Foenix Toolbox Programmer's Guide

Firmware functions for the Foenix Retro System F256 computers

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Chapter 1

Introduction

Copyright Information

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Chapter 2

Devices

Devices on the Foenix computers fall into one of two main categories: channel devices, and block devices.

Channel Devices

Channel devices are predominantly sequential, byte oriented devices. They are essentially byte streams. A program can read or write a series of bytes from or to the device. A channel can have the notion of a "cursor" which represents the point where a read or write will happen. Examples of channel devices include the console, the serial ports, and files.

Currently, the only fully supported channel devices are open files, the keyboard, and the screen. In the future, there should be full support for the serial ports, the parallel port, and the MIDI ports. Channel devices are assigned as follows:

Number	Device
0	Main console (keyboard and main screen or channel B)
1	Secondary console (keyboard and EVID or channel A)
2	Serial Port 1
3	Serial Port 2
5	MIDI Ports
6	Files

By default, channels 0 and 1 are open automatically to devices 0 and 1 respectively at boot time.

Block Devices

Block devices organize their data into blocks of bytes. A block may be read from or written to a block device, and blocks maybe accessed in any order desired. The F256K2e comes with two block devices: the internal and external SD cards.

Out of the box, there are three block devices supported by Foenix Toolbox:

Number	Device
0	sd0—External SD card
1	sd1—Internal SD card

File Channels

Files represent a special channel pseudo-device. Although files are stored on block devices, they may be open as file channels, which may be accessed like a channel device. There is a special file channel driver, which

converts channel reads and writes on a file to the appropriate block calls. Access to these file channels is managed in part through the file system calls listed below.

Paths

File and directory names follow the Unix style path conventions. That is, the forward slash (/) is used as a separator, and drives are treated as directories ("/sd", "/hd", etc.). FAT32 long file names are supported, but not Unicode characters. Special path names "." and "..". are supported to specify a path relative to the current path. Example paths are:

/sd0/hello.txt
/sd1/system/format.elf
../games/HauntedCastle/start

Chapter 3

Toolbox Functions

3.1 Channel Functions

Example: C

Example: Assembler

$sys_chan_read_b - 0xFFE024$

Read a single character from the channel. Returns the character, or 0 if none are available.

Prototype	short sys_chan_read_b(short channel)
channel	the number of the channel
Returns	the value read (if negative, error)

Example: C

```
// Read a byte from channel #0 (keyboard)
short b = sys_chan_read_b(0);
if (b >= 0) {
    // We have valid data from 0-255 in b
}
```

Example: Assembler

$sys_chan_read - 0xFFE028$

Read bytes from a channel and fill a buffer with them, given the number of the channel and the size of the buffer. Returns the number of bytes read.

Prototype	short sys_chan_read(short channel, unsigned char * buffer, short size)
channel	the number of the channel
buffer	the buffer into which to copy the channel data
size	the size of the buffer.
Returns	number of bytes read, any negative number is an error code

```
char buffer[80];
short n = sys_chan_read(0, buffer, 80);
if (n >= 0) {
    // We correctly read n bytes into the buffer
    } else {
        // We have an error
}
```

Example: Assembler

```
pei #80 ; Push the size of the buffer
```

pei #'buffer ; Push the address of the buffer

pei #<>buffer

lda #0 ; Select channel #0

jsl sys_chan_read ; Try to read the bytes from the channel

ply ; Clean up the stack

ply ply

bit #\$ffff ; If result is negative...
bmi error ; Go to process the error

sta n ; Otherwise: save the number of bytes read

$sys_chan_readline - 0xFFE02C$

Read a line of text from a channel (terminated by a newline character or by the end of the buffer). Returns the number of bytes read.

Prototype	short sys_chan_readline(short channel, unsigned char * buffer, short size)
channel	the number of the channel
buffer	the buffer into which to copy the channel data
size	the size of the buffer
Returns	number of bytes read, any negative number is an error code

Example: C

```
short c = ...; // The channel number
unsigned char buffer[128];
short n = sys_chan_read_line(c, buffer, 128);
```

Example: Assembler

```
pei #128 ; Push the size of the buffer pei #'buffer ; Push the pointer to the buffer
```

pei #<>buffer

ply ; Clean up the stack

ply ply

sta n ; Save the number of bytes read

$sys_chan_write_b - 0xFFE030$

Write a single byte to the channel.

