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Eletromagnetismo I - UFSM00068

Lista de Exercícios 1

Álgebra Vetorial

 Determine o vetor unitário ao longo da direção OP, se O for a origem e P o ponto (4, −5, 1).

$$|OP| = \sqrt{4^2 + 5^2 + 1} = \sqrt{42}$$

$$|OP| = \left(\frac{4}{\sqrt{42}} \hat{a}_{x} + \frac{-5}{\sqrt{42}} \hat{a}_{y} + \frac{1}{\sqrt{42}} \hat{a}_{z}\right) = \frac{1}{\sqrt{42}} \left(\frac{4}{\sqrt{42}} \hat{a}_{x} + \frac{-5}{\sqrt{42}} \hat{a}_{y} + \frac{1}{\sqrt{42}} \hat{a}_{z}\right) = \frac{1}{\sqrt{42}} \left(\frac{4}{\sqrt{42}} \hat{a}_{x} - \frac{7715}{\sqrt{42}} \hat{a}_{y} + \frac{1543}{\sqrt{42}} \hat{a}_{z}\right)$$

Os vetores posição dos pontos M e N são â_x - 4â_y - 2â_z e 3â_x + 5â_y - â_z, respectivamente. Determine o vetor distância orientado de M a N.

$$\overline{MN} = (32 + 52 - 2) - (2 - 42 - 22) = (22 + 92 + 2)$$

3. Os vetores posição dos pontos P e Q são $4\hat{a}_x+6\hat{a}_y-2\hat{a}_z$ e $\hat{a}_x+8\hat{a}_y+3\hat{a}_z$, respectivamente. Determine o vetor distância orientado de P a Q,

$$\overrightarrow{PQ} = (\widehat{n}_x + 8\widehat{n}_y + 3\widehat{n}_z) - (4\widehat{n}_x + 6\widehat{n}_y - 2\widehat{n}_z) = (-3\widehat{n}_x + 2\widehat{n}_y + 5\widehat{n}_z)$$

4. Dados $\vec{A}=4\hat{a}_y+10\hat{a}_z$ e $\vec{B}=2\hat{a}_x+3\hat{a}_y$, encontre a projeção de \vec{A} sobre \vec{B} .

$$\frac{\vec{A} \cdot \vec{B}}{|\vec{B}|} = \frac{0 + |2 + 0|}{\sqrt{2^2 + 3^2}} = \frac{12}{\sqrt{13}}$$

5. Determine o ângulo entre $\vec{A} = 2\hat{a}_x + 3\hat{a}_y + \hat{a}_z$ e $\vec{B} = -\hat{a}_x + 5\hat{a}_y + \hat{a}_z$.

$$\cos \theta = \frac{\overrightarrow{A} \cdot \overrightarrow{B}}{|\overrightarrow{A}||\overrightarrow{B}|} = \frac{-2 + 15 + 1}{|\overrightarrow{14}| \cdot \sqrt{27}} = \frac{14}{\sqrt{378}}$$

$$\theta = \arccos\left(\frac{14}{\sqrt{378}}\right)$$

6. Ache o menor ângulo entre $\vec{A} = 10\hat{a}_x + 2\hat{a}_z$ e $\vec{B} = -4\hat{a}_y + 0.5\hat{a}_z$ usando tanto o produto escalar quanto o produto vetorial.

PE)
$$\cos \theta = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}||\vec{B}|} = \frac{O + O + I}{\sqrt{16.15}} = \frac{I}{\sqrt{1690}}$$

$$\theta = \arccos\left(\frac{I}{\sqrt{1690}}\right)$$

PI) $\sin \theta = \frac{\vec{A} \times \vec{B}}{|\vec{A}||\vec{B}|} = \frac{\hat{a}_{x} \cdot \hat{a}_{y} \cdot \hat{a}_{z}}{|\vec{a}_{y}||\vec{a}_{z}||} = \frac{8\hat{a}_{x} - 5\hat{a}_{y} - 40\hat{a}_{z}}{\sqrt{1690}} = \frac{\sqrt{1690}}{\sqrt{1690}} = \frac{\sqrt{$

7. Considere $\vec{A} = 4\hat{a}_x - 2\hat{a}_y + 5\hat{a}_z$ e $\vec{B} = 3\hat{a}_x + \hat{a}_y - \hat{a}_z$. Determine $\vec{A} \times \vec{B}$.

