

SCRUM Planning Optimization Model

(Derived from Entities, Relationships, Goals, Conditions,
Decision Variables)

Auto-generated from CSV specifications

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1 1. Sets (Entities)

- \mathcal{P} (Project) — products/initiatives; attributes: id, name, project_start, project_end, description, budget, status, target_audience, priority.
- \mathcal{T} (Team) — Scrum teams; attributes: id, name, team_size, team_start, team_status, location, team_type.
- \mathcal{W} (Worker) — individual members; attributes: id, name, first_name, email, start_date, status, availability.
- \mathcal{F} (Feature) — mid-sized functionality; attributes: id, title, description, status, priority, estimated_effort.
- \mathcal{S} (Skill) — competencies; attributes: id, label, description, level, certified, category.
- \mathcal{R} (Role) — responsibilities; attributes: id, role_name, description, area_of_responsibility.
- \mathcal{PO} (ProductOwner) — product leadership; attributes: id, name, email, availability.
- \mathcal{SM} (ScrumMaster) — process coach; attributes: id, name, email, experience.
- \mathcal{PB} (ProductBacklog) — ordered requirements; attributes: id, created_on, last_updated, number_of_entries, status.
- \mathcal{SP} (Sprint) — timebox; attributes: id, sprint_number, start_date, end_date, status, achievement_of_goal.
- \mathcal{SPP} (SprintPlanning) — kickoff; attributes: id, date, duration, moderation, outcome_documentation.
- \mathcal{DS} (DailyScrum) — daily; attributes: id, date, time, duration, moderation.
- \mathcal{SR} (SprintReview) — review; attributes: id, date, duration, feedback_documentation, attendees_count.
- \mathcal{SRE} (SprintRetrospective) — retro; attributes: id, date, duration, improvement_actions, team_satisfaction, moderation.
- \mathcal{SBL} (SprintBacklog) — selected items/plan; attributes: id, number_of_tasks, last_updated, status, total_effort.
- \mathcal{SG} (SprintGoal) — objective; attributes: id, objective_description, achievement_status, benefit.
- \mathcal{E} (Epic) — large requirement; attributes: id, title, description, priority, status, estimated_effort.
- \mathcal{US} (UserStory) — user-centric requirement; attributes: id, title, description, acceptance_criteria, priority, story_points, status.
- \mathcal{TSK} (Task) — smallest work unit; attributes: id, title, description, status, effort, type.
- \mathcal{DEV} (DevelopmentSnapshot) — increment; attributes: id, version_number, creation_date, test_status, deployment_target, documentation.
- \mathcal{BL} (Blocker) — impediment; attributes: id, title, description, severity, status, detected_on, resolved_on.

- \mathcal{SH} (Stakeholder) — interested party; attributes: id, name, organization, role, email, area_of_interest, influence_level, relevance_to_feature.
- \mathcal{VEL} (Velocity) — throughput measure; attributes: id, number_of_sprints_used, avg_story_points, max_velocity, min_velocity, trend.
- \mathcal{REP} (ReleasePlan) — planned releases; attributes: id, version, planned_date, included_features, status.
- \mathcal{RM} (Roadmap) — long-term view; attributes: id, start_date, end_date, milestones, objectives, versions.
- \mathcal{SCB} (ScrumBoard) — task board; attributes: id, board_type, columns, number_of_cards, last_updated.
- \mathcal{FED} (FeatureDocumentation) — docs; attributes: id, title, description, creation_date, change_log, linked_requirements, author.

Relationship Incidence (from Relationships.csv). We encode each relationship Rk as a binary incidence matrix over the corresponding sets, respecting cardinalities:

