1 Samurat Mondal

Roll: 2010/1105088

Numerical Method Lab

## LAB-1

NAME OF EXP.: Newton's Forward and Backward
Interpolation.

THEORY: The interpolation is the technique of estimating the value of a function for any intermediate value of the independent value.

· Newton's Forward Interpolation

If y = f(x) takes the value of  $y_0, y_1, \dots, y_m$ rowesponding to  $n = n_0, n_1, \dots, n_m$ , then

 $f(x) = y_0 + \mu \Delta y_0 + \frac{\mu(\mu-1)\Delta^2 y_0 + ... + \mu(\mu-1)...(\mu-n)}{2!}$   $x \Delta^n y_0$ 

where,  $M = \frac{\kappa - \kappa_0}{h}$ 

· Newton's Backward Interpolation  $f(x) = yn + \mu \Delta yn + \mu (\mu+1) \Delta^2 yn + \dots$   $\frac{2!}{2!}$   $+ \mu (\mu+1) \dots (\mu+(n-1)) \Delta^n yn$  n!

We use these two methods only if the values under re have equal intervals.

(2)

## CODING

Question -

Find the number of men getting wages between Rs 10 and Rs 15 from following data.

- · By Newton's Forward interpolation
- · Python

# calculating u mentioned in the formula

def u\_cal (u, n);

temp - u

for i in range (1, n):

temp = temp \* (u-i);

return temp;

# calculating factorial given number n

def fact (n):

for i in range (2, n+1):

return f;

```
(3)
       M = 4
       \mathcal{L} = [10, 20, 30, 40];
     # y[][] is used for difference table
       y = [[o \text{ for } i \text{ in range } (n)]] \text{ for } j \text{ in range } (n)];
       y[o][o] = 9;
       4[1][0] = 39;
        y[2][0] = 74;
         y[3][0] = 116;
    # Calculating the forward difference table
      for i in range (1, n):
           for j in range (n-i):
                 y [i] [i] = y[j+1][i-1] - y[j][i-1];
     brint ("_
     print (" n(i) y(i) y1 (i) y2(i) y3(i)");
     print ("
    # Displaying forward difference table
      for i in range (n):
           print (x[i], end = "\t\t\t");
              for j in range (n-i):
                  print (y [i] [j], end = "\t\t\t");
              print (" ");
```

```
4
```

tralue = 15;

# initialising u and sum

Sum = y [0] [0];

u = (value - ½ [0]) / (½ [1] - ½ [0]);

print (" u = ", u);

for i in range (1, n);

Sum = sum + (u - cal (u, i) \* y [0][i]) / fact(i);

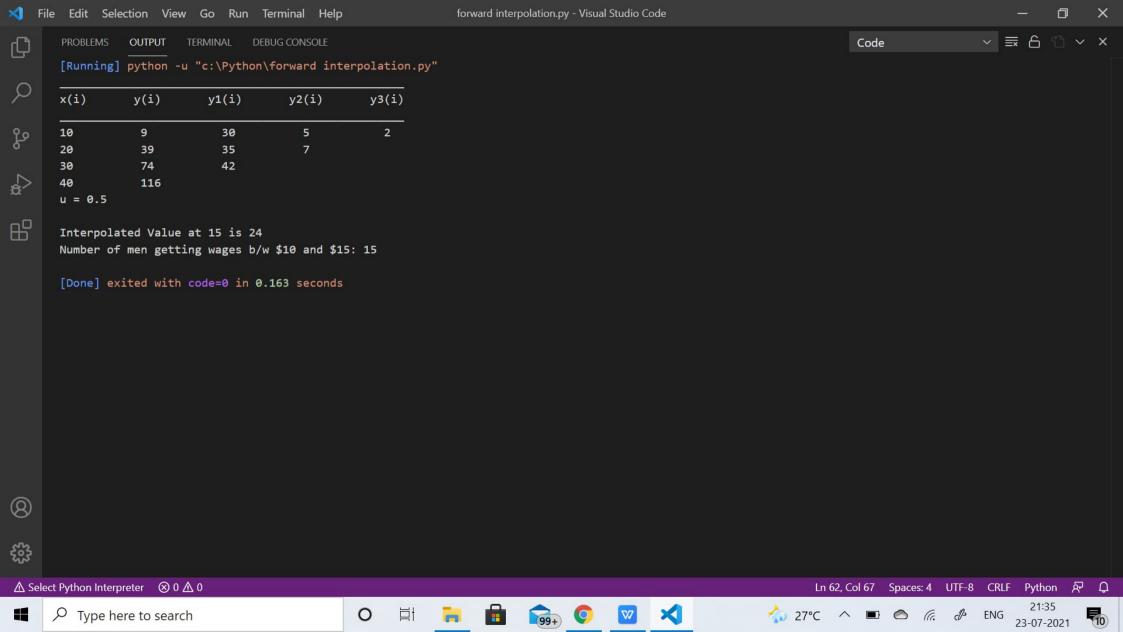
print (" \n Interpolated Value at ", value, " is", round (sum))

result = round (sum) - (y [0] [0]);

print (" Number of men getting wages by \$10 and \$15:",

result);

RESULT: The screenshot of the output is attached



Question: Find the lowest degree polynomial of the data and then calculate 
$$y(5)$$
 $\frac{\pi}{0}$ 
 $\frac{y}{0}$ 
 $\frac{\pi}{0}$ 
 $\frac{y}{0}$ 
 $\frac{\pi}{0}$ 
 $\frac{y}{0}$ 
 $\frac{\pi}{0}$ 
 $\frac{\pi}{0}$ 
 $\frac{y}{0}$ 
 $\frac{\pi}{0}$ 
 $\frac$ 

- · By Newton's Backward Interpolation
- · Python

# calculating u mentioned in the formula

def u = cal (u, n):

temp = u;

for i in range (1, n): temp = temp \* (u + i);

return temp;

# calculating factorial of given number n

def fact (n):

for i in range (2, m+1): f \* = i;

return f;

```
n = 5;
 \mathcal{K} = [0, 2, 4, 6, 8];
# y[][] is used for difference table
  y = [[o \text{ for } i \text{ in } range(n)] \text{ for } j \text{ in } range(n)],
  y[0][0] = 5;
  y[1][0] = 9;
  y[2][0] = 61;
  y[3][0] = 209;
  y[4][0] = 501;
# Calculating the backward difference table
  for i in range (1, n):
       for j in range (n-1, i-1, -1):
         y[i][i] = y[j][i-1] - y[i-1][i-1];
print (" Newton's Backward Interpolation");
brint ("
point (" n(i) y(i) y1(i) y2(i) y3(i) y4(i)");
print ("
# Displaying the table
  for i in range (0, n):
       print (n[i], end = "\t\t\t");
       for j' in range (0, i+1):
```

```
print (y[i][j], end = " \t \t \t \t");
     brint (" ");
 Value = 5;
 Sum = y [4][0];
 n = (Value - n[4])/(n[1] - n[0]);
 print (" u = " , u);
 for i in range (1, n):
        sum = sum + (u_cal (u,i) * y[4][i])/fact(i);
 print ("In Interpolated Value at", value, "is", sum);
KESULT: The screenshot of the output is attached
             below.
LONCLUSION: In this lab we learnt how to
               estimate the value of a function
               for any intermediate value of the independent
```

variable using Newton's Forward

and Backward Interpolation.

