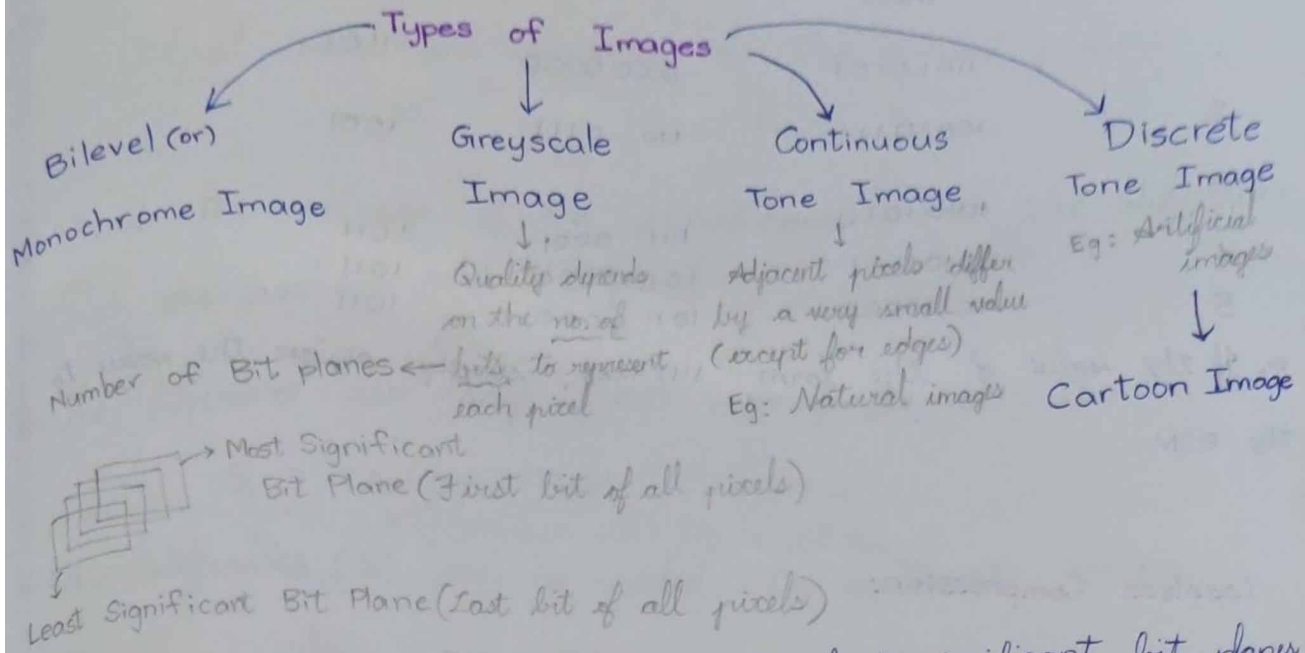


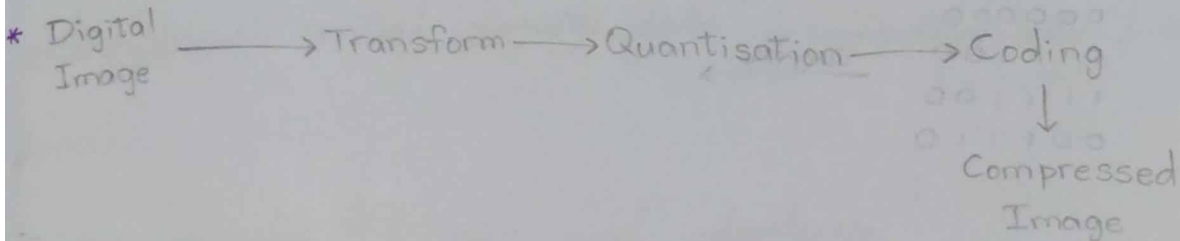
# IMAGES



\* Compression can be achieved by removing the least significant bit planes

\* Sampling → Converting continuous data to discrete/digital data  
Eg: Taking a photo with a camera

Quantisation → Assigning values to each pixel of an image



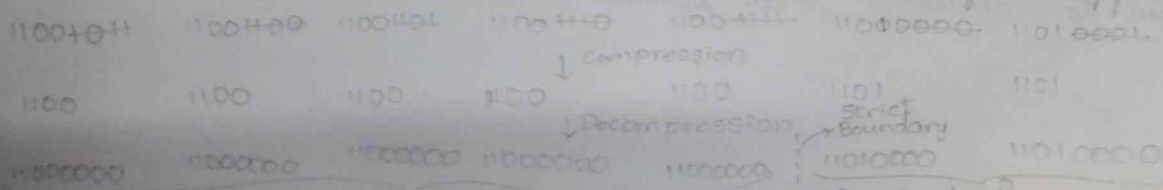
## Scalar Quantisation: 8-bit image



\* In scalar quantisation, we just remove the last few bits from each pixel.

\* Not an optimal quantisation technique → Causes the formation of prominent edges

Artificial appearance



## Improved Grayscale Quantisation:

S.No.	VALUE	RSM	COMPRESSED STREAM
1	11010101	0000 0000	1101
2	10010111	1001 0111	1001
3	10101010	1011 0001	1011
4	10101111	1011 0000	1011
5	10110000	1011 0000	1011

\*. If the value of the form 1111 xxxx, simply assign the value to the RSM

## Lossless Compression:

Eg: 212 214 216 216 217 215

212  $\rightarrow$  -2 +2 +2 +1 -2

Based on the assumption: Neighbourhood pixels are the same  
 $\Downarrow$   
 Difference between consecutive values is low  
 $\rightarrow$  The difference is stored

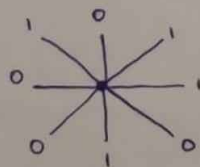
## Bilevel Image Compression (Run Length Encoding):

Eg: 000000  
 011100  
 111100  
 001110

Compress  $\rightarrow$

$0^*7 + 1^*3 + 0^*2 + 1^*4 + 0^*4 + 1^*2$

## Bilevel Image Context Compression:



\*. The neighbourhood of a pixel is grouped into a context and represented by n-bits.