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{a}_{x} & \hat{a}_{y} & \hat{a}_{z} \\ 4 & -2 & 5 \end{vmatrix} = (2-5)\hat{a}_{x} + (15+4)\hat{a}_{y} + (4+6)\hat{a}_{z} = \\ 3 & 1 & -1 \end{vmatrix} = -3\hat{a}_{x} + 19\hat{a}_{y} + 10\hat{a}_{z}$$

8. Dados $\vec{A}=2\hat{a}_x-\hat{a}_z,\; \vec{B}=3\hat{a}_x+\hat{a}_y$ e $\vec{C}=-2\hat{a}_x+6\hat{a}_y-4\hat{a}_z,\; \text{mostre que }\vec{C}$ é perpendicular simultaneamente a \vec{A} e \vec{B} .

9. Determine o produto escalar, o produto vetorial e o ângulo entre os vetores $\vec{P}=2\hat{a}_x-6\hat{a}_y+5\hat{a}_z$ e $\vec{Q}=3\hat{a}_y+\hat{a}_z$.

$$\vec{P} \cdot \vec{Q} = (2, -6, 5) \cdot (0, 3, 1) = 0 - 18 + 5 = -13$$

$$\vec{P} \cdot \vec{Q} = \begin{vmatrix} \alpha_x & \alpha_y & \alpha_z \\ 2 & -6 & 5 \end{vmatrix} = (-6 - 15) \hat{\alpha}_x + (-2) \hat{\alpha}_y + (6 + 6) \hat{\alpha}_z = -13$$

$$-11 \hat{\alpha}_x - 2\hat{\alpha}_y + 12\hat{\alpha}_z = -13$$

$$\cos \theta = \vec{p} \cdot \vec{a} = \frac{-13}{\sqrt{4+36+25} \cdot \sqrt{10}} = \frac{-13}{\sqrt{650}}$$

$$\theta = \arccos \left(\frac{-13}{\sqrt{550}} \right)$$

10. Dados os vetores $\vec{A} = 2\hat{a}_x + 5\hat{a}_z$ e $\vec{B} = \hat{a}_x - 3\hat{a}_y + 4\hat{a}_z$, determine $|\vec{A} \times \vec{B}| + \vec{A} \cdot \vec{B}$.

$$|\vec{A} \cdot \vec{B}| + |\vec{A} \cdot \vec{B}| = |\vec{2} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6} \cdot \vec{6}| + (2,0,6) \cdot (1,-3,4) = |\vec{1} \cdot \vec{6}| + (2$$

11. Considere $\vec{A} = \hat{a}_x - \hat{a}_z$, $\vec{B} = \hat{a}_x + \hat{a}_y + \hat{a}_z$, $\vec{C} = \hat{a}_y + 2\hat{a}_z$ e determine:

a)
$$\vec{A} \cdot (\vec{B} \times \vec{C}) = (1,0,-1) \cdot \begin{pmatrix} \vec{a}_{1} & \vec{a}_{2} & \vec{a}_{3} \\ 0 & 1 & 2 \end{pmatrix} = (1,0,-1) \cdot (1,-2,1) = 1+0-1=0$$

b)
$$(\vec{A} \times \vec{B}) \cdot \vec{C} = \begin{vmatrix} \vec{a}_{x} & \vec{a}_{y} & \vec{a}_{z} \\ 0 & 1 \end{vmatrix} \cdot (0,1,2) = (1,-2,1) \cdot (0,1,2) = 0$$

 $0-2+2=0$

c)
$$\vec{A} \times (\vec{B} \times \vec{C}) = (1,0,-1) \times (1,-1,1) = \begin{vmatrix} \hat{\alpha}_1 & \hat{\alpha}_2 & \hat{\alpha}_2 \\ 1 & 0 & -1 \\ 1 & -1 \end{vmatrix} = (-1,-1,-1) = -2\hat{\alpha}_1 \cdot 2\hat{\alpha}_2 - 2\hat{\alpha}_2 \cdot 2\hat{\alpha}_2 - 2\hat{\alpha}_2 -$$

$$d) (\vec{A} \times \vec{B}) \times \vec{C} = (1, -2, 1) \times (0, 1, 2) = \begin{vmatrix} \hat{s}_{x} & \hat{s}_{y} & \hat{s}_{z} \\ -1 & 1 \end{vmatrix} = (-5, -2, 1) = -5\hat{s}_{x} - 2\hat{s}_{y} + 1\hat{s}_{z}$$

12. Demonstre que $(\vec{A} \cdot \vec{B})^2 + |\vec{A} \times \vec{B}|^2 = (|\vec{A}||\vec{B}|)^2$.

Entro:
$$(|\vec{A}||\vec{B}||\cos\theta)^2 + (|\vec{A}||\vec{B}||\sin\theta)^2 = (|\vec{A}||\vec{B}|)^2$$

