CFD HW 2 Semyon Lopatkin

Information to know

Root is considered to be a solution when error goes under 1%

And

*Both codes incorporate 2 numerical methods and user is able to pick which to use *

Part 1

Code: from __future__ import division import time import math from operator import itemgetter #import numpy Re1 = 174981 Re2 = 94682Re3 = 80281Re4 = 43955Re5 = 36309Re6 = 21680Re7 = 14628 Re8 = 36309Re9 = 80281n = 0 #probs needs to be inside the loop smh pn = 1 #pipe number nn = 1 #iteration counter #u = #probs needs to be inside the loop smh #I = #probs needs to be inside the loop smh a = [Re1, Re2, Re3, Re4, Re5, Re6, Re7, Re8, Re9, 0] # array L = [2,4,2,4,2,4,8,2,2]method = int(input("1 for Secant Method, 2 for False Position Method")) if method == 1:

x0 = float(input("what is initial xi-1?"))
x1 = float(input("what is initial xi?"))

```
xx0 = x0
  xx1 = x1
if method == 2:
  xl = float(input("what is initial xl?"))
  xu = float(input("what is initial xu?"))
  xxI = xI
  xxu = xu
  xxr = 0 #placeholder, so the ERR function works correctly
#fof = 4*math.log(Re*f^0.5,10)-f^-.5-0.4 #refference, nstbh
\#dfof = 2*(math.ln(10)*f+2x^-1.5) \#derrivative of fof, nstbh
#fu = 4*math.log(Re*u^0.5,10)-u^-.5-0.4
#dif = x0-x1
#fr = fu - (fu*(dif))/(fx0-fx1)
while method == 1: #SECANT
  a = [Re1, Re2, Re3, Re4, Re5, Re6, Re7, Re8, Re9]
  time.sleep(0.1)
  ind_pos = [n] # indexing the positon of a value in the array
  Re = itemgetter(*ind_pos)(a) #get the needed value
  print (Re) #debug for my sanity
  time.sleep(0.1)
  fx0 = float(4*math.log(Re*x0**0.5,10)-x0**-.5-0.4)
  #print(fx0)
  fx1 = float(4*math.log(Re*x1**0.5,10)-x1**-.5-0.4)
  err = (x1-x0)/x1
  x2 = x1 - ((float(fx1)*(float(x0)-float(x1)))/((float(fx0)-float(x1))))
  err = (x1-x0)/x1
```

```
print("Iteration: ", nn, "xi-1: ", x0, "xi: ", x1, "xi+1: ", x2, "f(xi): ", fx1, "f(xi-1): ", fx0, "ERROR: ", err)
  nn = nn + 1
  x0 = x1
  x1 = x2
  if err < 0.005:
     print("SUCCESS, PIPE", pn, "- ERROR UNDER 1%")
    pn=pn+1
     n=n+1
    x0 = xx0
    x1 = xx1
  elif pn == 9 or n == 9:
     print("DONE")
     break
while method == 2: #FALSE POSITION
  a = [Re1, Re2, Re3, Re4, Re5, Re6, Re7, Re8, Re9, 0]
  time.sleep(0.1)
  ind_pos = [n] # indexing the positon of a value in the array
  Re = itemgetter(*ind_pos)(a) #get the needed value
  print (Re) #debug for my sanity
  fxu = 4*math.log(Re*xu**0.5,10)-xu**-.5-0.4
  fxI = 4*math.log(Re*xI**0.5,10)-xI**-.5-0.4
  xr = xu-((fxu*(xl-xu))/(fxl-fxu))
  fxr = 4*math.log(Re*xr**0.5,10)-xr**-.5-0.4
  fxrfxl = fxl*fxr
  ERR = abs((xxr-xr)/xr)
  xxr=xr
  if fxrfxl < 0:
    xu = xr
     #print("XU: ", xu)
  elif fxrfxl > 0:
     xI = xr
```

```
#print("XL: ", xl)

elif fxrfxl == 0:
    print("root is:", xr)

print("Iteration: ", nn, "xl: ", xl, "xu: ", xu, "xr: ", xr, "f(xl): ", fxl, "f(xr):", fxr, "f(xr)*f(xl): ", fxrfxl, "ERROR: ", ERR)

nn = nn +1

if ERR < 0.005:

print("SUCCESS, PIPE", pn, "- ERROR UNDER 1%")

pn=pn+1

n=n+1

xl = xxl

xu = xxu

elif pn > 9 or n > 9:
    print("DONE")
```

break

Methods Comparison

Equation of the interest in the Part 1 is:

$$4Log(Re*\sqrt{f}) - f^{-0.5} - 0.4 = 0$$
 Equation 1.

False Position Method

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Image 1. False Position Method

Only took 624 iterations for the False Position to calculate friction factor for all 9 pipes.