- $R1: \text{is_assigned_to_project} \Rightarrow A_{t,p}^{T,P} \in \{0,1\}.$
- $R2: \text{belongs_to_team} \Rightarrow A_{w,t}^{W,T} \in \{0,1\}.$
- $R3: \text{has_skill} \Rightarrow A_{w,s}^{W,S} \in \{0,1\}.$
- $R4: \text{takes_on_role} \Rightarrow A_{w,r}^{W,R} \in \{0,1\}.$
- $R5: \text{manages_backlog} \Rightarrow A_{po,pb}^{PO,PB} \in \{0,1\}.$
- $R6: \text{is_supported_by} \Rightarrow A_{t,sm}^{T,SM} \in \{0,1\}.$
- $R7: \text{contains_feature} \Rightarrow A_{pb,f}^{PB,F} \in \{0,1\}.$
- $R8: \text{contains_epic} \Rightarrow A_{pb,e}^{PB,E} \in \{0,1\}.$
- $R9: \text{contains_user_story} \Rightarrow A_{e,u}^{E,US} \in \{0,1\}.$
- $R10: \text{consists_of_tasks} \Rightarrow A_{u,t}^{US,TSK} \in \{0,1\}.$
- $R11: \text{is_in_sprint_backlog} \Rightarrow A_{u,sbl}^{US,SBL} \in \{0,1\}.$
- $R12: \text{belongs_to_sprint} \Rightarrow A_{sbl,sp}^{SBL,SP} \in \{0,1\}.$
- $R13: \text{pursues_goal} \Rightarrow A_{sp,sg}^{SP,SG} \in \{0,1\}.$
- $R14: \text{contains_tasks} \Rightarrow A_{scb,t}^{SCB,TSK} \in \{0,1\}.$
- $R15: \text{documents_feature} \Rightarrow A_{fd,f}^{FED,F} \in \{0,1\}.$
- $R16: \text{is_blocked_by} \Rightarrow A_{t,b}^{TSK,BL} \in \{0,1\}.$
- $R17: \text{participates_in} \Rightarrow A_{sh,sr}^{SH,SR} \in \{0,1\}.$
- $R18: \text{moderates_retrospective} \Rightarrow A_{sm,sre}^{SM,SRE} \in \{0,1\}.$

- $R19 : \text{refers_to_team} \Rightarrow A_{vel,t}^{VEL,T} \in \{0,1\}$.
- $R20 : \text{plans_release} \Rightarrow A_{rep,f}^{REP,F} \in \{0,1\}$.
- $R21 : \text{is_part_of_roadmap} \Rightarrow A_{rep,rm}^{REP,RM} \in \{0,1\}$.
- $R22 : \text{generates_snapshot} \Rightarrow A_{sp,dev}^{SP,DEV} \in \{0,1\}$.

2 2. Indices

- $p \in \mathcal{P}, t \in \mathcal{T}, w \in \mathcal{W}, f \in \mathcal{F}, s \in \mathcal{S}, r \in \mathcal{R}, po \in \mathcal{PO}, sm \in \mathcal{SM}, pb \in \mathcal{PB}, sp \in \mathcal{SP}, spp \in \mathcal{SPP}, ds \in \mathcal{DS}, sr \in \mathcal{SR}, sre \in \mathcal{SRE}, sbl \in \mathcal{SBL}, sg \in \mathcal{SG}, e \in \mathcal{E}, u \in \mathcal{US}, tsk \in \mathcal{TSK}, dev \in \mathcal{DEV}, b \in \mathcal{BL}, sh \in \mathcal{SH}, vel \in \mathcal{VEL}, rep \in \mathcal{REP}, rm \in \mathcal{RM}, scb \in \mathcal{SCB}, fd \in \mathcal{FED}$.

Attribute Parameters (examples). For attributes used by goals/conditions we define parameters:

- spoints_u (US.story_points), uprio_u (US.priority), ustatus_u (indicator for status=Ready).
- teffort_{tsk} (TSK.effort), $\text{ttype_unplanned}_{tsk} \in \{0,1\}$, tstatus_{tsk} .
- bsev_b (BL.severity), $\text{bcrit}_b \in \{0,1\}$, $\text{bopen}_b \in \{0,1\}$.
- $\text{wavail}_w \in [0,1]$ (WORKER.availability), wstatus_w .
- sbl_tot_{sbl} (SBL.total_effort), sblstatus_{sbl} .
- vavg_{vel} (VEL.avg_story_points), $\text{vtrend}_{vel}^+ \in \{0,1\}$.
- sgbenefit_{sg} , $\text{sgaligned}_{sg} \in \{0,1\}$.
- fest_f (FEATURE.estimated_effort), fprio_f , $\text{frefined}_f \in \{0,1\}$.
- pbudget_p (PROJECT.budget).
- repdate_{rep} (REP.planned_date), $\text{repapproved}_{rep} \in \{0,1\}$.
- shrel_{sh} (SH.relevance_to_feature), sratt_{sr} (SR.attendees_count), $\text{srquorum} \in \mathbb{Z}_+$.
- $\text{spactive}_{sp} \in \{0,1\}$ (SPRINT.status=Active).

