IMAGE SEGMENTATION - ASSIGNMENT 01

IS_Thresholding_based_Segmentation

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EXERCISE 1:

<u>Requirement</u>: thực hiện tốt hơn việc segmentation bàn tay với các phần xương, da, và background bằng các thuật toán global, local thresholding như trong file hướng dẫn thực hành

Code and results:

```
    ✓ Họ và tên: Nguyễn Thanh Trúc
    MSSV: 20110342
    ♠ 1 import numpy as np
    2 import cv2
    3 from matplotlib import pyplot as plt
    4 from skimage.color import rgb2gray
    5 from skimage.filters import threshold_otsu, threshold_multiotsu, threshold_nibing
    6 from skimage.measure import label, regionprops
    7 from skimage.segmentation import mark_boundaries
    8 from scipy import ndimage as ndi
    9 import pandas as pd
    10 import os
    11 import os
    12 import timeit
    13 import random
```

```
1 def ShowImage(ImageList, nRows = 1, nCols = 2, WidthSpace = 0.00, HeightSpace =
     import matplotlib.gridspec as gridspec
     gs = gridspec.GridSpec(nRows, nCols)
    gs.update(wspace=WidthSpace, hspace=HeightSpace) # set the spacing between a
    plt.figure(figsize=(20,20))
    for i in range(len(ImageList)):
      ax1 = plt.subplot(gs[i])
        ax1.set_xticklabels([])
        ax1.set yticklabels([])
       ax1.set_aspect('equal')
         plt.subplot(nRows, nCols,i+1)
         image = ImageList[i].copy()
         if (len(image.shape) < 3):</pre>
             plt.imshow(image, plt.cm.gray)
            plt.imshow(image)
         plt.title("Image " + str(i))
         plt.axis('off')
     plt.show()
```

```
[31] 1 def get_subfiles(dir):
              return next(os.walk(dir))[2]
[32] 1 def ResizeImage(IM, DesiredWidth, DesiredHeight):
              from skimage.transform import rescale, resize
              OrigWidth = float(IM.shape[1])
              OrigHeight = float(IM.shape[0])
              Width = DesiredWidth
              Height = DesiredHeight
              if((Width == 0) & (Height == 0)):
                  return IM
              if(Width == 0):
                  Width = int((OrigWidth * Height)/OrigHeight)
              if(Height == 0):
                  Height = int((OrigHeight * Width)/OrigWidth)
              dim = (Width, Height)
              resizedIM = cv2.resize(IM, dim, interpolation = cv2.INTER_NEAREST)
              return resizedIM
[33] 1 def p_tile_threshold(image, pct):
      2 """Runs the p-tile threshold algorithm.
3 Reference:
       4 Parker, J. R. (2010). Algorithms for image processing and
       5 computer vision. John Wiley & Sons.
       6 @param image: The input image
```

```
[33] 1 def p_tile_threshold(image, pct):
    """Runs the p-tile threshold algorithm.
    Reference:
    Parker, J. R. (2010). Algorithms for image processing and
    computer vision. John Wiley & Sons.
    @param image: The input image
    @utype image: ndarray
    @uparam pct: The percent of desired background pixels (black pixels).
    | It must lie in the interval [0, 1]
    @type pct: float
    @return: The p-tile global threshold
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    @return: The p-tile global threshold
    image.shape[0] * image.shape[1]
    hist = np.histogram(image, bins=range(256))[0]
    hist = np.cumsum(hist)
    return np.argmin(np.abs(hist - n_pixels))
```

```
[34] 1 def otsu(gray):
          pixel_number = gray.shape[0] * gray.shape[1]
          mean_weigth = 1.0/pixel_number
         his, bins = np.histogram(gray, np.array(range(0, 256)))
         final_thresh = -1
         final_value = -1
          WBackground = []
          WForeground = []
         Values = []
          for t in bins[1:-1]: # This goes from 1 to 254 uint8 range (Pretty sure wont
              Wb = np.sum(his[:t]) * mean_weigth
              Wf = np.sum(his[t:]) * mean_weigth
              mub = np.mean(his[:t])
              muf = np.mean(his[t:])
              value = Wb * Wf * (mub - muf) ** 2
              WBackground.append(Wb)
              WForeground.append(Wf)
              Values.append(value)
              if value > final_value:
                  final thresh = t
                  final value = value
     final_img = gray.copy()
     print("Otsu threshold: ",final_thresh)
     final_img[gray > final_thresh] = 255
     final_img[gray < final_thresh] = 0</pre>
     return final_img, final_thresh, [WBackground, WForeground, Values]
[35]
    1 def min_err_threshold(image):
            """Runs the minimum error thresholding algorithm.
           Kittler, J. and J. Illingworth. "On Threshold Selection Using Clustering
           @param image: The input image
           @type image: ndarray
           @return: The threshold that minimize the error
           @rtype: int
           hist = np.histogram(image, bins=range(256))[0].astype(np.float)
           # The number of background pixels for each threshold
           w backg = hist.cumsum()
           w backg[w backg == 0] = 1 # to avoid divisions by zero
           w_foreg = w_backg[-1] - w_backg
           w_foreg[w_foreg == 0] = 1 # to avoid divisions by zero
           cdf = np.cumsum(hist * np.arange(len(hist)))
```

