

# Freshness Value Manager

**Technical Reference** 

Complex Device Driver Version 2.0.0

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### **Document Information**

# **History**

Author	Date	Version	Remarks
Florian Röhm	2017-02-20	1.0.0	Initial creation
Heiko Hübler	2017-02-23	1.0.0	FEATC-1186: Release TMC Security Modules: Freshness Handling (FvM)
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### **Reference Documents**

No.	Source	Title	Version
[1]	Toyota	E/E PF BSW Reference Implementation Requirement Specification	19pfbswrefrs-a00-00-a
[2]	AUTOSAR	AUTOSAR_SWS_DET.pdf	4.0.3
[3]	AUTOSAR	AUTOSAR_BasicSoftwareModules.pdf	V1.0.0



### **Caution**

We have configured the programs in accordance with your specifications in the questionnaire. Whereas the programs do support other configurations than the one specified in your questionnaire, Vector's release of the programs delivered to your company is expressly restricted to the configuration you have specified in the questionnaire.



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# 1 Component History

The component history gives an overview over the important milestones that are supported in the different versions of the component.

Component Version	New Features
1.00.00	> Initial version
1.01.01	> Support of Freshness verify value padding
	> Rx Freshness value construction pattern according to [1]
1.02.00	> QM Release of the Freshness Value Manager module

Table 1-1 Component history



### 2 Introduction

This document describes the functionality, API and configuration of the CDD FvM as specified in [1].

Supported AUTOSAR Release*:	4.3	
Supported Configuration Variants:	Pre-compile	
Vendor ID:	FvM_VENDOR_ID	30 decimal
		(= Vector-Informatik, according to HIS)
Module ID:	FvM_MODULE_ID	255 decimal
		(according to ref. [3])

<sup>\*</sup> For the detailed functional specification please also refer to the corresponding AUTOSAR SWS.

The Freshness Value Manager stores the freshness values used by the SecOC module.

It is responsible to keep track of the correct incrementation of the counters (Tx path) and the correct reconstruction of the counter (Rx path). The global sync messages are received by the FvM as well and will be stored and used for the generation of the freshness values.

### 2.1 Architecture Overview

The following figure shows where the FvM is located in the AUTOSAR architecture.

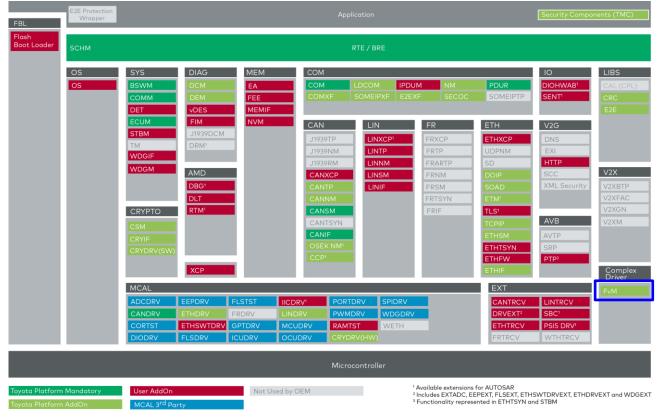


Figure 2-1 AUTOSAR Architecture Overview



# 3 Functional Description

### 3.1 Features

The features listed in the following tables cover the complete functionality specified for the FvM.

The functionality is specified in [1], the corresponding features are listed in Table 3-1.

The following features specified in [1] are supported:

### **Supported Features**

- Providing Tx and Rx freshness values for SecOC
- Trip and Reset Counter synchronization

Table 3-1 Supported features

### 3.2 Initialization

The FvM has to be initialized by calling FvM\_Init() before it can be used.

If variables exist which cannot be initialized by the startup code the function FvM InitMemory() has to be called.

### 3.3 States

Initially the FvM is in state uninitialized. In this state no API can be used if the parameter checks are activated. The FvM can be brought to state initialized by calling the FvM\_Init API. It can be uninitialized again by calling FvM DeInit.

Furthermore the FvM has a sync state. Figure 3-1 shows the corresponding state machine.



