

SCRUM Domain Optimization Model

Generated from Entities, Relationships, Goals, Conditions, Decision Variables

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1 1. Sets (Entities)

- \mathcal{P} (Project): product or initiative to be developed.
- \mathcal{T} (Team): self-organized, cross-functional development team.
- \mathcal{W} (Worker): individual team member working on the project.
- \mathcal{F} (Feature): mid-sized functionality.
- \mathcal{S} (Skill): competence of a worker.
- \mathcal{R} (Role): defined responsibilities within the Scrum team.
- \mathcal{PO} (ProductOwner): responsible for product vision and Product Backlog.
- \mathcal{SM} (ScrumMaster): supports team in applying Scrum.
- \mathcal{PB} (ProductBacklog): ordered list of all requirements.
- \mathcal{SP} (Sprint): fixed time-box to create an increment.
- \mathcal{SPP} (SprintPlanning): sprint planning meeting.
- \mathcal{DS} (DailyScrum): daily 15-minute meeting.
- \mathcal{SR} (SprintReview): presentation and acceptance of results.
- \mathcal{SRE} (SprintRetrospective): retrospective for improvement.
- \mathcal{SBL} (SprintBacklog): selected backlog items + implementation plan.
- \mathcal{SG} (SprintGoal): objective to be achieved in the sprint.
- \mathcal{E} (Epic): large requirement split into stories.
- \mathcal{US} (UserStory): requirement from a user perspective.
- \mathcal{TSK} (Task): smallest unit of work.
- \mathcal{DEV} (DevelopmentSnapshot): product state at sprint end.
- \mathcal{BL} (Blocker): obstacle hindering progress.
- \mathcal{SH} (Stakeholder): interested party in the product.
- \mathcal{VEL} (Velocity): average amount of work per sprint.
- \mathcal{REP} (ReleasePlan): plan for releasing specific features.
- \mathcal{RM} (Roadmap): long-term planning across releases.
- \mathcal{SCB} (ScrumBoard): visual board of sprint tasks.
- \mathcal{FED} (FeatureDocumentation): documentation for a specific feature.

2 2. Indices

- $p \in \mathcal{P}, t \in \mathcal{T}, w \in \mathcal{W}, f \in \mathcal{F}, s \in \mathcal{S}, r \in \mathcal{R}, po \in \mathcal{PO}, sm \in \mathcal{SM}, pb \in \mathcal{PB}, sp \in \mathcal{SP}, spp \in \mathcal{SPP}, ds \in \mathcal{DS}, sr \in \mathcal{SR}, sre \in \mathcal{SRE}, sbl \in \mathcal{SBL}, sg \in \mathcal{SG}, e \in \mathcal{E}, u \in \mathcal{US}, \tau \in \mathcal{TSK}, dev \in \mathcal{DEV}, b \in \mathcal{BL}, sh \in \mathcal{SH}, v \in \mathcal{VEL}, rp \in \mathcal{REP}, rm \in \mathcal{RM}, scb \in \mathcal{SCB}, fd \in \mathcal{FED}.$

Data Parameters (derived from attributes and relationships). Where needed, categorical attributes (e.g., `status`) are represented by numeric indicator parameters derived from the CSVs:

- $s_u^{\text{done}} \in \{0, 1\}$ (`UserStory.status == done`), $\text{sp}_u \in \mathbb{Z}_{\geq 0}$ (`UserStory.story_points`).
- $\text{eff}_\tau \in \mathbb{R}_{\geq 0}$ (`Task.effort`), $\text{is_not_done}_f \in \{0, 1\}$ (`Feature.status \neq done`).
- $\text{avail}_w \in [0, 1]$ (`Worker.availability`), $\text{sev}_b \in \mathbb{R}_{\geq 0}$ (`Blocker.severity`).
- $\text{cost}_f \in \mathbb{R}_{\geq 0}$ (proxy from `Feature.estimated_effort` and unit cost).
- $\text{rel}_{sh,f} \in \mathbb{R}_{\geq 0}$ (from `Stakeholder.relevance_to_feature`).
- $\text{align}_f \in \mathbb{R}_{\geq 0}$ (alignment to `Roadmap.objectives`).
- $\text{fbq}_{sp} \in \mathbb{R}_{\geq 0}$ (quality of `SprintReview.feedback_documentation` for sprint sp).