 $(|\vec{A}||\vec{B}|)^2 \cos^2\theta + (|\vec{A}||\vec{B}|)^2 \sin^2\theta = (|\vec{A}||\vec{B}|)^2$
 $(|\vec{A}||\vec{B}|)^2 \cdot (\cos^2\theta + \sin^2\theta) = (|\vec{A}||\vec{B}|)^2$
 $(|\vec{A}||\vec{B}|)^2 \cdot 1 = (|\vec{A}||\vec{B}|)^2$

- 13. Considere $\vec{A}=\alpha\hat{a}_x+3\hat{a}_y-2\hat{a}_z$ e $\vec{B}=4\hat{a}_x+\beta\hat{a}_y+8\hat{a}_z$, determine:
 - a) Os valores de α e β se \vec{A} e \vec{B} forem paralelos.

b) A relação entre α e β se \vec{B} for perpendicular a \vec{A} .

14. Calcule a área de um triângulo determinado pelos pontos P₁ = (1,1,1), P₂ = (2,3,4) e P₁ = (3,0,-1)m.

$$\vec{v} = \vec{P}_1 \vec{P}_2 = (2-1, 3-1, 4-1) = (1, 2, 3)$$

$$\vec{v} = \vec{P}_1 \vec{P}_3 = (3-1, 0-1, -1-1) = (2, -1, -2)$$

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$$\vec{v} = \vec{P}_1 \vec{P}_3 = (3-1, 0-1, -1-1) = (3-1, 0-1, -1-1)$$

$$\vec{v} = \vec{P}_1 \vec{P}_2 = (3-1, 0-1, -1-1) = (3-1, 0-1, -1-1)$$

Lista de Exercícios 2

Sistemas e Transformação de Coordenadas

Expresse os seguintes pontos em coordenadas cilíndricas e esféricas

	cilíndricas	esféricas
a) $P = (1, -4, -3)$	P= J17	V = \126
	Pearctan(-4)	0 = arccos (-3/26)
	2=-3	4 = arctan (-4)
b) $Q = (3,0,5)$	P= 3	V= 134
	Vearctan(0)	0 = arc cos (5/134)
	2:5	e= arctan(o)
c) $R = (-2,6,0)$	P= 140	v = 140
	Y= arctan(-3)	0 = avecos (0)
	Z = 0	Y= arctan (-3)

 Dados dois pontos em coordenadas cilíndricas P = (10,60°,2) e Q = (5,30°, -4), determine a distância entre eles.

$$P = (10.\cos 60^{\circ}, 10.\sin 60^{\circ}, 2)$$

$$Q = (5.\cos 30^{\circ}, 5.\sin 30^{\circ}, -4)$$

$$d = \prod ((5\cos 30^{\circ} - 10\cos 60^{\circ})^{\frac{1}{2}}(5\sin 30^{\circ} - 10\sin 60^{\circ})^{\frac{1}{2}} - 6^{\frac{1}{2}})$$

$$d = \prod ((5\cos 30^{\circ} - 5)^{\frac{1}{2}} + (2.5 - 10\sin 60^{\circ})^{\frac{1}{2}} - 36)$$

3. Se
$$\vec{A} = 5\hat{a}_{\rho} + 2\hat{a}_{\phi} - \hat{a}_z$$
 e $\vec{B} = \hat{a}_{\rho} - 3\hat{a}_{\phi} + 4\hat{a}_z$, determine:

a)
$$\vec{A} \cdot \vec{B} = 5 - 6 - 4 = -5$$

b)
$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{a}\rho & \hat{a}\phi & \hat{a}z \\ 5 & 2 & -1 \\ 1 & -3 & 4 \end{vmatrix} = 4\hat{a}\rho - 21\hat{a}\phi - 17\hat{a}z$$

c) O ângulo entre
$$\vec{A} \in \vec{B}$$

$$\cos \theta = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}||\vec{B}|} = \frac{-5}{\sqrt{30 \cdot \sqrt{16}}} = \frac{-5}{\sqrt{780}}$$

$$\theta = \arccos(\frac{-5}{\sqrt{780}})$$

d) O vetor unitário normal ao plano que contém ambos \vec{A} e \vec{B}

$$\vec{\Lambda} = \frac{\vec{A} \cdot \vec{B}}{|\vec{A} \cdot \vec{B}|} = \frac{4 \hat{\alpha} \rho - 21 \hat{\alpha} \phi - 17 \hat{\alpha}^2}{\sqrt{716 + 441 + 289}} = \frac{4 \hat{\alpha} \rho + -21 \hat{\alpha} \phi + -17}{\sqrt{755}} \hat{\alpha}^2$$

e) O vetor projeção de \vec{A} em \vec{B} .