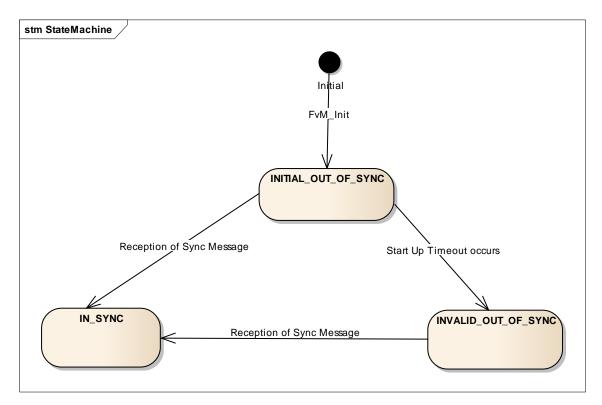


Figure 3-1 Sync Status State machine

### 3.4 Freshness Value

The freshness verify value is constructed with Trip-Counter, Reset-Counter, Message-Counter and Rest Flag.



### Freshness Value Parts:

Trip-Counter	Counter is incremented per driving cycle.
	This freshness value part is equal for each freshness value.
Reset-Counter	Counter is incremented cyclically by the freshness value master and
	reset if the Trip-Counter is incremented.
	This freshness value part is equal for each freshness value.
Message-	Counter is incremented on message transmit of a specific message.
Counter	This freshness value part exists per message.
Reset Flag	Least significant bits of the Reset-Counter

### 3.4.1 Freshness Value Synchronization

The Trip-Counter and Reset-Counter are transmitted by the freshness value master in a Sync-Message. The Sync-Message is protected by a MAC against manipulation. The MAC verification is handled by the SecOC.



### 3.4.2 Start Up Acceptance Time

If the parameter FvMStartUpAcceptanceTime is configured, the FvM will set the SecOC in an "accept all messages" state after start up. This "accept all messages" state of the SecOC is left if the "Start Up Acceptance Time" is over.

### 3.5 Main Functions

FvM provides following functions listed in Table 3-2 that have to be called cyclically by the Basic Software Scheduler or a similar component.

Main Function	Description
FvM_MainFunction()	This function decrements the Startup Cycle Counter. This function must be called cyclically with a cycle time identical to the configured Main Function Period.

Table 3-2 Main Functions

### 3.6 Error Handling

### 3.6.1 Development Error Reporting

By default, development errors are reported to the DET using the service Det\_ReportError() as specified in [2], if development error reporting is enabled (i.e. pre-compile parameter FvM DEV ERROR DETECT==STD ON).

If another module is used for development error reporting, the function prototype for reporting the error can be configured by the integrator, but must have the same signature as the service  $Det_ReportError()$ .

The reported FvM ID is 255.

The reported service IDs identify the services which are described in 5.1. The following table presents the service IDs and the related services:

Service ID	Service
FVM_SID_INIT	FvM_Init
FVM_SID_DEINIT	FvM_DeInit
FVM_SID_GET_VERSION_INFO	FvM_GetVersionInfo
FVM_SID_GET_RX_FRESHNESS	FvM_GetRxFreshness
FVM_SID_GET_TX_FRESHNESS	SecOC_GetTxFreshnessTruncData
FVM_SID_TX_FRESHNESS_CONFIRMATION	SecOC_SPduTxConfirmation
FVM_SID_VERIFICATION_STATUS_CALLOUT	FvM_VerificationStatusCallout

Table 3-3 Service IDs

The errors reported to DET are described in the following table:

Error Code	Description
FVM_E_PARAM_CONFIG	API service FvM_Init() called with wrong parameter.



Error Code	Description
FVM_E_PARAM	API service called with wrong parameter.
FVM_E_PARAM_POINTER	API service used with invalid pointer parameter (NULL).
FVM_E_UNINIT	API service used without module initialization.
FVM_E_ALREADY_INITIALIZED	The service FvM_Init() is called while the module is already initialized.
FVM_E_INVALID_REQUEST	The service FvM_DeInit() is called although the module is already de-initialized.

