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| Mark |  |

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| Team name: | *A2* | | |
| Homework number: | *06* | | |
| Due date: | 27/10/2024 | | |
|  |  |  |  |
| Contribution | NO | Partial | Full |
| La Barbera Marco |  |  | *x* |
| Lotto Giulio |  |  | *x* |
| Majocchi Tommaso |  |  | *x* |
| Maffezzini Andrea |  |  | *x* |
| Pompilio Matteo |  |  | *x* |
| Notes: none | | | |

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| --- | --- | --- | --- |
| Project name | UART rx from pc and ADC potentiometer voltage reading | | |
| Not done | Partially done  (major problems) | Partially done  (minor problems) | Completed |
|  |  |  | *x* |
| We successfully completed the homework.  Next, we will explain all the steps for accomplishing our goals:  **Part 3a:**  Firstly, we configure the board pinouts for the ADC pin PA1 (connected to our board’s potentiometer as verified in the schematic file) as follows:    Then, from “*Analog” -> “ADC1”* we configure the parameters (after enabling IN1), setting the External Trigger Conversion Source as TRGO, that will be set soon from the Timer settings of the TIM2. Also we set the sampling time to 480 cycles:    And enabling the interrupt:    For the timer, we set the usual values (timeout parametrized by the constant TEMPO), plus we enable the TRGO to trigger the callback function of the ADC (Trigger Event Selection as *Update Event*):    Finally, we configure the UART, for remote transmission of the values read by the potentiometer to the remote MATLAB console, as done and explained in the previous homework (using DMA):    Then in the “main.c” file we initialized the TIM 2 base generation in interrupt mode and the ADC in interrupt mode with these functions:    We declared two global variables:   * *buffer* will contain the final string to send; * *voltage* will contain the voltage readed by the ADC after a proper conversion acted by the *reading* variable (from range 0/4096 to 0/3.3V).   The timer triggers the start of conversion at 1 Hz rate as required, then at the end of conversion the ADC generates an interrupt. We implemented the ADC callback function as follows:    The *snprintf()* function, given *buffer* and itssize*,* sets the buffer to contain the value of our measurement, truncated by 3 decimal positions. The length will contain the number of characters parsed in our buffer. Finally, we transmit the buffer with Direct Memory Access through our *uart2* interface.  Switching to MATLAB, we can now run the script “UART\_read\_data.m” to read the voltage values at baud rate 115200 bps (as set on our board): as in the previous homework, we successfully receive the data on our console.  **Part 3b:**  The pinout configuration is very similar to the previous project (part 3a)... | | | |
| Professor comments: | | | |