Relationship-incidence parameters (from `Relationships.csv`):

- $R_{u,\tau}^{US-TSK} \in \{0, 1\}$ (R10: story u consists of task τ).
- $R_{pb,u}^{PB-US} \in \{0, 1\}$ and $R_{pb,f}^{PB-F} \in \{0, 1\}$ (R7, R11 via epic/story expansion).
- $R_{sbl,u}^{SBL-US} \in \{0, 1\}$ (R11), $R_{sp,sbl}^{SP-SBL} \in \{0, 1\}$ (R12), $R_{sp,sg}^{SP-SG} \in \{0, 1\}$ (R13).
- $R_{rp,f}^{REP-F} \in \{0, 1\}$ (R20), $R_{rp,rm}^{REP-RM} \in \{0, 1\}$ (R21).
- $R_{fd,f}^{FED-F} \in \{0, 1\}$ (R15).

3 3. Goals

For each goal Gk we show (i) ID and snake_case name, (ii) logical intent, and (iii) mathematical form. We use weights $w_k > 0$ from the CSV (default 1.0 where unspecified). A single scalar objective can be built by a weighted sum of goals of type “max” (added) and type “min” (subtracted), or treated as separate scenarios.

- **G0 maximize_completed_user_stories** (max): prioritize completed stories for the sprint.

$$\max w_0 \sum_{u \in \mathcal{US}} s_u^{\text{done}} x_u^{US}$$
- **G1 minimize_open_blockers** (min): reduce impact of unresolved blockers.

$$\min w_1 \sum_{b \in \mathcal{BL}} \text{sev}_b (1 - x_b^{BL})$$
- **G2 maximize_velocity_trend** (max): proxy by maximizing story points planned.

$$\max w_2 \sum_{u \in \mathcal{US}} \text{sp}_u x_u^{US}$$
- **G3 minimize_total_task_effort** (min): limit total selected task effort.

$$\min w_3 \sum_{\tau \in \mathcal{TSK}} \text{eff}_\tau x_\tau^{TSK}$$
- **G4 maximize_sprint_goal_achievement** (max): favor sprints that meet their goals.

$$\max w_4 \sum_{sp \in \mathcal{SP}} x_{sp}^{SG}$$

- **G5 minimize_feature_cycle_time** (min): proxy by avoiding not-done features in release.

$$\min w_5 \sum_{f \in \mathcal{F}} is_not_done_f x_f^{FR}$$
- **G6 maximize_team_availability** (max): maximize available capacity assigned to teams.

$$\max w_6 \sum_{w \in \mathcal{W}} \sum_{t \in \mathcal{T}} avail_w x_{w,t}^{WT}$$
- **G7 minimize_budget_spend** (min): proxy by minimizing cost of selected features.

$$\min w_7 \sum_{f \in \mathcal{F}} cost_f x_f^{FR}$$
- **G8 maximize_stakeholder_relevance_coverage** (max): select features valued by stakeholders.

$$\max w_8 \sum_{sh \in \mathcal{SH}} \sum_{f \in \mathcal{F}} rel_{sh,f} x_f^{FR}$$
- **G9 maximize_review_feedback_documentation** (max): encourage high-quality reviews (proxy via goal achievement).

$$\max w_9 \sum_{sp \in \mathcal{SP}} fbq_{sp} x_{sp}^{SG}$$
- **G10 minimize_blocker_severity_exposure** (min): further penalize severe unresolved blockers.

$$\min w_{10} \sum_{b \in \mathcal{BL}} sev_b (1 - x_b^{BL})$$
- **G11 maximize_roadmap_objectives_alignment** (max): prefer features aligned to roadmap.

$$\max w_{11} \sum_{f \in \mathcal{F}} align_f x_f^{FR}$$

4 4. Conditions

Each condition Ck is modeled as a constraint. (Logical descriptions reflect the CSV names; mathematical forms use the decision variables and relationship incidence.)

- **C0 minimize_unscheduled_tasks**: selected tasks must belong to a selected user story.

$$\forall \tau \in \mathcal{TSK} : x_\tau^{TSK} \leq \sum_{u \in \mathcal{US}} R_{u,\tau}^{US-TSK} x_u^{US}$$
- **C1 minimize_unassigned_worker_roles**: if a worker is assigned to any team, at least one role must be taken.

$$\forall w \in \mathcal{W} : \sum_{r \in \mathcal{R}} x_{w,r}^{WR} \geq \min\{1, \sum_{t \in \mathcal{T}} x_{w,t}^{WT}\}$$
- **C2 minimize_unplanned_epics**: planning a story implies its epic is represented in a product backlog.

$$\forall u \in \mathcal{US} : x_u^{US} \leq \sum_{pb \in \mathcal{PB}} R_{pb,u}^{PB-US}$$
- **C3 minimize_story_without_acceptance_criteria**: only stories with acceptance criteria may be selected.

$$\forall u \in \mathcal{US} : x_u^{US} \leq \mathbf{1}\{\text{acceptance_criteria}(u) \neq \emptyset\}$$

- **C4 minimize_sprint_without_goal:** a sprint marked achieved must reference a sprint goal.