$$\left(\frac{\vec{A} \cdot \vec{B}}{|\vec{B}|^{1}}\right) \cdot \vec{B} = \frac{-5}{\sqrt{16^{1}}} \cdot \left(1, \cdot 3, 4\right) = \frac{-5}{26} \hat{\alpha}_{p} + \frac{15}{16} \hat{\alpha}_{p} + \frac{-20}{16} \hat{\alpha}_{z}$$

4. Dados os vetores $\vec{A}=2\hat{a}_x+4\hat{a}_y+10\hat{a}_z$ e $\vec{B}=-5\hat{a}_\rho+\hat{a}_\phi-3\hat{a}_z$, determine:

a)
$$\vec{A} + \vec{B} \text{ em } P = (0, 2, -5)$$

$$P = \begin{bmatrix} 4 & = 1 \\ 4 & = 1 \end{bmatrix} \quad \text{(5)}$$

$$DW(0)$$

$$b = 90^{\circ}$$

$$\vec{B} = (-5\cos 90^{\circ} - 1\sin 90^{\circ})\hat{a}_{x} + (-5\sin 90^{\circ})\hat{a}_{y} - 3\hat{a}_{z}$$

$$\vec{B} = (-5\cdot 0 - 1\cdot 1)\hat{a}_{x} + (-5\cdot 1 + 1\cdot 0)\hat{a}_{y} - 3\hat{a}_{z} = (-1, -5, -3)$$

$$\vec{A} + \vec{B} = (1, 4, 10) + (-1, -5, -3) = \hat{a}_{x} - \hat{a}_{y} + 7\hat{a}_{z}$$

b) O ângulo entre \vec{A} e \vec{B} em P

$$\cos \theta = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}||\vec{B}|} = \frac{-2 - 20 - 30}{\sqrt{120} \cdot \sqrt{35}} = \frac{-52}{2\sqrt{1050}} = \frac{-52}{10\sqrt{42}} = \frac{-26}{5\sqrt{42}}$$

$$\theta = \arccos\left(\frac{-26}{5\sqrt{42}}\right)$$

c) A componente escalar de \vec{A} ao longo de \vec{B} em P.

$$\frac{\overrightarrow{A.S}}{|\overrightarrow{B}|} = \frac{-52}{\sqrt{35}}$$

 Dado um ponto P = (-2,6,3) e um vetor A = 6â_x + â_y, determine P em coordenadas cilíndricas e esféricas.

$$P = \sqrt{4+36} = \sqrt{40}$$

$$Y = \arctan(\frac{6}{2}) = \arctan(\frac{-3}{3})$$

$$Y = \sqrt{4+36+9} = \sqrt{49} = 7$$

$$P(\rho, \phi, z) = (\sqrt{40}, \tan^{-3}(-3), 3)$$

$$P(\nu, \theta, \phi) = (7, \cos^{-3}(\frac{3}{4}), \tan^{-3}(-3))$$

Ainda, expresse o vetor \vec{A} no ponto P em coordenadas cilíndricas e esféricas.

$$\hat{A}_{(P_{i}0,r)} = (G \cdot \frac{1}{10} + 1 \cdot \frac{3}{10}) \circ p + (-6 \cdot \frac{3}{10} + \frac{1}{10}) \circ a + 0 = -\frac{3}{10} \circ p - \frac{19}{10} \circ a + 0 = \frac{3}{10} \circ p - \frac{19}{10} \circ a + (-6 \cdot \frac{3}{10} + \frac{1}{10}) \circ a + (-$$

Por fim, calcule o módulo do vetor \vec{A} nos três sistemas.

$$|A_{(1,1,2)}| = \sqrt{36+1+0} = \sqrt{37}$$

$$|A_{(1,1,2)}| = \sqrt{\frac{3}{10}} + \frac{361}{10} = \sqrt{\frac{37}{10}} = \sqrt{37}$$

$$|A_{(1,1,2)}| = \sqrt{\frac{3}{10}} + \frac{81}{10} + \frac{361}{10} = \sqrt{37}$$

$$|A_{(1,1,2)}| = \sqrt{\frac{3}{10}} + \frac{81}{10} + \frac{361}{10} = \sqrt{37}$$

