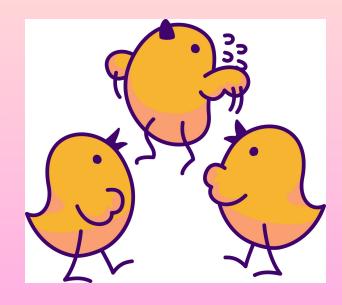


Transformer 구현하기

현청천 / cchyun@gmail.com



- 1. Why Transformer
- 2. Embedding
 - 1. Weight Shared Embedding
 - 2. Positional Encoding
- 3. Scaled Dot-Product Attention
- 4. Scaled Dot-Product Attention (masked)
- 5. Multi-Head Attention
- 6. Position-wise Feed-Forward Network
- 7. Reference

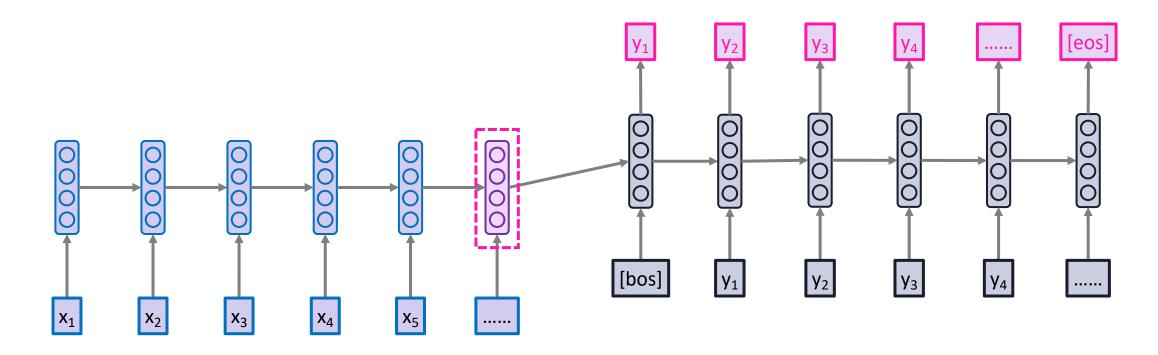


Why Transformer

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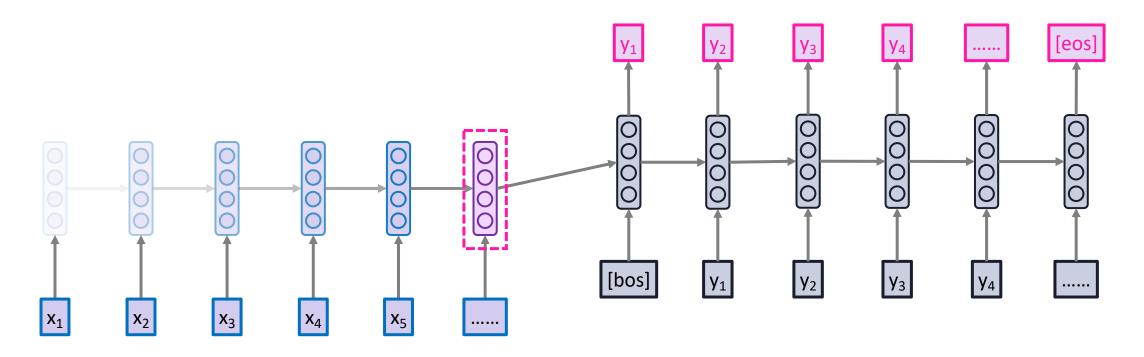
Source Sentence Encoding

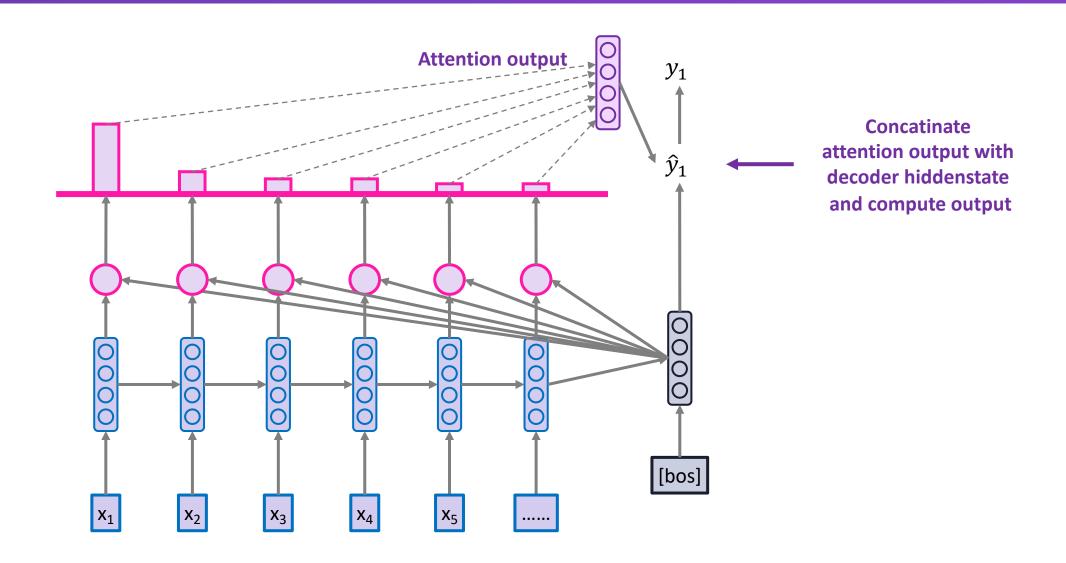
Source Sentence의 모든 정보를 저장 해야 함 (Information bottleneck)



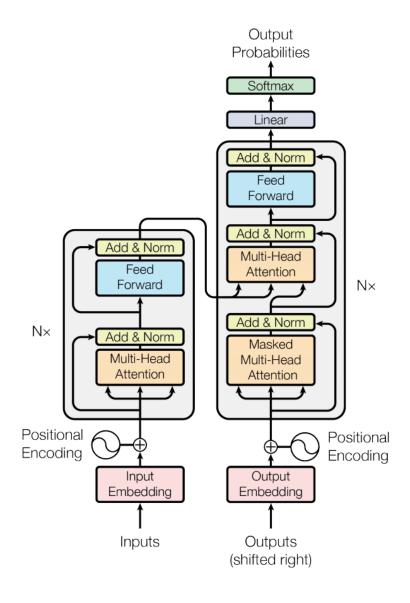
Source Sentence Encoding

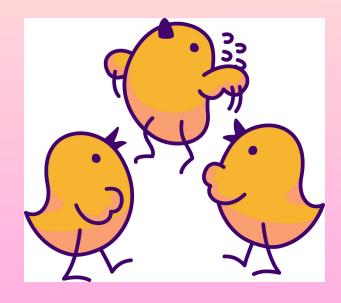
과거 step의 정보는 최신 step의 보다 덜 사용 됨(Vanishing Gradient)





Why Transformer (Transformer)

