Building Embedded Operating System with IMGUI Demo for *Raspberry π - 4 - model B* with *Yocto*

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1 introduction

These instructions[5] follow the configuration and build of a Linux-based operating system for *Raspberry* π - 4 - *model B*[7] with *Yocto*[2]. Find project overview in [6].

The *operating system* (OS) build is done in several steps organized in corresponding sections as follows. Read in Section 2 how to fetch *metadata*. Section 3 shows how to configure the OS build. In Section 4 learn how to build the OS *image* and see how to copy *image* to SD card in Section 5. Section 6 is dedicated to post-install issues like the configuration of the WiFi interface from the command line.

2   metadata

Metadata is a set of instructions to build targets. It is organized in *recipe* files with the *.bb* suffix. Further there are *class* files with the suffix *.bbclass* with information shared between *recipes*. Finally, there are configuration files with the extension *.conf*. These define configuration variables to control the build process. *Metadata* is organized in *layers*. Layers logically separate information of a project. *OpenEmbedded*[1] defines the following layer types.

- base layers contain base *metadata* for the build

- machine aka *board support package* (BSP) layers include *hardware* (HW) support

- distribution layers hold the policy configuration

- *software* (SW) layers are used for additional SW

- miscellaneous layers do not fall in upper categories

The complete list of *github* SW *metadata* repositories used in this project includes *Yocto* layers, the *Raspberry π - 4 - model B* BSP layer, a SW layer with custom recipes, and the build configuration itself. Please refer [6] for details.

In short, users fetch *metadata* in contrast to the *real data* fetched by *bitbake* during OS build. See Section 4 for details. It is an user decision where to put fetched *metadata*. However, it is nice to have all layer sub-directories in one location. In these instructions this location is referred as <layer_directory>. The second directory to create is the <build_directory>. This is where the build and build configuration live. I suggest that this one is not inside the <layer_directory> to not mix *data* and *metadata*.

It is very likely that you will need to install *Yocto* requirements[3] to be able to run *bitbake*. Make sure to have the following command-line tools on your host machine: *chrpath*, *diffstat*, *lz4c*, *rpcgen*; Also have a look at your storage device. Fetched *metadata* requires 400 *MB* of free space. The build needs at least 100 *GB*.

I have a shell script to fetch *metadata* from public *github* repositories. This modification may serve people to build their own OS for *Raspberry π - 4 - model B*. The script performs *metadata* fetch, the *bitbake* initialisation and a simple check of installed layers.

```sh
#!/bin/sh
# metafetch.sh
# fetch rpi metadata
# release 3.3.2

FETCHER=https://github.com/
GITFETCHER=git@github.com:
BRANCH=kirkstone
DEFLAYER=$HOME/yocto_$BRANCH/metadata
DEFBUILD=$HOME/yocto_$BRANCH/rpi4

erreur() { echo $* && exit 0 || kill $$; }

usage() {

    printf "
usage:
\t $0 <options>
    option          \t purpose                    \t default
    -h              \t print this                 \t usage
    -g              \t switch to git protocol     \t https protocol
    -r <branch>     \t branch                     \t $BRANCH
    -l <layerdir>   \t metadata directory         \t $DEFLAYER
    -b <buildir>    \t build directory            \t $DEFBUILD
"

    erreur
}

confirm() {

    read -p "please confirm (y/n) " choix
    [ "$choix" == "y" ] && echo 1 || echo 0
}


while getopts ":l:b:r:hg" option; do

    case $option in

        l ) LAYER=$OPTARG;;
        b ) BUILD=$OPTARG;;
        r ) BRANCH=$OPTARG;;
```

```bash
        g )  FETCHER=$GITFETCHER;;
        h )  usage $0;; # erreur $? usage: $0 -l layerdir -b buildir -r branch -g
    ;;
        * )  usage $0;; # erreur $? minimal usage: $0 -l layerdir -b buildir;;
    esac
done

[ -n "$LAYER" ]  ||  LAYER=$DEFLAYER
[ -n "$BUILD" ]  ||  BUILD=$DEFBUILD
[ -d $LAYER ]  ||  mkdir -p $LAYER ||  erreur $? cannot create $LAYER
[ -d $BUILD ]  ||  mkdir -p $BUILD ||  erreur $? cannot create $BUILD
LAYER=$(realpath $LAYER) && printf "\nmetadata:\t $LAYER\n" || erreur $? cannot
    find $LAYER
BUILD=$(realpath $BUILD) && printf "build:\t\t $BUILD\n" || erreur $? cannot find
    $BUILD
printf "branch:\t\t $BRANCH\nprotocol:\t $FETCHER\n\n"

[ $(confirm) = 0 ] && erreur $? $0 interrupt || echo $0 continue

git clone -b $BRANCH ${FETCHER}yoctoproject/poky.git $LAYER/poky
git clone -b $BRANCH ${FETCHER}openembedded/meta-openembedded.git $LAYER/oe
git clone -b $BRANCH ${FETCHER}agherzan/meta-raspberrypi $LAYER/rpi/meta-
    raspberrypi
git clone -b $BRANCH ${FETCHER}kaloyanski/meta-thc.git $LAYER/thc/meta-thc
git clone -b $BRANCH ${FETCHER}TripleHelixConsulting/rpiconf.git $BUILD/conf

sed -i s#/home/yocto/layer#$LAYER#g $BUILD/conf/bblayers.conf || erreur sed $?

OEINIT=oe-init-build-env
cd $LAYER/poky && pwd || erreur $? cannot find $LAYER/poky
[ -x $OEINIT ] && . ./$OEINIT $BUILD || erreur $? cannot find $OEINIT

bitbake-layers show-layers

printf "\n\t how to start a new build\n\n"

echo cd $LAYER/poky
echo . ./$OEINIT $BUILD
echo bitbake core-image-x11
echo
```

