

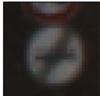

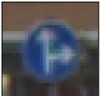

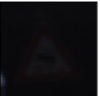

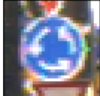

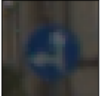

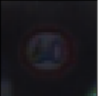

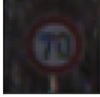

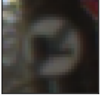

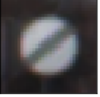





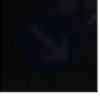

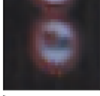

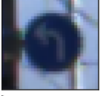

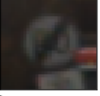

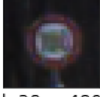

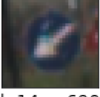

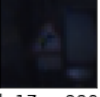



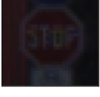

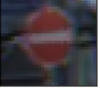


[Project Writeup] Traffic Sign Classification 19-Sept-2017

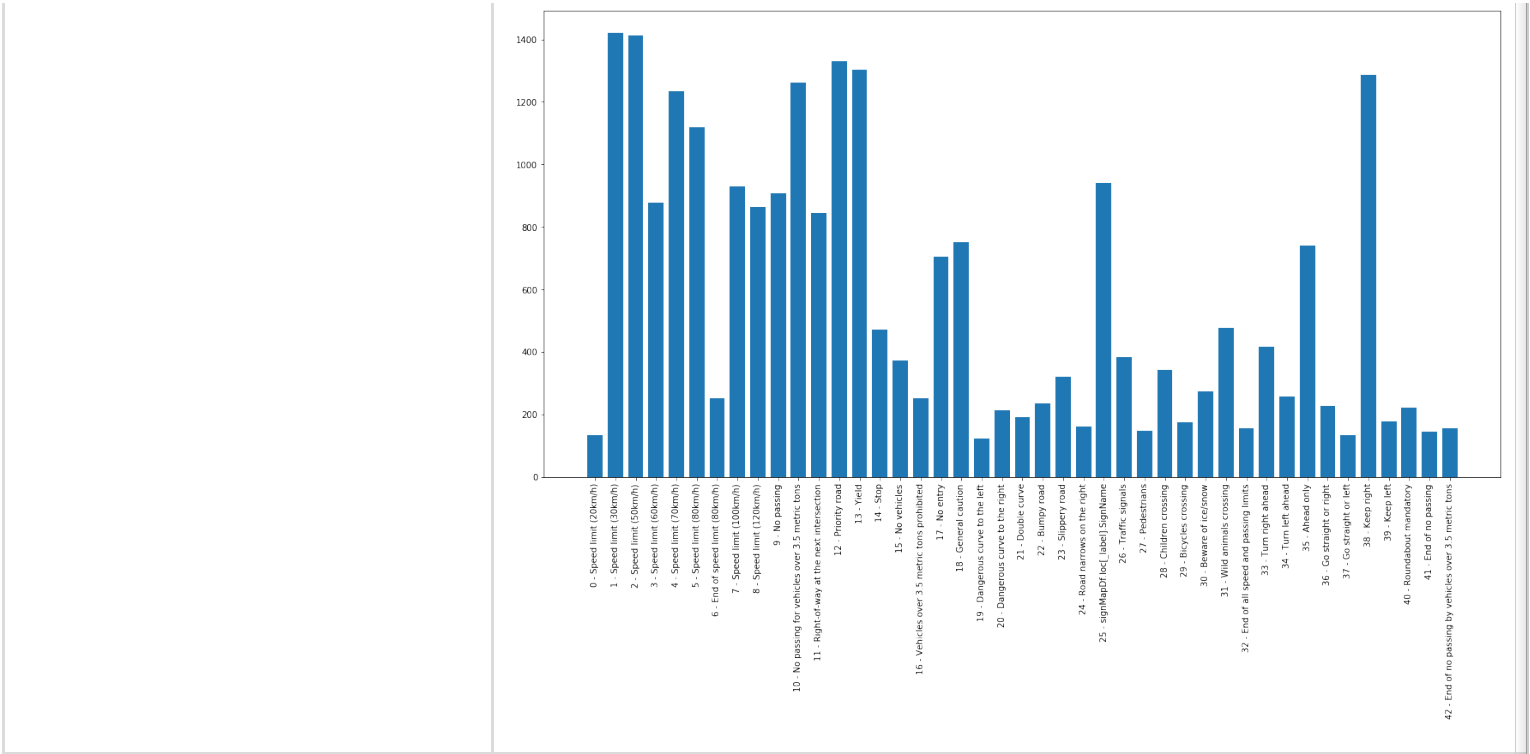
Link to this Notebook: <https://www.evernote.com/l/AC4DAe79zp9GILVrEQZ5uI4TXZB2YRZL2MQ>

