

# ECE 342 FINAL PROJECT

## *Enclosure Artifacts*

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# Contents

<b>1</b>	<b>Interfaces</b>	<b>3</b>
<b>2</b>	<b>Mechanical Drawings</b>	<b>4</b>
2.1	PCB . . . . .	4
2.2	Enclosure Bottom Mechanical Drawing . . . . .	5
2.3	Enclosure Bottom Model . . . . .	6
2.4	Enclosure Top Mechanical Drawing . . . . .	7
2.5	Enclosure Top Model . . . . .	8
<b>3</b>	<b>Final Product</b>	<b>9</b>
3.1	3D Model . . . . .	9
3.2	3D Printed Enclosure . . . . .	10

# 1 Interfaces

Interface table	
Interface	Properties
Inputs	
USB	USB type A for arduino power and serial communication. Dimensions: 470mils x 415mils or 11.94mm x 10.54mm
12V Power	Used to supply power to motors. Diameter: 380mil or 9.65mm
Sensor Inputs	Five pin right angle conector for sensor communication. Dimensions: 580mil x 223mil or 14.73mm x 8.20mm
Outputs	
Motors	Three 4 pin right angle connectors that connect the motors to the PCB. Dimensions: 483mil x 223mil or 12.27mm x 8.20mm
Fans	40 mm (1574.8mil) fans for air flow. Dimensions (screw holes): 32mm x 32mm or 1259.84mil x 1259.84mil
LCD	LCD used for debugging. Dimensions (screen): 2800mil x 950mil or 71.12mm x 24.13mm

Figure 1: Interface table for each of the components that will need a hole in the enclosure.

