Chuanruo Ning

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EDUCATION BACKGROUND

• Peking University, Beijing, China

Bachelor of Science, Turing Class, Computer Science and Technology Sept 2020 - Present (expected Jun 2024)

GPA: 3.85/4.00 (2022-2023) **3.79**/4.00 (2021-2022) Top 10% in CS Department

Selected Honors and Awards:

John Hopcroft Scholarship, 2022

Peking University Dean's Scholarship, Peking University, 2022

Freshman Scholarship, Peking University, 2020

MANUSCRIPTS

• Learning Dense Visual Actionable Affordance for Deformable Object Manipulation

Chuanruo Ning*, Ruihai Wu*, Hao Dong (* denotes equal contribution)

Under review of CVPR 2023

RESEARCH EXPERIENCE

• Research Assistant, Center on Frontiers of Computing Studies, Peking University

2022.12 - Present

- Affordance learning for object manipulation, Supervisor: Dr. Kaichun Mo (NVIDIA), Prof. Hao Dong,
- Propose 'Confidence' to measure uncertainty in affordance learning.
- Tackle the data inefficiency in learning affordance for manipulating diverse objects.
- Enable the model to perform few-shot learning on novel objects by sampling interactions in low-confidence area.
- Research Assistant, Hyperplane Lab, Center on Frontiers of Computing Studies, Peking University 2022.1 Present
 - Deformable Object Manipulation, Supervisor: Ph.D. Candidate Ruihai Wu, Prof. Hao Dong
 - Learn dense visual representations for deformable object manipulation, which reveals the dynamic and kinematic property of deformable objects.
 - Propose a novel training pipeline to take the future states after one manipulation step into consideration.
 - By training in a reversed step-by-step manner, we enable the representation to be aware of 'potential', thus finding the global optimal action.
 - Paper under review of CVPR 2023

SKILLS

- Language: Chinese: native English: proficient TOEFL 110
- Deep Learning Frameworks: PyTorch (Proficient), TensorFlow (Proficient)
- Programming languages: Python, C&C++