My sources code are AlAdl, AlAnkabut, AlGhaffar, AlKabir, AlLatif, AlMatiin, AlWajid.

1. **AlAdl: PuddleDetector**
   * Violation
2. **AlAnkabut: WebDetector**
   * Filling
3. **AlGhaffar: CarpalDetector**
   * Filling
4. **AlKabir: BroomDetector**
   * Filling
5. **AlLatif: LineDetector**
   * Filling and Touching
6. **AlMatiin: MotorDetector**
   * **Violation**
7. **AlWajid: ArucoDetector**
   * **Position**

**The two main things that are being prioritized are Filling and Violation. Aruco is not**

|  |  |  |
| --- | --- | --- |
| **No** | **Function** | **Object** |
| 1 | Violation | Puddle |
| 2 | Paper |
| 3 | Motorcycle |
| 4 | Car |
| 5 | Truck |
| 6 | Colt |
| 7 | Forklift |
| 8 | Filling | Broom |
| 9 | Mop |
| 10 | Fibermop |
| 11 | Dustpan |