$\frac{dn}{dt} = \frac{dn}{dx^{2}} = f(l,t)$ (x,t)  $\in (0,1)$   $\times (0,1)$ N(1,0)=(in N(1)  $f(x,t) = (\pi^2 - 1)e^{-t}sin(x)$ u(0) + 1 = u(1) + 1 = 0Analytic Suluxica N= 11 Nodes  $M(x,t) = e^{-t} S \cdot n(x x)$ Where they can be seaced 65 any 0:x:N f(xit) = usyrinput

1), weak Form

$$\frac{du}{d\tau} - \frac{du}{dx} = f(x,t)$$

$$\int_{0}^{t} \frac{du}{d\tau} v(x) dx - \int_{0}^{t} \frac{du}{dx} v(x) du = \int_{0}^{t} f(x,t) v(x) dx$$

$$\int_{0}^{t} \frac{du}{d\tau} v(x) dx - \int_{0}^{t} \frac{du}{dx} v(x) dx$$

$$V = \frac{du}{dx} d$$

$$\alpha e e (4) \quad \text{Boundary Conditions}$$

$$\alpha (x,0) = \sin(\alpha x)$$

$$u(0)+1=u(1)+1=0$$

$$\int \frac{\partial +}{\partial x} V(x) dx - V(x) \frac{\partial x}{\partial x} \Big|_{0} + \int_{0}^{0} \frac{J(x)}{\partial x} dx = \int_{0}^{1} f(x, +) V(x) dx$$

$$q \times - \Lambda(x)$$

$$(x)\frac{\partial x}{\partial x}\Big|_{0}^{0}+\int$$

$$\int_0^0 \frac{J_i x}{3 N}$$

 $\phi_i(x) = \phi_i(x) = sin(xx)$ 





VCX7 = Ø; CX/  $\int_{0}^{\infty} \frac{\partial u}{\partial t} dt dt dt + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} dx - \int_{0}^{1} f(x, t) dx = 0$ 



$$R'_{i} = \int_{0}^{1} \left( \frac{u(t+\delta t) - u(t)}{0 + t} \right) \varphi_{i}(x) dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial P_{i}}{\partial x} dx - \int_{0}^{1} \frac{f(x)t}{f(x)} dx$$

$$= \int_{0}^{1} \left( \frac{u(t+\delta t) - u(t)}{0 + t} \right) \varphi_{i}(x) dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial P_{i}}{\partial x} dx - \int_{0}^{1} \frac{f(x)t}{f(x)} dx$$

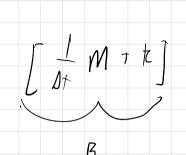
$$= \int_{0}^{1} \left( \frac{u(t+\delta t) - u(t)}{0 + t} \right) \varphi_{i}(x) dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial P_{i}}{\partial x} dx - \int_{0}^{1} \frac{f(x)t}{f(x)} \frac{\partial u}{\partial x} dx$$

$$= \int_{0}^{1} \left( \frac{u(t+\delta t) - u(t)}{0 + t} \right) \varphi_{i}(x) dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx - \int_{0}^{1} \frac{f(x)t}{f(x)} \frac{\partial u}{\partial x} dx - \int_{0}^{1} \frac{f(x)t}{f(x)} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx - \int_{0}^{1} \frac{f(x)t}{f(x)} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dx + \int_{0}^{1} \frac{\partial u}{\partial x} \frac{\partial u}{$$

$$\frac{1}{0+} m \vec{u}^{n+1} - f m \vec{u}^{n} + k \vec{u}^{n} - f^{n} = 0$$

$$\frac{1}{0+} n \vec{u}^{n} \left[ \vec{1} - 0 + m^{n} k \right] + 0 + m^{-1} f^{n}$$

## **Backward Euler (same steps as forward)**



$$\hat{h} = \frac{1}{2r} B^{-1} M \hat{n} + B \hat{F}$$

$$\frac{1}{2} = \int_{-1}^{1} \left(\frac{2}{h} - \frac{1}{2}\right) \left(\frac{2}{h} - \frac{1}{2}\right) \frac{h}{2} d\xi$$
Using quadrature for local elements
$$= \int_{-1}^{1} \int_{2h}^{1} \int_{-1}^{1} d\xi d\xi$$

$$= \int_{-1}^{1} \int_{2h}^{1} \int_{-1}^{1} d\xi d\xi$$

$$= \int_{-1}^{1} \int_{2h}^{1} \int_{-1}^{1} d\xi d\xi$$

$$= \int_{-1}^{1} \int_{-1}^{1} \int_{2h}^{1} \int_{-1}^{1} d\xi d\xi$$

 $=\frac{4}{8}\int_{-1}^{1}(1-\frac{3}{2})^{2}d\frac{3}{2}$