Table 3-4 Errors reported to DET



# 4 Integration

This chapter gives necessary information for the integration of the MICROSAR FvM into an application environment of an ECU.

### 4.1 Scope of Delivery

The delivery of the FvM contains the files which are described in the chapters 4.1.1 and 4.1.2:

### 4.1.1 Static Files

File Name	Description
FvM.c	This is the source file of the FvM.
FvM.h	This is the header file of the FvM.

Table 4-1 Static files

### 4.1.2 Dynamic Files

The dynamic files are generated by the configuration tool Davinci Configurator 5.

File Name	Description
FvM_Cfg.h	This file contains:      global constant macros     global function macros     global data types and structures     global data prototypes     global function prototypes     of CONFIG-CLASS PRE-COMPILE data.
FvM_Lcfg.h	This file contains:      global constant macros      global function macros      global data types and structures      global data prototypes      global function prototypes      GONFIG-CLASS LINK data.
FvM_Lcfg.c	This file contains:  local constant macros  local function macros  local data types and structures  local data prototypes  local data  global data  of CONFIG-CLASS LINK and PRE-COMPILE data.
FvM_PBcfg.h	This file contains:  • global constant macros  • global function macros



File Name	<ul> <li>▶ global data types and structures</li> <li>▶ global data prototypes</li> <li>▶ global function prototypes</li> <li>of CONFIG-CLASS POST-BUILD data.</li> </ul>
FvM_PBcfg.c	This file contains:  local constant macros  local function macros  local data types and structures  local data prototypes  local data  global data  of CONFIG-CLASS POST-BUILD data.
FvM_Types.h	This file contains types and defines for the FvM.

Table 4-2 Generated files

### 4.2 Critical Sections

► FVM\_EXCLUSIVE\_AREA\_RX\_FRESHNESS

This critical section protects RAM variables used for the Rx path.

► FVM\_EXCLUSIVE\_AREA\_TX\_FRESHNESS

This critical section protects RAM variables used for the Tx Path.



# 5 API Description

### 5.1 Services provided by FvM

### 5.1.1 FvM\_InitMemory

### **Prototype**

void FvM InitMemory (void)

### **Parameter**

void none

### Return code

void none

### **Functional Description**

Function for \*\_INIT\_\*-variable initialization.

### **Particularities and Limitations**

Module is uninitialized.

Service to initialize module global variables at power up. This function initializes the variables in \*\_INIT\_\* sections. Used in case they are not initialized by the startup code.

### Call context

- > TASK
- > This function is Synchronous
- This function is Non-Reentrant

Table 5-1 FvM\_InitMemory

### 5.1.2 FvM\_Delnit

### **Prototype**

void FvM\_DeInit (void)

### **Parameter**

void none

### Return code

void none

### **Functional Description**

DeInitialization function.

### **Particularities and Limitations**

Specification of module initialization

> Interrupts are disabled. Module is initialized.

This function sets the module state to uninitialized.

### Call context

> TASK



- > This function is Synchronous
- > This function is Non-Reentrant

Table 5-2 FvM\_Delnit

### 5.1.3 FvM\_Init

Prototype		
<pre>void FvM_Init (const FvM_ConfigType *ConfigPtr)</pre>		
Parameter		
ConfigPtr [in] Configuration structure for initializing the module		
Return code		
void	none	
Functional Description		

### Functional Description

Initialization function.

### **Particularities and Limitations**

Specification of module initialization

> Interrupts are disabled. Module is uninitialized. FvM\_InitMemory has been called unless FvM is initialized by start-up code.

This function initializes the module FvM. It initializes all variables and sets the module state to initialized.