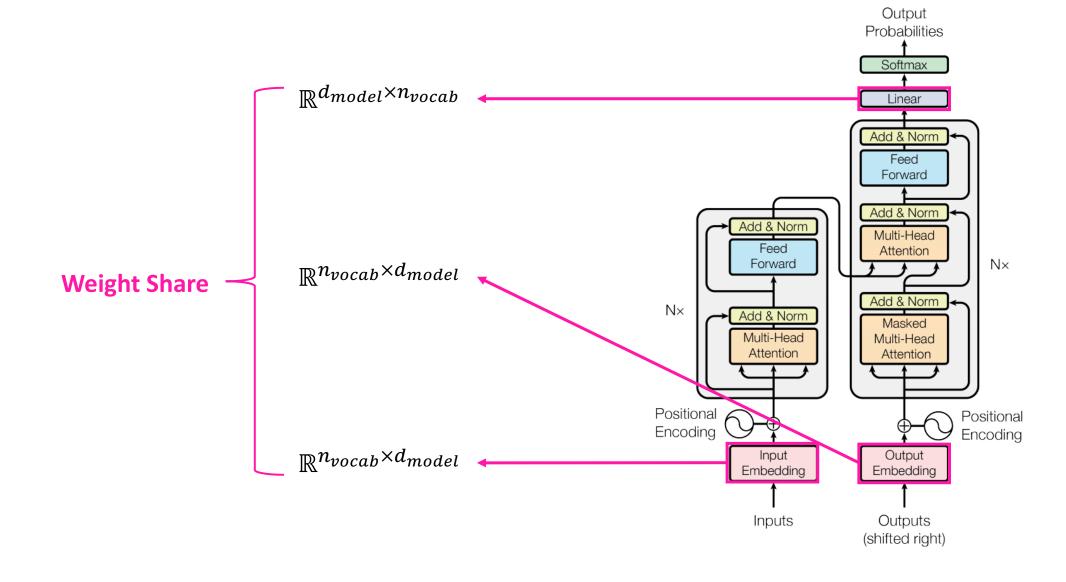




Embedding

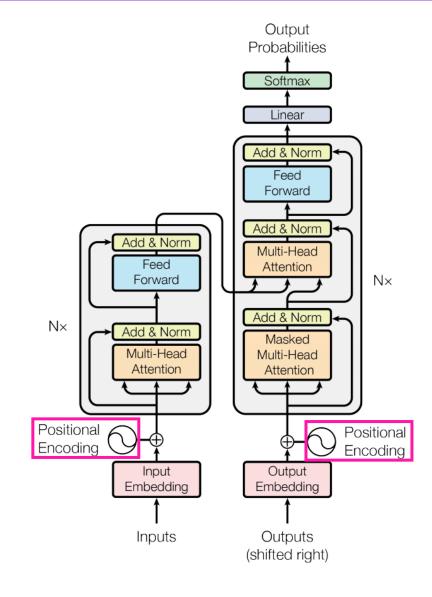
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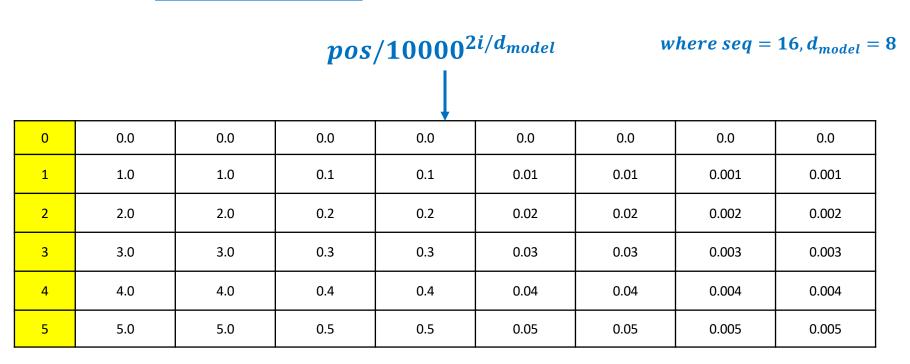
$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$

 $PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$



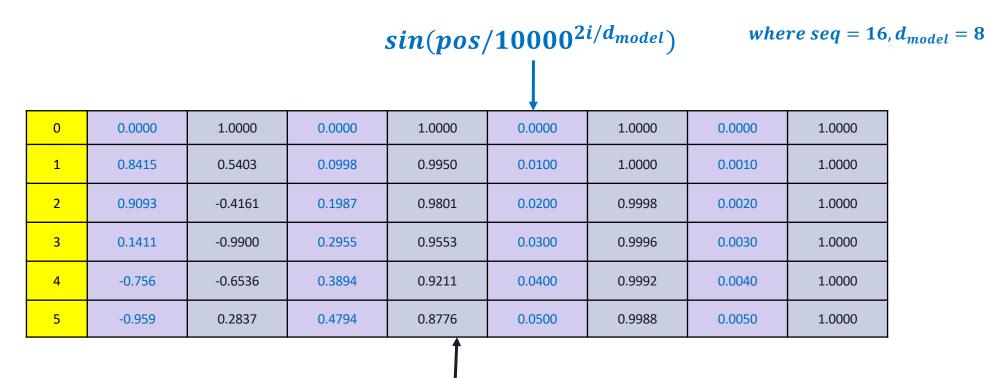


$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$
 $PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$



$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$

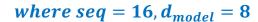
$$PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$$

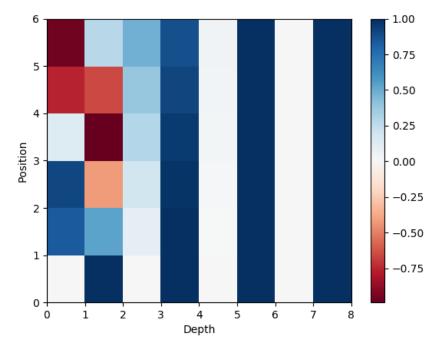


 $\cos(pos/10000^{2i/d_{model}})$

$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$

$$PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$$



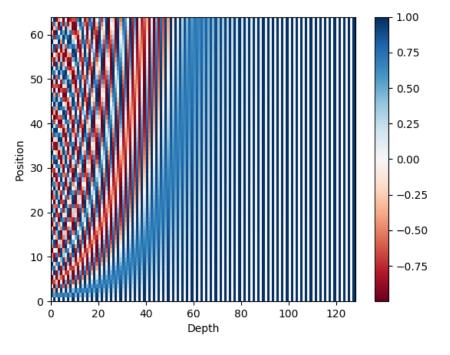


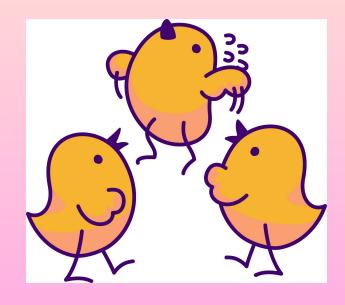
Embedding - Positional Encoding

$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$

$$PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$$

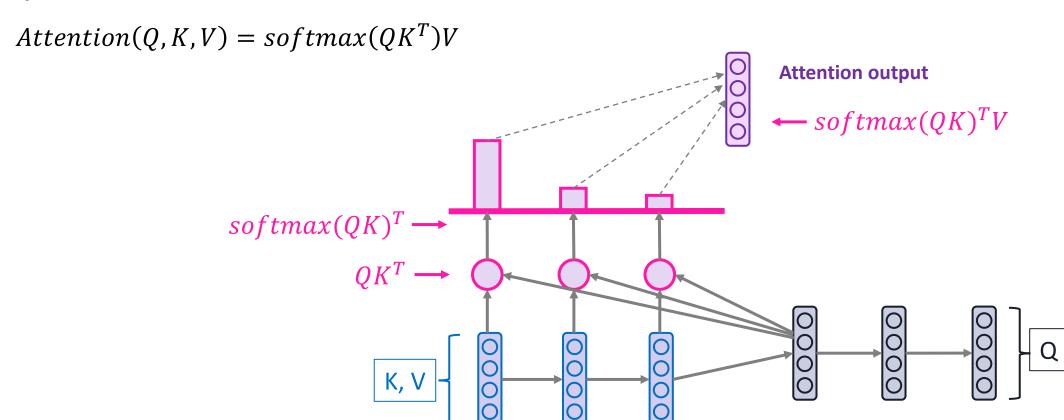






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Dot-product Attention





Dot-product Attention

 $Attention(Q, K, V) = softmax(QK^T)V$

- $Q \in \mathbb{R}^{|Q| \times d_k}$
- $K \in \mathbb{R}^{|K| \times d_k}$
- $V \in \mathbb{R}^{|K| \times d_v}$
- $QK^T = [|Q| \times d_k] \times [d_k \times |K|]$

Problem of Dot-product Attention

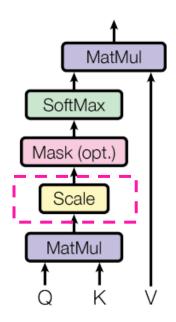
- d_k 가 커지면 QK^T 의 결과값의 편차가 커짐
- $softmax(QK^T)$ 의 결과 값이 편차가 커짐
- Gradient가 작아짐
- 학습이 잘 안됨