Prototype	short sys_chan_write_b(short channel, uint8_t b)
channel	the number of the channel
b	the byte to write
Returns	0 on success, a negative value on error

Example: C

```
// Write 'a' to the console
short result = sys_chan_write_b(0, 'a');
```

Example: Assembler

$sys_chan_write - 0xFFE034$

Write bytes from a buffer to a channel, given the number of the channel and the size of the buffer. Returns the number of bytes written.

Prototype	short sys_chan_write(short channel, const uint8_t * buffer, short size)
channel	the number of the channel
buffer	
size	
Returns	number of bytes written, any negative number is an error code

Example: C

```
char * message = 'Hello, world!\n';
short n = sys_chan_write(0, message, strlen(message));
```

Example: Assembler

```
pei #15
                          ; Push the size of the buffer
   pei #'message
                          ; Push the pointer to the message
    pei #<>message
    lda #0
                          ; Select the console (channel #0)
    jsl sys_chan_write
                          ; Write the buffer to the console
    ply
                          ; Clean up the stack
    ply
    ply
    ; ...
message:
    .null "Hello, world!", 13, 10
```

$sys_chan_status - 0xFFE038$

Gets the status of the channel. The meaning of the status bits is channel-specific, but four bits are recommended as standard:

- 0x01: The channel has reached the end of its data
- 0x02: The channel has encountered an error
- 0x04: The channel has data that can be read
- 0x08: The channel can accept data

Prototype	short sys_chan_status(short channel)
channel	the number of the channel
Returns	the status of the device

Example: C

```
// Check the status of the file_in channel
short status = sys_chan_status(file_in);
if (status & 0x01) {
    // We have reached end of file
}
```

Example: Assembler

```
lda file_in
jsl sys_chan_status
and #$01
beq have_data
; We have reached end of file
```

$sys_chan_flush - 0xFFE03C$

Ensure any pending writes to a channel are completed.

	Prototype	short sys_chan_flush(short channel)
Ì	channel	the number of the channel
Ì	Returns	0 on success, any negative number is an error code

Example: C

```
short file_out = ...; // Channel number
sys_chan_flush(file_out); // Flush the channel
```

Example: Assembler

$sys_chan_seek - 0xFFE040$

Set the position of the input/output cursor. This function may not be honored by a given channel as not all channels are "seekable." In addition to the usual channel parameter, the function takes two other parameters:

- position: the new position for the cursor
- base: whether the position is absolute (0), or relative to the current position (1).

Prototype	short sys_chan_seek(short channel, long position, short base)
channel	the number of the channel
position	the position of the cursor
base	whether the position is absolute or relative to the current position
Returns	0 = success, a negative number is an error.

Example: C

```
short c = ...; // The channel number sys_chan_seek(c, -10, 1); // Move the point back 10 bytes
```

Example: Assembler

$sys_chan_ioctrl - 0xFFE044$

Send a command to a channel. The mapping of commands and their actions are channel-specific. The return value is also channel and command-specific. The buffer and size parameters provide additional data to the commands, what exactly needs to go in them (if anything) is command-specific. Some commands require data in the buffer, and others do not.

Prototype	short sys_chan_ioctrl(short channel, short command, uint8_t * buffer, short size)
channel	the number of the channel
command	the number of the command to send
buffer	pointer to bytes of additional data for the command
size	the size of the buffer
Returns	0 on success, any negative number is an error code

```
short c = ...; // The channel number
short cmd = ...; // The command
short r = sys_chan_ioctrl(c, cmd, 0, 0); // Send simple command
```

Example: Assembler

```
pei #0
                       ; Push 0 for the size
pei #0
                       ; Push the null pointer for the buffer
pei #0
lda cmd
                       ; Push the command
pha
lda c
jsl sys_chan_ioctrl
                       ; Issue the command
                       ; Clean up the stack
ply
ply
ply
ply
```

$sys_chan_open - 0xFFE048$

Open a channel device for reading or writing given: the number of the device, the path to the resource on the device (if any), and the access mode. The access mode is a bitfield:

0x01: Open for reading0x02: Open for writing

• 0x03: Open for reading and writing

Prototype	short sys_chan_open(short dev, const char * path, short mode)
dev	the device number to have a channel opened
path	a "path" describing how the device is to be open
mode	s the device to be read, written, both
Returns	the number of the channel opened, negative number on error

Example: C

```
// Serial port: 9600bps, 8-data bits, 1 stop bit, no parity short chan = sys_chan_open(2, "9600,8,1,N", 3);
```

Example: Assembler

```
pei #3
                         ; Mode: Read & Write
    pei #'path
                         ; Pointer to the path
    pei #<>path
    lda #2
                         ; Device #2 (UART)
    jsl sys_chan_open
                         ; Open the channel to the UART
   ply
                         ; Clean up the stack
    ply
    ply
    ; ...
path:
    .null "9600,8,1,N"
```

$sys_chan_close - 0xFFE04C$

Close a channel that was previously open by sys_chan_open.

Prototype	short sys_chan_close(short chan)
chan	the number of the channel to close
Returns	nothing useful

Example: C

```
short c = ...; // The channel number
sys_chan_close(c); // Close the channel
```

Example: Assembler

$sys_chan_swap - 0xFFE050$

Swaps two channels, given their IDs. If before the call, channel ID channel1 refers to the file "hello.txt", and channel ID channel2 is the console, then after the call, channel1 is the console, and channel2 is the open file "hello.txt". Any context for the channels is preserved (for instance, the position of the file cursor in an open file).

Prototype	short sys_chan_swap(short channel1, short channel2)
channel1	the ID of one of the channels
channel2	the ID of the other channel
Returns	0 on success, any other number is an error

$sys_chan_device - 0xFFE054$

Given a channel ID (the only parameter), return the ID of the device associated with the channel. The channel must be open.

Prototype	short sys_chan_device(short channel)
channel	the ID of the channel to query
Returns	the ID of the device associated with the channel, negative number for error

3.2 Block Device Functions

$sys_bdev_register - 0xFFE05C$

Register a device driver for a block device. A device driver consists of a structure that specifies the name and number of the device as well as the various handler functions that implement the block device calls for that device.

See the section "Extending the System" below for more information.

Prototype	short sys_bdev_register(p_dev_block device)
device	pointer to the description of the device to register
Returns	0 on succes, negative number on error

$sys_bdev_read - 0xFFE060$

Read a block from a block device. Returns the number of bytes read.

Prototype	short sys_bdev_read(short dev, long lba, uint8_t * buffer, short size)
dev	the number of the device
lba	the logical block address of the block to read
buffer	the buffer into which to copy the block data
size	the size of the buffer.
Returns	number of bytes read, any negative number is an error code

Example: C

```
unsigned char buffer[512];

// Read the MBR of the interal SD card
short n = sys_bdev_read(BDEV_SD1, 0, buffer, 512);
```

Example: Assembler

```
pei #512 ; Push the size of the buffer
pei #'buffer ; Push the pointer to the read buffer
pei #<>buffer
pei #0 ; Push LBA = 0
pei #0
lda #1 ; The device number for the internal SD

jsl sys_bdev_read ; Read sector 0

ply ; Clean up the stack
ply
ply
ply
ply
```

$sys_bdev_write - 0xFFE064$

Write a block from a block device. Returns the number of bytes written.

Prototype	short sys_bdev_write(short dev, long lba, const uint8_t * buffer, short size)
dev	the number of the device
lba	the logical block address of the block to write
buffer	the buffer containing the data to write
size	the size of the buffer.
Returns	number of bytes written, any negative number is an error code

Example: C

```
unsigned char buffer[512];
// Fill in the buffer with data...
// Write the MBR of the interal SD card
short n = sys_bdev_write(BDEV_SD1, 0, buffer, 512);
```

Example: Assembler

```
pei #512 ; Push the size of the buffer
pei #'buffer ; Push the pointer to the read buffer
pei #<>buffer
pei #0 ; Push LBA = 0
pei #0
lda #1 ; The device number for the internal SD

jsl sys_bdev_write ; Write sector 0

ply ; Clean up the stack
ply
ply
ply
ply
```

$sys_bdev_status - 0xFFE068$

Gets the status of a block device. The meaning of the status bits is device specific, but there are two bits that are required in order to support the file system:

• 0x01: Device has not been initialized yet

• 0x02: Device is present

Prototype	short sys_bdev_status(short dev)
dev	the number of the device
Returns	the status of the device

```
short bdev = ...; // The device number
short status = sys_bdev_status(bdev);
```

Example: Assembler

$sys_bdev_flush - 0xFFE06C$

Ensure any pending writes to a block device are completed.