\*. Contexts tend to be repeated in an image. The more they are repeated, the lesser the number of bits in the compressed stream to represent that context (Shannon-Fano, Huffman Coding)

\* Run length encoding and context encoding can be applied to any image by considering each bit plane of the image to be a bilevel image and encoding all the  $n$ -bit planes.

\* Find the average of the context and encode the difference between the average and the pixel.

\* The difference can range from  $-(m-1)$  to  $+(m-1)$  Eg: 256

$$\Delta = \text{Average} - \text{Pixel}$$

\* The difference ( $\Delta$ ) can be coded by arithmetic coding

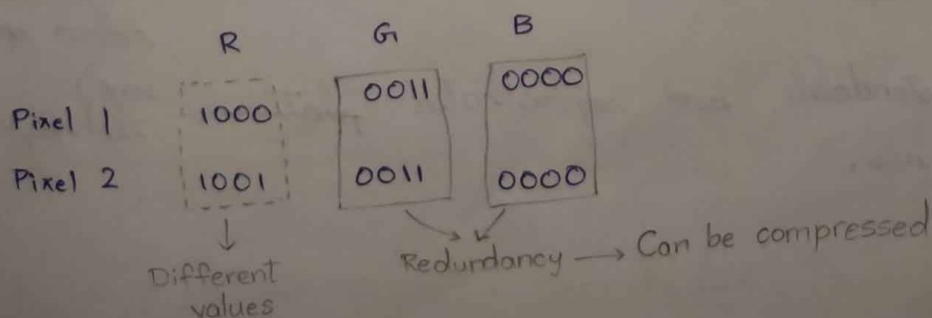
\* Corner pixels are not averaged and are coded by their pixel values as it is

### Transform Based Compression

\* The input spatial domain data is converted into frequency domain

\* This removes the inter-pixel redundancy

Continuous tone coloured images are split into R, G and B planes on which greyscale compression techniques are applied



## Discrete Tone Image Compression:

i)

\* In discrete-toned images, due to self-similarity property, multiple regions are similar.

\* The first unique region is coded and the following similar regions are made to point to the coded region.

ii) Block Similarity:

\* The image is divided into blocks.

\* If multiple blocks are similar, the newer block points to the other original blocks that are similar.

## JPEG

\* Cannot be used for <sup>Only 0's and 1's</sup> ~~bilevel~~ ~~grayscale~~ images.

\* JPEG compression can be used for grayscale and colour images.

### Merits:

\* JPEG has parameters to decide the quality of the decompressed image.

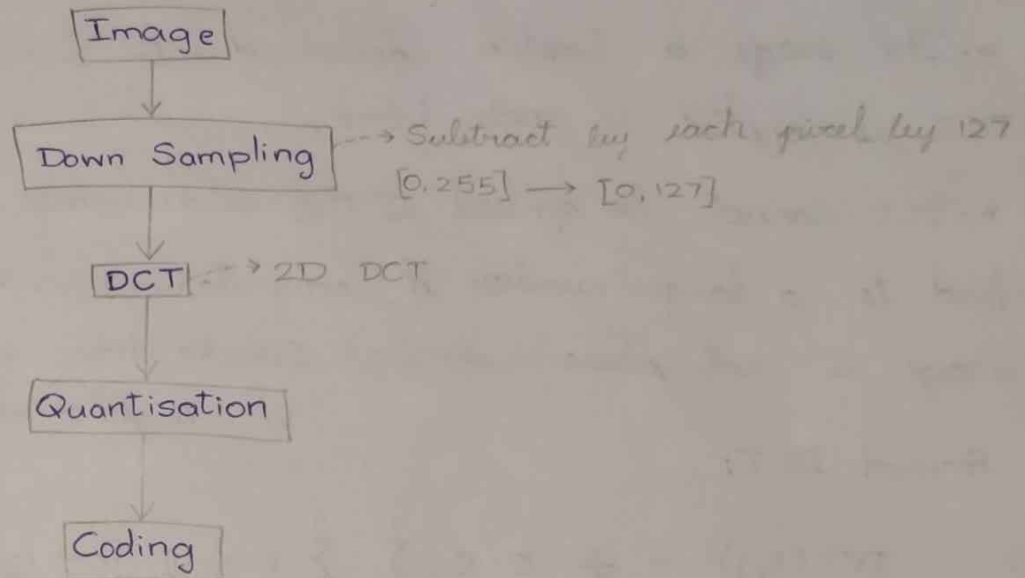
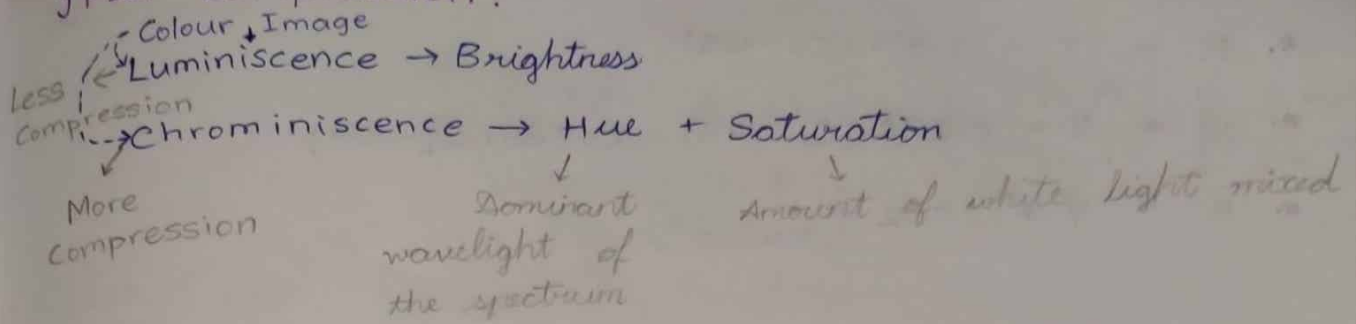
\* Images decompressed using JPEG, their evaluation ranges from good to excellent.