## 2 Mechanical Drawings

### 2.1 PCB

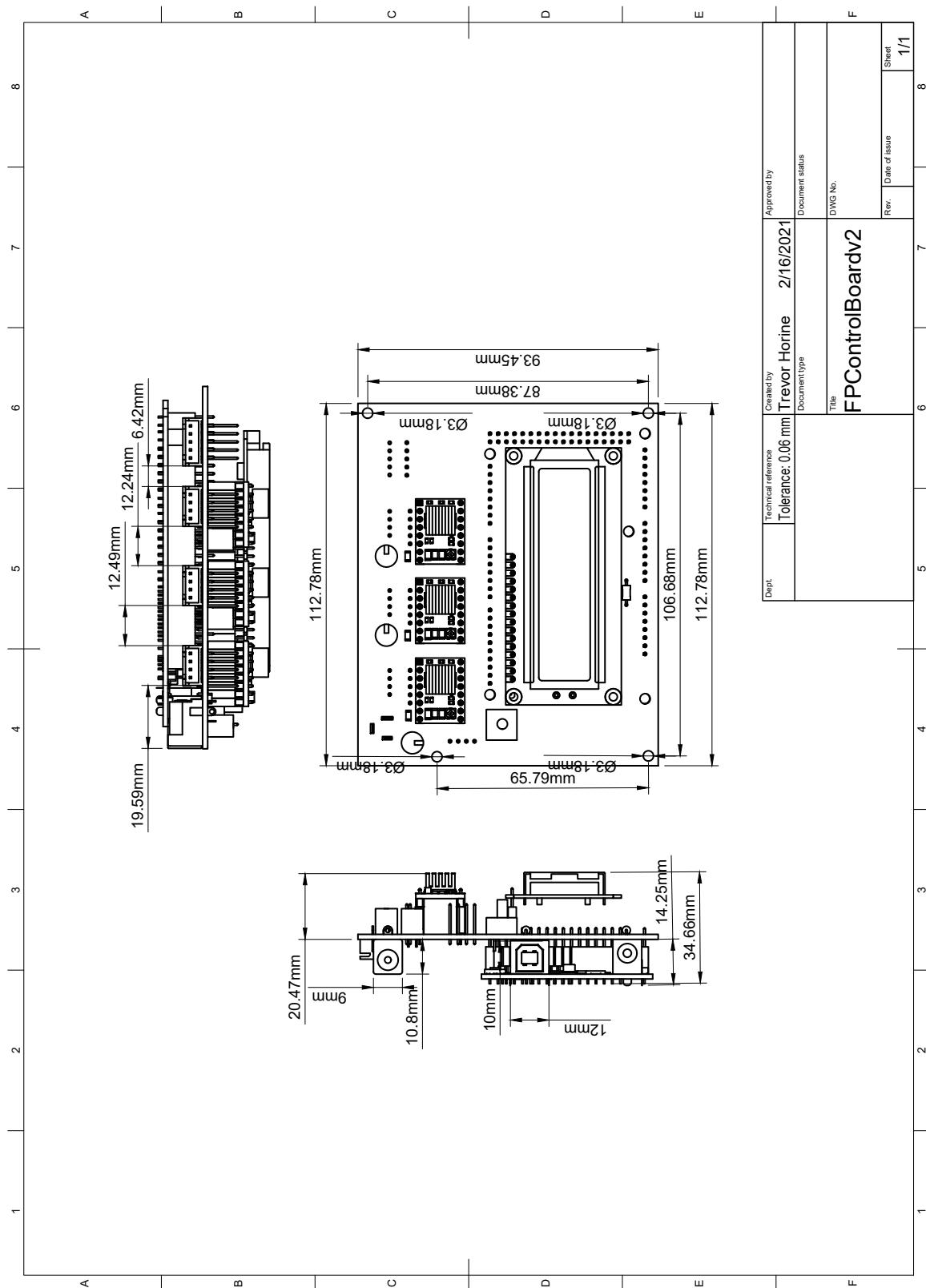


Figure 2: Mechanical drawing of PCB, with dimensions and locations of mounting holes