### Call context

- > TASK
- > This function is Synchronous
- > This function is Non-Reentrant

Table 5-3 FvM\_Init

### 5.1.4 FvM\_GetVersionInfo

Prototype		
void FvM_GetVersionI	nfo (Std_VersionInfoType *versioninfo)	
Parameter		
versioninfo [out]	Pointer to where to store the version information. Parameter must not be NULL.	
Return code		
void	none	
Functional Description		
Returns the version information.		
Particularities and Limitations		
none		
FvM_GetVersionInfo() returns version information, vendor ID and AUTOSAR module ID of the component.		
Call context		
> TASK ISR2		



- > This function is Synchronous
- > This function is Reentrant

Table 5-4 FvM\_GetVersionInfo



**Prototype** 

### 5.1.5 SecOC GetRxFreshness

# Std\_ReturnType SecOC\_GetRxFreshness ( uint16 SecOCFreshnessValueID, const uint8 \*SecOCTruncatedFreshnessValue, uint32 SecOCTruncatedFreshnessValueLength, uint16 SecOCAuthVerifyAttempts, uint8 \*SecOCFreshnessValue,

uint32 \*SecOCFreshnessValueLength)

Parameter	
SecOCFreshnessValueID	Holds the identifier of the freshness value.
SecOCTruncatedFreshnessValue	Holds the truncated freshness value that was contained in the Secured I-PDU.
SecOCTruncatedFreshnessValueLength	Holds the length in bits of the truncated freshness value.
SecOCAuthVerifyAttempts	Holds the number of authentication verify attempts of this PDU since the last reception. The value is 0 for the first attempt and incremented on every unsuccessful verification attempt.
SecOCFreshnessValue	Holds the length in bits of the freshness value.
SecOCFreshnessValueLength	Holds the freshness value to be used for the calculation of the authenticator.

Return code	
Std_ReturnType	E_OK: request successful  E_NOT_OK: request failed, a freshness value cannot be provided due to general issues for freshness or this FreshnessValueId.
	E_BUSY: The freshness information can temporarily not be provided.

### **Functional Description**

This interface is used by the SecOC to obtain the current freshness value.

### **Particularities and Limitations**

> None

### Call context

> TASK

Table 5-5 SecOC\_GetRxFreshness



### 5.1.6 SecOC\_GetTxFreshnessTruncData

### **Prototype**

### Single Channel

```
Std_ReturnType SecOC_GetTxFreshnessTruncData (uint16 SecOCFreshnessValueID, uint8* SecOCFreshnessValue, uint32* SecOCFreshnessValueLength, uint8* SecOCTruncatedFreshnessValue, uint32* SecOCTruncatedFreshnessValueLength)
```

Parameter	
SecOCFreshnessValueID	Holds the identifier of the freshness value.
SecOCFreshnessValueLength	Holds the length of the provided freshness in bits.
SecOCTruncatedFreshnessValueLength	Provides the truncated freshness length configured for this freshness. The function may adapt the value if needed or can leave it unchanged if the configured length and provided length is the same.
SecOCFreshnessValue	Holds the current freshness value
SecOCTruncatedFreshnessValue	Holds the truncated freshness to be included into the Secured I-PDU. The parameter is optional.

Return code		
Std_ReturnType	E_OK: request successful	
	E_NOT_OK: request failed, a freshness value cannot be provided due to general issues for freshness or this FreshnessValueld.	
	E_BUSY: The freshness information can temporarily not be provided	

### **Functional Description**

This interface is used by the SecOC to obtain the current freshness value. The interface function provides the truncated freshness transmitted in the secured I-PDU as well.

### **Particularities and Limitations**

> none

### Call context

> TASK

Table 5-6 SecOC\_GetTxFreshnessTruncData



# 5.1.7 SecOC\_SPduTxConfirmation

Prototype		
Single Channel		
void SecOC_SPduTxConfirmation (uint16 SecOCFreshnessValueID)		
Parameter		
SecOCFreshnessValueID	Holds the identifier of the freshness value.	
Return code		
void	None	
Functional Description		
This interface is used by the SecOC to indicate that the Secured I-PDU has been initiated for transmission.		
Particularities and Limitations		
> none		
Call context		
> TASK   ISR2		
> This function is synchronous.		
> This function is reentrant for different freshness value lds.		

Table 5-7 SecOC\_SPduTxConfirmation



### 5.2 Services used by FvM

In the following table services provided by other components, which are used by the FvM are listed. For details about prototype and functionality refer to the documentation of the providing component.

