int buzzer = 11;

int sensor = 2;

int led = 13;

void setup()

{

pinMode(buzzer, OUTPUT);

pinMode(sensor, INPUT);

pinMode(led, OUTPUT);

digitalWrite(buzzer,LOW);

digitalWrite(sensor,LOW);

digitalWrite(led,LOW);

while(millis()<13000)

{

digitalWrite(led,HIGH);

delay(50);

digitalWrite(led,LOW);

delay(50);

}

digitalWrite(led,HIGH);

}

void loop()

{

if(digitalRead(sensor)==HIGH)

{

digitalWrite(buzzer,HIGH);

delay(3000);

digitalWrite(buzzer,LOW);

while(digitalRead(sensor)==HIGH);

}

}