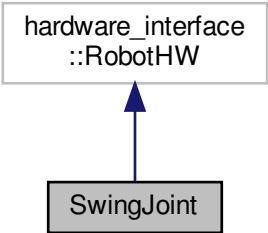


hardware_interface
::RobotHW



```
graph BT; SwingJoint --> RobotHW[hardware_interface::RobotHW];
```

A UML class diagram showing an inheritance relationship. A box labeled 'SwingJoint' is at the bottom, and a box labeled 'hardware_interface::RobotHW' is at the top. A blue arrow points from 'SwingJoint' up to 'hardware_interface::RobotHW', indicating that 'SwingJoint' inherits from 'hardware_interface::RobotHW'.

SwingJoint