\* JPEG works efficiently for all image features (aspect ratio, colour space,

\* Easily understandable and sophisticated ~~platform~~ <sup>size</sup> technique for all platforms.



## JPEG Compression:



Committee of Illumination (CIE):

- \* RGB For more compression → Y C<sub>r</sub> C<sub>b</sub> (Luminance Component (Grayscale) ⊗)
- \* Y-component alone gives the grayscale image, and gives more information.
- \* We focus on compressing C<sub>r</sub> C<sub>b</sub> as they convey lesser information.

RGB to YC<sub>r</sub>C<sub>b</sub>:

$$* Y = \left(\frac{77}{256}\right) R + \left(\frac{150}{256}\right) G + \left(\frac{29}{256}\right) B$$

$$* C_b = -\left(\frac{44}{256}\right) R - \left(\frac{87}{256}\right) G + \left(\frac{131}{256}\right) B + 128$$

$$* C_r = \left(\frac{131}{256}\right) R - \left(\frac{110}{256}\right) G - \left(\frac{21}{256}\right) B + 128$$

R, G, B ∈ [0, 255]

$Y C_r C_b$  to RGB:

$$* R = Y + 1.371 (C_r - 128)$$

$$* G = Y - 0.698 (C_r - 128) - 0.366 (C_b - 128)$$

$$* B = Y + 1.732 (C_b - 128)$$

Mostly,  
 $Y \in [16, 235]$

$C_r, C_b \in [16, 240]$

## 2-D DCT

\* The image is broken down into blocks and 2-D DCT is applied to each block.

\* DCT cannot be applied to the whole image as it will lead to a large number of computations and the whole image is not always similar. (Blocks have similar pixels due to neighbourhood property)

Forward DCT:

$$DCT(i, j) = \frac{1}{4} C_i C_j \sum_{x=0}^7 \sum_{y=0}^7 P(x, y) \cdot \left[ \frac{\cos \left( \frac{(2x+1) i \pi}{16} \right)}{16} \right] \cdot \left[ \frac{\cos \left( \frac{(2y+1) \cdot j \pi}{16} \right)}{16} \right]$$

0 to 7 for 8x8 matrix

where,

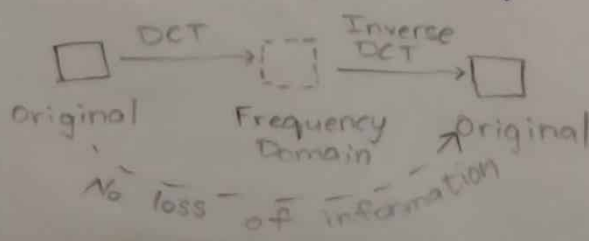
$$0 \leq i \leq 7$$

$$C_f = \begin{cases} \frac{1}{\sqrt{2}} & f=0 \\ 1 & f>0 \end{cases}$$

Converting spatial domain data to frequency domain:

$$DCT(i, j) = \frac{1}{\sqrt{2N}} C_i C_j \sum_{x=0}^{N-1} \sum_{y=0}^{N-1} P(x, y) \cos \left[ \frac{(2x+1) \cdot i \pi}{2N} \right] \cdot \cos \left[ \frac{(2y+1) \cdot j \pi}{2N} \right]$$

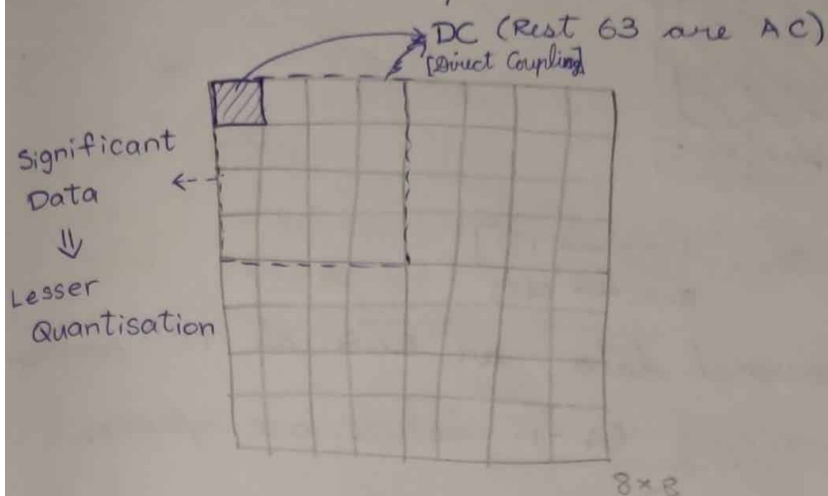
\* DCT does not perform any compression.