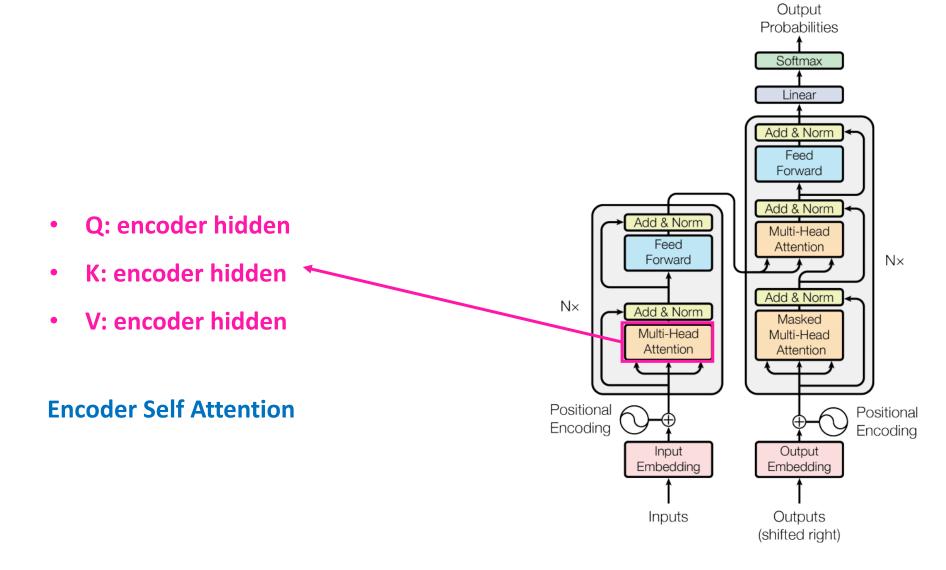
$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$

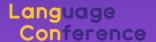
- QK^T 의 결과를 $\sqrt{d_k}$ 로 나눔
- 값의 편차가 줄어듬

$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$



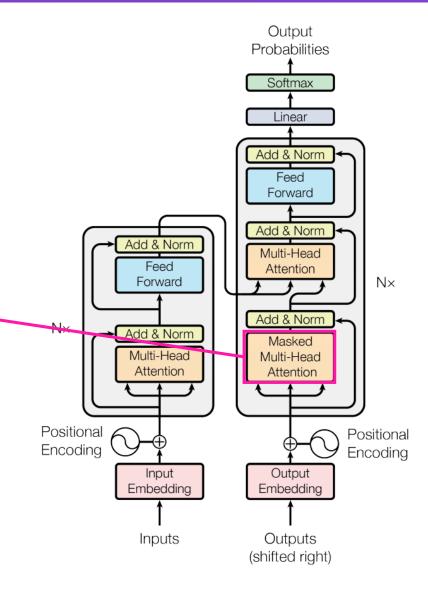




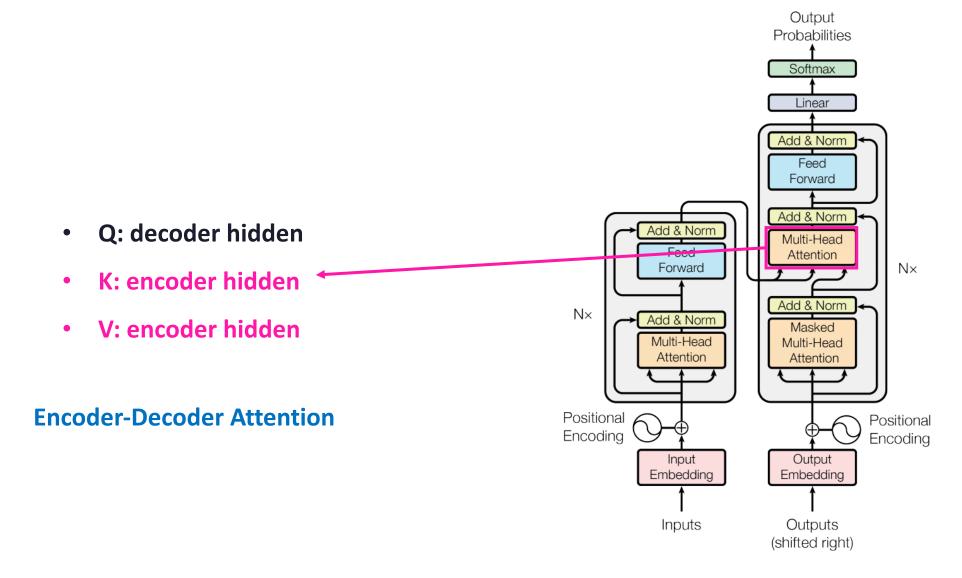


- Q: decoder hidden
- K: decoder hidden
- V: decoder hidden

Decoder Self Attention (masked)

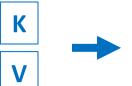








$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$



| Education | 0.1 | 0.2 | 0.3 | 0.4 |
|-----------|-----|-----|-----|-----|
| is | 0.2 | 0.3 | 0.4 | 0.5 |
| most | 0.3 | 0.4 | 0.5 | 0.6 |
| powerful | 0.4 | 0.3 | 0.2 | 0.1 |
| weapon | 0.5 | 0.4 | 0.3 | 0.2 |
| [pad] | 0.1 | 0.1 | 0.1 | 0.1 |



| 교육은 | 0.1 | 0.2 | 0.3 | 0.4 |
|-------|-----|-----|-----|-----|
| 가장 | 0.2 | 0.3 | 0.4 | 0.5 |
| 중요한 | 0.3 | 0.4 | 0.5 | 0.6 |
| 무기이다 | 0.4 | 0.3 | 0.2 | 0.1 |
| [pad] | 0.1 | 0.1 | 0.1 | 0.1 |

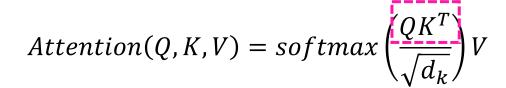
 $[seq_K \times d_{model}]$

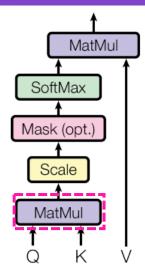
- seq_K : 6
- d_{model} : 4

 $[seq_Q \times d_{model}]$

- seq_Q : 5
- d_{model} : 4





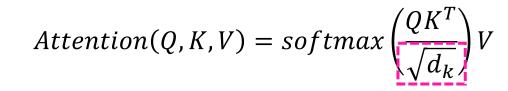


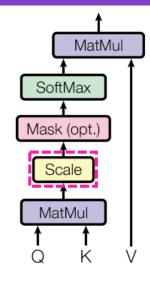


| | Education | is | most | powerful | weapon | [pad] |
|-------|-----------|------|------|----------|--------|-------|
| 교육은 | 0.3 | 0.4 | 0.5 | 0.2 | 0.3 | 0.1 |
| 가장 | 0.4 | 0.54 | 0.68 | 0.3 | 0.44 | 0.14 |
| 중요한 | 0.5 | 0.68 | 0.86 | 0.4 | 0.58 | 0.18 |
| 무기이다 | 0.2 | 0.3 | 0.4 | 0.3 | 0.4 | 0.1 |
| [pad] | 0.1 | 0.14 | 0.18 | 0.1 | 0.14 | 0.04 |

$$[seq_Q \times d_{model}] \times [d_{model} \times seq_K] = [seq_Q \times seq_K]$$