$$\forall sp \in \mathcal{SP} : x_{sp}^{SG} \leq \sum_{sg \in \mathcal{SG}} R_{sp,sg}^{SP-SG}$$
- **C5 minimize_exceeded_sprint_duration:** (feasibility check) end date after start date (data validity).

$$\forall sp \in \mathcal{SP} : \text{end_date}(sp) - \text{start_date}(sp) \geq 0$$
- **C6 minimize_overallocated_team_size:** assigned workers cannot exceed team capacity Cap_t .

$$\forall t \in \mathcal{T} : \sum_{w \in \mathcal{W}} x_{w,t}^{WT} \leq Cap_t$$
- **C7 minimize_missing_feature_docs:** if a feature is selected for release, it must have documentation.

$$\forall f \in \mathcal{F} : x_f^{FR} \leq \sum_{fd \in \mathcal{FED}} R_{fd,f}^{FED-F}$$
- **C8 minimize_stale_backlog:** only user stories in a recently updated backlog may be planned.

$$\forall u \in \mathcal{US} : x_u^{US} \leq \sum_{pb \in \mathcal{PB}} R_{pb,u}^{PB-US} \cdot \mathbf{1}\{\text{last_updated}(pb) \geq \Delta\}$$
- **C9 minimize_unmoderated_events:** (policy) retrospectives must be moderated if sprint goal is achieved.

$$\forall sp \in \mathcal{SP} : x_{sp}^{SG} \leq \mathbf{1}\{\exists sre \in \mathcal{SRE} \text{ with } \text{moderation}(sre) = \text{true}\}$$
- **C10 minimize_unestimated_stories:** only estimated stories may be planned.

$$\forall u \in \mathcal{US} : x_u^{US} \leq \mathbf{1}\{sp_u > 0\}$$
- **C11 minimize_untracked_velocity:** velocity targets require historical basis $minSprints$.

$$\sum_{u \in \mathcal{US}} sp_u x_u^{US} \leq (\sum_{v \in \mathcal{VEL}} \mathbf{1}\{\text{number_of_sprints_used}(v) \geq minSprints\}) \cdot V_{\max}$$

5. Decision Variables

We adopt the previously defined decision variables and domains.

- $x_{t,p}^{TP} \in \{0, 1\}$ (**DV0 assign_team_to_project**): team t is assigned to project p .
- $x_{w,t}^{WT} \in \{0, 1\}$ (**DV1 assign_worker_to_team**): worker w belongs to team t .
- $x_{w,r}^{WR} \in \{0, 1\}$ (**DV2 assign_worker_role**): worker w takes role r .
- $x_{w,s}^{WS} \in \{0, 1\}$ (**DV3 assign_worker_skill**): worker w has skill s (operational use for staffing).
- $x_f^{FR} \in \{0, 1\}$ (**DV4 select_feature_for_release**): feature f is included in a release plan.
- $x_u^{US} \in \{0, 1\}$ (**DV5 place_story_in_sprint**): user story u is assigned to a (current) sprint backlog.
- $x_\tau^{TSK} \in \{0, 1\}$ (**DV6 select_task_for_sprint**): task τ is included in the sprint plan/board.
- $x_b^{BL} \in \{0, 1\}$ (**DV7 close_blocker**): blocker b is resolved (closed) within the sprint.

- $x_{sp}^{SG} \in \{0, 1\}$ (**DV8 set_sprint_goal_achieved**): sprint sp achieves its goal.
- $y_{p,f}^{Bud} \in [0, 1]$ (**DV9 allocate_budget_to_feature**): share of project p budget allocated to feature f .
- $x_{po,pb}^{POB} \in \{0, 1\}$ (**DV10 assign_product_owner_to_backlog**): PO po manages backlog pb .
- $x_{sm,t}^{SM} \in \{0, 1\}$ (**DV11 assign_scrum_master_to_team**): Scrum Master sm supports team t .

Linking (illustrative) constraints. Typical couplings between decisions and budget:

$$\text{Budget per project:} \quad \forall p \in \mathcal{P} : \quad \sum_{f \in \mathcal{F}} cost_f y_{p,f}^{Bud} \leq \text{budget}(p)$$

$$\text{Release-selection consistency:} \quad \forall f \in \mathcal{F} : \quad x_f^{FR} \leq \sum_{p \in \mathcal{P}} y_{p,f}^{Bud}$$

Composite objective (optional). If a single-objective scalarization is desired, maximize

$$\max \quad \sum_{k \in \{0,2,4,6,8,9,11\}} w_k \cdot \text{Goal}_k - \sum_{k \in \{1,3,5,7,10\}} w_k \cdot \text{Goal}_k,$$

where each Goal_k corresponds to the expressions enumerated in Section 3.