VIETNAM NATIONAL UNIVERSITY - HCM
Ho Chi Minh City University of Technology
Faculty of Computer Science and Engineering

EMBEDDED SYSTEM (CO3053)

ESP32 LAB 02

ESP32 GPIO and FreeRTOS task

Name	Student's ID
Nguyễn Hữu Trung Nhân	1752392

Ho Chi Minh City, May 2020 - Semester 192

Contents

1 Create printing student ID task

These are some library that I included:

```
#include <stdio.h>
#include "freertos/FreeRTOS.h"
#include "freertos/task.h"
#include "sdkconfig.h"
#include "driver/gpio.h"
```

A task printing my student ID every second is implemented as below:

```
void task1(void *p){
    while(1){
        printf("1752392\n");
        vTaskDelay(1000/portTICK_PERIOD_MS);
    }
    vTaskDelete(NULL);
}
```

The "portTICK_PERIOD_MS" is a constant that has been defined before in the library. The value of "port_PERIOD_MS" is 10, which means that 1 port tick takes 10ms. Therefore 1000/portTICK_PERIOD_MS = 1000/10 = 100 port ticks. 100 port ticks will take 1000ms = 1 second.

2 Create pressing button task

I used button "BOOT" on the ESP32 as a button input. The GPIO of button "BOOT" is 0. Below is how I set up the push button:

```
#define push_gpio 0

void setup_push(void){
    gpio_pad_select_gpio(push_gpio);
    gpio_set_direction(push_gpio, GPIO_MODE_INPUT);
    gpio_set_pull_mode(push_gpio, GPIO_PULLDOWN_ONLY);
}
```

Below is how I implemented the task to print ”ESP32” every when the button is pressed:

```
void task2(void *p){
    unsigned int flag = 0;
    while(1){
        if(gpio_get_level(push_gpio) != 0){
            flag = 0;
            vTaskDelay(18/portTICK_PERIOD_MS);
        }

        if (gpio_get_level(push_gpio) == 0){
            vTaskDelay(27/portTICK_PERIOD_MS);

            if (gpio_get_level(push_gpio) == 0){
                if (flag == 0){
                    printf("ESP32\n");
                    flag = 1;
                }
            }
        }
    }
    vTaskDelete(NULL);
}
```

Two delay lines (line 6 and line 10) are used for debouncing button.

3 Full code

Below is my full code:

```
1  #include <stdio.h>
2  #include "freertos/FreeRTOS.h"
3  #include "freertos/task.h"
4  #include "sdkconfig.h"
5  #include "driver/gpio.h"
6
7  #define push_gpio 0
8
9  void task1(void *p){
10     while(1){
11         printf("1752392\n");
12         vTaskDelay(1000/portTICK_PERIOD_MS);
13     }
14     vTaskDelete(NULL);
15 }
16
17 void task2(void *p){
18     unsigned int flag = 0;
19     while(1){
20         if(gpio_get_level(push_gpio) != 0){
21             flag = 0;
22             vTaskDelay(18/portTICK_PERIOD_MS);
23         }
24
25         if (gpio_get_level(push_gpio) == 0){
26             vTaskDelay(27/portTICK_PERIOD_MS);
27
28             if (gpio_get_level(push_gpio) == 0){
29                 if (flag == 0){
30                     printf("ESP32\n");
31                     flag = 1;
32                 }
33             }
34         }
35     }
36     vTaskDelete(NULL);
37 }
38
39 void setup_push(void){
40     gpio_pad_select_gpio(push_gpio);
41     gpio_set_direction(push_gpio, GPIO_MODE_INPUT);
42     gpio_set_pull_mode(push_gpio, GPIO_PULLDOWN_ONLY);
43 }
44
45 void app_main()
46 {
47     setup_push();
48     xTaskCreate(&task1, "task1", 1024*2, (void*) 0, tskIDLE_PRIORITY + 1, NULL);
49     xTaskCreate(&task2, "task2", 1024*2, (void*) 0, tskIDLE_PRIORITY + 2, NULL);
50
51 }
```

4 Answer the question

Does the ESP-IDF need the vTaskStartScheduler() routine?
Answer: According to what I have done in this lab, vTaskStartSchedular() function is not neccessary to be called, everything worked just fine.