Prototype	short sys_bdev_flush(short dev)
dev	the number of the device
Returns	0 on success, any negative number is an error code

Example: C

```
short bdev = ...; // The device number
sys_bdev_flush(bdev);
```

Example: Assembler

$sys_bdev_ioctrl - 0xFFE070$

Send a command to a block device. The mapping of commands and their actions are device-specific. The return value is also device and command-specific.

Four commands should be supported by all devices:

- GET_SECTOR_COUNT (1): Returns the number of physical sectors on the device
- GET_SECTOR_SIZE (2): Returns the size of a physical sector in bytes
- GET_BLOCK_SIZE (3): Returns the block size of the device. Really only relevant for flash devices and only needed by FatFS
- GET_DRIVE_INFO (4): Returns the identification of the drive

Prototype	short sys_bdev_ioctrl(short dev, short command, uint8_t * buffer, short size)
dev	the number of the device
command	the number of the command to send
buffer	pointer to bytes of additional data for the command
size	the size of the buffer
Returns	0 on success, any negative number is an error code

```
short dev = ...; // The device number
short cmd = ...; // The command
short r = sys_bdev_ioctrl(dev, cmd, 0, 0); // Send simple command
```

Example: Assembler

pei #0 ; Push buffer size of 0

pei #0 ; Push null pointer for buffer

pei #0

lda cmd ; Push the command number

pha

lda bdev ; Select the block device

jsl sys_bdev_ioctrl ; Send the command

ply ; Clean up the stack

ply ply

3.3 File System Functions

$sys_fsys_open - 0xFFE074$

Prototype	short sys_fsys_open(const char * path, short mode)
path	the ASCIIZ string containing the path to the file.
mode	the mode (e.g. r/w/create)
Returns	the channel ID for the open file (negative if error)

$sys_fsys_close - 0xFFE078$

Prototype	short sys_fsys_close(short fd)
fd	the channel ID for the file
Returns	0 on success, negative number on failure

$sys_fsys_opendir - 0xFFE07C$

Prototype	<pre>short sys_fsys_opendir(const char * path)</pre>
path	the path to the directory to open
Returns	the handle to the directory if $\xi = 0$. An error if $\xi = 0$

$sys_fsys_closedir - 0xFFE080$

Prototype	short sys_fsys_closedir(short dir)
dir	the directory handle to close
Returns	0 on success, negative number on error

$sys_fsys_readdir - 0xFFE084$

Prototype	short sys_fsys_readdir(short dir, p_file_info file)
dir	the handle of the open directory
file	pointer to the t_file_info structure to fill out.
Returns	0 on success, negative number on failure

$sys_fsys_findfirst - 0xFFE088$

Prototype	short sys_fsys_findfirst(const char * path, const char * pattern, p_file_info file)
path	the path to the directory to search
pattern	the file name pattern to search for
file	pointer to the t_file_info structure to fill out
Returns	the directory handle to use for subsequent calls if $\xi = 0$, error if negative

$sys_fsys_findnext - 0xFFE08C$

Prototype	short sys_fsys_findnext(short dir, p_file_info file)
dir	the handle to the directory (returned by fsys_findfirst) to search
file	pointer to the t_file_info structure to fill out
Returns	0 on success, error if negative

$sys_fsys_get_label - 0xFFE090$

Prototype	short sys_fsys_get_label(const char * path, char * label)
path	path to the drive
label	buffer that will hold the label should be at least 35 bytes
Returns	0 on success, error if negative

$sys_fsys_set_label - 0xFFE094$

Prototype	short sys_fsys_set_label(short drive, const char * label)
drive	drive number
label	buffer that holds the label
Returns	0 on success, error if negative

$sys_fsys_mkdir - 0xFFE098$

	<pre>short sys_fsys_mkdir(const char * path)</pre>
path	the path of the directory to create.
Returns	0 on success, negative number on failure.