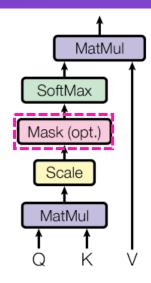


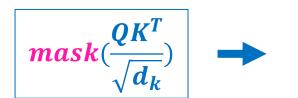


| | Education | is | most | powerful | weapon | [pad] |
|-------|-----------|------|------|----------|--------|-------|
| 교육은 | 0.15 | 0.2 | 0.25 | 0.1 | 0.15 | 0.05 |
| 가장 | 0.2 | 0.27 | 0.34 | 0.15 | 0.22 | 0.07 |
| 중요한 | 0.25 | 0.34 | 0.43 | 0.2 | 0.29 | 0.09 |
| 무기이다 | 0.1 | 0.15 | 0.2 | 0.15 | 0.2 | 0.05 |
| [pad] | 0.05 | 0.07 | 0.09 | 0.05 | 0.07 | 0.02 |



$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$

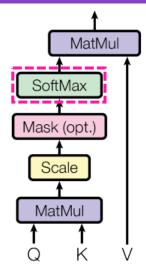




| | Education | is | most | powerful | weapon | [pad] |
|-------|-----------|------|------|----------|--------|-------|
| 교육은 | 0.15 | 0.2 | 0.25 | 0.1 | 0.15 | -inf |
| 가장 | 0.2 | 0.27 | 0.34 | 0.15 | 0.22 | -inf |
| 중요한 | 0.25 | 0.34 | 0.43 | 0.2 | 0.29 | -inf |
| 무기이다 | 0.1 | 0.15 | 0.2 | 0.15 | 0.2 | -inf |
| [pad] | 0.05 | 0.07 | 0.09 | 0.05 | 0.07 | -inf |



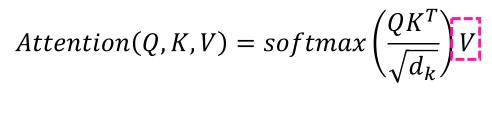
$$Attention(Q, K, V) = softmax \left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$





| | | Education | is | most | powerful | weapon | [pad] |
|-------|----------|-----------|------|------|----------|--------|-------|
| 교육은 | <u> </u> | 0.19 | 0.20 | 0.21 | 0.18 | 0.10 | 0 |
| 가장 | | 0.19 | 0.20 | 0.22 | 0.18 | 0.19 | 0 |
| 중요현 | 한 | 0.18 | 0.20 | 0.22 | 0.18 | 0.19 | 0 |
| 무기이 | 다 | 0.18 | 0.19 | 0.20 | 0.19 | 0.20 | 0 |
| [pad] | l | 0.19 | 0.20 | 0.20 | 0.19 | 0.20 | 0 |



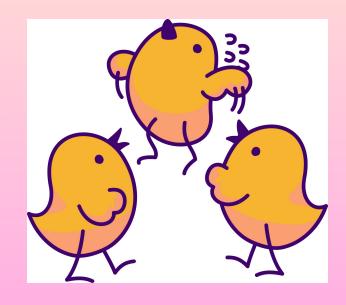


| Mativial |
|-------------|
| |
| SoftMax |
| 1 |
| Mask (opt.) |
| Scale |
| MatMul |
| † † V |
| of V |

| softmax | $\frac{QK^T}{\sqrt{d_k}}$ V | - |
|---------|-------------------------------|---|
|---------|-------------------------------|---|

| 교육은 | 0.29 | 0.32 | 0.34 | 0.36 |
|-------|------|------|------|------|
| 가장 | 0.29 | 0.32 | 0.34 | 0.37 |
| 중요한 | 0.29 | 0.32 | 0.34 | 0.37 |
| 무기이다 | 0.30 | 0.32 | 0.34 | 0.36 |
| [pad] | 0.30 | 0.32 | 0.34 | 0.36 |

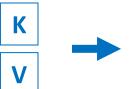
$$[seq_Q \times seq_K] \times [seq_K \times d_{model}] = [seq_Q \times d_{model}]$$



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$$Attention(Q, K, V) = softmax\left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$



| Education | 0.1 | 0.2 | 0.3 | 0.4 |
|-----------|-----|-----|-----|-----|
| is | 0.2 | 0.3 | 0.4 | 0.5 |
| most | 0.3 | 0.4 | 0.5 | 0.6 |
| powerful | 0.4 | 0.3 | 0.2 | 0.1 |
| weapon | 0.5 | 0.4 | 0.3 | 0.2 |
| [pad] | 0.1 | 0.1 | 0.1 | 0.1 |

Q -

| 교육은 | 0.1 | 0.2 | 0.3 | 0.4 |
|-------|-----|-----|-----|-----|
| 가장 | 0.2 | 0.3 | 0.4 | 0.5 |
| 중요한 | 0.3 | 0.4 | 0.5 | 0.6 |
| 무기이다 | 0.4 | 0.3 | 0.2 | 0.1 |
| [pad] | 0.1 | 0.1 | 0.1 | 0.1 |

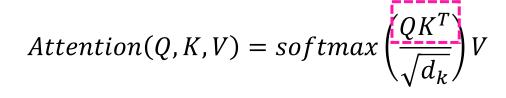
 $[seq_K \times d_{model}]$

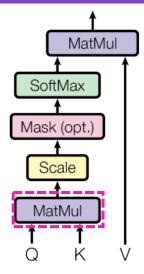
- seq_K : 6
- d_{model} : 4

 $[seq_Q \times d_{model}]$

- seq_Q : 5
- d_{model} : 4





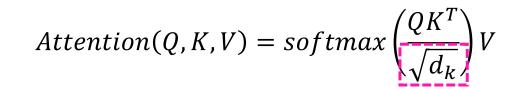


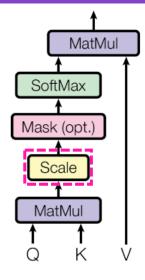


| | Education | is | most | powerful | weapon | [pad] |
|-------|-----------|------|------|----------|--------|-------|
| 교육은 | 0.3 | 0.4 | 0.5 | 0.2 | 0.3 | 0.1 |
| 가장 | 0.4 | 0.54 | 0.68 | 0.3 | 0.44 | 0.14 |
| 중요한 | 0.5 | 0.68 | 0.86 | 0.4 | 0.58 | 0.18 |
| 무기이다 | 0.2 | 0.3 | 0.4 | 0.3 | 0.4 | 0.1 |
| [pad] | 0.1 | 0.14 | 0.18 | 0.1 | 0.14 | 0.04 |

$$[seq_Q \times d_{model}] \times [d_{model} \times seq_K] = [seq_Q \times seq_K]$$



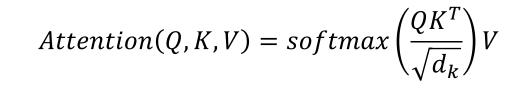


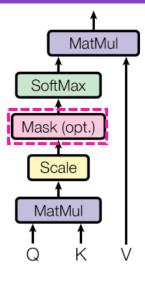




| | | Education | is | most | powerful | weapon | [pad] |
|--|-------|-----------|------|------|----------|--------|-------|
| | 교육은 | 0.15 | 0.2 | 0.25 | 0.1 | 0.15 | 0.05 |
| | 가장 | 0.2 | 0.27 | 0.34 | 0.15 | 0.22 | 0.07 |
| | 중요한 | 0.25 | 0.34 | 0.43 | 0.2 | 0.29 | 0.09 |
| | 무기이다 | 0.1 | 0.15 | 0.2 | 0.15 | 0.2 | 0.05 |
| | [pad] | 0.05 | 0.07 | 0.09 | 0.05 | 0.07 | 0.02 |







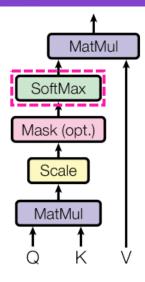


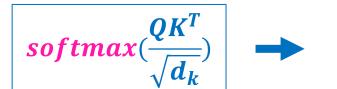
| | Education | is | most | powerful | weapon | [pad] |
|-------|-----------|------|------|----------|--------|-------|
| 교육은 | 0.15 | -inf | -inf | -inf | -inf | -inf |
| 가장 | 0.2 | 0.27 | -inf | -inf | -inf | -inf |
| 중요한 | 0.25 | 0.34 | 0.43 | -inf | -inf | -inf |
| 무기이다 | 0.1 | 0.15 | 0.2 | 0.15 | -inf | -inf |
| [pad] | 0.05 | 0.07 | 0.09 | 0.05 | 0.07 | -inf |

