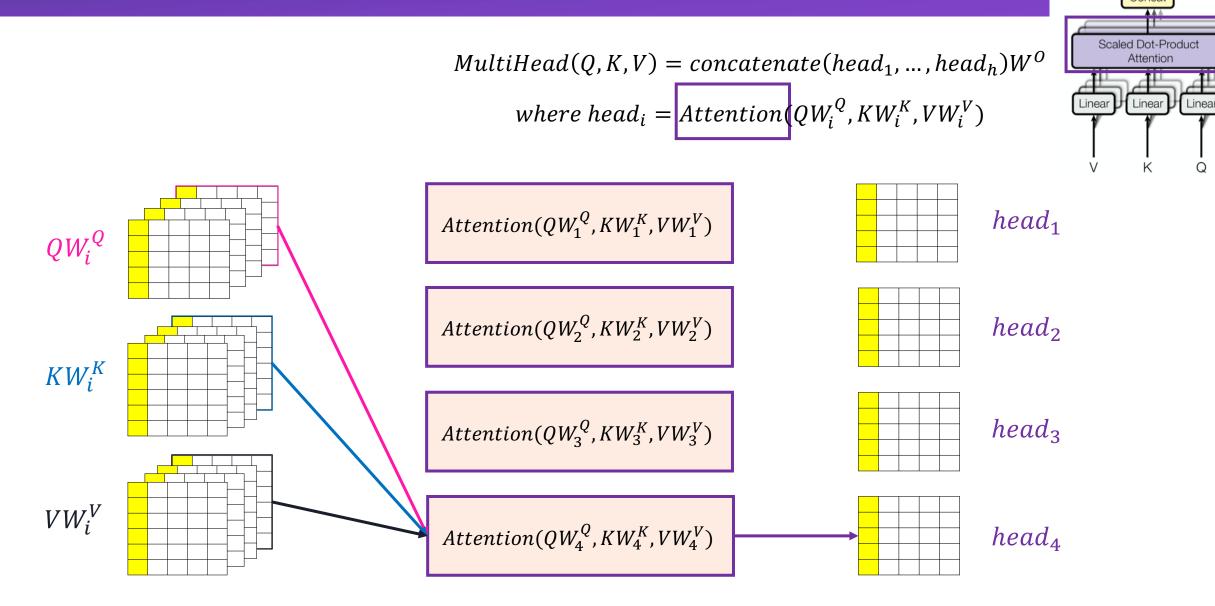
 $head_1$ 

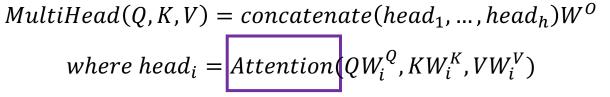


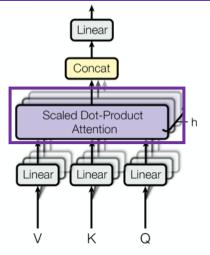
 $VW_i^V$ 

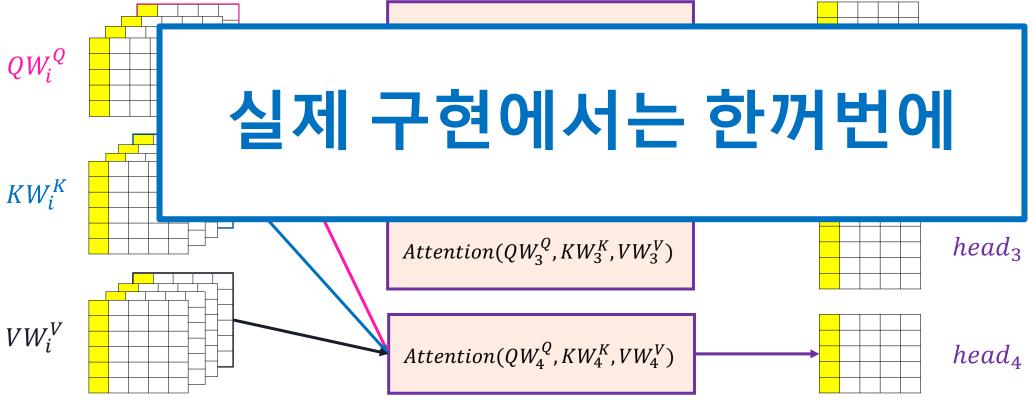


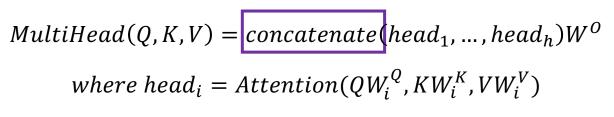


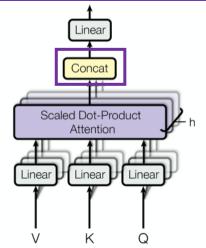


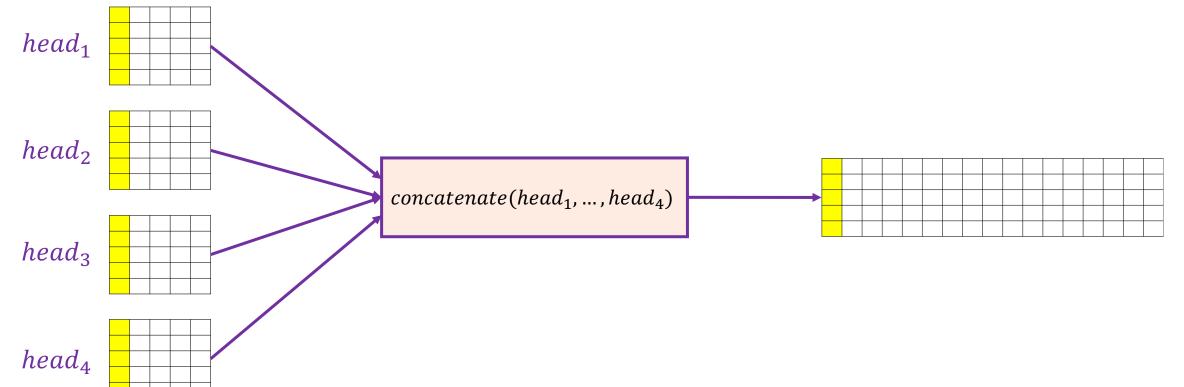


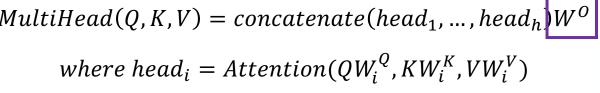












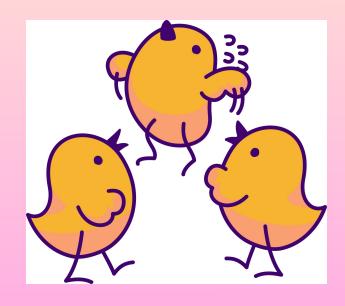