Download *metafetch.sh* here. It is designed in a way that after a succesful run you may start a build with *bitbake*. The script takes <layer_directory> and <build_directory> from the command-line. You may use next commands to run *metafetch.sh*. The first one is a minimal example. You may specify directories like the first example. Otherwise the script will use default values. The default *Yocto branch* is *kirkstone*. You may want to specify another *branch* with the second command.

```bash
./metafetch -l <layer_directory> -b <build_directory>
./metafetch -l <layer_directory> -b <build_directory> -r <branch_name>
```

3 configuration

Build configuration is in <build_directory>/conf, check files *local.conf* and *bblayers.conf*. *Yocto* layers are specified in *bblayers.conf*. The build directives are in *local.conf*. Variables in this file control the build. Sometimes I call these *directives* to avoid repetitions. Many directives are not covered in these instructions. Please refer *bitbake*[8] documentation for details. It is not always easy to understand the meaning and the relations between different directives. What is more, *bitbake* syntax is pretty complicated. In short, your life can easily become unbearable if the build configuration is too long. Here is a short list.

3.1 MACHINE

No doubt, this is the most important directive, set here to *raspberrypi4-64*. You may want to change this value if you build an OS for a different HW. If you want to examine OS built for *Raspberry π - 4 - model B* on your host machine with *qemu*, set *MACHINE* to *qemuarm64*. I confirm that this works although I did not find this approach very useful to test a *graphical user interface* (GUI).

3.2 PACKAGE_INSTALL

This is where to specify additional SW packages. This is useful for packages not included in the *image* by default. In my experience, the default OS has all necessary programs or compact alternatives. However this is the directive used to append *imgui*.

3.3   IMAGE_FSTYPES

This is another important directive. Here I have removed archived
images that I do not need to decrease the built time and added the
wic format to have an *image* file ready to be copied to the SD card
immediately after the build. See Section 5 for details.

4 build

Yocto provides a list of image types. As I want to have a compact OS and I need a X server to run a GUI, I rely on $core-image-x11$[2]. This is a very basic $X11$ image.

The primary build tool of *OpenEmbedded* based projects, such as the *Yocto* project, *bitbake*, works in the <build_directory>. Here is a list of the most important sub-directory names by default. These are configurable but usually there is no need to change their default names.

- <build_directory>/conf - build (*local.conf*) and layer (*bblayers.conf*) configuration files

- <build_directory>/downloads - fetched source code archives

- <build_directory>/tmp/work - working directory where source code is extracted, configured, compiled and installed

- <build_directory>/tmp/deploy/ipk - final SW packages in *ipk* format

- <build_directory>/tmp/deploy/images/raspberrypi4-64 - boot files, compiled kernels and OS *images*.

First, you need to initialize build environment.

```
source <layer_directory>/poky/oe−init−build−env <build_directory>
```

This will change your system path to <build_directory>. You may run now next command to check the project layers.

```
bitbake−layers show−layers
```

If this is fine, the following command is going to build the OS *image*.

task	description
do_fetch	fetch the source code
do_unpack	unpack the source code
do_patch	apply patches to the source
do_configure	source configuration
do_compile	compile the source code
do_install	copy files to the holding area
do_package	analyse holding area
do_package_write_ipk	create *ipk* package
do_package_qa	quality checks on the package

Table 1: A list of *bitbake* tasks

```
bitbake core−image−x11
```

Be patient because, unless your host machine is a supercomputer, this will take hours. Find a list of tasks performed by *bitbake* for a typical SW package in Table 1.