Lista de Exercícios 3

Cálculo Vetorial

- Utilizando o comprimento diferencial dl, determine o comprimento de cada uma das seguintes curvas:
 - a) $\rho = 3; \pi/4 < \phi < \pi/2; z = constante.$

$$d\vec{l} = d\rho \hat{a}_{\rho} + \rho d\phi \hat{a}_{\phi} + dz \hat{a}_{z} = 0 + 3d\phi \hat{a}_{\phi} + 0$$

$$L = \int_{\frac{\pi}{4}}^{\frac{\pi}{4}} d\phi = 3\left(\frac{\pi}{2} - \frac{\pi}{4}\right) = \frac{3\pi}{4}$$

b) $r = 1; \theta = 30^{\circ}; 0 < \phi < 60^{\circ}$.

$$d\vec{l} = dr\hat{a}_r + rd\theta\hat{a}_\theta + r\sin\theta d\phi\hat{a}_\phi = 0 + 0 + 1.5 \cdot d\phi\hat{a}_\phi$$

$$C = \int_0^{60^{1/3}} d\phi = \frac{1}{2} \left(\frac{\pi}{3}\right) = \frac{\pi}{6}$$

c) $r = 4;30^{\circ} < \theta < 90^{\circ}; \phi = \text{constante}.$

$$d\vec{l} = dr\hat{a}_r + rd\theta\hat{a}_\theta + r\sin\theta d\phi\hat{a}_\phi = \mathcal{O} + 4d\theta\hat{a}_\theta + O$$

$$= \int_{-\pi/6}^{\pi/2} 4d\theta = 4\cdot \left(\frac{\pi}{2} - \frac{\pi}{6}\right) = \frac{4\pi}{3}$$

Determine o gradiente dos seguintes campos escalares:

a)
$$U = 5y - x^3y^2$$
.

$$\vec{\nabla}V = \frac{\partial V}{\partial x}\hat{a}_x + \frac{\partial V}{\partial y}\hat{a}_y + \frac{\partial V}{\partial z}\hat{a}_z = -3 \times^2 y^2 \hat{a}_x + (5 - 2y^3)\hat{a}_y$$

b) $U = x^2y + xyz$.

$$\vec{\nabla}V = \frac{\partial V}{\partial x}\hat{a}_x + \frac{\partial V}{\partial y}\hat{a}_y + \frac{\partial V}{\partial z}\hat{a}_z = (2\times y + y^z)\hat{a}_x + (x^2 + x^2)\hat{a}_y + (xy)\hat{a}_z$$

c) $V = \rho z \sin \phi + z^2 \cos^2 \phi + \rho^2$.

$$\vec{\nabla}V = \frac{\partial V}{\partial \rho}\hat{a}_{\rho} + \frac{1}{\rho}\frac{\partial V}{\partial \phi}\hat{a}_{\phi} + \frac{\partial V}{\partial z}\hat{a}_{z} = \frac{(z\cdot\sin\psi+2\rho)\hat{a}_{\rho} + (\beta\sin\psi+2z\cos^{2}\psi)\hat{a}_{z}}{V_{\rho}(\betaz\cos\psi+z^{2}\cdot2\cos\psi\cdot(-\sin\psi)\hat{a}_{\psi} = (z\cdot\sin\psi+2\rho)\hat{a}_{\rho} + (z\cdot\cos\psi-2z^{2}\cdot\cos\psi\cdot(-\sin\psi)\hat{a}_{\psi} + (\beta\sin\psi+2z\cos^{2}\psi)\hat{a}_{z})}$$

 Determine o divergente dos seguintes campos vetoriais e os calcule nos pontos especificados:

a)
$$\vec{A} = yz\hat{a}_x + 4xy\hat{a}_y + y\hat{a}_z \text{ em } (1, -2, 3).$$

$$\vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} = 0 + 4x + 0 = 4x \quad \text{em} \quad 4$$

b) $\vec{B} = \rho z \sin \phi \hat{a}_{\rho} + 3\rho z^2 \cos \phi \hat{a}_{\phi} \text{ em } (5, \pi/2, 1).$

$$\vec{\nabla} \cdot \vec{A} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho A_{\rho}) + \frac{1}{\rho} \frac{\partial A_{\phi}}{\partial \phi} + \frac{\partial A_{z}}{\partial z} = \frac{1}{\rho} \cdot (\rho \rho)^{2} \sin \varphi + \frac{1}{\rho} (3\rho z^{2}(-\sin \varphi)) + 0 =$$

$$= 2z \sin \varphi - 3z^{2} \sin \varphi = z \sin \varphi (2-3z) \quad cm \quad -1$$

c) $\vec{C} = 2r \cos \theta \cos \phi \hat{a}_r + r^{1/2} \hat{a}_\phi \text{ em } (1, \pi/6, \pi/3).$