## 2.2 Enclosure Bottom Mechanical Drawing

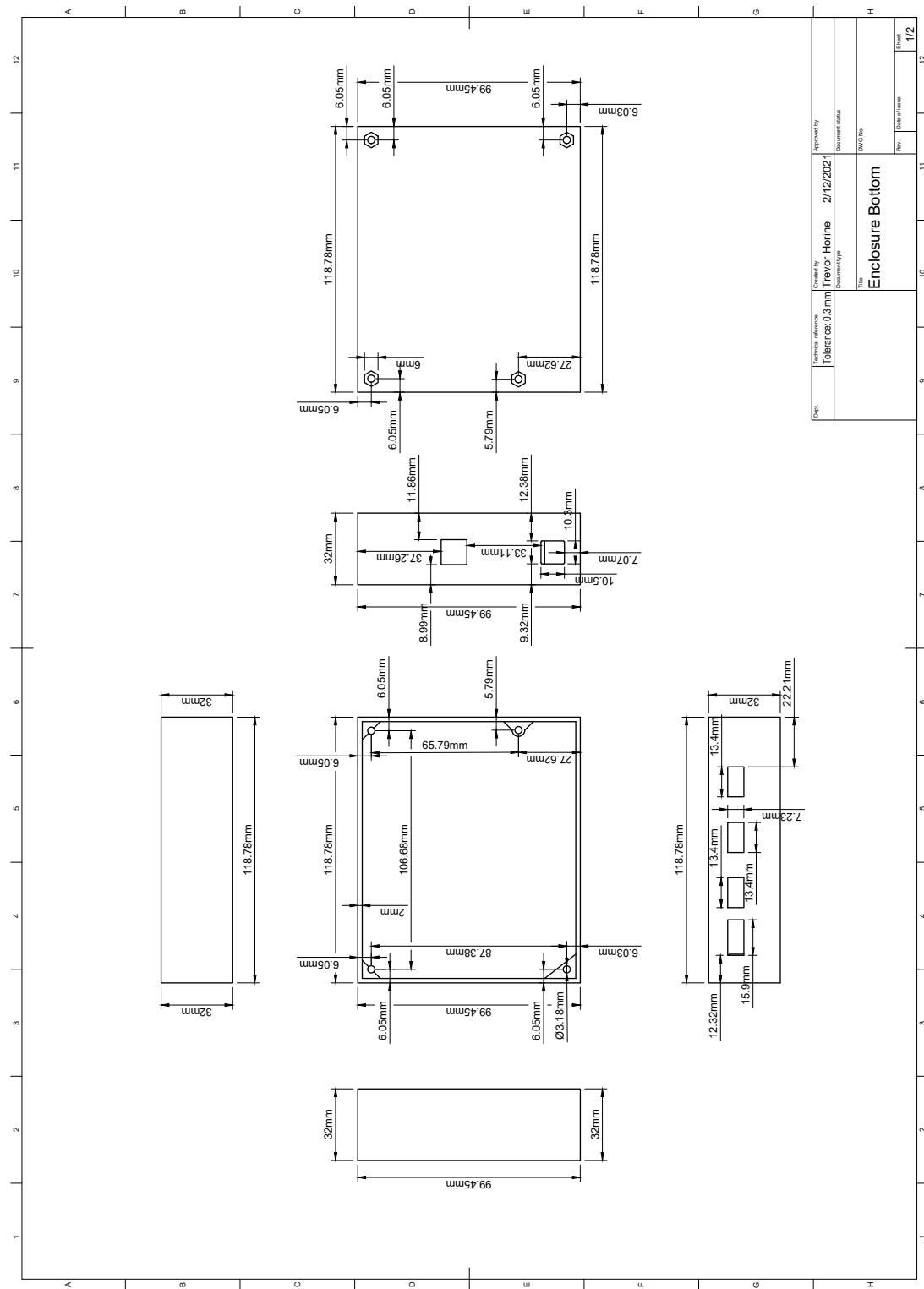


Figure 3: Mechanical drawing of the bottom half of the enclosure designed to hold the PCB.