5 Result Snapshot

Please zoom in to see more clearly

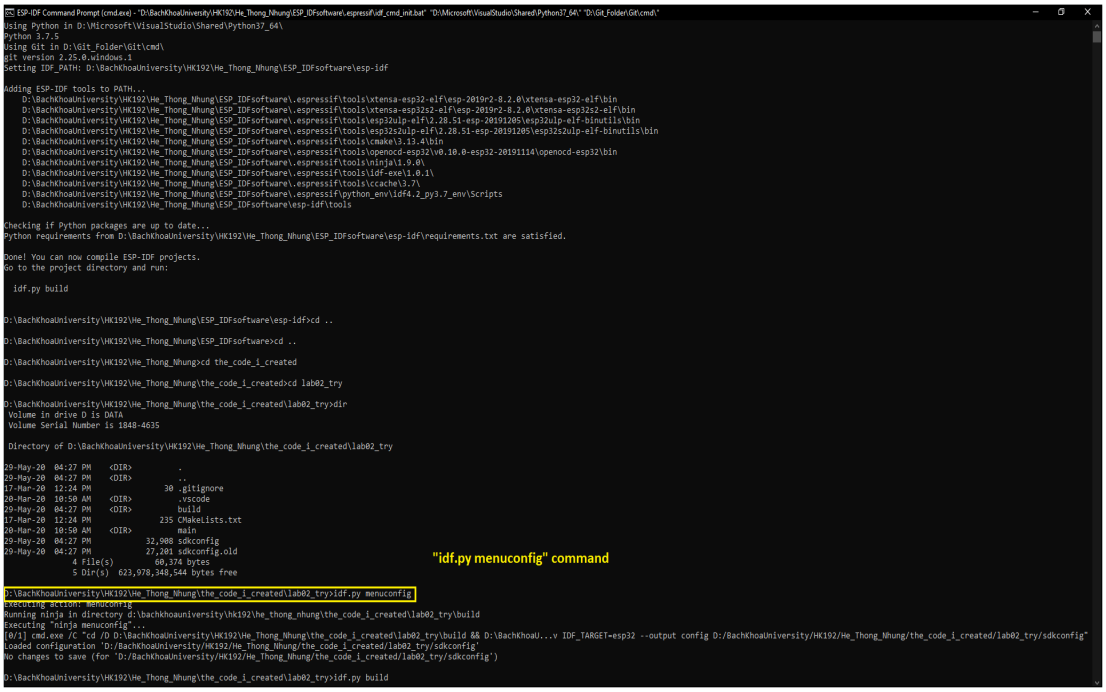

Figure 1