—— Can't see next value



$$Attention(Q, K, V) = softmax \left(\frac{QK^{T}}{\sqrt{d_{k}}}\right)V$$





| | Education | is | most | powerful | weapon | [pad] |
|-------|-----------|------|------|----------|--------|-------|
| 교육은 | 1.00 | 0 | 0 | 0 | 0 | 0 |
| 가장 | 0.48 | 0.51 | 0 | 0 | 0 | 0 |
| 중요한 | 0.30 | 0.33 | 0.36 | 0 | 0 | 0 |
| 무기이다 | 0.23 | 0.24 | 0.26 | 0.24 | 0 | 0 |
| [pad] | 0.19 | 0.20 | 0.20 | 0.19 | 0.20 | 0 |

교육은

가장

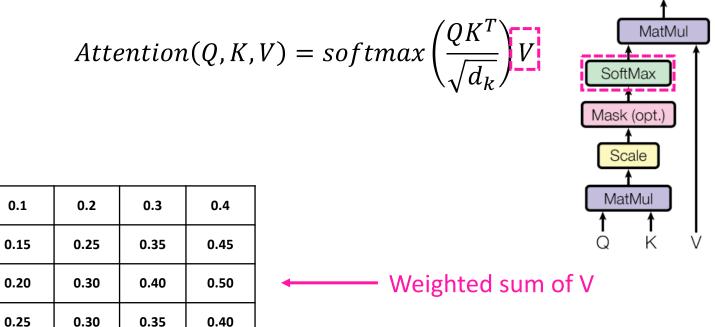
중요한

무기이다

[pad]

0.30





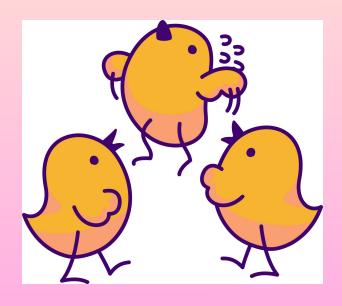


| $seq_0 \times seq_K$ | $] \times [seq_K \times d_{mo}]$ | $_{del}] = [se$ | $q_0 \times d_{model}$ |
|----------------------|----------------------------------|-----------------|------------------------|

0.32

0.34

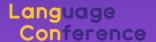
0.36



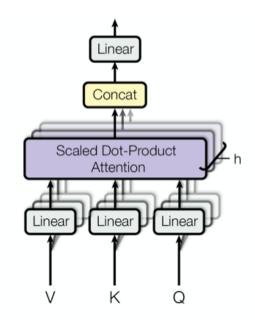
Multi-Head Attention

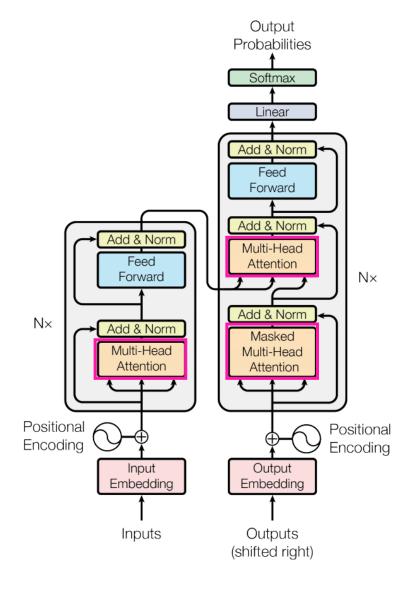
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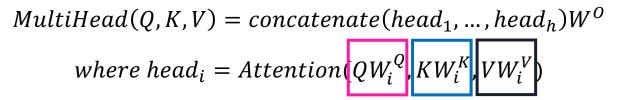
Multi-Head Attention

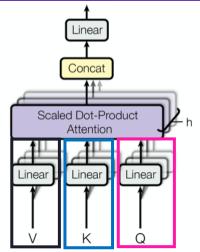


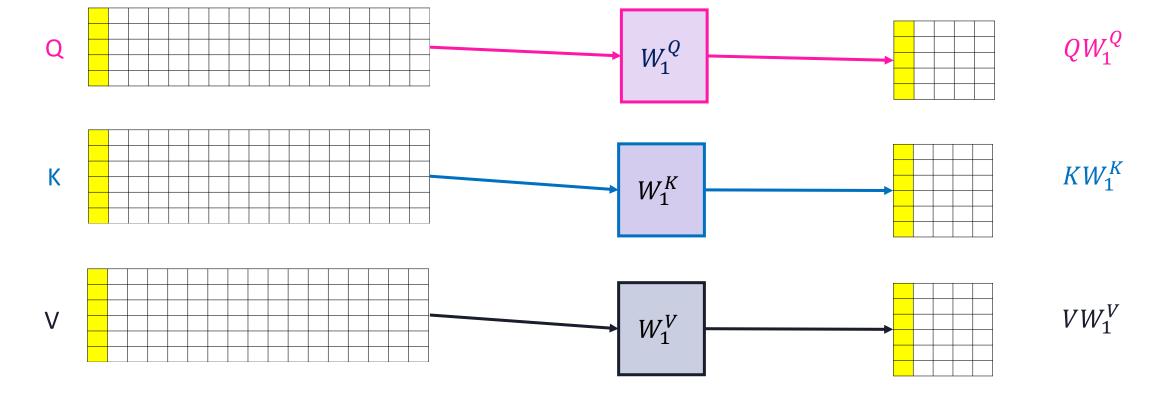
 $MultiHead(Q, K, V) = concatenate(head_1, ..., head_h)W^O$ $where\ head_i = Attention(QW_i^Q, KW_i^K, VW_i^V)$

