Chuanruo Ning

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EDUCATION BACKGROUND

• Peking University, Beijing, China

Bachelor of Science, Turing Class, Computer Science and Technology

Sept 2020 - Present (expected Jun 2024)

GPA: 3.85/4.00 (2022-2023) **3.79**/4.00 (2021-2022)

Selected Honors and rewards:

John Hopcroft Scholarship, 2022

Peking University Dean's Scholarship, Peking University, 2022

Freshman Scholarship, Peking University, 2020

MANUSCRIPTS

Learning Dense Visual Actionable Affordance for Deformable Object Manipulation

Ruihai Wu*, Chuanruo Ning*, Hao Dong

Under review of CVPR

RESEARCH EXPERIENCE

• Research Assistant, Center on Frontiers of Computing Studies, Peking University

2022.12 - Present

- Affordance learning for object manipulation, Supervisor: Dr. Kaichun Mo, Prof. Hao Dong,
- Propose 'Confidence' to measure uncertainty in affordance learning.
- Solving the data inefficiency in learning affordance for manipulating diverse objects.
- Enable the model to perform few-shot learning on novel objects by sampling interactions in low-confidence area.
- Research Assistant, Hyperplane Lab, Center on Frontiers of Computing Studies, Peking University 2021.1 Present
 - **Deformable Object Manipulation**, Supervisor: Prof. Hao Dong, Ph.D. Ruihai Wu
 - Learning dense visual representation for deformable object manipulation, which reveals the dynamic and kinematic property of deformable objects.
 - We also propose a novel training pipeline to take the future states after manipulation into consideration.
 - By training in a reversed step-by-step manner, we enable the representation to be aware of 'potential', thus finding the global optimal action.

SKILLS

- Language: Chinese: native English: proficient TOEFL 110
- Deep Learning Frameworks: PyTorch (Proficient), TensorFlow (Proficient)
- Programming languages: Python, C&C++