Secant Method

Teration: 37 x1: 0.004701125375499179 xu: 0.0035 xr: 0.004701125375499179 f(x1): -0.11506361128425058 f(xr): -0.02189839459738574 f(xr)*f(xl): 0.0025197083637027258 ERROR: 0.0113223 48035791843 80281

Iteration: 38 x1: 0.004711341611950063 xu: 0.0035 xr: 0.004711341611950063 f(xl): -0.02189839459738574 f(xr): -0.004191247298807377 f(xr)*f(xl): 9.178158720451103e-05 ERROR: 0.002168 4346609404507

SUCCESS, PIFE 9 - ERROR UNDER 1%

Image 2. Secant Method

<u>Unlike</u> for the <u>False Position</u>, it only takes 38 iterations to reach the root for all 9 pipes.

Problem Analysis

	р	mu
Q1 (m3/s)	(kg/m3)	(Ns/m2)
1	1.23	1.79E-05

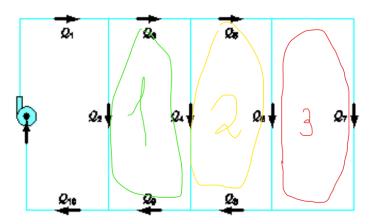
1	1.23	1.79E-05			
Pipe	Length (m)	D (m)	S (m3)	Q (m3/s)	V (m/s)
2	4	0.5	0.1963	0.5411	2.7571975
3	2	0.5	0.1963	0.4588	2.3378344
4	4	0.5	0.1963	0.2512	1.28
5	2	0.5	0.1963	0.2075	1.0573248
6	4	0.5	0.1963	0.1239	0.6313376
7	8	0.5	0.1963	0.0836	0.4259873
8	2	0.5	0.1963	0.2075	1.0573248
9	2	0.5	0.1963	0.4588	2.3378344
Re	f (secant method)	f (false position)	dP (kPa)	dP (kPa)	Method difference
9.47E+04	0.00478	0.00449	0.1786	0.1678	6%
8.03E+04	0.00495	0.00464	0.0665	0.0623	7%
4.40E+04	0.00567	0.00522	0.0457	0.0420	9%
3.63E+04	0.00593	0.00544	0.0163	0.0149	9%
2.17E+04	0.00674	0.00604	0.0132	0.0118	12%
1.46E+04	0.00743	0.00653	0.0133	0.0117	14%
3.63E+04	0.00593	0.00544	0.0163	0.0149	9%
8.03E+04	0.00495	0.00464	0.0665	0.0623	7%

Table 1.

<u>False Position</u> estimated the root to be lower than the <u>Secant Method</u> root estimates, therefore pressure drops ended up being smaller across the pipes. Additionally values are checked through established physical relationships:

Checking

Physical relationships are established inside of these loops:



That gets us:

Loop 3:
$$P_6 + P_7 = 0$$

Loop 2:
$$P_4 + P_5 + P_6 + P_8 = 0$$

Loop 1:
$$P_2 + P_3 + P_4 + P_9 = 0$$

Set Of Equations 1. Pressure drop relations

Secant Method

Loop 3 0.0133-0.0132 = **0.0001**

Loop 2 0.0163-0.0457+0.0163+0.0132 = **0.0001**

Loop 1 0.1786-0.0665-0.0457-0.0665 = **-0.0001**

False Position Method

Loop 3 0.0118-0.0117 = **0.0001**

Loop 2 0.0420-0.0149-0.0118-0.0149 = **0.0004**

Loop 1 0.1678-0.0623-0.0420-0.0623 = **0.0012**

This tells us that both methods are pretty accurate at getting the root of the function, yet Secant Method is more accurate as it deviates less from the Set Of Equations 1.