Decision Variables (from DecisionVariables.csv). We model the planning choices as:

$x_{u,sp} \in \{0, 1\}$	(DV0) assign_user_story_to_sprint
$y_{f,rep} \in \{0, 1\}$	(DV1) select_feature_for_release
$a_{tsk,w} \in \{0, 1\}$	(DV2) assign_task_to_worker
$h_{tsk} \in [0, 40]$	(DV3) set_task_effort_hours
$n_u^{\text{sprint}} \in \{1, \dots, 99\}$	(DV4) choose_sprint_for_user_story
$\text{cap}_{sp} \in [0, 200]$	(DV5) decide_team_capacity_story_points
$z_b^{\text{res}} \in \{0, 1\}$	(DV6) approve_blocker_resolution
$d_{sp}^{\text{start}} \in \{1, \dots, 31\}$	(DV7) schedule_sprint_start_day
$r_f^{\text{rank}} \in \{1, \dots, 100\}$	(DV8) prioritize_feature_rank
$\beta_p \in [0, 10^6]$	(DV9) budget_allocation_to_project
$g_{sp}^{\text{target}} \in [0, 100]$	(DV10) set_sprint_goal_benefit_target
$N_{sbl}^{\text{tasks}} \in \{0, \dots, 300\}$	(DV11) decide_number_of_tasks_in_sprintbacklog
$i_{sh, sr}^{\text{inv}} \in \{0, 1\}$	(DV12) select_stakeholder_for_review

3.3. Goals

We scalarize the multi-objective using weights w_k from **Goals.csv**. Each goal Gk is shown with its logical intent and mathematical term. The overall objective is:

$$\max \sum_{k:\text{maximize}} w_k \cdot \text{Term}_k - \sum_{k:\text{minimize}} w_k \cdot \text{Term}_k.$$

- G0 maximize_total_story_points** (IsSum=True, GoalType=max, Weight=1.0)
 Logical: Prefer plans that include higher total story points.
 Math term: $\text{Term}_{G0} = \sum_{u \in \mathcal{US}} \sum_{sp \in \mathcal{SP}} \text{spoints}_u x_{u,sp}.$
- G1 minimize_total_task_effort** (IsSum=True, GoalType=min, Weight=1.0)
 Logical: Reduce total planned task effort.
 Math term: $\text{Term}_{G1} = \sum_{tsk \in \mathcal{TSK}} h_{tsk}.$
- G2 minimize_open_blocker_severity** (IsSum=True, GoalType=min, Weight=2.0)
 Logical: Reduce impact from open blockers.
 Math term: $\text{Term}_{G2} = \sum_{b \in \mathcal{BL}} \text{bsev}_b (1 - z_b^{\text{res}}) \text{bopen}_b.$
- G3 maximize_team_availability** (IsSum=True, GoalType=max, Weight=1.0)
 Logical: Prefer allocations to more available workers.
 Math term: $\text{Term}_{G3} = \sum_{tsk \in \mathcal{TSK}} \sum_{w \in \mathcal{W}} \text{wavail}_w a_{tsk,w}.$
- G4 minimize_sprint_backlog_total_effort** (IsSum=True, GoalType=min, Weight=1.5)
 Logical: Keep sprint backlog effort low.
 Math term: $\text{Term}_{G4} = \sum_{sbl \in \mathcal{SBL}} \text{sbl_tot}_{sbl}.$
- G5 maximize_velocity_avg_story_points** (IsSum=True, GoalType=max, Weight=1.0)
 Logical: Favor teams/sprints with higher historical velocity.
 Math term: $\text{Term}_{G5} = \sum_{vel \in \mathcal{VEL}} \text{vavg}_{vel}.$