## 2D Inverse DCT:

$$P(x, y) = \frac{1}{\sqrt{2N}} \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} C_i C_j \text{DCT}(i, j) \cdot \cos\left[\frac{(2x+1)i\pi}{2N}\right] \cdot \cos\left[\frac{(2y+1)j\pi}{2N}\right]$$

→ Average of the 8x8 pixels obtained by DCT



## Quantisation:

\* JPEG → Default Quantisation Table  
→  $1 + (i+j) * R$

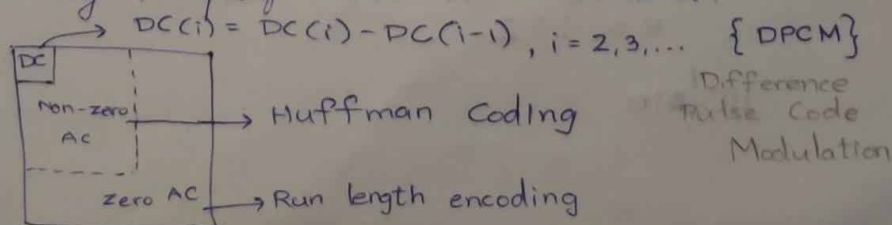
\* When  $R = 2$ ,

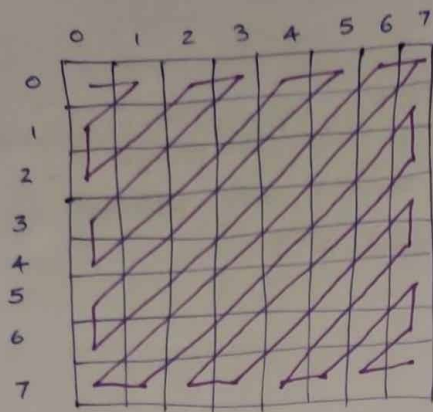
→ Lesser Quantisation

1	3	5	7	9	11	13	15
3	5	7	9	11	13	15	17
5	7	9	11	13	15	17	19
7	9	11	13	15	17	19	21
9	11	13	15	17	19	21	23
11	13	15	17	19	21	23	25
13	15	17	19	21	23	25	27
15	17	19	21	23	25	27	29

\* After quantisation, more non-zero AC coefficients will appear in the upper left corner and more zero AC coefficients will appear towards the bottom left corner.

\* Run length encoding is performed to this data.





Zig-Zag Scan  $[2D \rightarrow 1D]$   
 $8 \times 8 \rightarrow 64 \times 1$

\*. In the one-dimensional data, an EOB at  $n^{th}$  position implies that the remaining  $64 - n$  values are zeroes.

Possible Values for difference between DC components

The values in the range will be coded with  $i$  bits

$i$	Possible Values	Unary Code
0	0	0
1	-1, +1	10
2	-3, -2, 2, 3	110
3	-7, -6, -5, -4, 4, 5, 6, 7	1110
4		
...		
16	32768	111111111111111111

Eg: 1118, -2, -7

1118 will be present in some  $i^{th}$  row of the above table

$\therefore$  The unary code will have  $i$  1's followed by a 0.

$R = i$  [Row Number]

~~$C = \text{Unary Code}[i]$  Column~~

$C = \text{Column Number [1118]}$  in ~~the~~ row corresponding to  $i$

-2 is present at  $i = 2$

$\therefore C = 110$   $C = 2$

$R = i = 2$

110|010



For -7,  $i = 3$

~~C = 1110~~

$$R = i = 3$$

$$C = 1$$

$$(R, C) = (3, 1)$$

$1110 \mid 0001$   
 ↓  
 Unary code      R-bit representation of C

For AC components,

Row	0	1	2	3	4
0	10	011	01	110	
1	110	101	101	1110	
2	10101	1110	110	1111	
3					
4					
⋮					
16					

$(R, C)$

↓

$(R, Z)$  → No. of zeros preceding the non-zero AC component

Eg:  $1118 \xrightarrow{\text{DC}} -2 \quad \xrightarrow{\text{RC}} \quad 0 \quad 2 \quad 0 \quad 0 \quad 0 \quad 2$

For -2,

$i = 2 \Rightarrow R = 2$  } From previous table

$$C = 2$$

$Z = 0$  [No zeros before -2]

$(R, Z) = (2, 0) \rightarrow 1011$  (From current table)

$(R, C) = (2, 2) \rightarrow 10$

$\therefore 1011 \mid 10$

For 2,

$$R = 2$$

$$C = 3$$

$$Z = 1 \text{ [1 zero before 2]}$$

$$(R, C) \rightarrow (2, 3) \Rightarrow \text{11}$$

$$(R, Z) \rightarrow (2, 1) \Rightarrow 1110$$

$$(R, C) \rightarrow (2, 3) \Rightarrow 11$$

$$\therefore 1110 | 11$$

For next 2,

$$R = 2$$

$$C = 3$$

$$Z = 3$$

$$(R, Z) \rightarrow (2, 3) \Rightarrow 1111$$

$$(R, C) \rightarrow (2, 3) \Rightarrow 11$$

$$\therefore 1111 | 11$$

\*. Without JPEG compression,

$$\begin{array}{ccc} 64 & \times & 24 \\ \downarrow & & \downarrow \\ \text{No. of} & & \text{No. of} \\ \text{pixels} & & \text{bits for 1 pixel} \end{array} = 1536 \text{ bits}$$