b_mean = cdf / w_backg

28

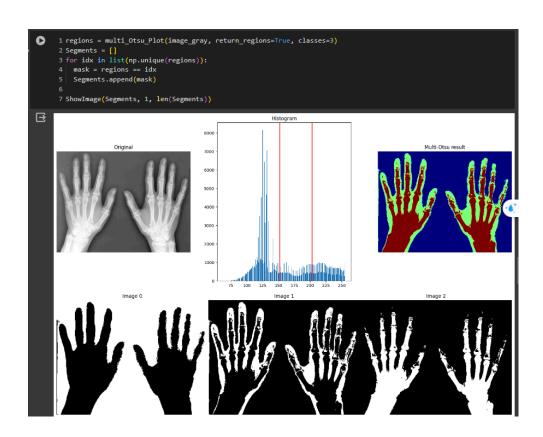
 $f_{mean} = (cdf[-1] - cdf) / w_foreg$

```
30
      b_std = ((np.arange(len(hist)) - b_mean)**2 * hist).cumsum() / w_backg
      f_std = ((np.arange(len(hist)) - f_mean) ** 2 * hist).cumsum()
      f_std = (f_std[-1] - f_std) / w_foreg
      b_std[b_std == 0] = 1
      f_std[f_std == 0] = 1
      # Estimating error
      error_a = w_backg * np.log(b_std) + w_foreg * np.log(f_std)
40
      error_b = w_backg * np.log(w_backg) + w_foreg * np.log(w_foreg)
      error = 1 + 2 * error a - 2 * error b
      final_img = image.copy()
      final_thresh = np.argmin(error)
      print("The threshold that minimize the error: ",final_thresh)
      final img[image > final thresh] = 255
48
      final_img[image < final_thresh] = 0</pre>
49
50
      return final img, final thresh
```

```
[36]
     1 def two_peaks_threshold(image, smooth_hist=True, sigma=5):
            from \ scipy.ndimage \ import \ gaussian\_filter
            """Runs the two peaks threshold algorithm. It selects two peaks
            from the histogram and return the index of the minimum value
            The first peak is deemed to be the maximum value fo the histogram,
            while the algorithm will look for the second peak by multiplying the
            histogram values by the square of the distance from the first peak.
           This gives preference to peaks that are not close to the maximum.
            Reference:
            Parker, J. R. (2010). Algorithms for image processing and
            computer vision. John Wiley & Sons.
            @param image: The input image
            @type image: ndarray
            @param smooth_hist: Indicates whether to smooth the input image
              histogram before finding peaks.
            @type smooth_hist: bool
            @param sigma: The sigma value for the gaussian function used to
              smooth the histogram.
            @type sigma: int
            @return: The threshold between the two founded peaks with the
              minimum histogram value
            @rtype: int
            hist = np.histogram(image, bins=range(256))[0].astype(np.float)
            plt.plot(hist)
            plt.title("Histogram of Image")
            plt.show()
```