### 2.3 Enclosure Bottom Model

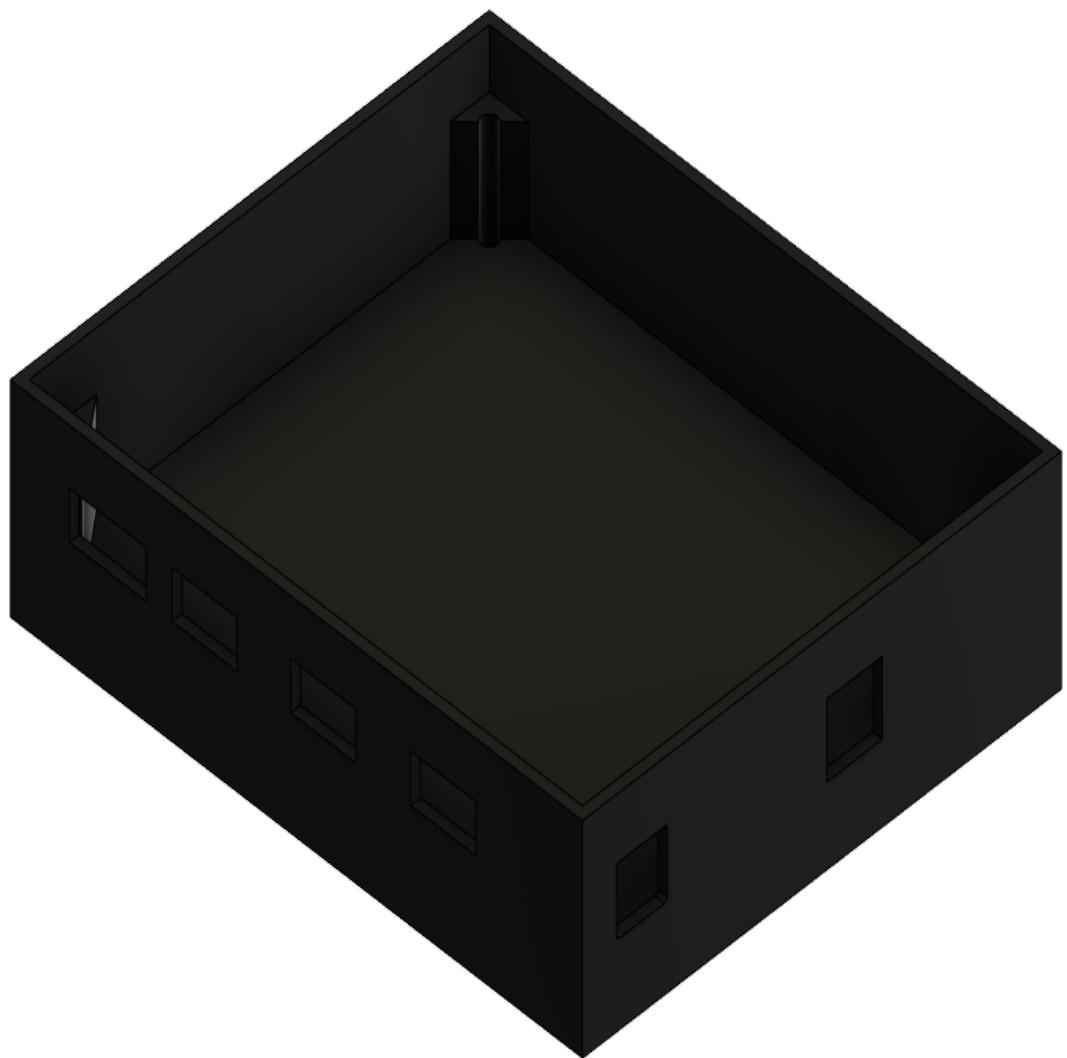


Figure 4: This is a rendering of the 3D model of the bottom half of the enclosure.

## 2.4 Enclosure Top Mechanical Drawing

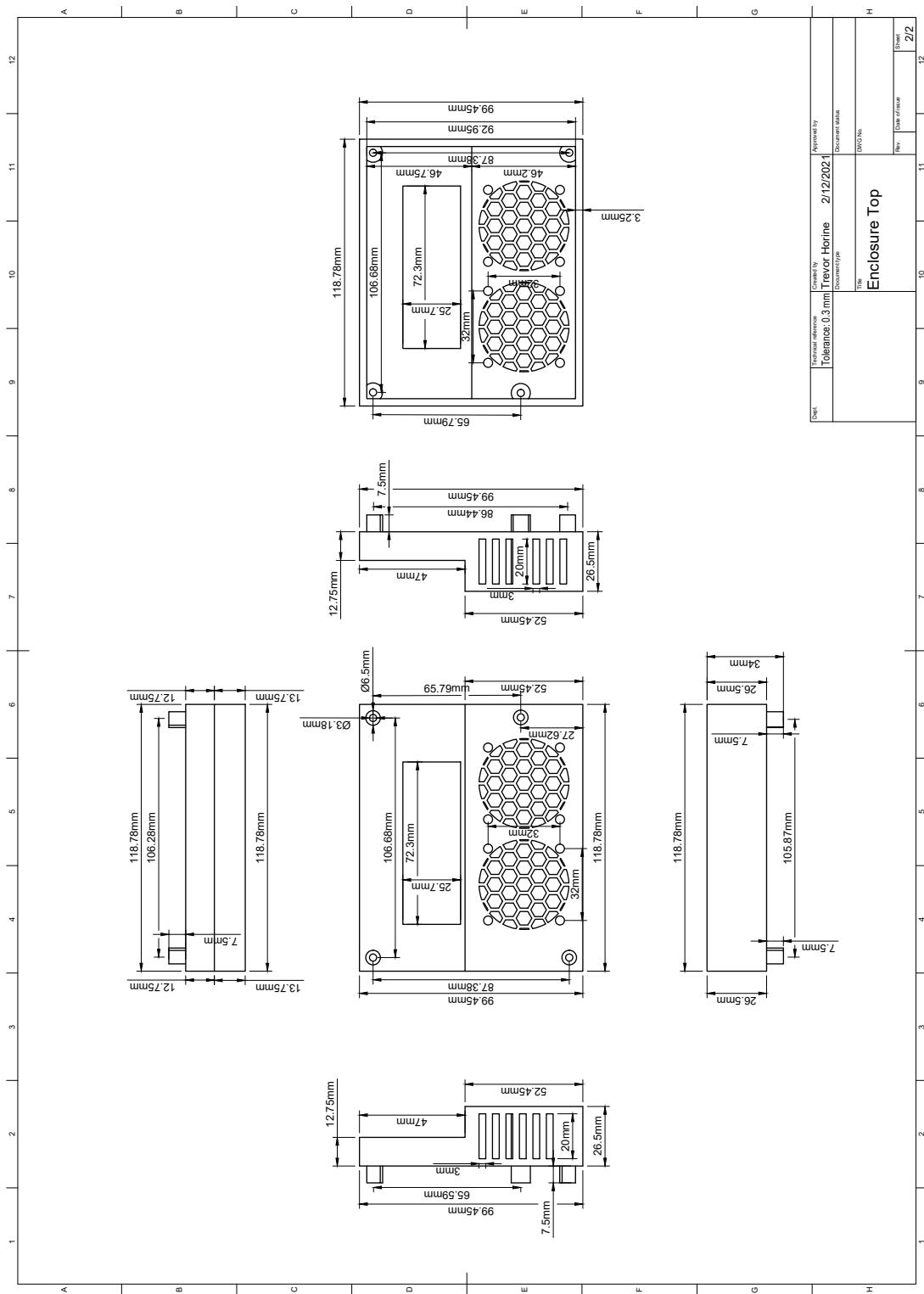


Figure 5: Mechanical drawing of the top half of the enclosure designed to hold the PCB.