\*. With JPEG,

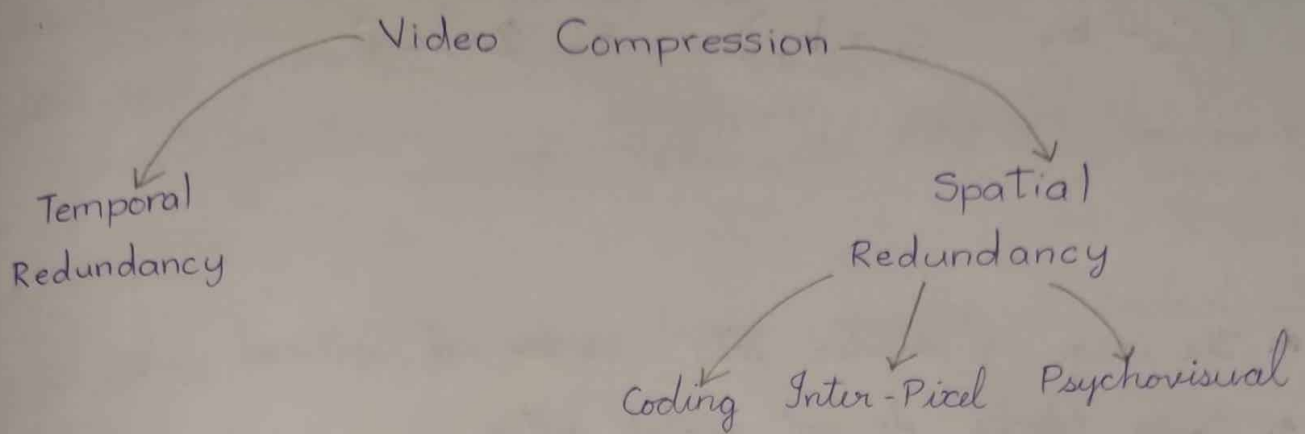
$$\begin{array}{ccc} 23 & + & 23 \\ \downarrow & & \downarrow \\ 23 \text{ bits} & & 23 \text{ bits to} \\ \text{to encode DC} & & \text{encode remaining} \\ & & \text{63 AC components} \end{array} = 46 \text{ bits}$$

For 3 planes,

$$46 \times 3 = 138 \text{ bits}$$

$$*. \text{Compression Ratio} = 1536 / 138 \approx 11$$

# VIDEO COMPRESSION



Temporal Dependency:

- \* I-frame <sup>Independent</sup> → Coded independently
- \* P-frame <sup>Predicted</sup> → Coded based on previous I or P-frame
- \* B-frame → Coded with previous and successive P or I-frames

Sub-Sampling:

- \* Selecting certain frames (Alternate frames)

Differencing:

- \* Difference between two consecutive frames is calculated in order to find the difference matrix.
- \* Difference matrix will have lots of zeros (Consecutive frames are generally very similar).
- \* The difference value and its position in the matrix alone need to be shared.

~~The image is~~

Block Differencing:

- \* The image is divided into blocks and differencing is applied to these blocks.

Motion Compensation: (For object translation) [Cannot be used for rotation and scaling]

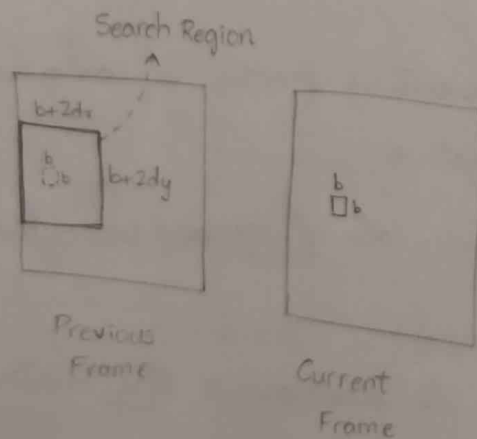
$$\begin{matrix} \text{y-coordinate} \\ \text{in previous} \\ \text{frame } T \end{matrix} \quad \begin{matrix} \text{y-coordinate} \\ \text{in current} \\ \text{frame} \end{matrix} \quad \begin{matrix} \text{x-coordinate} \\ \text{in previous} \\ \text{frame} \end{matrix} \quad \begin{matrix} \text{x-coordinate} \\ \text{in current} \\ \text{frame} \end{matrix} \quad \begin{matrix} \text{y-coordinate} \\ \text{in current} \\ \text{frame} \end{matrix} \quad \begin{matrix} \text{x-coordinate} \\ \text{in current} \\ \text{frame} \end{matrix} \quad \begin{matrix} \text{Motion Vector} \end{matrix}$$

$$(C_x - b_x, C_y - b_y) = (\Delta x, \Delta y)$$

- \* The image is divided into blocks of optimal size.
- \* Large blocks do not match often.
- \* Small blocks do not offer much compression
- \* Threshold  $\rightarrow$  Error tolerance between similar blocks

Block Search Procedure:

- \* The block might have translated from its position in the previous frame.
- \* Therefore, the block is searched in the range  $(b+2dx, b+2dy)$ .