Files Submitted

CRITERIA	MEETS SPECIFICATION
Submission Files	<div>The Submission includes<ul style="list-style-type: none"><i>Traffic_Sign_Classifier.ipynb</i> files<i>testSet/</i> test imagesWriteup file as <i>writeup.pdf</i><i>Traffic_Sign_Classifier.html</i></div>

Dataset Exploration

CRITERIA	MEETS SPECIFICATION
Dataset Summary	<div>Database includes 3 files<ul style="list-style-type: none">Train.p - training pickle filevalid.p - validation pickle fileTest.p - test pickle file</div> <div>Each file is a pickle file, It has features and labels in keys `features` and `labels`</div>
Exploratory Visualization	<div>The submission includes an exploratory visualization on the dataset.</div> <div>Training data has 43 traffic signs, each sign differs in the number of samples available for training.</div> <div><div><div><div>I: 41 c: 210</div></div><div><div>I: 31 c: 690</div></div><div><div>I: 36 c: 330</div></div><div><div>I: 26 c: 540</div></div><div><div>I: 23 c: 450</div></div><div><div>I: 1 c: 1980</div></div></div><div><div><div>I: 40 c: 300</div></div><div><div>I: 22 c: 330</div></div><div><div>I: 37 c: 180</div></div><div><div>I: 16 c: 360</div></div><div><div>I: 3 c: 1260</div></div><div><div>I: 19 c: 180</div></div></div><div><div><div>I: 4 c: 1770</div></div><div><div>I: 11 c: 1170</div></div><div><div>I: 42 c: 210</div></div><div><div>I: 0 c: 180</div></div><div><div>I: 32 c: 210</div></div><div><div>I: 27 c: 210</div></div></div><div><div><div>I: 29 c: 240</div></div><div><div>I: 24 c: 240</div></div><div><div>I: 9 c: 1320</div></div><div><div>I: 5 c: 1650</div></div><div><div>I: 38 c: 1860</div></div><div><div>I: 8 c: 1260</div></div></div><div><div><div>I: 10 c: 1800</div></div><div><div>I: 35 c: 1080</div></div><div><div>I: 34 c: 360</div></div><div><div>I: 18 c: 1080</div></div><div><div>I: 6 c: 360</div></div><div><div>I: 13 c: 1920</div></div></div><div><div><div>I: 7 c: 1290</div></div><div><div>I: 30 c: 390</div></div><div><div>I: 39 c: 270</div></div><div><div>I: 21 c: 270</div></div><div><div>I: 20 c: 300</div></div><div><div>I: 33 c: 599</div></div></div><div><div><div>I: 28 c: 480</div></div><div><div>I: 12 c: 1890</div></div><div><div>I: 14 c: 690</div></div><div><div>I: 15 c: 540</div></div><div><div>I: 17 c: 990</div></div><div><div>I: 2 c: 2010</div></div></div><div><div><div>I: 25 c: 1350</div></div><div><div></div></div><div><div></div></div><div><div></div></div><div><div></div></div><div><div></div></div></div></div>



Design and Test a Model Architecture

CRITERIA	MEETS SPECIFICATION
Preprocessing	<ul style="list-style-type: none">Just normalisation was done on data and that achieved 0.96 accuracy on Validation dataset.Doing rotation, scaling based augmentation made the run time increase and the results where not better. A simple normalisation and adding of two convolutional layers before the LeNet architecture got better result,<ul style="list-style-type: none">Training Accuracy = 0.989Validation Accuracy = 0.968
Model Architecture	PF the table below this table
Model Training	Learning rate of 0.001 was used. LeNet architecture was used for training a data set with images of shape (32, 32, 3) EPOCHS = 10 AdamOptimizer a variant of Stochastic Gradient Descent was used as optimiser.
Solution Approach (The submission describes the approach to finding a solution. Accuracy on the validation set is 0.93 or greater.)	Training Accuracy = 0.989 Validation Accuracy = 0.968