Scaled Dot-Product

Attention

 $MultiHead(Q, K, V) = concatenate(head_1, ..., head_h)W^O$ 

 $concatenate(head_1, ..., head_4)$ 





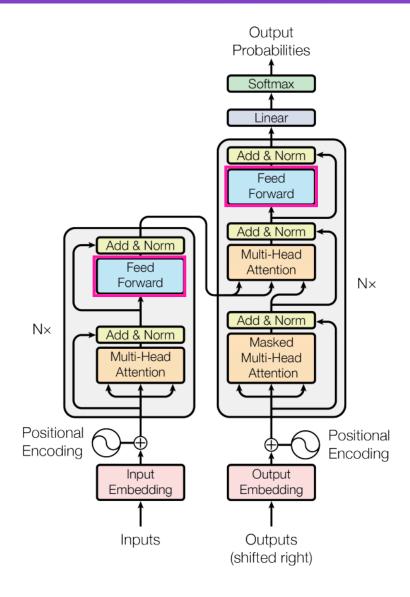
# Position-wise Feed-Forward Network

LangCon 2020

### Position-wise Feed-Forward Network



$$FFN(x) = \max(0, xW_1 + b_1)W_2 + b_2$$





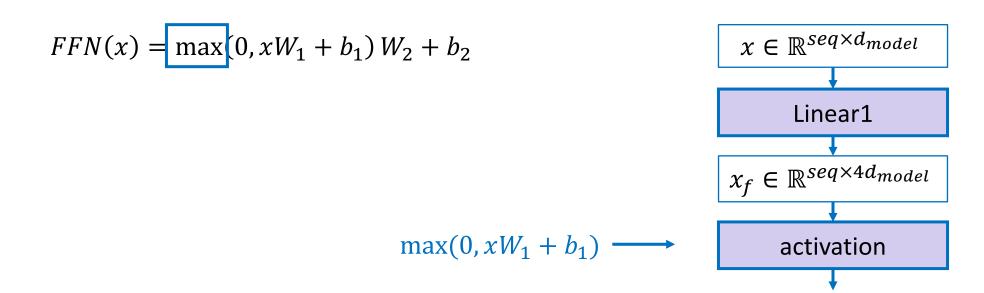
$$FFN(x) = \max(0, xW_1 + b_1) W_2 + b_2$$