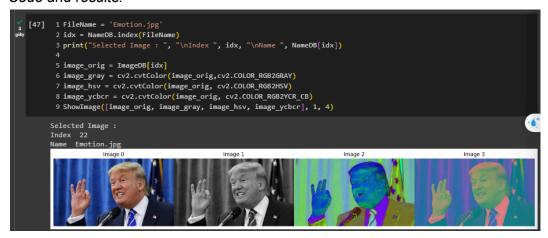
```
29
       30
             if smooth hist:
                 hist = gaussian_filter(hist, sigma=sigma)
              f peak = np.argmax(hist)
             s_peak = np.argmax((np.arange(len(hist)) - f_peak) ** 2 * hist)
             thr = np.argmin(hist[min(f_peak, s_peak): max(f_peak, s_peak)])
             thr += min(f_peak, s_peak)
             final_img = image.copy()
             print("The threshold between the two founded peaks with the minimum histogra
              final_img[image > thr] = 255
              final_img[image < thr] = 0</pre>
             return final_img, thr, hist
[37] 1 def multi_Otsu_Plot(image_gray, classes=3, return_regions=False):
       # three classes.
thresholds = threshold_multiotsu(image_gray,classes=classes)
       6 regions = np.digitize(image_gray, bins=thresholds)
         fig, ax = plt.subplots(nrows=1, ncols=3, figsize=(20, 7))
      10 ax[0].imshow(image_gray, cmap='gray')
     11 ax[0].set_title('Original')
          ax[0].axis('off')
     ax[1].hist(image_gray.ravel(), bins=255)
ax[1].set_title('Histogram')
      17 for thresh in thresholds:
             ax[1].axvline(thresh, color='r')
      18
         # Plotting the Multi Otsu result.
ax[2].imshow(regions, cmap='jet')
         ax[2].set_title('Multi-Otsu result')
      22 ax[2].axis('off')
      plt.subplots_adjust()
          plt.show()
         if return_regions:
      26 return regions
0 [38]
        1 def adjust_gamma(image, gamma=1.0):
         2 # build a lookup table mapping the pixel values [0, 255] to
         4 invGamma = 1.0 / gamma
            table = np.array([((i / 255.0) ** invGamma) * 255
              for i in np.arange(0, 256)]).astype("uint8")
         7 # apply gamma correction using the lookup table
         8 return cv2.LUT(image, table)
v
0 [39]
         1 def SegmentColorImageByMask(IM, Mask):
         2 Mask = Mask.astype(np.uint8)
         result = cv2.bitwise_and(IM, IM, mask = Mask)
return result
0
giây [40]
         1 def morphology(Mask, Size):
         from skimage.morphology import erosion, dilation, opening, closing, white_toph
             from skimage.morphology import disk
            selem = disk(abs(Size))
         5 if (Size > 0):
              result = dilation(Mask, selem)
              result = erosion(Mask, selem)
            return result
```