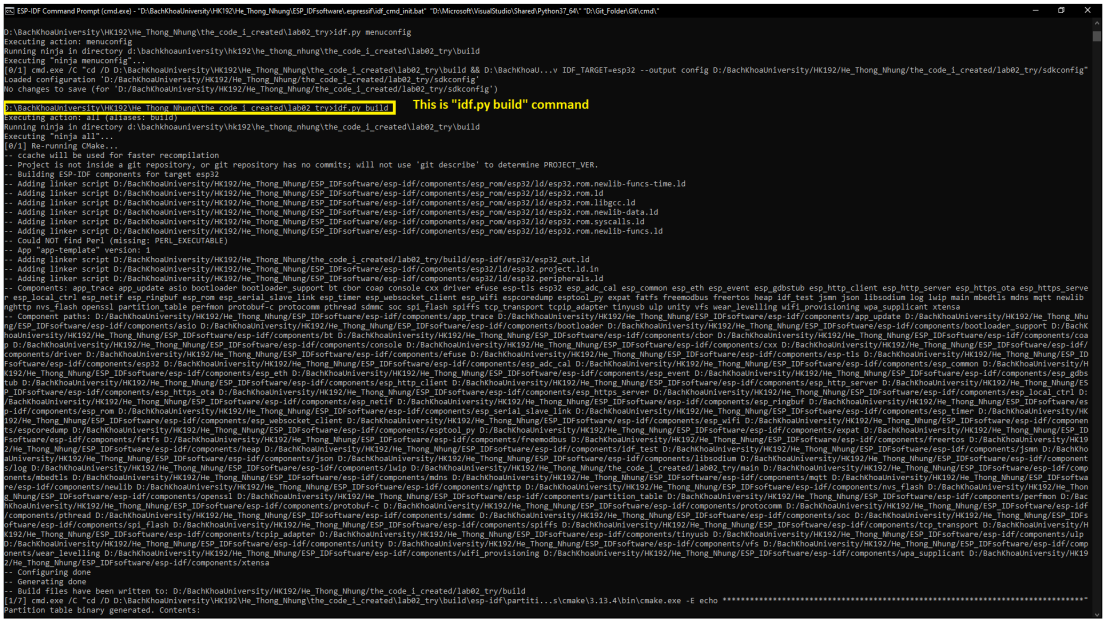

Figure 2

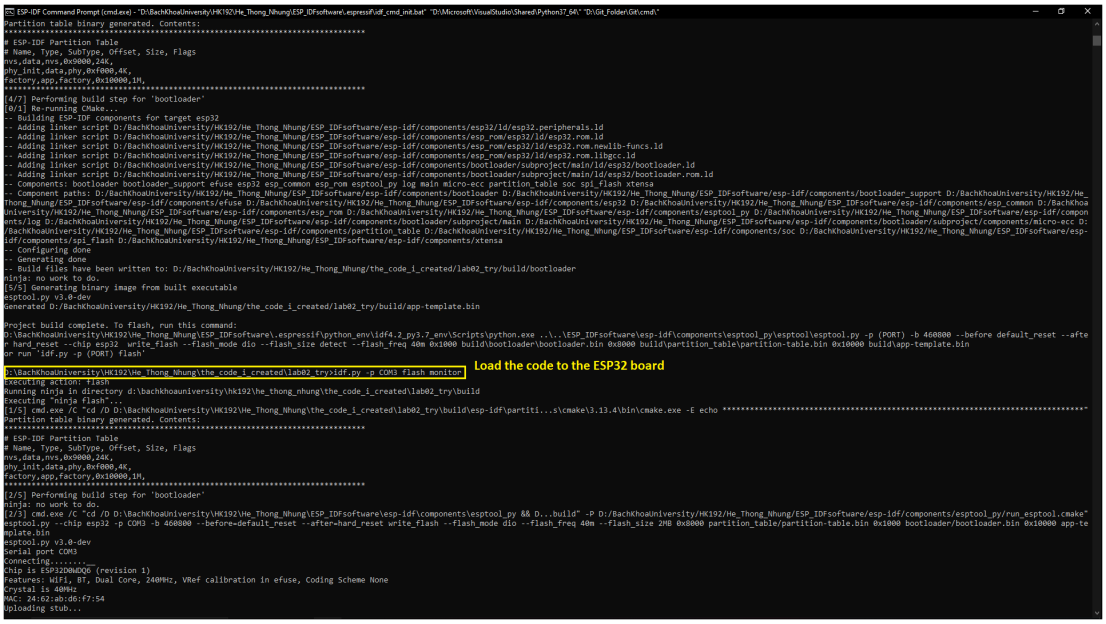

Figure 3

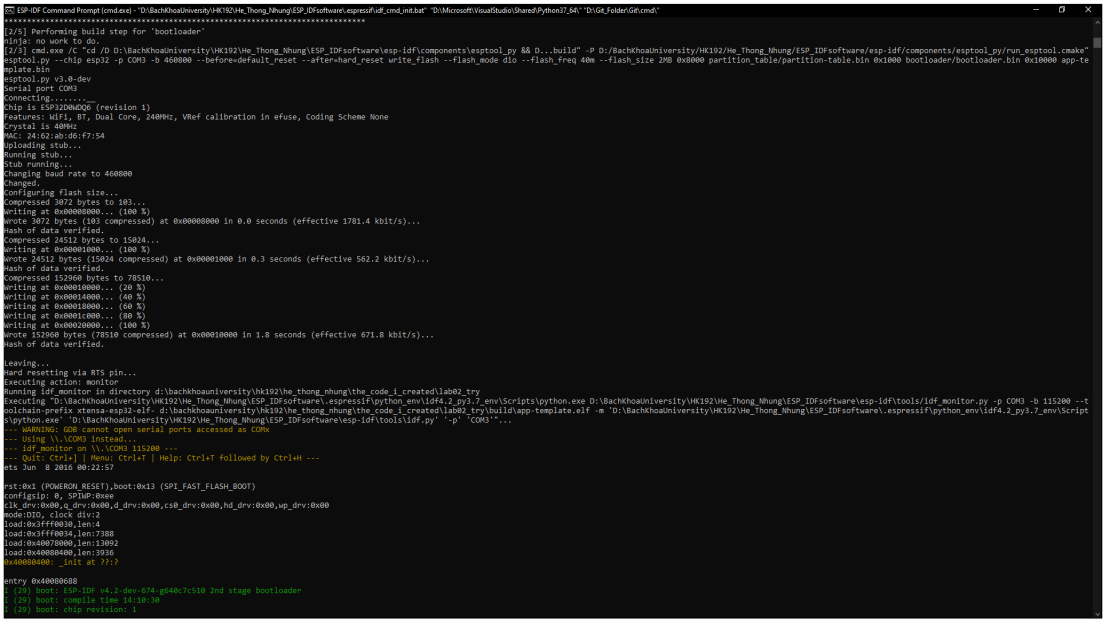

