

WEEK8 Project 2 & 3

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Outline

WEEK8 Project 2
& 3

Genghang Zhuang,
Rihui Song

Project 2 & 3

Project 2: Path Planning based on 3D LiDAR

Project 3: Object Detection based on DVS

Project 2 & 3

Project 2: Path
Planning based on 3D
LiDAR

Project 3: Object
Detection based on
DVS

Future Work

Every Week Work
Final Presentation

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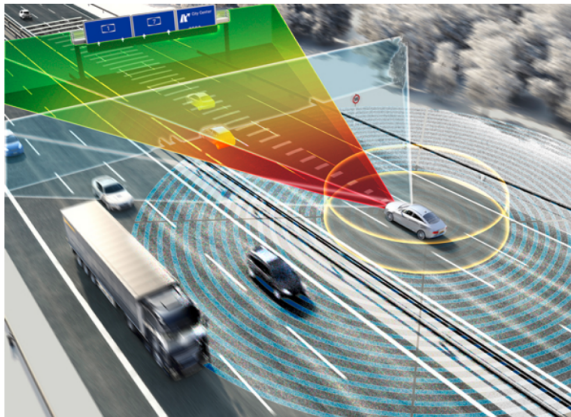
Final Presentation

Background

3D LiDAR: News, 2017

NEWS >>

Continental develops next-generation 3D lidar environment model for automated driving



Continental is working on the next generation of an environment model that will deliver a seamless, true-to-life, 360° view of the entire vehicle's surroundings – a basic requirement for sophisticated advanced driver assistance systems (ADAS) and automated driving.

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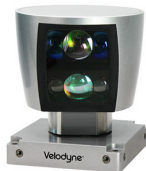
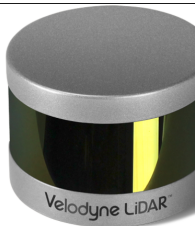
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Background

3D LiDAR: Sensor



Velodyne LiDAR (Light Detection And Ranging)



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3D LiDAR: Work Principle

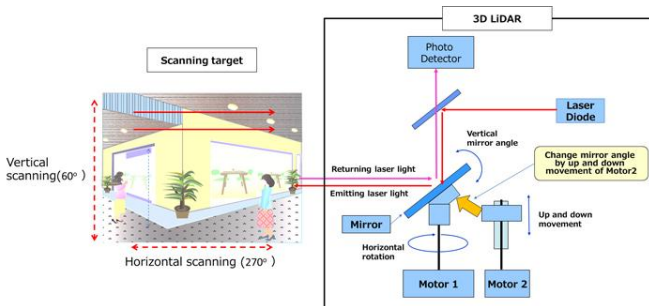
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3D LiDAR: Data-Point Cloud



Figure: out-door



Figure: in-door

sensor_msgs/PointCloud2 Message

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Challenges and Tips

Point Cloud Projection Bird view

Obstacle Detection height map

Path Planning Dijkstra

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DVS: News, 2018

从源头重塑整个机器视觉行业，这家中国公司要搞事情

李康 雷锋网 2018-01-25

近日，雷锋网发布了一条公司的介绍，引起良好反响，具体内容如下：



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DVS: News, 2018

机器“眼球”的重生

原来体积庞大但有效信息很少的监控视频数据上百倍缩减;在纳秒级的物理极限捕捉影像的变化，甚至可以拍到子弹的轨迹;强光和弱光环境都能很好适应，甚至能够看清明亮霓虹灯中的广告字，在夜间也保持着相当的灵敏度。听起来似乎很玄幻，但已经有公司将它们转变为了现实。

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DVS: News, 2018



高效率

这款传感器的体系架构能够实现
在焦平面实现像素的并行图像处理以及基于事件驱动的读出方式。



低数据速率

只有动态像素影响。传感器能捕捉超快速运动并且数据量减少了1000倍。



连续性

每一个沿运动轨迹线的像素点都能被捕捉收集，并在纳秒级分辨率记录信息。



快速响应

传感器速度不受传统的相机的概念限制，比如帧率和曝光时间。事实上，CeleX™没有曝光时间。



高动态范围

CeleX™的动态范围超过了120dB。它同样支持从月光到日光的宽光照范围。



兼容性

CeleX™与现有的图像传感器兼容，因此它可以根据需求很容易生成全帧图片。

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DVS: Sensor



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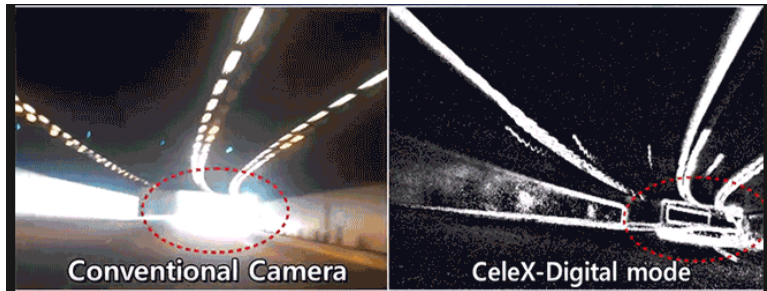
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DVS Data: Images



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challenges and tips

Noise filtering Median filtering

Edge detection Canny edge detection

Object Detection Region filling

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- ▶ each group: 10 mins presentation
- ▶ TAs give some comments

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TBD...

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