$sys_fsys_delete - 0xFFE09C$

Prototype	<pre>short sys_fsys_delete(const char * path)</pre>
path	the path of the file or directory to delete.
Returns	0 on success, negative number on failure.

$sys_fsys_rename - 0xFFE0A0$

Prototype	short sys_fsys_rename(const char * old_path, const char * new_path)
old_path	he current path to the file
new_path	the new path for the file
Returns	0 on success, negative number on failure.

$sys_fsys_set_cwd - 0xFFE0A4$

Prototype	<pre>short sys_fsys_set_cwd(const char * path)</pre>
path	the path that should be the new current
Returns	0 on success, negative number on failure.

$sys_fsys_get_cwd - 0xFFE0A8$

Prototype	short sys_fsys_get_cwd(char * path, short size)
path	the buffer in which to store the directory
size	the size of the buffer in bytes
Returns	0 on success, negative number on failure.

$sys_fsys_load - 0xFFE0AC$

Prototype	short sys_fsys_load(const char * path, uint32_t destination, uint32_t * start)
path	the path to the file to load
destination	the destination address (0 for use file's address)
start	pointer to the long variable to fill with the starting address
Returns	0 on success, negative number on error

$sys_fsys_register_loader - 0xFFE0B0$

Prototype	short sys_fsys_register_loader(const char * extension, p_file_loader loader)
extension	the file extension to map to
loader	pointer to the file load routine to add
Returns	0 on success, negative number on error

$sys_fsys_stat - 0xFFE0B4$

Prototype	short sys_fsys_stat(const char * path, p_file_info file)
path	the path to the file to check
file	pointer to a file info record to fill in, if the file is found.
Returns	0 on success, negative number on error

3.4 Text System Functions

$sys_txt_set_mode - 0xFFE0E0$

Prototype	short sys_txt_set_mode(short screen, short mode)
screen	the number of the text device
mode	a bitfield of desired display mode options
Returns	0 on success, any other number means the mode is invalid for the screen

$sys_txt_set_xy - 0xFFE0E8$

V 2	void sys_txt_set_xy(short screen, short x, short y)
screen	the number of the text device
X	the column for the cursor
У	the row for the cursor

$sys_txt_get_xy - 0xFFE0EC$

Prototype	void sys_txt_get_xy(short screen, p_point position)
screen	the number of the text device
position	pointer to a t_point record to fill out

$sys_txt_get_region - 0xFFE0F0$

Prototype	short sys_txt_get_region(short screen, p_rect region)
screen	the number of the text device
region	pointer to a t_rect describing the rectangular region (using character cells for size and size)
Returns	0 on success, any other number means the region was invalid

$sys_txt_set_region - 0xFFE0F4$

Prototype	short sys_txt_set_region(short screen, p_rect region)
screen	the number of the text device
region	pointer to a t_rect describing the rectangular region (using character cells for size and size)
Returns	0 on success, any other number means the region was invalid

$sys_txt_set_color - 0xFFE0F8$

Prototype	void sys_txt_set_color(short screen, unsigned char foreground, unsigned char background)
screen	the number of the text device
foreground	the Text LUT index of the new current foreground color (0 - 15)
background	the Text LUT index of the new current background color (0 - 15)

$sys_txt_get_color - 0xFFE0FC$

Prototype	void sys_txt_get_color(short screen, unsigned char * foreground, unsigned char * background)
screen	the number of the text device
foreground	the Text LUT index of the new current foreground color (0 - 15)
background	the Text LUT index of the new current background color (0 - 15)

$sys_txt_set_cursor_visible - 0xFFE100$

Prototype	void sys_txt_set_cursor_visible(short screen, short is_visible)
screen	the screen number 0 for channel A, 1 for channel B
is_visible	TRUE if the cursor should be visible, FALSE (0) otherwise