## 2.5 Enclosure Top Model

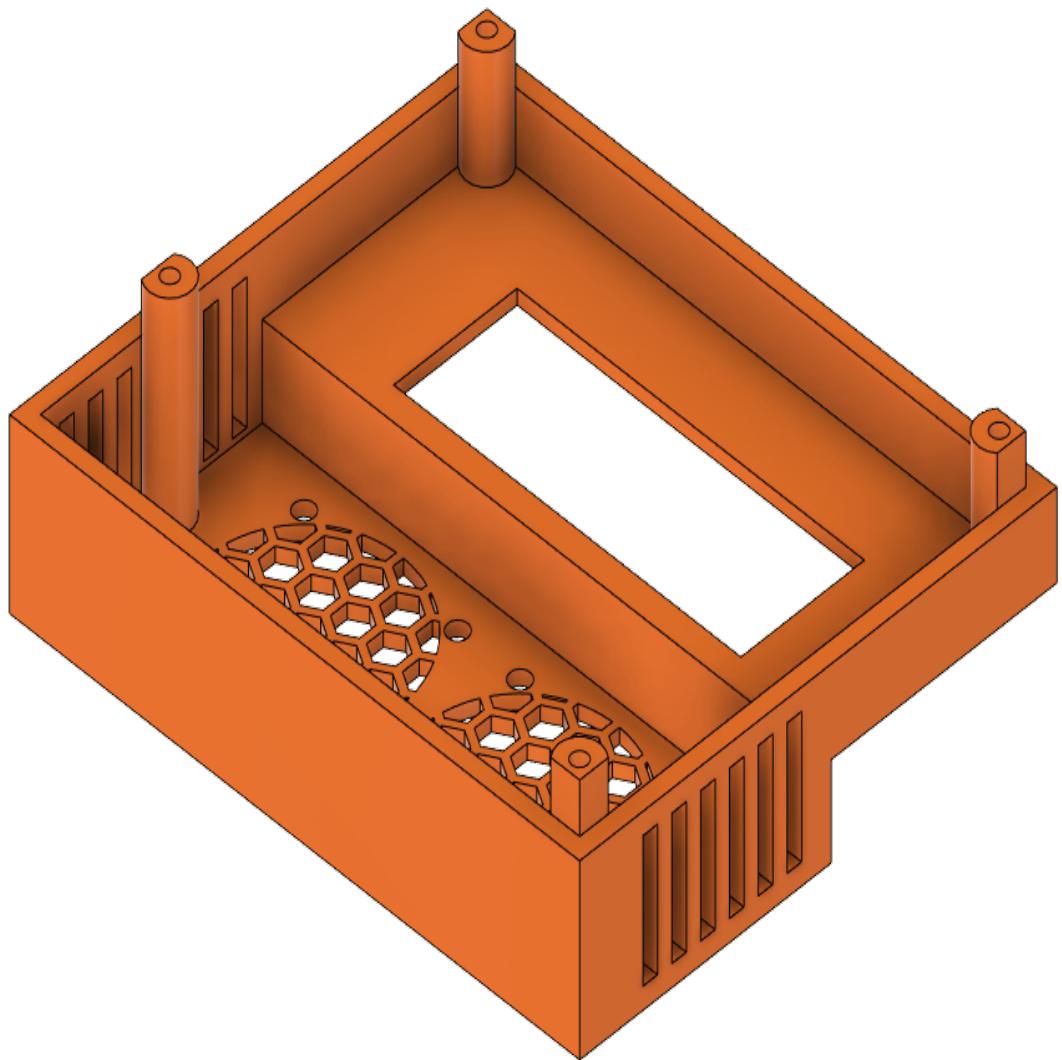


Figure 6: This is a rendering of the 3D model of the top half of the enclosure.