 Determine o rotacional dos seguintes campos vetoriais e os calcule nos pontos especificados:

a)
$$\vec{A} = yz\hat{a}_x + 4xy\hat{a}_y + y\hat{a}_z \text{ em } (1, -2, 3).$$

$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \hat{a}_x \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) + \hat{a}_y \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) + \hat{a}_z \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_z}{\partial y} \right)$$

b) $\vec{B} = \rho z \sin \phi \hat{a}_{\rho} + 3\rho z^{2} \cos \phi \hat{a}_{\phi} \text{ em } (5, \pi/2, 1).$

$$\vec{\nabla} \times \vec{A} = \frac{1}{\rho} \begin{vmatrix} \hat{a}_{\rho} & \rho \hat{a}_{\phi} & \hat{a}_{z} \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ A_{\rho} & \rho A_{\phi} & A_{z} \end{vmatrix} = \hat{\sigma}_{\rho} \left(\frac{\partial A_{z}}{\partial \varphi} - \frac{\partial A_{\varphi}}{\partial z} \right) + \hat{\alpha}_{\varphi} \left(\frac{\partial A_{\rho}}{\partial z} - \frac{\partial A_{z}}{\partial \rho} \right) \hat{\rho}_{\rho} + \hat{\alpha}_{z} \left(\frac{\partial A_{\varphi}}{\partial \rho} - \frac{\partial A_{\varphi}}{\partial \rho} \right) =$$

$$= \left(0 - 6z\rho\cos\varphi \right) \hat{a}_{\rho} + \left(\rho\sin\varphi - 0 \right) \hat{a}_{\varphi} + \left(6\rho z^{2}\cos\varphi - \rho z\cos\varphi \right) \hat{a}_{z} =$$

$$= \left(-6z\rho\cos\varphi \right) \hat{a}_{\rho} + \left(\rho\sin\varphi \right) \hat{a}_{\varphi} + \left(z\cos\varphi(6z-1) \right) \hat{a}_{z} \quad \text{cm} \quad 5 \hat{a}_{\varphi}$$

c) $\vec{C} = 2r \cos \theta \cos \phi \hat{a}_r + r^{1/2} \hat{a}_\phi \text{ em } (1, \pi/6, \pi/3).$

$$\vec{\nabla} \times \vec{A} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{a}_r & r \hat{a}_{\theta} & r \sin \theta \hat{a}_{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_r & r A_{\theta} & r \sin \theta A_{\phi} \end{vmatrix}$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{\partial rsin\theta}{\partial \theta} A_{V} - \frac{\partial r\theta}{\partial \phi} \right) + \frac{\hat{\alpha}_{\theta}}{rsin\theta} \left(\frac{\partial A_{V} - \partial rsin\theta}{\partial v} A_{V} \right) + \frac{\hat{\alpha}_{\psi}}{v} \left(\frac{\partial rA_{\theta} - \partial A_{V}}{\partial v} \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{\partial rsin\theta}{\partial \theta} - \frac{\partial r}{\partial v} A_{V} \right) + \frac{\hat{\alpha}_{\psi}}{v} \left(\frac{\partial rA_{\theta} - \partial A_{V}}{\partial v} \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{\partial rsin\theta}{\partial \theta} - \frac{\partial r}{\partial v} A_{V} \right) + \frac{\hat{\alpha}_{\psi}}{v} \left(\frac{\partial rA_{\theta} - \partial A_{V}}{\partial v} \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{r^{1}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \frac{\hat{\alpha}_{\theta}}{sin\theta} \left(-2r\cos\theta \cdot \sin\theta - \frac{3}{2}r^{1/2} \sin\theta \right) + \frac{\hat{\alpha}_{\psi}}{v} \left(+2r\sin\theta \cos\phi \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{r^{1}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \hat{\alpha}_{\theta} \left(-2r\cos\theta \cdot \sin\theta - \frac{3}{2}r^{1/2} \right) + \hat{\alpha}_{\psi} \left(2\sin\theta \cos\phi \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{r^{2}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \hat{\alpha}_{\theta} \left(-2r\cos\theta \cdot \sin\theta - \frac{3}{2}r^{1/2} \right) + \hat{\alpha}_{\psi} \left(2\sin\theta \cos\phi \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{r^{2}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \hat{\alpha}_{\theta} \left(-2r\cos\theta \cdot \sin\theta - \frac{3}{2}r^{1/2} \right) + \hat{\alpha}_{\psi} \left(2\sin\theta \cos\phi \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{r^{2}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \hat{\alpha}_{\theta} \left(-2r\cos\theta \cdot \sin\theta - \frac{3}{2}r^{1/2} \right) + \hat{\alpha}_{\psi} \left(2\sin\theta \cos\phi \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{r^{2}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \hat{\alpha}_{\theta} \left(-2r\cos\theta \cdot \sin\theta - \frac{3}{2}r^{1/2} \right) + \hat{\alpha}_{\psi} \left(2\sin\theta \cos\phi \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{r^{2}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \hat{\alpha}_{\theta} \left(-2r\cos\theta \cdot \sin\theta - \frac{3}{2}r^{1/2} \right) + \hat{\alpha}_{\psi} \left(2\sin\theta \cos\phi \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{r^{2}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \hat{\alpha}_{\theta} \left(-2r\cos\theta \cdot \sin\theta - \frac{3}{2}r^{1/2} \right) + \hat{\alpha}_{\psi} \left(2\sin\theta \cos\phi \right)$$