$sys_txt_set_font - 0xFFE104$

Prototype	short sys_txt_set_font(short screen, short width, short height, unsigned char * data)
screen	the number of the text device
width	width of a character in pixels
height	of a character in pixels
data	pointer to the raw font data to be loaded

$sys_txt_setsizes - 0xFFE0E4$

Prototype	void sys_txt_setsizes(short chan)
chan	

$sys_txt_get_sizes - 0xFFE108$

Prototype	void sys_txt_get_sizes(short screen, p_extent text_size, p_extent pixel_size)
screen	the screen number 0 for channel A, 1 for channel B
text_size	the size of the screen in visible characters (may be null)
pixel_size	the size of the screen in pixels (may be null)

$sys_txt_set_border - 0xFFE10C$

Prototype	void sys_txt_set_border(short screen, short width, short height)
screen	the number of the text device
width	the horizontal size of one side of the border (0 - 32 pixels)
height	the vertical size of one side of the border (0 - 32 pixels)

$sys_txt_set_border_color - 0xFFE110$

Prototype	void sys_txt_set_border_color(short screen, unsigned char red, unsigned char green, unsigned char blue)
screen	the number of the text device
red	the red component of the color (0 - 255)
green	the green component of the color (0 - 255)
blue	the blue component of the color (0 - 255)

$sys_txt_put - 0xFFE114$

Prototype	void sys_txt_put(short screen, char c)
screen	the number of the text device
С	the character to print

$sys_txt_print - 0xFFE118$

	Prototype	<pre>void sys_txt_print(short screen, const char * message)</pre>
	screen	the number of the text device
Ī	message	the ASCII Z string to print

3.5 Interrupt Functions

$sys_int_enable_all - 0xFFE004$

This function enables all maskable interrupts at the CPU level. It returns a system-dependent code that represents the previous level of interrupt masking. Note: this does not change the mask status of interrupts in the machine's interrupt controller, it just changes if the CPU ignores IRQs or not.

```
Prototype void sys_int_enable_all()
```

Example: C

```
// Enable processing of IRQs sys_int_enable_all();
```

Example: Assembler

```
; Enable processing of IRQs
jrl sys_int_enable_all
```

$sys_int_disable_all - 0xFFE008$

This function disables all maskable interrupts at the CPU level. It returns a system-dependent code that represents the previous level of interrupt masking. Note: this does not change the mask status of interrupts in the machine's interrupt controller, it just changes if the CPU ignores IRQs or not.

Prototype	<pre>void sys_int_disable_all()</pre>
-----------	---------------------------------------

Example: C

```
// Disable processing of IRQs sys_int_disable_all();
```

Example: Assembler

```
; Disable processing of IRQs
jrl sys_int_disable_all
```

$sys_int_disable - 0xFFE00C$

This function disables a particular interrupt at the level of the interrupt controller. The argument passed is the number of the interrupt to disable.

	Prototype	void sys_int_disable(unsigned short n)
Γ	n	the number of the interrupt: $n[74] = \text{group number}, n[30] = \text{individual number}.$

```
// Disable the start-of-frame interrupt sys_int_disable(INT_SOF_A);
```

Example: Assembler

```
lda #INT_SOF_A ; Enable the start-of-frame interrupt
jsl sys_int_disable
```

$sys_int_enable - 0xFFE010$

This function enables a particular interrupt at the level of the interrupt controller. The argument passed is the number of the interrupt to enable. Note that interrupts that are enabled at this level will still be disabled, if interrupts are disabled globally by sys_int_disable_all.

Prototype	void sys_int_enable(unsigned short n)
n	the number of the interrupt

Example: C

```
// Enable the start-of-frame interrupt sys_int_enable(INT_SOF_A);
```

Example: Assembler

```
lda #INT_SOF_A ; Enable the start-of-frame interrupt jsl sys_int_enable
```

$sys_int_register - 0xFFE014$

Registers a function as an interrupt handler. An interrupt handler is a function which takes and returns no arguments and will be run in at an elevated privilege level during the interrupt handling cycle.

The first argument is the number of the interrupt to handle, the second argument is a pointer to the interrupt handler to register. Registering a null pointer as an interrupt handler will "deregister" the old handler.

The function returns the handler that was previously registered.