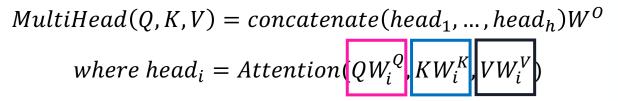


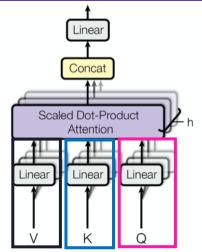


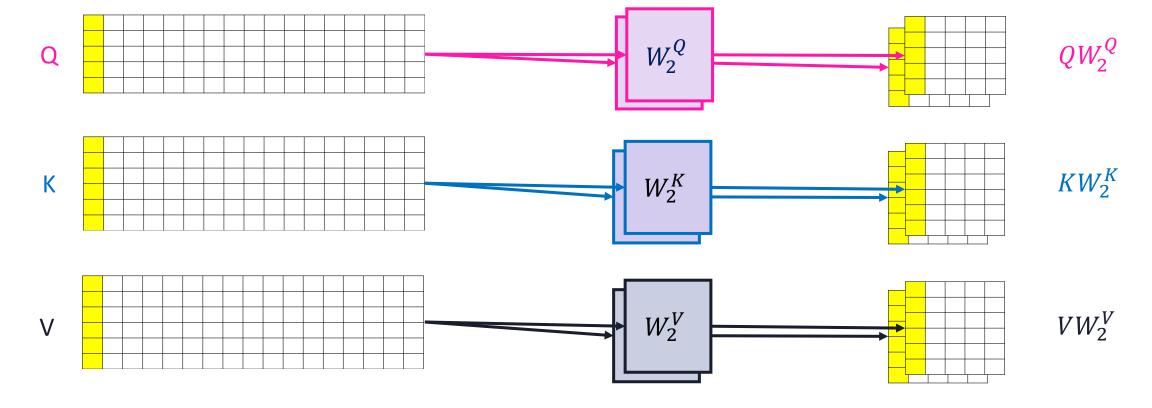


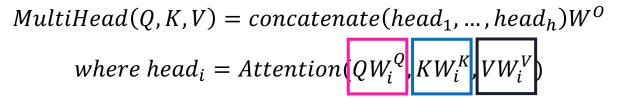


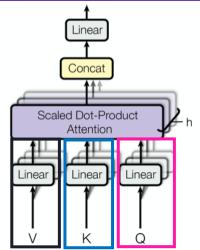


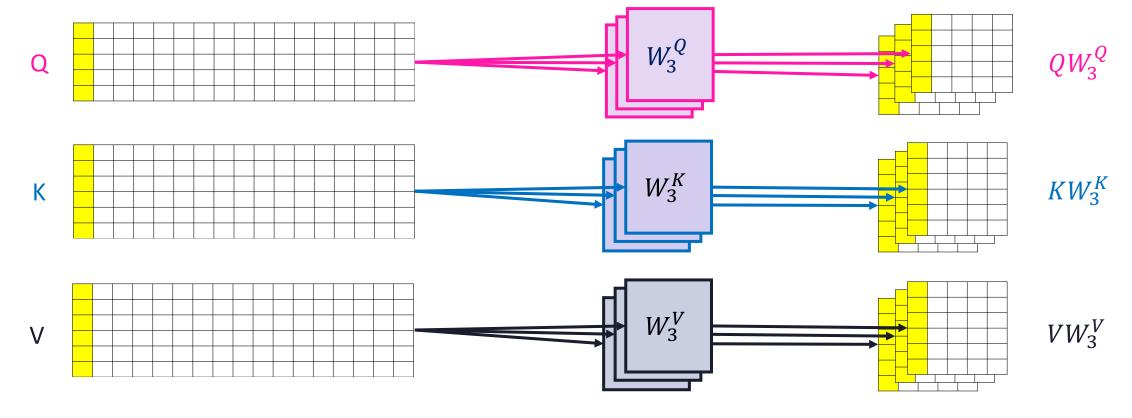


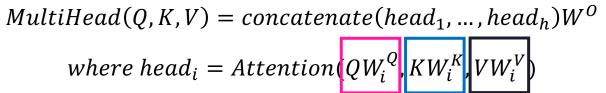




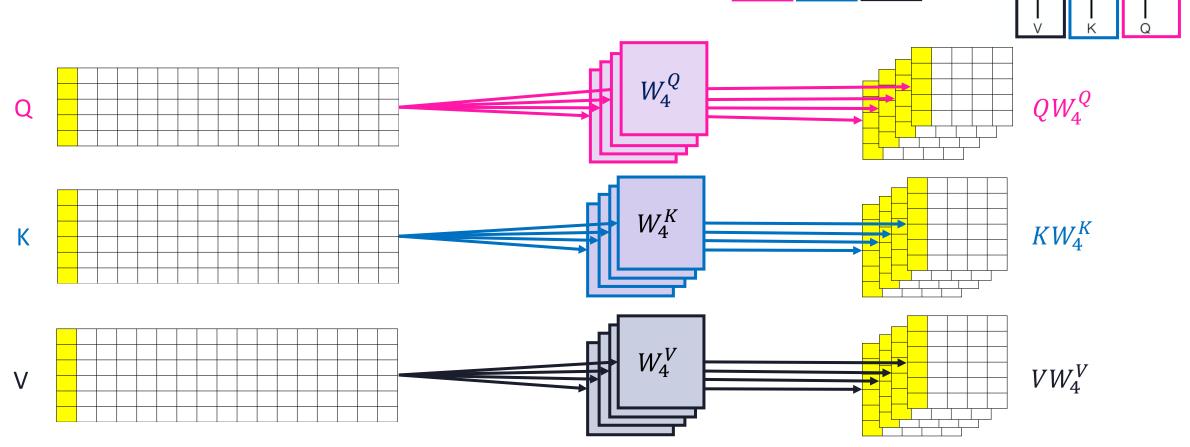


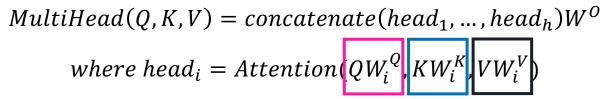


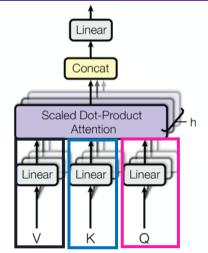


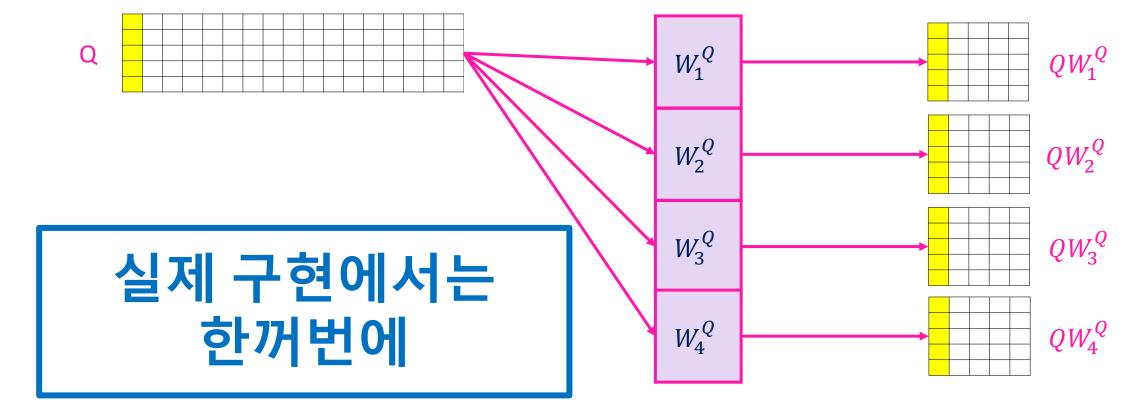


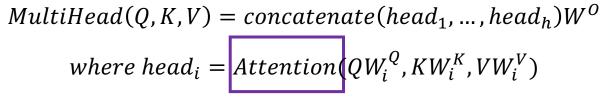
Scaled Dot-Product

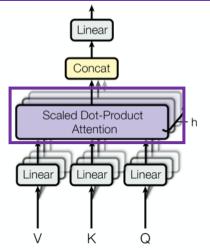




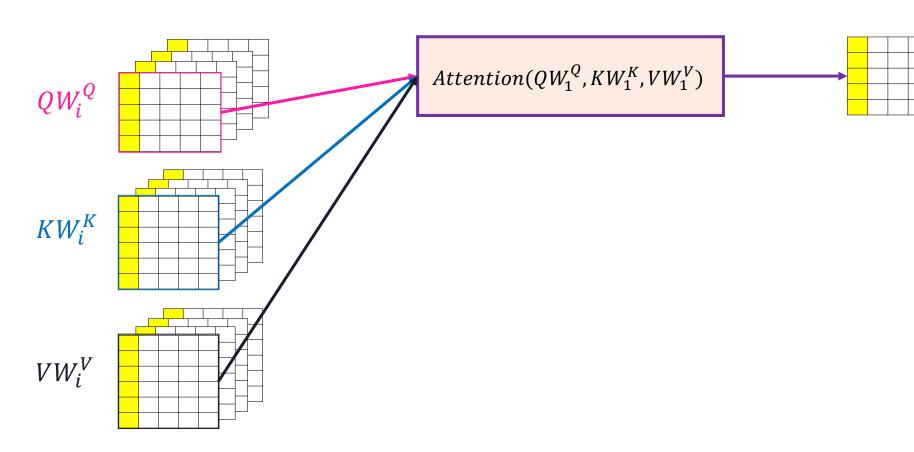