First 2 Iterations by Hand

Part 2

Code:

```
import time
import math
print("Starting")
print(" The equation of interest is: 1-40.775*((3+xl)/(3*xl+((xl**2)/2))**3)=0 ")
xl = float(input("what is initial xl?"))
xu = float(input("what is initial xu?"))
method = int(input("1 for Bisection Method, 2 for False Position Method"))
n=1
xr = xI/2+xu/2
xxr = 0 #placeholder, so the ERR function works correctly
while method == 1:
  time.sleep(1)
  xr = xI/2+xu/2
  ERR = abs((xxr-xr)/xr)
  print (ERR)
  fxI = 1-40.775*((3+xI)/(3*xI+((xI**2)/2))**3)
  fxr = 1-40.775*((3+xr)/(3*xr+((xr**2)/2))**3)
  fxrfxl = fxl*fxr
  xxr = xr #store old xr
  print("Iteration: ", n, "xl: ", xl, "xu: ", xu, "xr: ", xr, "f(xl): ", fxl, "f(xr): ", fxr, "f(xr)*f(xl): ", fxrfxl, "ERROR: ", ERR)
  n = n+1
  if fxrfxl < 0:
     xu = xr
     #print("XU: ", xu)
  elif fxrfxl > 0:
     xI = xr
```

```
#print("XL: ", xl)
  elif fxrfxl == 0:
     print("root is:", xr)
  \#ERR = (xu-xr)/xr
  if ERR < 0.01:
     print("SUCCESS - ERROR UNDER 1%")
     break
while method == 2:
  time.sleep(1)
  fxu = 1-40.775*((3+xu)/(3*xu+((xu**2)/2))**3)
  fxI = 1-40.775*((3+xI)/(3*xI+((xI**2)/2))**3)
  xr = xu-((fxu*(xl-xu))/(fxl-fxu))
  fxr = 1-40.775*((3+xr)/(3*xr+((xr**2)/2))**3)
  fxrfxl = fxl*fxr
  ERR = abs((xxr-xr)/xr)
  #print("LOOK HEREEEEE: ", xxr, xr) #debug
  xxr = xr#store old xr
  print("Iteration: ", n, "xl: ", xl, "xu: ", xu, "xr: ", xr, "f(xl): ", fxl, "f(xr):", fxr, "f(xr)*f(xl): ", fxrfxl, "ERROR: ", ERR)
  if fxrfxl < 0:
     xu = xr
  elif fxrfxl > 0:
     xI = xr
  elif fxrfxl == 0:
     print("root is:", xr)
  n = n+1
  if ERR < 0.01:
     print("SUCCESS - ERROR UNDER 1%")
     break
```

Methods Comparison

Equation of the interest in the Part 2 is:

$$1 - 40.775 \frac{3+y}{\left(3y + \frac{y^2}{2}\right)^3} = 0$$

Equation 2.

Bisection Method

Tetration: 7 xl: 1.5 xu: 1.53125 xr: 1.515625 f(xl): -0.030953086419752918 f(xr): 0.0033762383758055847 f(xr)*f(xl): -0.00010450499821999649 ERROR: 0.001309278350515464 0.0051813471502590676 Tetration: 8 xl: 1.5 xu: 1.515625 xr: 1.5078125 f(xl): -0.030953086419752918 f(xr): -0.013602161649019173 f(xr)*f(xl): 0.00042102888501753934 ERROR: 0.0051813471502590676 SUCCESS - ERROR UNDER 1%

Image 3. Bisection Method

From *Image*. 3 it can be seen that only 8 iterations are needed for the <u>Bisection</u> method to get the solution for *Equation 2*.

The solution found by this numerical method is $x_r = 1.5078125$

Plugging this value into Equation 2. yields -0.0136 rather than 0.

False Position

Iteration: 22 xl: 0.5 xu: 1.8149375383549944 xr: 1.7968643374581967 f(xl): -32.25844333181611 f(xr): 0.4309694389639083 f(xr)*f(xl): -13.902403222383809 ERROR: 0.010058188879391 LOOK HEREEEEE: 1.7968643374581967 1.779766786646888 f(xl): -32.25844333181611 f(xr): 0.4126436949605158 f(xr)*f(xl): -13.31124325011501 ERROR: 0.009606624272116455 SUCCESS - ERROR UNDER 1%

Image 4. False Position

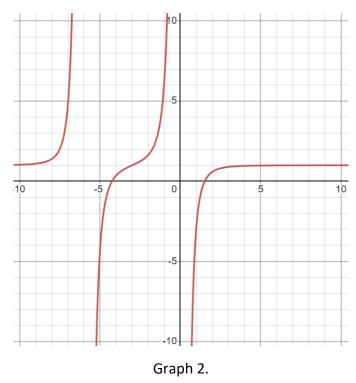
From *Image. 4* it can be seen that 23 iterations are needed for the <u>False Position</u> method to get the solution for *Equation 1*.

The solution found by this numerical method is $x_r = 1.77976$

Plugging this value into Equation 1 yields 0.4126 rather than 0.

Analysis

In the current situation <u>Bisection Method</u> wins over almost by 3-fold. And even if we plug in the xr values into the equation <u>Bisection Method</u> will be more accurate. But why is that? We can take a closer look at the graph of the equation of interest:



While the <u>Bisection Method</u> is getting xr that is in the middle of "search" boundaries (xu and xl), which does not complicate things, unless any of the asymptotes were selected as boundary locations.

<u>False Position</u> on the other hand, does not tend to zero the bracket, rather it employs Secant lines to find the xr, which makes only 1 point move closer to the solution. This with conjunction of the specific bracket chosen (0.5-2.5, f' is very big) makes it take more iterations and makes them less accurate.

First 2 Iterations by Hand