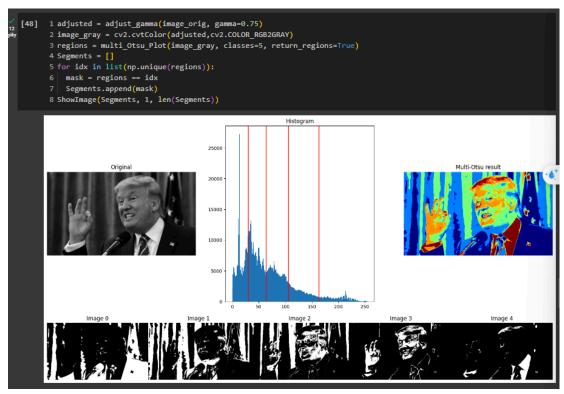
```
[41]
      2 from google.colab import drive
       3 drive.mount('/content/gdrive')
     Mounted at /content/gdrive
      1 path_Data = "/content/gdrive/MyDrive/Image Segmentation"
      2 checkPath = os.path.isdir(path Data)
      3 print("The path and file are valid or not :", checkPath)
☐ The path and file are valid or not : True
[43] 1 all_names = get_subfiles(path_Data)
      2 print("Number of Images:", len(all_names))
      3 IMG = []
      4 for i in range(len(all_names)):
           tmp = plt.imread(path_Data + '/' + all_names[i])
           IMG.append(tmp)
      8 ImageDB = IMG.copy()
      9 NameDB = all names
     10 print(NameDB)
     Number of Images: 28
['Code.jpg', 'Car.jpg', 'Face.jpg', 'Shelf.jpg', 'Dust.jpg', 'Leaf.jpg', 'Gesture.jr
    1. Thực hiện tốt hơn việc segmentation bàn tay với các phần xương, da và
    background bằng các thuật toán global và local thresholding.
       1 FileName = 'Hand.jpg'
 0
       2 idx = NameDB.index(FileName)
       3 print("Selected Image : ", "\nIndex ", idx, "\nName ", NameDB[idx])
       5 image_orig = 6 image_gray = <built-in function cvtColor> OR_RGB2GRAY)
       7 image_hsv = cv2.cvtColor(image_orig, cv2.COLOR_RGB2HSV)
       8 image_ycbcr = cv2.cvtColor(image_orig, cv2.COLOR_RGB2YCR_CB)
       9 ShowImage([image_orig, image_gray, image_hsv, image_ycbcr], 1, 4)
 Selected Image :
      Index 14
           Hand.jpg
[45] 1 adjusted = adjust_gamma(image_orig, gamma=1.8)
       2 image_gray = cv2.cvtColor(adjusted,cv2.COLOR_BGR2GRAY)
       3 ShowImage([image_orig, adjusted, image_gray],1,3)
```

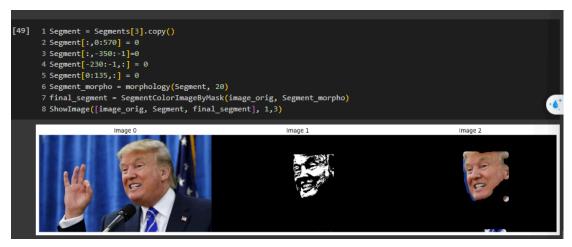


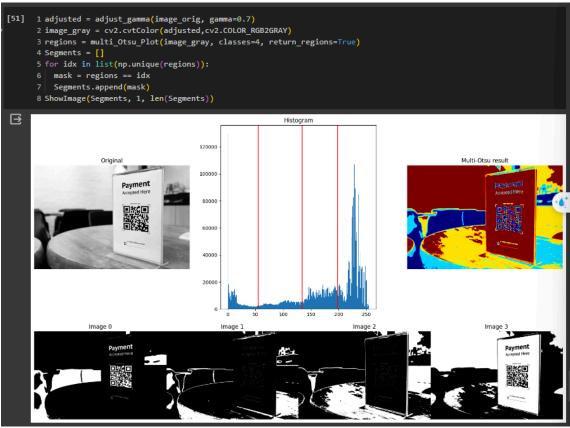
EXERCISE 2:

<u>Requirement</u>: chọn thêm 2 ví dụ trong danh sách hình và định nghĩa object cần segment trong các hình là gì và thực hiện segmentation tốt nhất bằng global và local thresholding Code and results:











PHẦN LÀM THÊM BỔ SUNG ĐỂ LẤY CỘNG

