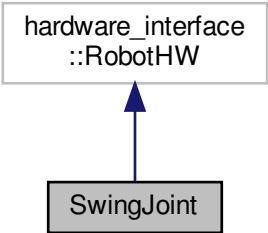


hardware_interface
::RobotHW



```
classDiagram
    class hardware_interface {
        <<abstract>>
        <<interface>>
    }
    class SwingJoint
    SwingJoint --|> hardware_interface
```

The diagram consists of two rectangular boxes. The top box is white with a thin black border and contains the text 'hardware_interface' on the first line and '::RobotHW' on the second line. The bottom box is gray with a black border and contains the text 'SwingJoint'. A solid blue arrow points vertically from the top edge of the 'SwingJoint' box to the bottom edge of the 'hardware_interface::RobotHW' box, indicating an inheritance relationship.

SwingJoint