\* Distortion Measure

Mean Absolute Pixel Difference

$$= \frac{1}{b^2} \sum_{i=1}^b \sum_{j=1}^b (C_{ij} - b_{ij})$$

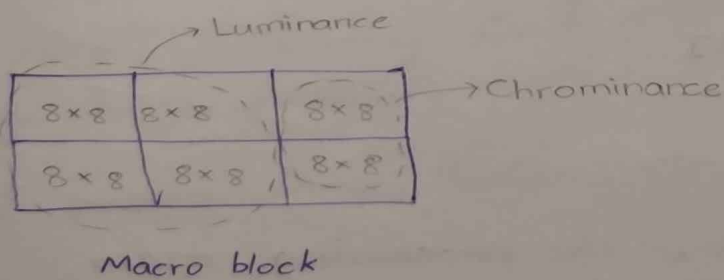
Pixel in previous frame  $\rightarrow$  Pixel in current frame



- \* If a match is found for the block, a motion vector is calculated by comparing the top left corners of the current and previous frames.
- \* A frame is predicted with the help of the motion vector.
- \* If there is no match for a block, then it is coded independently.

### H261 Standard (First video compression technique)

- \* The image is divided into blocks.
- \* The predicted image is calculated.
- \* If the block size is too large, multiple objects might lie in the same block, but search computation is reduced.
- \* If the search area is reduced, more number of blocks will be coded independently.
- \* H-261 makes use of macro blocks.



- \* H-261 is used in video calling and video conferencing.
- \* In H-261, all subsequent frames depend on the first I and P frames. Therefore H-261 is not suitable for storing videos (More I-frames can solve this problem).

## Filtering:

- \*. Remove the noise in the image and abrupt frequencies.

Eg:

110	218	110
111	222	111
101	222	112

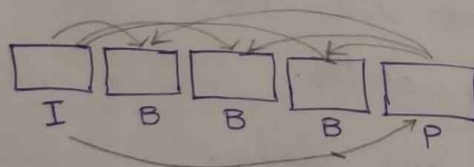
Abnormal Frequencies / Noise

$$\frac{1}{4} \times 110 + \frac{1}{2} \times 218 + \frac{1}{4} \times 110$$

## MPEG-I (Moving Picture Expert Group)

- I → Independent frame or Intraframe (Intracoding)
- P → Predictive Coded frame (Coded based on previous I/P frame)
- B → Bidirectional Predictive Coded frame (Coded based on previous I/P frame as well as successive I/P frame)
  - ↓
  - Not used for prediction
  - ⇓
  - Prevents error propagation

### Group of Pictures (GOP):



### Display Order:

Eg: I B B P B B P B B I

### Processing Order:

1, 4, 2, 3, 7, 5, 6, 10, 8, 9, 13, 11, 12

I P B B P B B P B B I B B

- \*. Decoder gets the frames in the processing order.

- \*. More B frames ⇒ Consecutive frames are very similar for a longer duration

- \*. As the distance of the B frame increases from the reference frame (I/P), the search area needs to be increased

- \* In MPEG-I, the frames must be of dimensions  $768 \times 576$
- \* 396 macro-blocks for 25 FPS or lesser
- \* 330 macro-blocks for 30 FPS or lesser
- \* MPEG-I is suitable for slow moving images. It is not suitable for quick scene changes

## STATISTICAL MODELLING

### Finite Context Modelling:

- \* The probability of occurrence of a symbol is calculated based on the context.

More compression

More probability tables

Adaptive Modelling

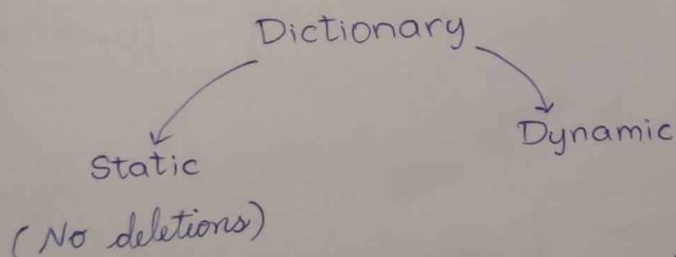
(More compression but lots of computations)

Order 0 → Consider only current symbol  
(1 row)

Order 1 → Consider previous symbol also  
(256 rows)

Order 2 → Consider 2 previous symbols (256 rows)

### Dictionary Based Compression:

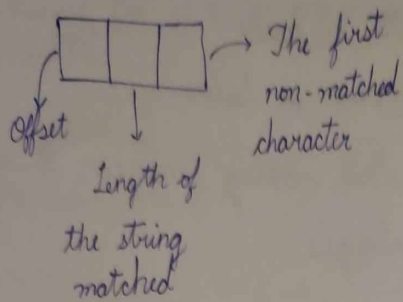


**Static Dictionary:** to the entropy when the data is large.

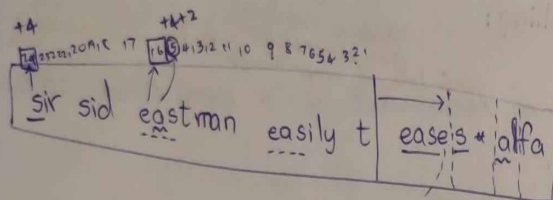
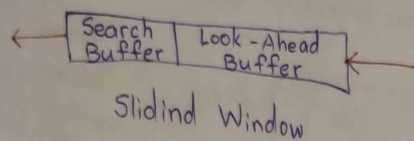
- \* Can compress to the entropy when the data is large.
- (If lesser data, dictionary itself will occupy large space nullifying the compression)

- \* General purpose large <sup>static</sup> dictionaries may not provide compression as good as domain specific static dictionaries

## Dynamic (Adaptive) Dictionary:



## Sliding Window Algorithm (LZSS Algorithm):

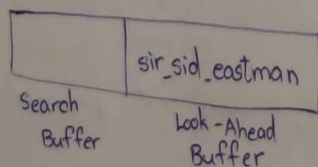


[16, 3, 'e']

[12, 1, '-']

[21, 1, 'l']