Prototype	p_int_handler sys_int_register(unsigned short n, p_int_handler handler)
n	the number of the interrupt
handler	pointer to the interrupt handler to register
Returns	the pointer to the previous interrupt handler

Example: Assember

```
; Handler for the start-of-frame interrupt
; Must be a far sub-routine (returns through RTL)
sof_handler:
    ; Handler code here...
   rtl
    ; Code to register the handler...
   pei #'sof_handler
                            ; push pointer to sof_handler
   pei #<>sof_handler
   lda #INT_SOF_A
                            ; A = the number for the SOF_A interrupt
   jsl sys_int_register
   ply
                            ; Clean up the stack
   ply
   sta old
                            ; Save the pointer to the old handler
   stx old+2
```

$sys_int_pending - 0xFFE018$

Query an interrupt to see if it is pending in the interrupt controller. NOTE: User programs will probably never need to use this call, since it is handled by the Toolbox itself.

Prototype	short sys_int_pending(unsigned short n)
n	the number of the interrupt: $n[74] = \text{group number}, n[30] = \text{individual number}.$
Returns	non-zero if interrupt n is pending, 0 if not

Example: C

Example: Assembler

```
; Check to see if the start-of-frame interrupt is pending
lda #INT_SOF_A
jsl sys_int_pending
cmp #0
beq sof_not_pending
; Code for when start-of-frame is pending
sof_not_pending:
```

$sys_int_clear - 0xFFE020$

This function acknowledges the processing of an interrupt by clearing its pending flag in the interrupt controller. NOTE: User programs will probably never need to use this call, since it is handled by the Toolbox itself.

Prototype	void sys_int_clear(unsigned short n)
n	the number of the interrupt: $n[74] = \text{group number}, n[30] = \text{individual number}.$

Example: C

```
// Acknowledge the processing of the start-of-frame interrupt sys_int_clear(INT_SOF_A);
```

Example: Assembler

```
; Acknowledge the processing of the start-of-frame interrupt lda #INT_SOF_A jsl sys_int_clear
```

3.6 General Functions

$sys_proc_exit - 0xFFE000$

This function ends the currently running program and returns control to the command line. It takes a single short argument, which is the result code that should be passed back to the kernel. This function does not return.

l	$\mathbf{void} \ \mathrm{sys_proc_exit}(\mathbf{short} \ \mathrm{result})$	
	result	the code to return to the kernel

Example: C

 $sys_proc_exit(0)$; // Quit the program with a result code of 0

Example: Assembler

$sys_proc_run - 0xFFE0D8$

Prototype	short sys_proc_run(const char * path, int argc, char * argv[])
path	the path to the executable file
argc	the number of arguments passed
argv	the array of string arguments
Returns	the return result of the program

$sys_get_info - 0xFFE01C$

Prototype	void sys_get_info(p_sys_info info)
info	pointer to a s_sys_info structure to fill out

$sys_mem_get_ramtop - 0xFFE0B8$

Prototype	uint32_t sys_mem_get_ramtop()
Returns	the address of the first byte of reserved system RAM (one above the last byte the user program can use)

$sys_mem_reserve - 0xFFE0BC$

Prototype	uint32_t sys_mem_reserve(uint32_t bytes)
bytes	the number of bytes to reserve
Returns	address of the first byte of the reserved block

$sys_time_jiffies - 0xFFE0C0$

Prototype	uint32_t sys_time_jiffies()
Returns	the number of jiffies since the last reset

$sys_rtc_set_time - 0xFFE0C4$

Prototype	void sys_rtc_set_time(p_time time)
time	pointer to a t_time record containing the correct time

$sys_rtc_get_time - 0xFFE0C8$

Prototype	void sys_rtc_get_time(p_time time)
time	pointer to a t_time record in which to put the current time

$sys_kbd_scancode - 0xFFE0CC$

Prototype	uint16_t sys_kbd_scancode()
Returns	the next scan code from the keyboard 0 if nothing pending

$sys_kbd_layout - 0xFFE0D4$

Prototype	<pre>short sys_kbd_layout(const char * tables)</pre>
tables	pointer to the keyboard translation tables
Returns	0 on success, negative number on error