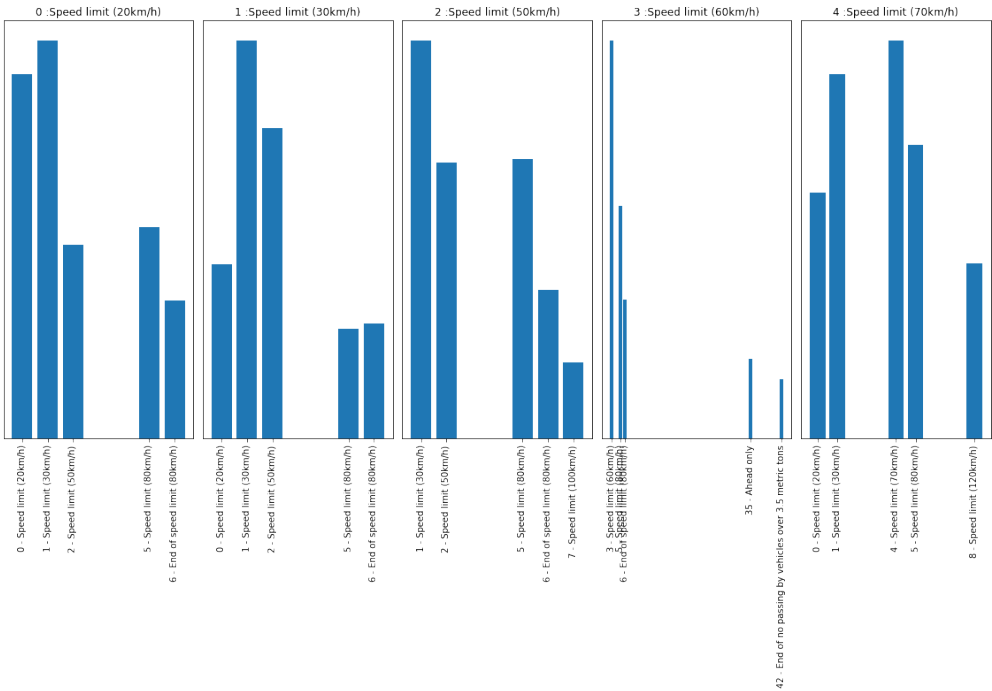
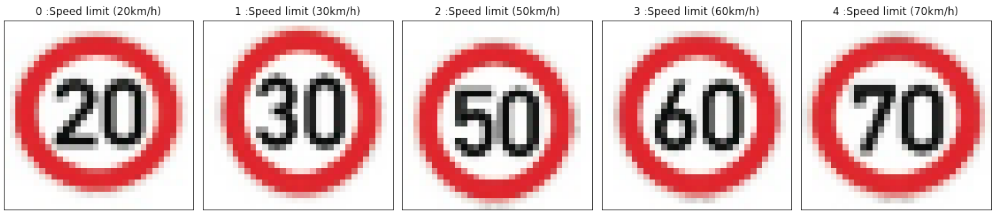
Model Architecture

type	stride	size	filter/feature
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conv	1 x 1 [padding=same]	5 x 5	7

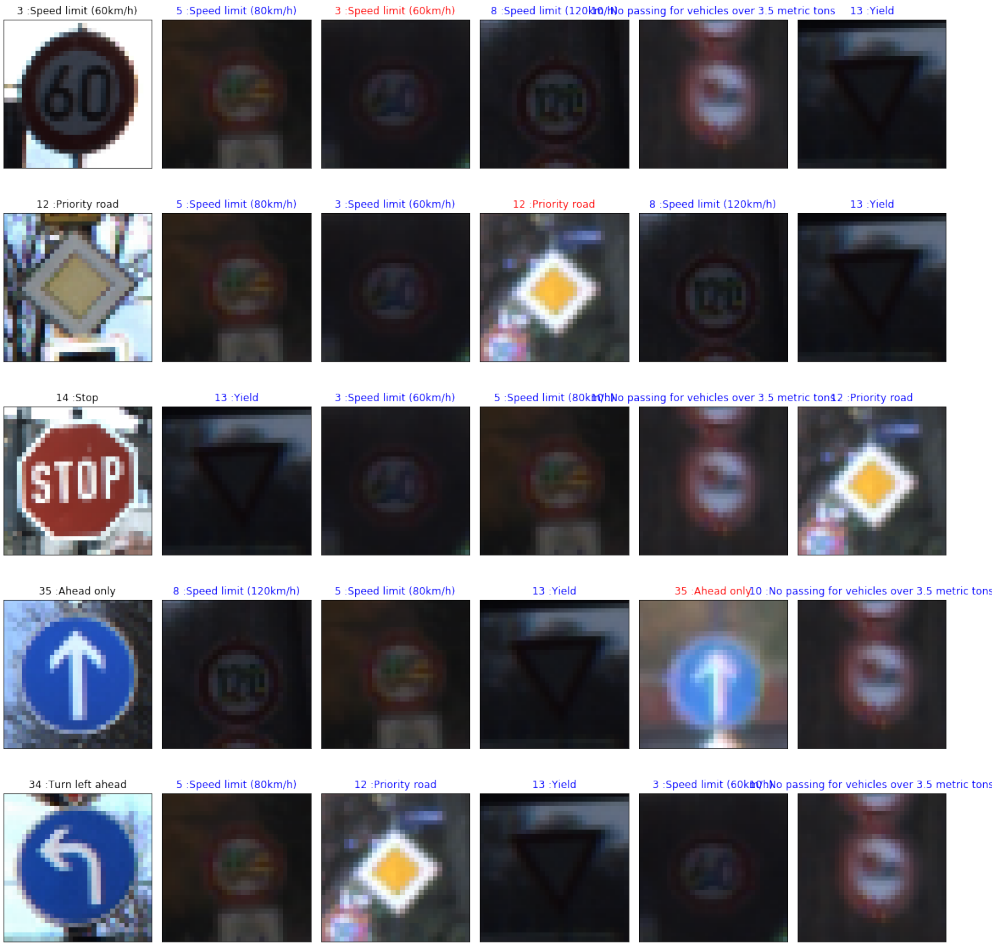
conv	1 x 1 1 [padding=valid]	5 x 5	10
Max pooling	2 x 2 [padding=valid]	2 x 2	
conv	1 x 1	5 x 5	16
Max pool	2 x 2	2 x 2	
flatten			
Fully connected			200
Fully connected			80
Fully connected			43
softmax			43