$$xW_1 + b_1 \longrightarrow xW_1 + b_1$$

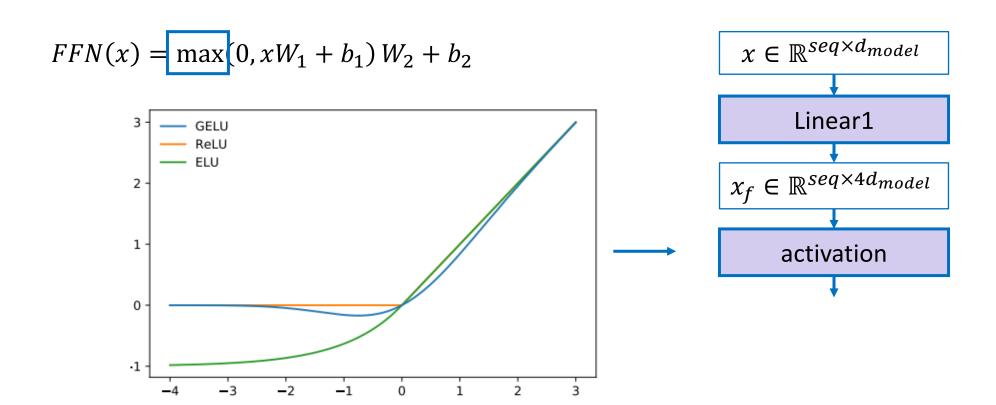
$$xW_1 + b_1 \longrightarrow x_f \in \mathbb{R}^{seq \times 4d_{model}}$$

### Position-wise Feed-Forward Network

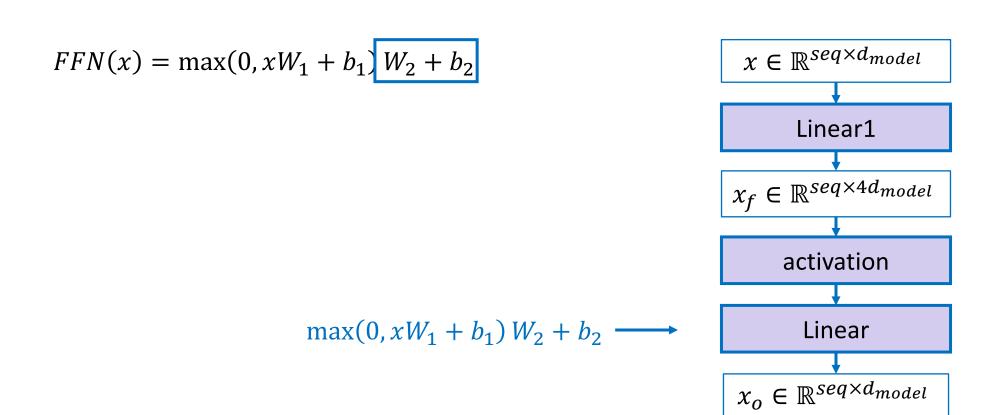


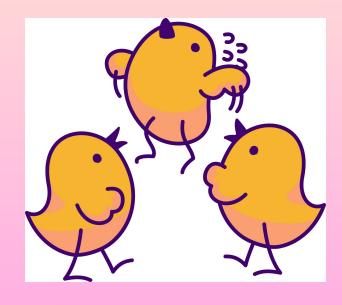












# Reference

#### Reference



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• CS224n - Machine Translation, Seq2Seq and Attention:

http://web.stanford.edu/class/cs224n/slides/cs224n-2020-lecture08-nmt.pdf

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 <a href="https://github.com/yandexdataschool/nlp\_course/blob/2019/resources/slides/nlp19\_04\_seq2seq\_attention.pdf">https://github.com/yandexdataschool/nlp\_course/blob/2019/resources/slides/nlp19\_04\_seq2seq\_attention.pdf</a>

Learning Spoons - Attention :

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