- **G6 maximize_sprint_goal_benefit** (IsSum=True, GoalType=max, Weight=1.0)
 Logical: Increase delivered benefit vs. target.
 Math term: $\text{Term}_{G6} = \sum_{sp \in \mathcal{SP}} \sum_{sg \in \mathcal{SG}} A_{sp,sg}^{SP,SG} \cdot \min\{\text{sgbenefit}_{sg}, g_{sp}^{\text{target}}\}.$
- **G7 minimize_feature_estimated_effort** (IsSum=True, GoalType=min, Weight=1.0)
 Logical: Prefer lower-effort features in the plan.
 Math term: $\text{Term}_{G7} = \sum_{f \in \mathcal{F}} \sum_{rep \in \mathcal{REP}} \text{fest}_f y_{f,rep}.$
- **G8 maximize_feature_priority** (IsSum=True, GoalType=max, Weight=0.8)
 Logical: Prefer higher-priority features.
 Math term: $\text{Term}_{G8} = \sum_{f \in \mathcal{F}} \sum_{rep \in \mathcal{REP}} \text{fprio}_f y_{f,rep}.$
- **G9 minimize_project_budget** (IsSum=True, GoalType=min, Weight=1.2)
 Logical: Minimize allocated budget.
 Math term: $\text{Term}_{G9} = \sum_{p \in \mathcal{P}} \beta_p.$
- **G10 minimize_release_planned_date** (IsSum=False, GoalType=min, Weight=0.7)
 Logical: Release as early as possible.
 Math term: $\text{Term}_{G10} = \max_{rep \in \mathcal{REP}} \text{redate}_{rep} \cdot \left[\sum_{f \in \mathcal{F}} y_{f,rep} \geq 1 \right]$ (or surrogate $\sum_{rep} \text{redate}_{rep} \sum_f y_{f,rep}$).
- **G11 maximize_stakeholder_relevance** (IsSum=True, GoalType=max, Weight=0.9)
 Logical: Invite more relevant stakeholders to reviews.
 Math term: $\text{Term}_{G11} = \sum_{sr \in \mathcal{SR}} \sum_{sh \in \mathcal{SH}} \text{shrel}_{sh} i_{sh,sr}^{\text{inv}}.$

4 4. Conditions

Each condition from `Conditions.csv` is shown with ID, name, logic, and a mathematical constraint. “Must-Match” (CriteriaType = 2) are hard constraints; “Cannot-Match” (= 0) forbidding constraints; “May-Match” (= 1) are soft and can be modeled via penalties or left to goals.

- **C0 must_match_user_story_status_ready** (IsSum=False, GoalType=min, CriteriaType=2, Weight=1.0)
 Logical: Only *Ready* user stories can be selected into sprints.
 Constraint: $x_{u,sp} \leq \text{ustatus}_u \quad \forall u \in \mathcal{US}, \forall sp \in \mathcal{SP}.$
- **C1 must_match_feature_status_refined** (IsSum=False, GoalType=min, CriteriaType=2, Weight=1.0)
 Logical: Only *Refined* features can be chosen for a release.
 Constraint: $y_{f,rep} \leq \text{frefined}_f \quad \forall f \in \mathcal{F}, \forall rep \in \mathcal{REP}.$
- **C2 cannot_match_task_type_unplanned** (IsSum=False, GoalType=min, CriteriaType=0, Weight=1.5)
 Logical: Unplanned tasks cannot be assigned.
 Constraint: $a_{tsk,w} \leq 1 - \text{ttype_unplanned}_{tsk} \quad \forall tsk \in \mathcal{TSK}, \forall w \in \mathcal{W}.$
- **C3 must_match_sprint_status_active** (IsSum=False, GoalType=min, CriteriaType=2, Weight=1.0)

Logical: Assignments only into *Active* sprints.

Constraint: $x_{u,sp} \leq \text{spactive}_{sp} \quad \forall u, sp.$

- **C4 must_match_product_backlog_status_ordered** (IsSum=False, GoalType=min, CriteriaType=2, Weight=1.0)

Logical: Only items from an *Ordered* Product Backlog can be planned.

Constraint: $x_{u,sp} \leq \sum_{pb \in \mathcal{PB}} \text{pb_ordered}_{pb} \left(\sum_{e \in \mathcal{E}} A_{pb,e}^{PB,E} A_{e,u}^{E,US} \right),$ with $\text{pb_ordered}_{pb} \in \{0, 1\}.$

- **C5 may_match_worker_availability_high** (IsSum=True, GoalType=min, CriteriaType=1, Weight=0.8)

Logical: Prefer workers with availability ≥ 0.8 .

Soft constraint (example): $\sum_{tsk,w} a_{tsk,w} \max\{0, 0.8 - \text{wavail}_w\} \leq \epsilon.$

- **C6 must_match_team_type_cross_functional** (IsSum=False, GoalType=min, CriteriaType=2, Weight=1.0)

Logical: Only cross-functional teams can receive work.

Constraint (team capacity binding): $\sum_u \text{spoints}_u x_{u,sp} \leq \sum_{t \in \mathcal{T}} \text{cap}_{sp} \text{isXFunc}_t A_{t,p}^{T,P} \quad \forall sp,$
with $\text{isXFunc}_t \in \{0, 1\}.$

- **C7 cannot_match_blocker_severity_critical** (IsSum=False, GoalType=min, CriteriaType=0, Weight=2.0)

Logical: Tasks blocked by critical blockers must not be planned.