Test a Model on New Images

CRITERIA	MEETS SPECIFICATION
Acquiring New Images	<p>The submission includes 2 * five new German Traffic signs found on the web.</p> <p>One set has clear images of the traffic signs. The other set has images taken in dark normal road conditions.</p>
Performance on New Images	<p>Images acquired from: http://benchmark.ini.rub.de/?section=gtsrb&subsection=news</p> <p>On a set of sample computer images acquired 60 % accuracy.</p> <div> <div>0 Speed limit (20km/h)</div> <div>8 Speed limit (120km/h)</div> <div>5 Speed limit (80km/h)</div> <div>3 Speed limit (60km/h)</div> <div>4 Speed limit (70km/h)</div> <div>6 End of speed limit (80km/h)</div> </div> <div> <div>1 Speed limit (30km/h)</div> <div>3 Speed limit (60km/h)</div> <div>5 Speed limit (80km/h)</div> <div>6 End of speed limit (80km/h)</div> <div>8 Speed limit (120km/h)</div> <div>10 No passing for vehicles over 3.5 metric tons</div> </div> <div> <div>2 Speed limit (50km/h)</div> <div>5 Speed limit (80km/h)</div> <div>8 Speed limit (120km/h)</div> <div>3 Speed limit (60km/h)</div> <div>10 No passing for vehicles over 3.5 metric tons</div> <div>7 Speed limit (50km/h)</div> </div> <div> <div>3 Speed limit (60km/h)</div> <div>3 Speed limit (60km/h)</div> <div>5 Speed limit (80km/h)</div> <div>10 No passing for vehicles over 3.5 metric tons</div> <div>13 Yield</div> <div>8 Speed limit (120km/h)</div> </div> <div> <div>4 Speed limit (70km/h)</div> <div>8 Speed limit (120km/h)</div> <div>5 Speed limit (80km/h)</div> <div>4 Speed limit (70km/h)</div> <div>18 General caution</div> <div>3 Speed limit (60km/h)</div> </div>



While the set with road conditions gave 100 accuracy.



Suggestions to Make Your Project Stand Out!

Here are a few ideas for going beyond the requirements outlined in the rubric.

AUGMENT THE TRAINING DATA

Augmenting the training set might help improve model performance. Common data augmentation techniques include rotation, translation, zoom, flips, and/or color perturbation. These techniques can be used individually or combined.

ANALYZE NEW IMAGE PERFORMANCE IN MORE DETAIL

Calculating the accuracy on these five German traffic sign images found on the web might not give a comprehensive overview of how well the model is performing. Consider ways to do a more detailed analysis of model performance by looking at predictions in more detail. For example, calculate the [precision and recall](#) for each traffic sign type from the test set and then compare performance on these five new images..

If one of the new images is a stop sign but was predicted to be a bumpy road sign, then we might expect a low recall for stop signs. In other words, the model has trouble predicting on stop signs. If one of the new images is a 100 km/h sign but was predicted to be a stop sign, we might expect precision to be low for stop signs. In other words, if the model says something is a stop sign, we're not very sure that it really is a stop sign.

Looking at performance of individual sign types can help guide how to better augment the data set or how to fine tune the model.

CREATE VISUALIZATIONS OF THE SOFTMAX PROBABILITIES

For each of the five new images, create a graphic visualization of the soft-max probabilities. Bar charts might work well.

VISUALIZE LAYERS OF THE NEURAL NETWORK

See Step 4 of the Iptyon notebook for details about how to do this.