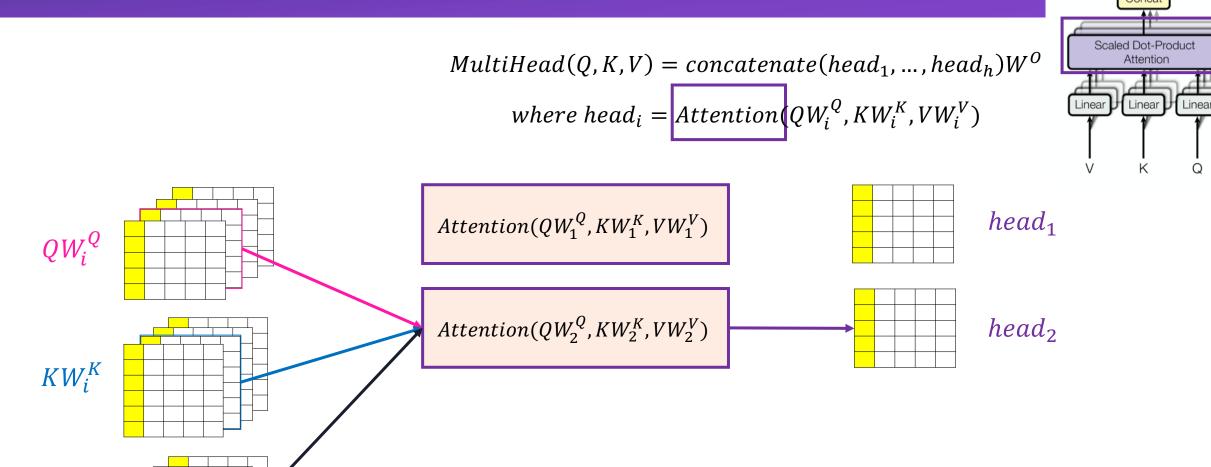


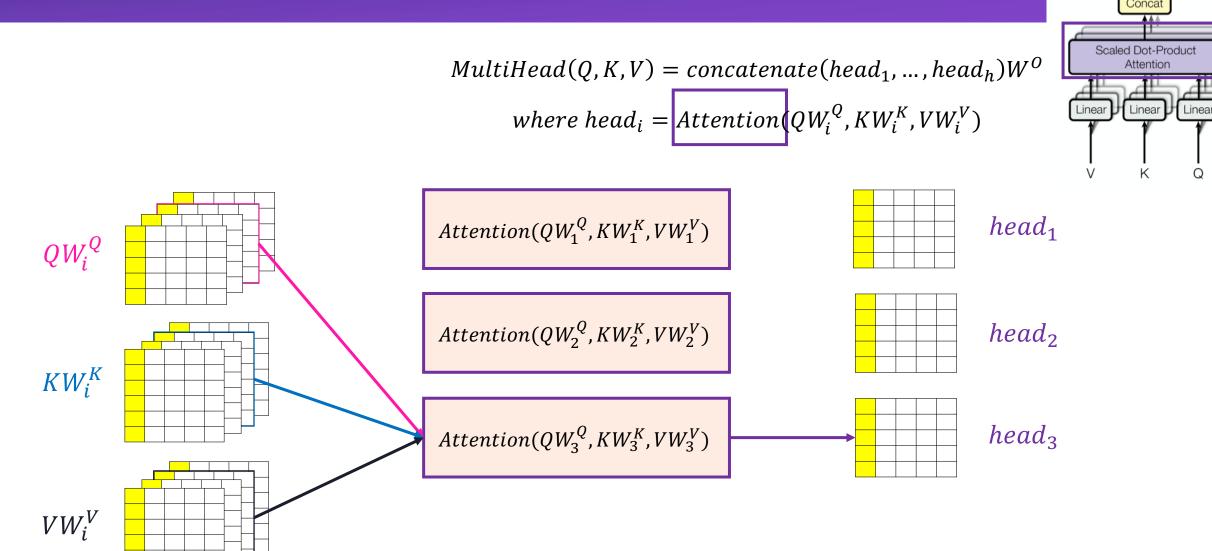


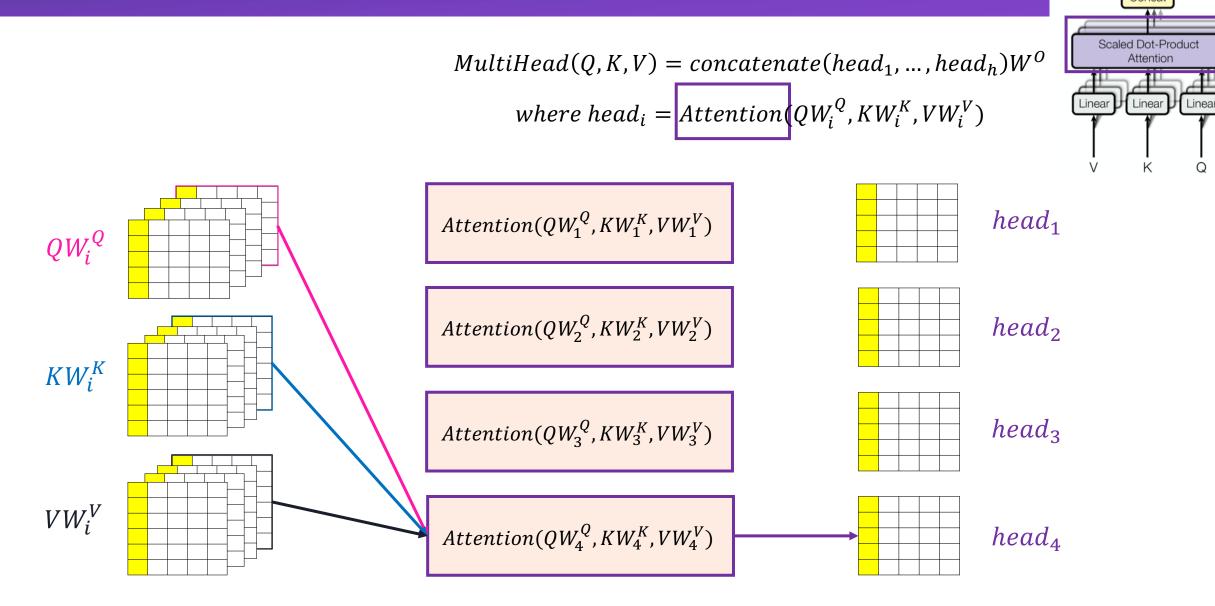
 $head_1$

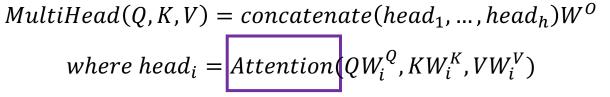


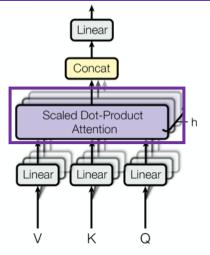
 VW_i^V

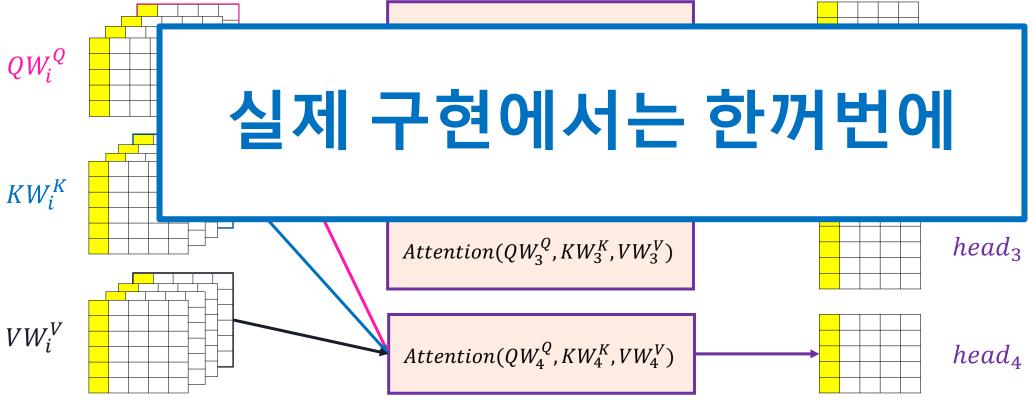


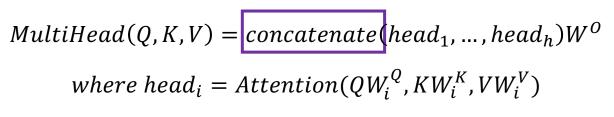


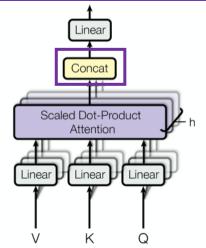


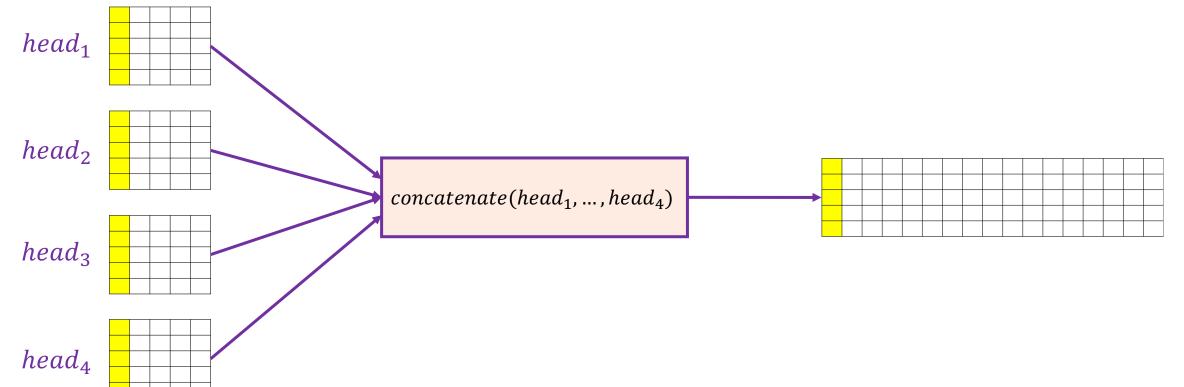


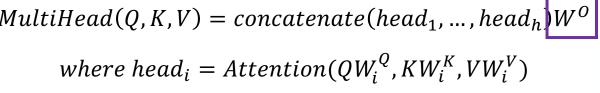












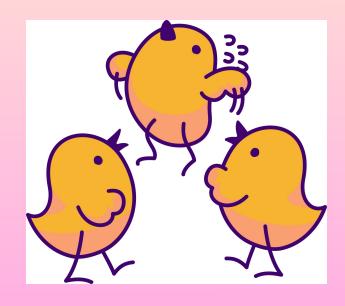
Scaled Dot-Product

Attention

 $MultiHead(Q, K, V) = concatenate(head_1, ..., head_h)W^O$

 $concatenate(head_1, ..., head_4)$