Figure 4

Figure 5

Figure 6

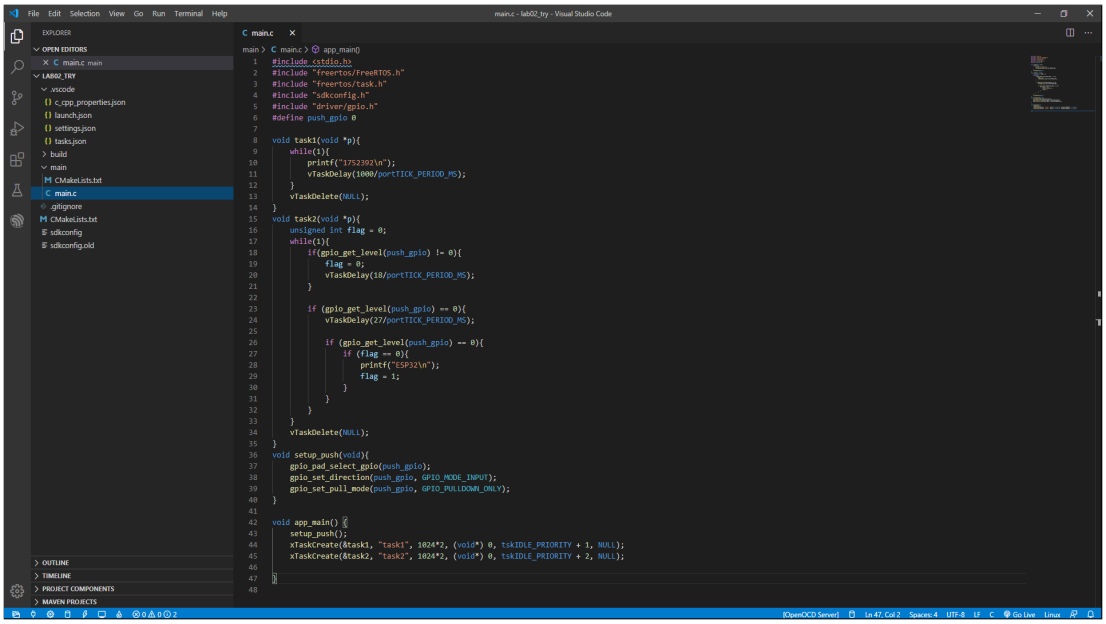

Figure 7: A snapshot of my work space