5 install

The OS includes a kernel ARM, 64 bit boot executable $image$ of $23MB$, a $Raspberry\ \pi$ - 4 - $model\ B$ configuration of Linux 5.15. The total size of kernel modules is $21MB$. Happily this kernel release has a $long-term\ support$ (LTS).

Yocto provides multiple package and $image$ formats. Find $image$ files in

$< build\_directory > /tmp/deploy/images/raspberrypi4 - 64$

Further, different ways exist to install $images$ on SD card. The final result is an OS with two partitions - $/root$ and $/boot$. There are not $swap$ and $home$ partitions. I recommend the classic command-line tool dd to copy data. It works fine with different $image$ formats like $rpi - sdimg$, $hddimg$ and wic. The last one is recommended. Find the SDcard device name, in example $/dev/ < xxx >$, unmount it with $umount$ if mounted, and do copy data from the command line with

```
dd  if=core−image−x11−raspberrypi4 −64.wic  of=/dev/<xxx>  status=progress
```

- note 1: run this command in <build_directory>/tmp/deploy/images/ras
  64

- note 2: run this command with $root$ privileges

- note 3: be careful to not specify the device name of your hard drive (see note 2)

The transfer is going to take a while. Once it is over, put the card in you $Raspberry\ \pi$ - 4 - $model\ B$ and turn it on. That's it.

6 run

Wireless connection is established via classic command-line tools like *ip* and *iw*. I use a *dynamic host configuration protocol* (DHCP) client, *udhcpc*, and *wpa_supplicant* to store WiFi connection. The shell scripts *wifini.sh* is designed by me and installed in */usr/bin*, as well as a running GUI example to demonstrate the usage of the *Dear ImGui* library.

```sh
#!/bin/sh
# wifini.sh
# wifi connection requirements:

# wpa_passphrase, wpa_supplicant, ip, iw, grep, awk
# designed by kaloyansen at gmail dot com
# copyleft triplehelix-consulting.com
# # # # # # # # # # # # # # # # # # # # # # # # # #

# files
WPACONF=/etc/wpa_supplicant.conf
WPASOCKET=/run/wpa_supplicant/$WIFACE
UDHCPID=/run/udhcpc.$WIFACE.pid
IFCONF=/etc/network/interfaces

# command-line tools
WPAPASS=/usr/bin/wpa_passphrase
IW=/usr/sbin/iw
WPASUPP=/usr/sbin/wpa_supplicant
DHCP=/sbin/udhcpc
IP=/sbin/ip

erreur() { echo $* && exit 1; }

# get wifi interface and network id
WIFACE=`$IW dev|grep Interface|awk '{print $2}'`
SSID=$(getopt s: $* | awk '{print $2}')

[ -n "$SSID" ] &&
    echo $0: $WIFACE $SSID ||
        erreur interface $WIFACE specify network: $0 -s '<SSID>'

[ "$USER" == "root" ] || erreur run $0 as root

# enable interface connexion on boot
if [ -f $IFCONF ]; then
    grep "auto $WIFACE" $IFCONF > /dev/null ||
        printf "auto $WIFACE\n" >> $IFCONF
else
    erreur $0: $IFCONF not found;
fi


grep "auto $WIFACE" $IFCONF > /dev/null ||
    printf "auto $WIFACE\n" >> $IFCONF
```

```
# verify connexion
$IW dev|grep $SSID > /dev/null &&
    erreur $0 info: $WIFACE $SSID ||
        echo $0 connecting to $SSID

# up interface
$IP link show $WIFACE | grep UP ||
    $IP link set $WIFACE up

# search network
$IW $WIFACE scan|grep $SSID ||
    erreur $0 warning: cannot find network $SSID;

# save network
grep $SSID $WPACONF ||
    $WPAPASS $SSID >> $WPACONF

# load network
[ -S "$WPASOCKET" ] ||
    $WPASUPP -B -D wext -i $WIFACE -c $WPACONF

# start a dhcp client
$DHCP -i $WIFACE ||
    erreur $0 warning: $?

# [ -f "$UDHCPID" ] ||
# ip addr show $WIFACE
# iw $WIFACE link
# ip route show
```

The script is available for download here. Specify network *id* from the command line with a short command-line option *s*. See next example usage.

```
wifini -s <SSID>
```

Once an *internet protocol* (IP) address is assigned to *Raspberry* π - 4 - *model B*, the *secure shell* (SSH) server by *Dropbear*[4] allows for secure remote login, control and file transfer.

7 outlook

This reports the progress in the development of a custom Linux-based OS for *Raspberry π - 4 - model B*[7]. The kernel version of this embedded OS is Linux release 5.15. An example GUI application using the *Dear ImGui* library is built as a part of the OS *image*. In addition, an SSH server provides remote connection, data transfer and device control. As the OS is now functional, performance and real-time tests are ongoing.

acronyms

bibliography

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