Eg: sir\_sid\_eastman



[0, 0, 's']

↓  
's' is not present in search buffer

[0, 0, 'i']

[0, 0, 'r']

[0, 0, '-']

↑ 3 2 1  
[sir\_ sid\_eastman]



4	2	'd'
---	---	-----

4	3	2	1	
sir	sid			eastman

4	1	'e'
---	---	-----

sir	sid	e	astman
-----	-----	---	--------

0	0	'a'
---	---	-----

10	1	't'
----	---	-----

0	0	'm'
---	---	-----

4	3	2	1	
sir	sid	eastm		an

4	1	'n'
---	---	-----

sir	sid	eastman	
-----	-----	---------	--

\* Search buffer  $\rightarrow$  1000 bytes  
 \* Look-ahead buffer  $\rightarrow$  10 bytes

Example Values

Search Buffer  $\rightarrow$  8000 bits  $\Rightarrow$  Offset max value = 8000  
 Bits required =  $\log_2(8000)$

Look Ahead Buffer  $\rightarrow$  80 bits  $\Rightarrow$  Length of match max value = 80  
 Bits required =  $\log_2(80)$

Non-match character  $\Rightarrow$  8

\* This method provides good compression when the same sequence of symbols occur in a concentrated manner

Q ALFALFALFAL

00A

00L

00F

37L

∴ Search buffer can never be the complete string

Q AAAAAAAAAA

00A

18A

LZSS ALGORITHM:

Search Buffer - 1 byte <sup>Fixed Size</sup>  
Look-Ahead Buffer - 1 byte } Example

Token (offset, len\_match) <sup>Taken off</sup>  
\* Repeating symbols (len\_match ≥ 2)  
Token(1, Offset, Length) → 1 + 8 + 8 = 17 bits

\* New symbol:

(0, 'x') → 1 + 8 = 9 bits

\* Repeating symbol (len\_match = 1)

(0, 'x') → 9 bits < 17 bits

\* For len\_match = 2,

If coded as ~~new~~ new symbols,

(0, 'x') + (0, 'y') → (1+8) + (1+8) = 18 bits

If coded as repeating symbols,

(1, 1, 2) → 1 + 8 + 8 = 17 bits

The advantage of coding as repeated symbols is only 1 bit. This advantage is insignificant when compared to the computations involved in encoding and decoding the matching symbols. Therefore, if the match is of length only 2, the symbols will be encoded only as new symbols.

Eg: LZSS

"MISS\_MISSISSIPPI"

Search Buffer  $\rightarrow$  16 bytes  $\Rightarrow$  4 bits

MISS\_MISSISSIPPI

LA Buffer  $\rightarrow$  16 bytes

$\Downarrow$   
4 bits

[O M] <sup>9</sup>  
(5 bits)

[O I] <sup>9</sup>  
(5)

[O S] <sup>9</sup>  
(5)

len\_match = 2  
New:  $9 + 9 = 18$   
 ~~$5 + 5 = 10$~~

Repeat:

$1 + 4 + 4 = 9$  ✓

MIS|S\_MISSISSIPPI

[ ][ ][ ][ ][O S] <sup>9</sup>  
(5)

More Compression

MISS|\_MISSISSIPPI

[O -] <sup>9</sup>  
(5)

MISS|MISSISSIPPI

[1 5 4] (9 bits)

MISS\_MISS|ISSIPPI

[1 8 3] (9)

MISS\_MISSISS|IPPI

[O I] <sup>9</sup>  
(5)

[O P] <sup>9</sup>  
(5)

len\_match = 3

New:  $9 + 9 + 9 = 27$   
 ~~$5 + 5 + 5 = 15$~~

Repeat:

$1 + 4 + 4 = 9$  ✓

9, 4, 1

OP (5)  
 DT (5)

## LZ 78 Algorithm

Eg: Good morning

Dictionary

Output String:

Index	String	(Index, Character)
0	NULL	(0, 'G')
1	G	(0, 'o')
2	o	(2, 'd')
3	od	(0, '-')
4	-	(0, 'm')
5	m	(2, 'r')
6	or	(0, 'n')
7	n	(0, 'i')
8	i	(7, 'g')
* 9	ng	

→ 8 bits

\* The dictionary is not sent to the decoder. Only the output string is sent to the decoder.

\* Decoding,

→ (0, 'G')

⇒ G

→ (0, 'o')

⇒ Go

→ (2, 'd')

⇒ Good

Dictionary

0	NULL
1	G
2	o
3	od



→ (0, '\_')

⇒ Good\_

→ (0, 'm')

⇒ Good m

→ (2, 'r')

⇒ Good mor

→ (0, 'n')

⇒ Good morn

→ (0, 'i')

⇒ Good morni

→ (7, 'g')

⇒ Good morning

Dictionary	
Index	String
0	NULL
1	G
2	o
3	od
4	-
5	m
6	or
7	n
8	i
9	ng

\*. If the last symbol matches, the corresponding output string will have the index alone (There is no character to follow).