$$= \frac{\hat{\alpha}_{V}}{r^{2}sin\theta} \left(\frac{r^{2}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \hat{\alpha}_{\theta} \left(-2r\cos\theta \cdot \sin\theta - \frac{3}{2}r^{1/2} \right) + \hat{\alpha}_{\theta} \left(\frac{r^{2}/2 \cdot \cos\theta}{r^{2}sin\theta} \right) + \hat{\alpha}_{\theta} \left(\frac{r^{2}/2 \cdot \cos\theta}{r^$$

Determine o laplaciano dos seguintes campos escalares:

a)
$$U = x^2y + xyz$$
.

$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = {}^{2} \mathbf{Y}$$

b)
$$V = \rho z \sin \phi + z^2 \cos^2 \phi + \rho^2$$
.

$$\begin{aligned} &= \rho z \sin \phi + z^{2} \cos^{2} \phi + \rho^{2}. \\ &\nabla^{2} V = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial V}{\partial \rho} \right) + \frac{1}{\rho^{2}} \frac{\partial^{2} V}{\partial \phi^{2}} + \frac{\partial^{2} V}{\partial z^{2}} \\ &= \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho z \sin \varphi + 2 \rho^{2} \right) + \frac{1}{\rho^{2}} \left(\frac{\partial}{\partial \varphi} \rho^{2} z \cos \varphi + z^{2} (2 \cos \varphi (-\sin \varphi)) \right) + 2 \cos^{2} \varphi \\ &= \frac{1}{\rho} \left(z \sin \varphi + 4 \rho \right) + \frac{1}{\rho^{2}} \left(-\rho_{z} \sin \varphi + 2 z^{2} \sin \varphi \cdot \cos \varphi \right) + 2 \cos^{2} \varphi \\ &= \frac{z \sin \varphi + 4 + \frac{1}{\rho^{2}} \left(-\rho_{z} \sin \varphi + 2 z^{2} \cdot (\cos \varphi \cdot \cos \varphi + \sin \varphi \cdot \sin \varphi) + 2 \cos^{2} \varphi \right)}{\rho^{2}} \\ &= \frac{z \sin \varphi + 4 - \frac{z \sin \varphi}{\rho^{2}} + \frac{2 z^{2}}{\rho^{2}} \left(-\cos^{2} \varphi + \sin^{2} \varphi \right) + 2 \cos^{2} \varphi \\ &= \frac{1}{\rho^{2}} \left(\sin^{2} \varphi - \cos^{2} \varphi \right) + 2 \cos^{2} \varphi \end{aligned}$$

6. Dado que $\dot{H} = x^2 \hat{a}_x + y^2 \hat{a}_y$, calcule $\int \dot{H} \cdot dl$, considerando L ao longo da curva $y = x^2$, de (0,0,0) até (1,1,0).

$$d! = dx \hat{a}_{x} + dy \hat{a}_{y} = dx \hat{a}_{x} + 2x dx \hat{a}_{y}$$

$$HJ(= x^{2}Jx + y^{2}(2xdx) = x^{2}dx + x^{4} \cdot 2x dx = x^{2}dx + 2x^{6}dx$$

$$\int_{0}^{1} (x^{2} + 1x^{6}) dx = (\frac{x^{3}}{3} + \frac{2x^{6}}{6})|_{0}^{1} = \frac{1}{3} + \frac{1}{3} = \frac{2}{3}$$

