

# Trevor M. Decker

## Employment History

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U.S. Citizen

### Research Assistant, CMU Field Robotics Center (2011 - Current)

- Assisted with software and hardware maintenance/development of 10+ robots
- Built multi-robot co-localization algorithms in low infrastructure environment
- Developed Kalman filter and EKF for sensor fusion
- Added vision system to robot to allow for automated initialization

### Intern, Amazon Prime Air (Summer 2015)

- Worked on computer vision and a real time embedded system for a new type of sensor
- Team is applying for multiple patents based on my work on the project
- Completed assigned internship project early, helped another intern finish a second project

### Intern, Volkswagen Electronics Research Laboratory (Summer 2014)

- Developed scalable architecture for sensor extrinsic calibration verification
- Upgraded legacy code to work with new system interface
- Participated in and helped organize Computer Vision reading group
- Won 3rd place at internal hackathon

### Introduction to robotics TA (Spring 2013,2014,2015)

- Co-created final lab for class 2013
- Designed new bayes filter localization lab, robots solve the lost robot problem
- Taught localization/state estimation lecture for professor
- Helped write and grade midterm/final 2014,2015

### Introduction to Electrical and Computer Engineering (Fall 2015)

- Responsible for helping students during labs and grading student homework

## Education

### Carnegie Mellon University (CMU), Pittsburgh, PA

- Masters of Science in Electrical Computer Engineering expect to graduate May 2016
- Bachelors of Science in Electrical Computer Engineering with minors in Computer Science, Robotics, and Business Administration (2015)

## Relevant Classes

### Mecatronic Design (Spring 2015)

- Received Coolest Robot award, Designed/built 5 degree of freedom robot to clean skyscraper windows
- Implemented vision system which can localise robot relative to the windows frame

### Real Time Embedded Systems (Fall 2014)

- Designed working RTOS with priority inversion

### Embedded Controls (Spring 2015)

- Programmed stable inverted pendulum

### Robot Kinematics And Dynamics (Spring 2014)

- Created kalman filter for vision system parameter estimation

### Computer Vision (Fall 2014)

- Designed optical text recognition system

## Activities

### Mentor, Girls Of Steel FIRST Robotics Team 3504 (2011 - 2013)

- Mentored CMU sponsored robotics team of 40+ high school girls
- Mentored programmers, who won Regional Innovation in Control award
- Co-taught Java programming course for students
- Acted as a Resident Assistant for 30 visiting Chinese students during a 2 week camp (2013)

Scan to see some of my work



### Robotic Buggy (2013 - Current)

- Creating a robot which can autonomously compete in a gravity race at CMU
- Lead Software Team (manage 8+ people) Responsible for all software and firmware
- Developed a scalable real time architecture for mapping,path planning, and localization
- Wrote motion model and observation model for GPS, IMU, encoders, cameras, ...
- Built computer vision road lane and building feature detectors to help extract robots state

### Apex Buggy Team (2011 - Current)

- Relay race at CMU with human driven carbon fiber carts built by students
- Co-founded team as a freshman (now has 40+ members), been an active member for 4+ years

<http://tinyurl.com/tdecker>

## Distinctions

- Computer Technician, Diagnosed repaired computers for 650+ students (2009 - 2011)
- Black Belt,Tang Soo Do Karate
- Volunteer of the Year,Carnegie Science Center 200+ hours (2007)

## Programming

Matlab ★★★★★

C ★★★★★

C++ ★★★★★

Java ★★★★★

Python ★★★★★

Verilog ★★★★★

HTML ★★★★★

PHP ★★★★★

JavaScript ★★★★★

SML ★★★★★

LaTex ★★★★★

## Libraries

ROS ★★★★★

Free RTOS ★★★★★

OpenCV ★★★★★

PCL ★★★★★

## Software

linux ★★★★★

Adobe Premiere ★★★★★

SolidWorks ★★★★★

## Mechanical

Mill ★★★★★

Lathe ★★★★★

3d printer ★★★★★

laser cutter ★★★★★

Carbon Fiber ★★★★★