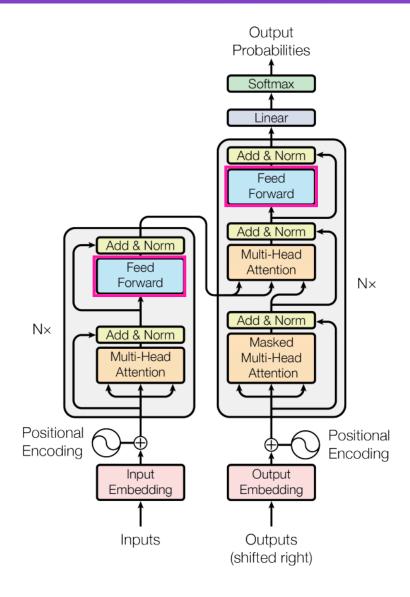
Position-wise Feed-Forward Network

LangCon 2020

Position-wise Feed-Forward Network



$$FFN(x) = \max(0, xW_1 + b_1)W_2 + b_2$$





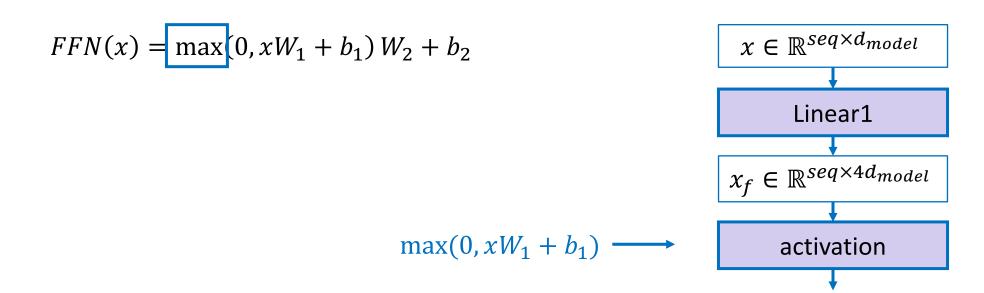
$$FFN(x) = \max(0, xW_1 + b_1) W_2 + b_2$$

$$xW_1 + b_1 \longrightarrow xW_1 + b_1$$

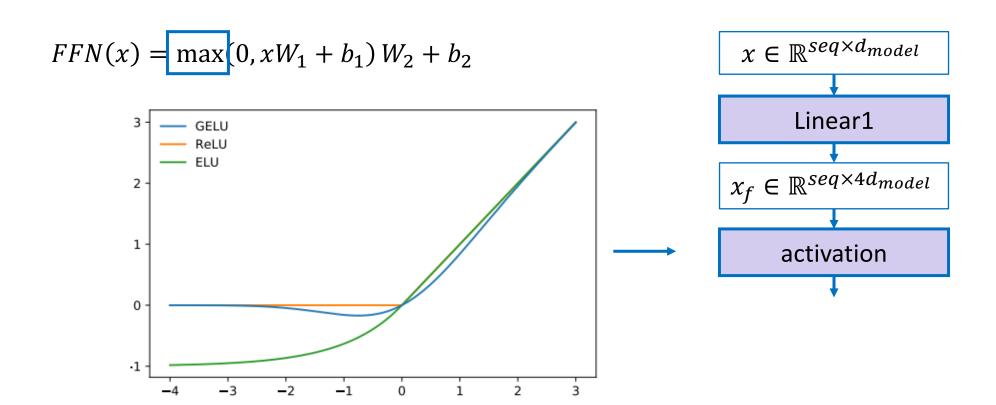
$$xW_1 + b_1 \longrightarrow x_f \in \mathbb{R}^{seq \times 4d_{model}}$$

Position-wise Feed-Forward Network

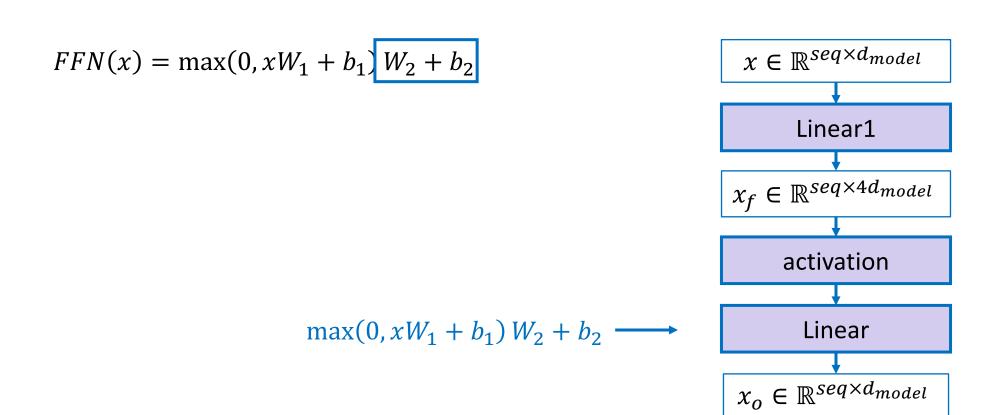


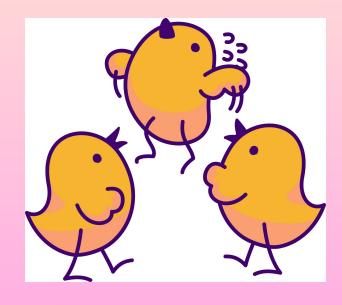












Reference

Reference



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