Eg: a a b a b a c b a c a c a b a c →  $8 \times 16 = 128$  bits

Dictionary

Index	String
0	NULL
1	a
2	ab
3	aba
4	c
5	b
6	ac
7	aca
8	ba

Output String

$\lceil \log_2 9 \rceil = 4$   
 $(0, 'a')$   
 $(1, 'b')$   
 $(2, 'a')$   
 $(0, 'c')$   
 $(0, 'b')$   
 $(1, 'c')$   
 $(6, 'a')$   
 $(5, 'a')$   
 $(4)$

$\frac{4}{11}$   
 $(\lceil \log_2 9 \rceil * 8 + 8) \times 9$   
 $= 12 \times 9$   
 $= 108$   
 $108 - 8$   
 $\therefore$  Last token does not have a character  
 $\therefore 108 \text{ bits}$

## Decoding,

→ (0, 'a')

⇒ a

→ (1, 'b')

⇒ aab

→ (2, 'a')

⇒ aababa

→ (0, 'c')

⇒ aababac

→ (0, 'b')

⇒ aababacb

→ (1, 'c')

⇒ aababacbac

→ (6, 'a')

⇒ aababacbacaca

\* → (5, 'a')

⇒ aababacbacacaba

\* → (4)

⇒ aababacbacacabac

## Dictionary

Index	String
0	NULL
1	a
2	ab
3	aba
4	c
5	b
6	ac
7	aca
8	ba

# LZW Algorithm

Eg: ababac

The dictionary initially has 255 entries for the unique symbols.

a	0
b	1
c	2
.	.
.	.
.	.

ab 255

ba 256

→ a ✓

⇒ 0

→ ab X

⇒ Add 'ab' to dictionary at 255

→ b ✓

⇒ 0 1

→ ba X

⇒ Add 'ba' to dictionary at 256

→ a ✓

→ ab ✓ ⇒ 0 1 255

→ aba X ⇒ Add aba to dictionary at 257

→ a ✓ ⇒ 0 1 255 0

→ ac X ⇒ Add ac to dictionary at 258

→ c ✓ ⇒ 0 1 255 0 2

∴ Encoded string: 0 1 255 0 2

Decoding:

→ 0 ⇒ a

→ 1 ⇒ ab → ~~Add 'ab' to dictionary at 255~~

→ 255 ⇒ ~~abab~~  
Not in dictionary → Add 'ab' to dictionary at 255

⇒ abab

→ 0 ⇒ ababa

→ 2 ⇒ ababac

Eg: ababbabbbabbbb

→ a ✓

→ abx → Add 'ab' to the dictionary at 255

⇒ 0

→ b ✓

→ bax 256 : ba

⇒ 0 1

~~→ b ✓~~

~~→ bbx 257 : bb~~

~~⇒ 0 1 1~~

~~→~~

→ a ✓

→ ab ✓

→ abbx 257 : abb

⇒ 0 1 255

→ b ✓

→ ba ✓

→ babx 258 : bab

⇒ 0 1 255 256

→ b ✓

→ bbx 259 : bb

⇒ 0 1 255 256 1

→ b ✓

\* → bb ✓

→ bbax 260 : bba

\* ⇒ 0 1 255 256 1 259

→ a ✓

→ ab ✓

\* → abb ✓

→ abbbx 261 : abbb

⇒ 0 1 255 256 1 259 257

\* → b ✓

→ bb ✓

⇒ 0 1 255 256 1 259 257 259



\* LZW may lead to a lot of additional entries in the dictionary for each new substring.

\* If the dictionary size becomes very large, the number of bits required to represent string will also increase, resulting in lesser or even no compression.

### LZMW Algorithm :

Eg: SWISS\_MISS

Assume, Existing Dictionary

S	100
W	101
I	102
-	103
M	104

INPUT SYMBOL	CURRENT SYMBOL	OUTPUT	ADD TO DICTIONARY
		100	-
S	S		
W	W	101	256 : SW
I	I	102	257 : WI
S	S	100	258 : IS
S	S	100	259 : SS
-	-	103	260 : S-
M	M	104	261 : -M
I	IS	258	262 : MIS
S	S	100	263 : ISS

Decoding : 100 101 102 100 100 103 104 258 100

INCOMING SYMBOL	OUTPUT STRING	ADD TO DICTIONARY
100	S	256 : SW
101	W	257 : WI
102	I	258 : IS
100	S	259 : SS
100	S	260 : S-
103	-	261 : -M
104	M	262 : MIS
258	IS	263 : ISS
100	S	

# LZAP Algorithm:

Eg: SWISS\_MISS

Existing Dictionary

100: S  
101: W  
102: I  
103: -  
104: M

INPUT	CURRENT	OUTPUT	ADD TO DICTIONARY
S	S	100	-
W	W	101	256: SW
I	I	102	257: WI
S	<del>100</del> S	100	258: IS
S	<del>100</del> S	100	259: SS
-	-	103	260: S-
M	M	104	261: -M
I	IS	258	262: MIS
			263: MIS
S	S	100	264: ISS

Q Compress YABBADABBADABBADOO using LZMW and LZAP

Let the existing dictionary be:

→ 12 bits  
100: Y  
101: A  
102: B  
103: D  
104: O

LZMW:

INPUT	CURRENT	OUTPUT	ADD
Y	Y	100	-
A	A	101	256: YA
B	B	102	257: AB
B	B	102	258: BB
A	A	101	259: BA
D	D	103	260: AD
A	AB	<del>101</del> 257	261: DAB
B	BA	259	262: ABBA

D	DA	103	263: BAD
A	ABBA	262	264: DABBA
D	D	0103	265: ABBAD
O	O	104	266: DO
O	O	104	267: OO

LZAP:

INPUT	CURRENT	OUTPUT	ADD
Y	Y	100	—
A	A	101	256: YA
B	B	102	257: AB
B	B	102	258: BB
A	A	101	259: BA
D	D	103	260: AD
A	AB	257	261: DAB
B	BA	259	262: DAB
			263: ABA
			264: <del>ABA</del> ABBA
			265: ABBA
D	DAB	262	