7. Se $\vec{H} = (x - y)\hat{a}_x + (x^2 + zy)\hat{a}_y + 5yz\hat{a}_z$, calcule $\int \vec{H} \cdot d\vec{l}$ ao longo do caminho $(1,0,0) \to (0,0,0) \to (0,0,1) \to (0,2,0)$.

$$\int_{1}^{0} \times dx + \int_{0}^{1} z dz + \int_{0}^{1} (64.64) dt =$$

$$\frac{x^{2}}{2} \Big|_{0}^{1} + O + \left(-3t^{2} + 2t^{3}\right) \Big|_{0}^{1} = -\frac{1}{2} - 3 + 2 = -\frac{3}{2}$$

8. Determine o vetor unitário normal à superfície $S=x^2+y^2-z$ no ponto (1,3,0).

9. Mostre que o campo vetorial $\vec{F} = y^2 z \hat{a}_x + 2xyz \hat{a}_y + (2z + xy^2) \hat{a}_z$ é um campo conservativo e encontre o campo escalar V associado tal que $\vec{F} = \vec{\nabla} V$.

$$(\nabla x F)_{X} = \partial_{1}(2z + xy^{2}) - \partial_{2}(2xyz) = 2xy - 2xy = 0$$

$$(\nabla x F)_{Y} = \partial_{2}(y^{2}z) - \partial_{x}(2z + xy^{2}) = y^{2} - y^{2} = 0$$

$$(\nabla x F)_{Z} = \partial_{x}(2xyz) - \partial_{y}(y^{2}z) = 2yz - 2yz = 0$$

$$V = xy^{2}z + g(y,z)$$

$$g = g(z) = z^{2} + c$$

$$V(x,y,z) = xy^{2}z + z^{2} + c$$

Use o resultado para calcular $\int \vec{F} \cdot d\vec{l}$ do ponto (2,1,1) até o ponto (3,2,2).

$$\int F_{dv} = V(3,2,2) - V(2,1,1) = (3.4.2+4) - (2.1.1+1) = 28 - 3 = 25$$

10. Seja $\vec{D} = \rho^2 \cos^2 \phi \hat{a}_{\rho} + z \sin \phi \hat{a}_{\phi}$, determine o fluxo líquido de \vec{D} sobre a superfície fechada de um cilindro definido por $0 \le z \le 1$, $\rho = 4$. Verifique o teorema da divergência para este caso.

$$\iint \vec{D} \cdot d\vec{S} = \iiint \vec{D} \cdot \vec{D} \ dV = \int_{0}^{2\pi} \int_{0}^{4} \int_{0}^{4} sp^{2} \cos^{2}\theta \ dz dp \ dy + \int_{0}^{2\pi} \int_{0}^{4} \int_{0}^{4} z \cos^{2}\theta \cdot \vec{Z} \sin^{2}\theta \cdot$$

11. Verifique o teorema da divergência para a função $A = r^2 \hat{a}_r + r \sin \theta \cos \phi \hat{a}_{\phi}$ sobre a superfície de um quadrante de hemisfério definido por $0 < r < 3; 0 < \phi < \pi/2; 0 < \theta < \pi/2$.

$$\int_{0}^{2\pi} \int_{0}^{2\pi} \int_{0}^{3} (4r - \sin \varphi) r^{2} \sin \theta dr d\theta d\varphi = \frac{81\pi}{2} - 9$$

12. Demonstre que $\vec{B} = (y+z\cos(xz))\hat{a}_x + x\hat{a}_y + x\cos(xz)\hat{a}_z$ é conservativo, sem calcular nenhuma integral.

$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix} = \frac{\partial \times \cos(\times z)}{\partial y} - \frac{\partial}{\partial z} \times \frac{1}{\partial z} + \frac{\partial}{\partial z} (y + z \cos(\times z) - \frac{\partial}{\partial x} \cos(x)),$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

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$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) - \cos(xz) + xz \sin(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) + \cos(xz) + \cos(xz)) \hat{a}_y + (1 - 1) \hat{a}_z = 0$$

$$= (0 - 0) + (\cos(xz) - xz \sin(xz) + \cos(xz) + \cos($$

13. Seja a função vetorial $\vec{A} = \rho \cos \phi \hat{a}_{\rho} + z \sin \phi \hat{a}_{z}$, verifique o teorema de Stokes para o caminho fechado L definido por $0 \le \rho \le 2$; $0 \le \phi \le 60^{\circ}$; z = 0.