### 3 Final Product

#### 3.1 3D Model

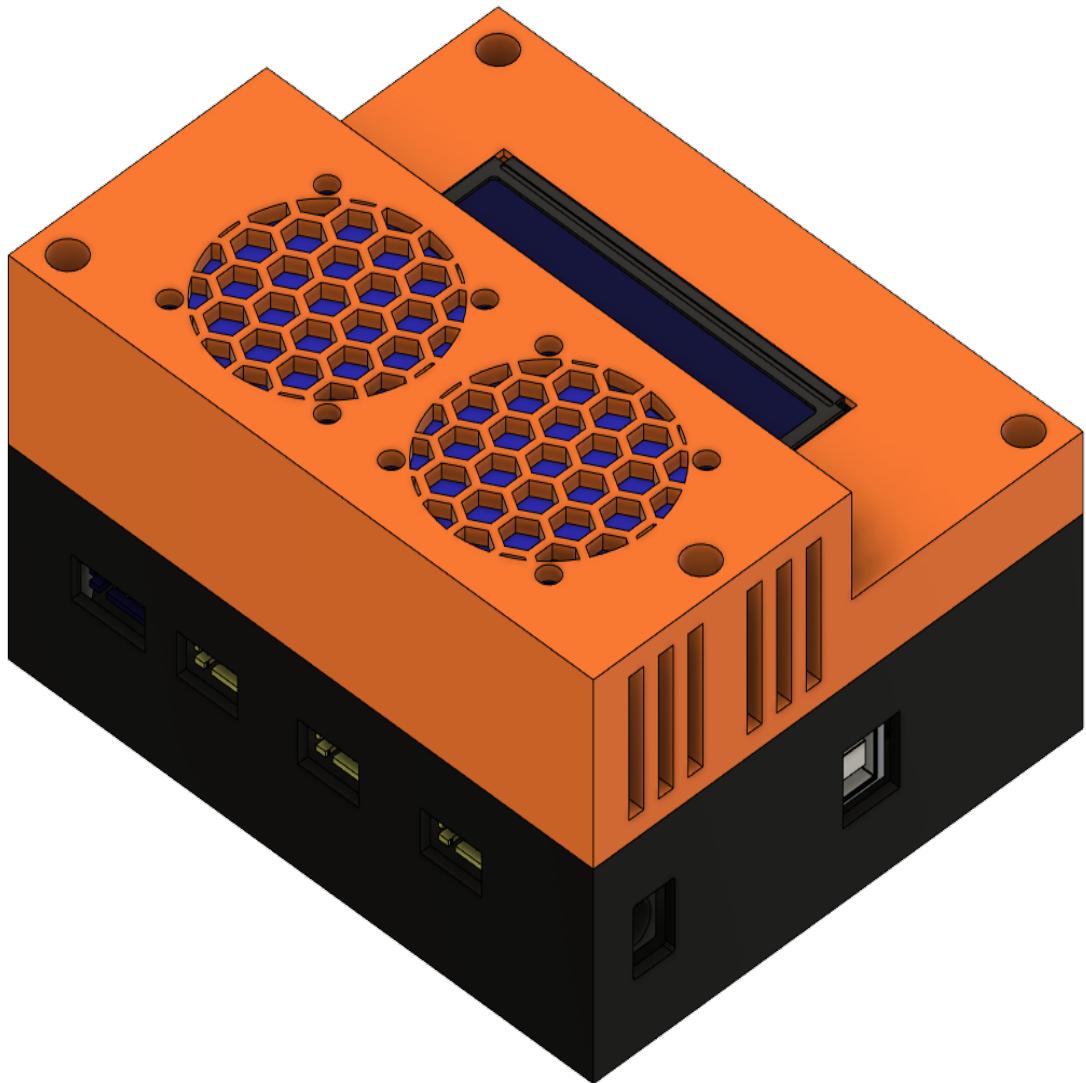


Figure 7: This is a rendering of the 3D model of what both pieces would look like together. This model has the model for the PCB inside, and has blue boxes for fans.

### 3.2 3D Printed Enclosure



Figure 8: This is a image of what the enclosure looks like with the board and fans inside.