Component	API
DET	Det_ReportError

Table 5-8 Services used by the FvM

# 5.3 Configurable Interfaces

### **5.3.1 Notification Functions**

### 5.3.1.1 <FvMTripCounterReachMaxNotification>

Prototype		
<pre>void <fvmtripcounterreachmaxnotification> (void)</fvmtripcounterreachmaxnotification></pre>		
Parameter		
none	none	
Return code		
void	none	
Functional Description		
Notification function that is called if the max value is reached.		
Particularities and Limitations		
none		
Call context		
> TASK ISR2		
> This function is Synchronous		
> This function is not Reentrant		

Table 5-9 <FvMTripCounterReachMaxNotification>

### 5.3.1.2 <FvMResetCounterReachMaxNotification>

Prototype		
void <fvmresetcounterreachmaxnotification> (void)</fvmresetcounterreachmaxnotification>		
Parameter		
none	none	
Return code		
void	none	
Functional Description		
Notification function that is called if the max value is reached.		



# **Particularities and Limitations**

none

### Call context

- > TASK|ISR2
- > This function is Synchronous
- > This function is not Reentrant

Table 5-10 <FvMResetCounterReachMaxNotification>

# 5.3.1.3 <FvMRxMessageCounterReachMaxNotification>

Prototype			
void <fvmrxmessagecounterreachmaxnotification> (uint16 freshnessValueID)</fvmrxmessagecounterreachmaxnotification>			
Parameter			
freshnessValueID[in]	freshness value id.		
Return code			
void	none		
Functional Description			
Notification function that is called if the max value is reached.			
Particularities and Limitations			
none			
Call context			
> TASK ISR2			
> This function is Synchronous			
> This function is Reentrant for different freshness value lds			

Table 5-11 <FvMRxMessageCounterReachMaxNotification>

# 5.3.1.4 <FvMTxMessageCounterReachMaxNotification>

Prototype		
void <fvmtxmessagecounterreachmaxnotification> (uint16 freshnessValueID)</fvmtxmessagecounterreachmaxnotification>		
Parameter		
freshnessValueID[in]	freshness value id.	
Return code		
void	none	
Functional Description		
Notification function that is called if the max value is reached.		
Particularities and Limitations		
none		
Call context		



- > TASK|ISR2
- > This function is Synchronous
- > This function is Reentrant for different freshness value Ids

Table 5-12 <FvMTxMessageCounterReachMaxNotification>

### 5.3.2 Callout Functions

### 5.3.2.1 FvM\_VerificationStatusCallout

# **Prototype**

void FvM\_VerificationStatusCallout (SecOC\_VerificationStatusType
verificationStatus)

₽.		ra	0.0	100	7	T2
	rσI	111111111111111111111111111111111111111		L WILL	N wil	

verificationStatus [in] Status of the verification and freshness value id.

### Return code

void none

### **Functional Description**

Called to indicate the verification status.

### **Particularities and Limitations**

### none

FvM\_VerificationStatusCallout() is called by the SecOC to indicate if the verification was successful or failed.

### Call context

- > TASK|ISR2
- > This function is Synchronous
- > This function is Reentrant

Table 5-13 FvM\_VerificationStatusCallout



# 6 Configuration

# 6.1 Configuration Variants

The FvM supports the configuration variants

> VARIANT-PRE-COMPILE

The configuration classes of the FvM parameters depend on the supported configuration variants. For their definitions please see the FvM\_bswmd.arxml file.



# 7 Glossary and Abbreviations

# 7.1 Glossary

Term	Description
EAD	Embedded Architecture Designer; generation tool for MICROSAR components

Table 7-1 Glossary

### 7.2 Abbreviations

Abbreviation	Description
API	Application Programming Interface
AUTOSAR	Automotive Open System Architecture
BSW	Basis Software
CDD	Complex Device Driver
DET	Development Error Tracer
ECU	Electronic Control Unit
ISR	Interrupt Service Routine
MICROSAR	Microcontroller Open System Architecture (the Vector AUTOSAR solution)
RTE	Runtime Environment
SRS	Software Requirement Specification
SWC	Software Component
SWS	Software Specification

Table 7-2 Abbreviations



# 8 Contact

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