Constraint: $\sum_w a_{tsk,w} \leq 1 - \max_{b \in \mathcal{BL}} \{A_{tsk,b}^{TSK,BL} \cdot \text{bcrit}_b\} \quad \forall tsk.$

- **C8 must_match_sprint_goal_achievement_status_aligned** (IsSum=False, GoalType=min, CriteriaType=2, Weight=1.0)

Logical: Only sprints whose goal is aligned may be populated.

Constraint: $\sum_u x_{u,sp} \leq M \cdot \sum_{sg} A_{sp,sg}^{SP,SG} \text{sgaligned}_{sg} \quad \forall sp.$

- **C9 may_match_sprint_review_attendees_sufficient** (IsSum=True, GoalType=min, CriteriaType=1, Weight=0.5)

Logical: Prefer reviews with quorum.

Soft constraint: $\sum_{sr} \max\{0, \text{srquorum} - \text{sratt}_{sr} - \sum_{sh} i_{sh,sr}^{\text{inv}}\} \leq \epsilon.$

- **C10 must_match_release_plan_status_approved** (IsSum=False, GoalType=min, CriteriaType=2, Weight=1.0)

Logical: Only *Approved* release plans may contain features.

Constraint: $y_{f,rep} \leq \text{repapproved}_{rep} \quad \forall f, rep.$

- **C11 may_match_velocity_trend_positive** (IsSum=False, GoalType=min, CriteriaType=1, Weight=0.6)

Logical: Prefer teams with increasing velocity.

Soft constraint: $\sum_{vel} (1 - \text{vtrend}_{vel}^+) \leq \epsilon$ (or encode via objective *G5*).

Additional Feasibility (structural) Constraints (from Relationships).

- Story-Sprint consistency: $\sum_{sp} x_{u,sp} \leq 1 \quad \forall u.$

- Story–Task linking: if any task of u is assigned then u must be scheduled: $\sum_w a_{tsk,w} \leq \sum_{sp} x_{u,sp} \quad \forall u, \forall tsk \text{ with } A_{u,tsk}^{US,TSK} = 1.$
- Release inclusion via plan: $y_{f,rep} \leq A_{rep,f}^{REP,F} \quad \forall f, rep.$
- SprintBacklog linkage: $\sum_u A_{u,sbl}^{US,SBL} \leq N_{sbl}^{tasks} \quad \forall sbl.$
- Capacity limit (illustrative): $\sum_u \text{sprints}_u x_{u,sp} \leq \text{cap}_{sp} \quad \forall sp.$
- Budget guard: $\sum_{f,rep} \text{fest}_f y_{f,rep} \leq \sum_p \beta_p.$

5 5. Decision Variables

- **DV0 assign_user_story_to_sprint:** Binary, Domain $\{0, 1\}$, Min 0, Max 1.
- **DV1 select_feature_for_release:** Binary, Domain $\{0, 1\}$, Min 0, Max 1.
- **DV2 assign_task_to_worker:** Binary, Domain $\{0, 1\}$, Min 0, Max 1.
- **DV3 set_task_effort_hours:** Real, Domain \mathbb{R}^+ , Min 0, Max 40.
- **DV4 choose_sprint_for_user_story:** Integer, Domain \mathbb{Z}^+ , Min 1, Max 99.
- **DV5 decide_team_capacity_story_points:** Real, Domain \mathbb{R}^+ , Min 0, Max 200.
- **DV6 approve_blocker_resolution:** Binary, Domain $\{0, 1\}$, Min 0, Max 1.
- **DV7 schedule_sprint_start_day:** Integer, Domain \mathbb{Z} , Min 1, Max 31.
- **DV8 prioritize_feature_rank:** Integer, Domain \mathbb{Z}^+ , Min 1, Max 100.
- **DV9 budget_allocation_to_project:** Real, Domain \mathbb{R}^+ , Min 0, Max 1,000,000.
- **DV10 set_sprint_goal_benefit_target:** Real, Domain \mathbb{R}^+ , Min 0, Max 100.
- **DV11 decide_number_of_tasks_in_sprintbacklog:** Integer, Domain \mathbb{Z}^+ , Min 0, Max 300.
- **DV12 select_stakeholder_for_review:** Binary, Domain $\{0, 1\}$, Min 0, Max 1.